## A Study of Function Landscape and Search Space with Evolutionary Algorithms

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Sallam, Karam

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# A Study of Function Landscape and Search Space with Evolutionary Algorithms 

Karam Mohamed Goda Mohamed Sallam

A thesis submitted in fulfilment of the requirements
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Australia

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Title: A Study of Function Landscape and Search Space with Evolutionary Algorithms

## Abstract 350 words maximum: (PLEASE TYPE)

Optimization techniques are used extensively to solve many real-world decision-making problems which have different characteristics and mathematical properties that make the process of finding their optimal solutions difficult. Evolutionary computation is one of the fastest growing areas that has been extremely successful when used to solve both unconstrained and constrained optimization problems (COPs) with a wide variety of properties.

In this thesis, using evolutionary algorithms (EAs) to solve optimization problems, whereby a search space is usually defined by the variables' bounds, is considered. However, in a COP, the feasible space, which is bounded by the constraint functions, may represent a relatively small portion of the search space. Existing EAs, using an analogy of black-box optimization, ignore specific information about the functions and search space even though details of their mathematical functions and properties are known. The objective of this research was to study the properties of the functions and search space to derive information that would be useful for designing effective and efficient EAs for solving optimization problems.

Although fitness landscape analysis (FLA) measures are helpful for judging a problem's complexity, they have rarely been used in the design of an EA. In most COPs, the optimal solution lies on the boundary of the feasible space. As this simple information may help to concentrate the search process in certain regions instead of the entire search space, this thesis proposes new EAs that use information from the function/problem landscape and search space for constrained problems to enhance the performances of algorithms for solving continuous optimization problems. Firstly, a FLA-based differential evolution (DE) algorithm for solving unconstrained optimization problems is developed. Secondly, an algorithm for solving COPs, in which the landscape information from both the objective and constraint functions is considered, is proposed. Thirdly, a new technique for identifying the active constraints is developed and then a reduced search space around the active constraints determined, a concept applied with evolutionary algorithms. Finally, the information from the FLA and mechanism for reducing the search space are used to design an algorithm that incorporates multiple population-based algorithms in a single algorithmic structure.

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#### Abstract

Optimization techniques are used extensively to solve many real-world decisionmaking problems which have different characteristics and mathematical properties that make the process of finding their optimal solutions difficult. Evolutionary computation is one of the fastest growing areas that has been extremely successful when used to solve both unconstrained and constrained optimization problems with a wide variety of properties.

In this thesis, using Evolutionary Algorithms (EAs) to solve optimization problems, whereby a search space is usually defined by the variables bounds, is considered. However, in a constrained problem, the feasible space, which is bounded by the constraint functions, may represent a relatively small portion of the search space. Existing EAs, using an analogy of black-box optimization, ignore specific information about the functions and search space even though details of their mathematical functions and properties are known. The objective of this research was to study the properties of the functions and search space to derive information that would be useful for designing effective and efficient EAs for solving optimization problems.

The specific interests of this study are in analyzing the landscape and identifying the most attractive region for an effective search. Although Fitness Landscape Analysis (FLA) measures are helpful for judging a problems complexity, they have rarely been used in the design of an EA. In most constrained problems, the optimal solution lies on the boundary of the feasible space. As this simple information may help to concentrate the search process in certain regions instead of the entire


search space, this thesis proposes new EAs that use information from the function/problem landscape and search space for constrained problems to enhance the performances of algorithms for solving continuous optimization problems.

Firstly, a FLA-based Differential Evolution (DE) algorithm for solving unconstrained optimization problems is developed. Secondly, an algorithm for solving constrained problems, in which the landscape information from both the objective and constraint functions is considered, is proposed. Thirdly, a new technique for identifying the active constraints is developed and then a reduced search space around the active constraints determined, a concept applied with evolutionary algorithms. Finally, the information from the FLA and mechanism for reducing the search space are used to design an algorithm that incorporates multiple population-based algorithms in a single algorithmic structure.

All four versions of the developed algorithm are tested by solving standard benchmark problems and their results compared with those obtained from several state-of-the-art algorithms. In all cases, they achieve significant improvements, with the first, second, third and fourth obtaining respective savings in computational time and fitness evaluations of $15.1 \%$ and $15.7 \%, 69.0 \%$ and $33.0 \%, 36.69 \%$ and $11.88 \%$ and $22.01 \%$ and $20.73 \%$, respectively.

## Keywords

Evolutionary algorithms, constrained optimization, differential evolution, landscape analysis, reduced search space

## List of Publications

## Journal Articles:

1. K. M. Sallam, S. M. Elsayed, R. A. Sarker, and D. L. Essam, "Landscapebased adaptive operator selection mechanism for differential evolution," Information Sciences, vol. 418, pp. 383-404, 2017. (based on Chapter 3, sections 3.3 and 3.4)
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3. K. M. Sallam, S. M. Elsayed, R. A. Sarker, and D. L. Essam, "Two-phase differential evolution framework for solving optimization problems," in Computational Intelligence (SSCI), 2016 IEEE Symposium Series on. IEEE, 2016, pp. 1-8. (Chapter 3)
4. K. M. Sallam, S. M. Elsayed, R. A. Sarker, and D. L. Essam, "Differential evolution with landscape-based operator selection for solving numerical optimization problems," in Intelligent and Evolutionary Systems: The 20th Asia Pacific Symposium, IES 2016, Canberra, Australia, November 2016, Proceedings. Springer, 2017, pp. 371-387. (Chapter 3)
5. K. M. Sallam, S. M. Elsayed, R. A. Sarker, and D. L. Essam, "Landscapebased Differential Evolution for Constrained Optimization Problems," submitted, in in Computational Intelligence (SSCI), 2017 IEEE Symposium Series on. IEEE, 2017. (Chapter 4)
6. K. M. Sallam, S. M. Elsayed, R. A. Sarker, and D. L. Essam, "Multi-method based orthogonal experimental design algorithm for solving cec2017 competition problems," in Evolutionary Computation (CEC), 2017 IEEE Congress on. IEEE, 2017, pp. 1350-1357. (Chapter 6)
7. K. M. Sallam, R. A. Sarker, D. L. Essam, and S. M. Elsayed, "Neurodynamic differential evolution algorithm and solving cec2015 competition problems," in Evolutionary Computation (CEC), 2015 IEEE Congress on. IEEE, 2015, pp. 1033-1040.

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## List of Abbreviations

| Abbreviations | Description |
| :--- | :--- |
| ACD | active constraint determination |
| ACO-MH | ant colony optimization meta-heuristic |
| AOS | adaptive operator selection |
| AP | adaptive pursuit |
| AUC | area under the curve |
| BBOB | black-box optimization benchmarking |
| BLX-alpfa | blend crossover |
| CARP | capacitated arc routing problem |
| CEO | constrained evolutionary optimization |
| CHTs | constraint handling techniques |
| CI | computational intelligence |
| CMA | covariance matrix adaptation |
| COCO | comparing continuous optimization |
| COPs | constrained optimization problems |
| DE | deferential evolution |
| DM | dispersion metric |
| DV | difference vector |
| EAs | evolutionary algorithms |
| ELA | exploratory landscape analysis |
| EP | evolutionary programming |
| ES | evolution strategy |
| FDC | fitness distance correlation |
| FLA |  |


| FVs | function values |
| :--- | :--- |
| G3 | generalized generation gap |
| GA | genetic algorithm |
| HMHH | heterogeneous meta-hyper-heuristic |
| HSD | heuristic space diversity |
| ICA | information characteristics |
| ILNS | information landscape negative searchability |
| IMM | Istanbul metropolitan municipality |
| LHD | Latin hyper-cube design |
| LPSR | linear population size reduction |
| LS | length scale |
| MAP | multi-armed bandit |
| MMTS | modified multiple trajectory search |
| MOPs | multi-objective optimization problems |
| NLD | normalized landscape |
| NPM | normalized performance measure |
| PAP | population-based algorithm portfolio |
| PCX | parent-centric crossover |
| PIC | partial information content |
| PMs | penalty methods |
| PSO | particle swarm optimization |
| QAP | quadratic assignment problem |
| R2S | reduced search space |
| SI | swarm intelligence |
| SoR | spx |


| SR | stochastic ranking |
| :--- | :--- |
| SSRT | search space reduction technique |
| TC | triangular crossover |
| UCB | upper confidence bound |
| UNDX | unimodal crossover |

## Chapter 1

## Introduction

This chapter begins by providing the background to and description of the research. Then, the objective of this study and its contributions to scientific knowledge are discussed. Finally, the organization of this thesis is presented.

### 1.1 Background

Optimization plays an important role in many practical decision-making processes. For several decades, it has attracted the attention of a large number of researchers and practitioners for solving complex optimization problems in many fields, such as scheduling a supply chain, controlling an infrastructure design, allaying natural disasters, organizing transportation systems and optimizing industrial processes, which can be mainly categorized as unconstrained and constrained. Its aim is to determine the values of a problem's design variables by optimizing (either maximizing or minimizing) one or more of its objective functions [? ]. The importance of using optimization methods to solve real-world application problems can be demonstrated using some examples. The estimated annual savings from scheduling crash tests at the Ford Motor Company are $\$ 1$ million [1]. By optimizing the locations of fire stations, the Istanbul Metropolitan Municipality (IMM) was able to increase the area covered by the citys fire station from $58.6 \%$ to $85.9 \%$ [2]. Applying optimization enabled Chevron (one of the worlds leading integrated energy companies) to provide approximately $\$ 1$ billion per year in benefits [3]. Optimizing ship routing at the Danaos Corporation maximized
its profits by $\$ 4.5$ million in 2011 and helped the company minimize carbon emissions, reduce staff workloads and increase customer satisfaction [4]. The estimated financial benefits from 2011 to 2028 obtained by optimizing water routing and hydroelectric generation on the Columbia River are expected to be between $\$ 765$ and $\$ 952$ million [5]. Using optimization has enabled Procter and Gamble to earn approximately $\$ 70$ billion in annual revenue [6] and the Bank of New York to solve collateral-management challenges involving short-term secured loans which reduced intra-day credit risk by $\$ 1.4$ Trillion [7].

Researchers and practitioners have used both traditional optimization and Computational Intelligence (CI) approaches to solve complex optimization problems. However, the former encounters many difficulties [8], such as their convergence to a near-optimal or optimal solution relies on the initial solution, they require specific mathematical properties, such as continuity, convexity and differentiability, to be satisfied and they may need to simplify a problem for mathematical representation by making different assumptions [9]. On the contrary, CI approaches, which are resilient to dynamic changes, have the capability to selforganize, do not require particular mathematical characteristics to be satisfied and can evaluate several solutions in parallel, are widely used in practice [10] [11]. However, there is no guarantee that they will obtain the optimum solutions and the quality of their solutions relies on the particular algorithm's design, the selection of its operators and its parameter settings.

Of current CI approaches, evolutionary algorithms (EAs), such as differential evolution (DE) [12], Evolution Strategy (ES) [13], Evolutionary Programming (EP) [14] and Genetic Algorithms (GAs) [15], are population-based algorithms that use some types of selection, crossover and mutation operators to generate new candidates and guide the search towards optimal solutions. Of them, DE has
been widely applied in many fields, gained popularity for solving continuous optimization problems and has shown its superiority over other methods for solving complex optimization problems with different characteristics [16, 17]. Over the years, several mutation strategies aimed at improving the performance of DE for solving continuous optimization problems have been proposed [18, 19]. However, none performs well for all kind of problems [20-22] and, moreover, no single algorithm has been found to be the best for solving all the problems considered in the literature [23, 24].

A function landscape is represented by a surface in the search space that reflects the fitness function value of each solution. A fitness landscape analysis (FLA) has become a popular method for analyzing the characteristics of optimization problems, such as their ruggedness, complexity, modality, presence of funnels, neutrality and variable separability. It consists of a set of solutions (populations of individuals) in which each individual has a fitness value (also known as an objective function value) and a neighborhood operator that may be expressed as a distance measure [25]. Many FLA methods for classifying a problem as either easy or difficult, such as auto-correlation [26, 27], fitness distance correlation [28], dispersion metric [29], length scale [30] and information characteristics analysis [31], have been suggested. Researchers and practitioners have used FLA to determine a function's modality [32] [25], the sizes of basins of attraction [33], the existence of funnels in a fitness landscape [34] and a problem's ruggedness [26, 27, 30]. It is expected that using such methods during the evolutionary process may help to determine the most appropriate algorithm and/or search operators for a problem.

In a Constrained Optimization Problem (COP), the functional constraints generate a feasible space that is usually much smaller than the search space defined by the variables' bounds. Also, as all constraints with values of zero at the optimal
solution are considered active ones, equality constraints are always active. In many real-world problems, the optimal solution lies on the boundary of the feasible region, that is, the intersection of the active constraints [35], with one of the most relevant characteristics of a boundary search its reduced search space as it explores only a portion of the whole search space [36]. Due to its importance, many attempts have been made to search the boundary of the feasible region [3538]. It is expected that designing an EA that uses a mechanism to focus the search process around the previously determined active constraints could help to obtain the optimal solution more quickly and solve a COP more efficiently than using only an EA.

### 1.2 Problem Description and Research Gaps

As previously discussed, optimization problems can be either unconstrained or constrained. They have different characteristics and mathematical proprieties, such as their objective functions and constraints may be unimodal or multi-modal, continuous or discontinuous, linear or nonlinear, and their variables discrete or real. Also, the feasible region of a COP can be either a small or large portion of the search space and either one bounded region or a set of disjointed ones or, in some practical problems, even unbounded [?]. These different characteristics make the process of locating the optimal solution challenging [? ].

Of the many solution approaches developed, EAs have demonstrated great success in solving both unconstrained problems and COPs with a wide variety of properties. However, their performances are highly dependent on the algorithms design, and the selection of its operators and parameter settings. Also, no single algorithm and/or search operator performs consistently well for all the types of optimization problems defined in the literature [17, 39]. Moreover, the process for
determining the most suitable EA and/or its search operators for solving a particular problem could be carried out using useful information about the problems landscape rather than a trail-and-error approach [?].

FLA has become a popular method for understanding the complexity of an optimization problem for which an EA either succeeds or fails [25]. However, such an approach is often carried out in an offline mode, i.e., the existing experiments were conducted independently from the evolutionary process [25]. Also, it was computationally expensive [40], and limited work has been carried out for solving optimization problems. Although the use of function and search space specific information may help in selecting the proper evolutionary operator in solving a particular problem, it has not been fully explored in designing such an optimization algorithm.

In a COP, the feasible space, which is bounded by the constraint functions, may represent a relatively small portion of the search space [41] and, in many cases, the optimal solution lies in the boundary of the feasible space [35, 36] (the intersection of the active constraints). Although EAs have been successfully used to solve COPs, they still suffer from the drawback of wasting a considerable amount of time (fitness evaluations) searching ineffective areas in the search space [42]. Therefore, it is expected that, using the simple information that the optimal solution lies on the boundary of the feasible region may help to concentrate the search process in certain regions instead of the entire search space. This will improve an algorithms performance by reducing the computational time and number of fitness evaluations it requires to reach the optimal solution.

### 1.3 Research Objective

Motivated by the research gaps discussed above, the overall goal in this thesis, is to propose new EAs that utilize information from a function's/problem's landscape and search space to enhance the performance of the algorithms in solving continuous optimization problems.

To achieve this goal, this studys sub-objectives are to:

1. analyze the performances of different DE variants;
2. propose a new algorithm which uses landscape information to select the most suitable DE, from a set, during the evolutionary process for solving unconstrained optimization problems;
3. propose an algorithm that uses the strength of more than one DE and chooses the best based on the objective function and constraint landscapes for solving COPs;
4. propose a mechanism for reducing the search space by focusing on the area around the active constraints; and
5. propose an algorithm that uses multiple EAs and both a Reduced Search Space (R2S) mechanism and landscape information.

### 1.4 Contributions to Scientific Knowledge

The general scientific contribution of this thesis is the development of methods that use information from a problems landscape and reduce the search space to enhance the performances of EAs. Firstly, a FLA-based DE algorithm for solving unconstrained optimization problems is proposed. Secondly, an algorithm for
solving COPS, in which the landscape information from both the objective and constraint functions are considered, is proposed. Thirdly, a new technique for identifying the active constraints and then determining a reduced search space around them is developed and applied with several EAs. Finally, the information from a FLA and R2S mechanism are used in the design of an algorithm that incorporates the following multiple population-based algorithms in a single algorithmic structure.

- Landscape-based DE algorithm for solving unconstrained optimization problems: it contains a fitness landscape measure for determining the best-performing DE operator in a pool during the evolutionary process. The performances of different DE variants for solving unconstrained problems are analyzed, with the experimental results demonstrating this algorithms superiority over both itself with different selection mechanisms and several state-of-the-art algorithms, and its capability to save $15.1 \%$ of computational time and $15.7 \%$ of fitness evaluations.
- Landscape-based algorithm for solving COPs: in it, information from the objective function and constraint landscapes is used to choose the best operator from a pool during the evolutionary process and its components are analyzed. This new design demonstrates its superiority over both several state-of-the-art algorithms and itself with other selection mechanisms, and achieves $69.0 \%$ and $33.0 \%$ savings in computational time and fitness evaluations, respectively.
- Reduced search space mechanism for solving COPs: it determines the active constraints based on the entire populations and focuses the search space around them. It is incorporated in six state-of-the-art algorithms, with the
results showing that it significantly improves the performances of these algorithms and leads to savings in computational time of $36.69 \%$ and fitness evaluations of $11.88 \%$.
- Multi-EAs algorithm for solving COPs: this novel algorithmic design uses multiple EAs and both the R2S mechanism and landscape measure. Its different components are analyzed and then the results obtained from its best variants compared with those from several state-of-the-art algorithms, with the results demonstrating its usefulness as it achieves $22.01 \%$ and $20.73 \%$ savings in computational time and fitness evaluations, respectively.


### 1.5 Organization of Thesis

This thesis consists of the following 7 chapters.

- Chapter 1: Introduction
- Chapter 2: Background Study and Literature Review
- Chapter 3: Landscape-based Algorithm for Unconstrained Optimization Problems
- Chapter 4: Landscape-based Algorithm for Constrained Optimization Problems
- Chapter 5: Reduced Search Space Mechanism for Constrained Optimization Problems
- Chapter 6: Multi-EAs Framework for Constrained Optimization Optimization Problems
- Chapter 7: Conclusions and Future Research Directions

Chapter 1 presents an introduction to this thesis, beginning with an overview of this research field, followed by a description of the problem as well as the motivation for, and objectives of, this study. Its scientific contributions are then discussed and its organization presented.

In Chapter 2, a review of the basic fundamentals of the topics covered in this thesis is presented. Firstly, unconstrained optimization problems and COPs are introduced and the EAs available for solving them described. Then brief descriptions of landscape analysis measures and constraint-handling techniques are provided. Next, a review of EAs, and FLA for solving unconstrained and constrained optimization problems are provided, and finally, a review of boundary search methods and search space reduction are discussed.

In Chapter 3, brief descriptions of the benchmark unconstrained optimization problems used are provided. A general multi-operator DE framework, in which more than one DE mutation strategy and the problems landscape information are used, is proposed. Also, an analysis of the algorithm's components is undertaken and, finally, its results presented and compared with those of several state-of-theart algorithms.

In Chapter 4, descriptions of the benchmark COPs used are provided. An algorithm for solving COPs, in which information from the objective function and constraint landscapes is used to choose the best operator from a pool during the evolutionary process, is described. The different components of the proposed algorithm are described, with the experimental results obtained from it for solving different sets of COPs analyzed and compared with those from several state-of-the-art algorithms.

In Chapter 5, a new R2S mechanism is introduced and then integrated with
six state-of-the-art algorithms for solving COPs. The different components of the proposed mechanism are described, with the experimental results obtained from algorithms with and without it analyzed and compared.

In Chapter 6, a new multi-method algorithm that uses information from the search space and a problem's landscape is proposed. Its various components are presented and the experimental results obtained from it for solving different sets of COPs analyzed and compared with those from several state-of-the-art algorithms.

In Chapter 7, this studys main findings and conclusions are discussed, and possible future research directions suggested.

## Chapter 2

## Background Study and Literature Review

This chapter provides an overview of the basic fundamentals of the topics covered in this thesis. It begins with a brief discussion of unconstrained and constrained optimization problems and reviews computational intelligence (CI) methods for solving them. Then brief descriptions of landscape analysis measures and constraint-handling techniques are provided. Next, a review of EAs, and FLA for solving unconstrained and constrained optimization problems is provided. Finally, a review of boundary-search methods and search space reduction mechanism is presented.

### 2.1 Optimization Problems

Optimization problems are commonly found in many real-world applications, such as scheduling, industrial process optimization, vehicle routing in large-scale networks and gene recognition in bio-informatics. Their task is to decide the values of the design variables via optimizing (either maximizing or minimizing) one or more objective functions [43]. These problems can be categorized into two different categories, unconstrained and constrained. They may comprise distinct kinds of variables, such as integer and real, and constrained ones may also have equality and/or inequality constraints. The objective and constraint functions can be either unimodal or multimodal, linear or nonlinear and continuous or discontinuous. These classifications are briefly discussed below.

Classification based on existence of constraints - as previously stated, an optimization problem is called a constrained one (COP) if its formulation contains one or more constraints, otherwise it is considered an unconstrained one.

Classification based on types of design variables - based on the types of its decision variables, an optimization problem can be discrete (integer), whereby the values of the design variables must be discrete, or continuous (real).

Classification based on types of functions included - in this category, an optimization problem is classified as being a linear, nonlinear, geometric or quadratic programming one. An optimization problem is called linear, if its objective function and all its constraints are linear functions of the design variables. It is called nonlinear, if its objective function or any of its constraints is nonlinear. If its objective function is quadratic and all its constraints are linear functions of its decision variables, an optimization problem is called a quadratic optimization problem. An optimization problem is called a geometric programming problem if its fitness function and constraints can be expressed as the sum of its power terms.

Classification based on the number of objective functions - there are two categories: 1) a single-objective problem is one in which there is only one objective function; and 2) a multi-objective problem has more than one objective function.

This thesis deals with continuous, single-objective, unconstrained and constrained optimization problems, which are defined in the following sections.

### 2.1.1 Unconstrained optimization problems

An unconstrained optimization problem consists of an objective function and a bound constraint, with the structure of those considered in this thesis being
defined as:

$$
\begin{array}{r}
\text { minimize or maximize } f(\vec{x}) \\
\text { subject to: } L_{j} \leq x_{j} \leq U_{j}, j=1,2, \ldots, D \tag{2.1}
\end{array}
$$

where $f(\vec{x})$ is the fitness function (objective function), $\vec{x}=\left[x_{1}, x_{2}, \ldots, x_{D}\right]$ a decision variables vector with $D$ dimensions, $x_{j}$, has lower and upper bounds $L_{j}$ and $U_{j}$, respectively.

### 2.1.2 Constrained optimization problems (COPs)

Optimizing a COP is more challenging than optimizing an unconstrained one, because to obtain an optimal solution, additional constraints have to be satisfied. A COP can be expressed mathematically as:

$$
\begin{array}{r}
\text { minimize or maximize } f(\vec{x}) \\
\text { subject to: } g_{k}(\vec{x}) \leq 0, k=1, \ldots, s \\
h_{e}(\vec{x})=0, e=1, \ldots, q \\
L_{j} \leq x_{j} \leq U_{j} \tag{2.2}
\end{array}
$$

This problem has $s$ inequality constraints, $g_{k}(\vec{x}), q$ equality constraints, $h_{e}(\vec{x})$, and each variable, $x_{j}$, has a lower and upper bound, $L_{j}, U_{j}$, respectively. The aim is to determine the values of all variables, $x_{1}, x_{2}, \ldots, x_{D}$, that minimize (or maximize) the objective function, $f(\vec{x})$, while satisfying all the constraints, including the bound ones. The feasible region of this problem can be either a small or large portion of the search space, and either a one bounded region or a set of disjointed ones and, in some practical problems, even unbounded [43]. The optimal solution may lie either on the boundary of feasible space or inside it.

Over the years, researchers and practitioners have used both traditional and computational intelligence (CI) approaches, such as EAs and Swarm Intelligence (SI), to solve complex optimization problems. However, the former encounter many difficulties [8], such as: 1) their convergence to a near-optimal or optimal solution relies on the initial solution; 2) they require specific mathematical properties, like continuity, convexity and differentiability, to be satisfied; and 3) they may need to simplify a problem by making different assumptions for the convenience of mathematical modeling [9]. Therefore, researchers have begun to use CI approaches because of their many advantages, for example, as evolutionary algorithms (EAs) are resilient to dynamic changes and have the capability of self-organization, they do not need particular mathematical characteristics to be achieved, can evaluate several solutions in parallel, are widely used in practice [10], and they have often been proven to work better than traditional methods [11]. However, there is no guarantee that EA-based methods can obtain exact solutions and the quality of their solutions relies on the design of algorithms, selection of operators and settings of their parameters. In fact, as no single EA has been found to be the best for solving all types of optimization problems, generally, using more than one algorithm in a single framework may help to overcome this limitation $[23,24]$. In the following section, an overview of EAs is presented.

### 2.2 Evolutionary Algorithms (EAs)

EAs are nature-inspired optimization methods that are used to evolve populations of individuals from generation to generation, to produce increasingly better solutions to an optimization problem [44]. They have a long history of successfully tackling different optimization problems [43].

Over the years, many EAs, such as differential evolution (DE) [12], evolutionary programming (EP) [14], genetic algorithms (GAs) [15] and evolution strategy (ES) [13], have been proposed. All EAs have similar structures, with the only differences between them being, their order and type of operations, and the ways in which they generate their initial population [45]. In their internal processes, individuals are represented (encoded) in different ways, i.e., binary, integer, real-value and string, and common operators, such as mutation, recombination (crossover) and/or selection, are used to generate new candidates. In a recombination operator, two or more selected parents generate one or more offspring. In contrast, a mutation operator is applied to one candidate in order to produce a perturbed candidate with the hope of maintaining diversity. Each new candidate will only survive to the next population only if it is better than its parent. These steps are iterated until a good solution is obtained or a stopping criterion is met [45].

As, based on the extant literature, DE has been acknowledged as a successful optimization algorithm for solving various optimization problems in the continuous domain $[16,17,43,46]$. The following sub-sections briefly describe the main features of a few well-known EAs.

### 2.2.1 Differential evolution (DE)

DE is an EA variant which was proposed by Storn and Price [12]. It is popular because it usually converges fast, is simple to implement and the same parameter values can be applied for various optimization problems. In the literature, it is shown to perform better than several other EAs for a wide range of problems [43]. DE is consistent and reliable for solving many real-life nonlinear COPs, such as those in power and chemical systems, communication, and pattern reconciliation [47]. It starts with an initial population, and then constructs a new solution from current or existing ones. To do this, three operators, "mutation, crossover
and selection", are employed during the search process. Its structure and main operators are described below. For more details, readers are referred to [16, 17, 46].

### 2.2.1.1 Mutation

DE uses a mutation operator before crossover. In a simple mutation (DE/rand/1), three candidates are randomly selected and a mutant individual is produced by multiplying a scaling factor $(F)$ by the difference (DV) between two individuals, with their result summed to a third one as [43]:

$$
\begin{equation*}
\vec{V}_{z, G}=\vec{x}_{r_{1}, G}+F \times\left(\vec{x}_{r_{2}, G}-\vec{x}_{r_{3}, G}\right) \tag{2.3}
\end{equation*}
$$

where $r_{z} \in[1, N P], z=1,2,3$ are random numbers such that $z \neq r_{1} \neq r_{2} \neq r_{3}$, $N P$ is the number of individuals (population size), $F$ is a positive number used to scale DV , and $G$ is the current generation. In the literature, several mutation operators, with different searching capabilities [43], such as: DE/best/1 [48], DE/rand-to-best/1 [49], DE/current-to-rand/1 [50], DE/current-to-best/1 [48], DE/rand/2 [48], and DE/current-to- $\phi$ best/1 [51], have been proposed.

### 2.2.1.2 Crossover

Generally, after mutation strategy, crossover operator is employed, to maintain population's diversity [17]. It is used to generate an offspring by mixing variables of the parents and of the mutated vectors. The two common simple crossover operators are exponential and binomial. In the former, firstly, an integer, $c$, in the decision space is randomly selected so that $c \in[1, D]$, where $D$ is the number of variables, $c$ acts as a starting point of the target vector for crossover. Another integer, $C$, selected from $[c, D]$ denotes the number of elements of the donor vector that are used in the offspring vector. Once $c$ and $C$ are selected, an offspring is
generated as:

$$
u_{i, j, G}= \begin{cases}v_{i, j, G} & \text { for } j=\langle c\rangle_{D},\langle c+1\rangle_{D}, \ldots,\langle c+C-1\rangle_{D}  \tag{2.4}\\ x_{i, j, G} & \text { otherwise }\end{cases}
$$

where $j=1,2, \ldots, D$ and the angular bracket, $\langle c\rangle_{D}$, denotes a modulo function of modulus $D$ with a starting index of $c$.

The binomial crossover, which is applied on every $j$ variable if a random number is less than the crossover rate $(C r)$, is calculated by:

$$
u_{i, j, G}= \begin{cases}v_{i, j, G} & \text { if }\left(\text { rand } \leq C r \text { or } j=j_{\text {rand }}\right)  \tag{2.5}\\ x_{i, j, G} & \text { otherwise }\end{cases}
$$

where rand $\in[0,1]$ and $j_{\text {rand }} \in[1,2, \ldots, D]$ are randomly selected to guarantee that at least one value is obtained from the offspring [43].

### 2.2.1.3 Selection

DE uses a selection operator to choose a vector from the parent and offspring ones based on their best fitness function values (FVs). In this step, the value of the objective functions for both the parent and offspring vectors are compared, and the one with better objective FV survives to the next generation according to:

$$
x_{i, G+1}= \begin{cases}u_{i, G+1} & \text { if }\left(f\left(u_{i, G+1}\right) \leq f\left(x_{i, G}\right) \text { or } j=j \text { rand }\right)  \tag{2.6}\\ x_{i, G} & \text { otherwise }\end{cases}
$$

From the literature, it is clear that no single DE algorithm performs well for all kinds of optimization problems. Mezura-Montes et al. [52] compared the


Figure 2.1: Taxonomy of parameter setting
performances of a number of them for solving unconstrained global optimization problems. Jeyakumar and Shanmugavelayutham [53] carried out a convergence analysis of 14 DE algorithms for solving 14 unconstrained global optimization functions, with the results obtained from these two studies demonstrated the fact that no single DE algorithm performs well for all kinds of optimization problems.

### 2.2.1.4 Control parameters of DE

In the literature, it is clear that the performance of DE is sensitive to the choice of the mutation and crossover operators, as well as their associated parameters (the amplification factor, $F$, crossover rate, $C r$, and population size, $N P$ ) [43]. $F$ is used to make a balance between exploration and exploitation. Smaller values of $F$, means av increase in the convergence rate, while larger values means maintain population diversity. $C r$ is used to determine the rate of change in an individual of the population.

Setting the control parameter values in EAs generally, and in DE specifically, can be divided into two processes, parameter tuning and parameter control [54]. Figure 2.1 shows the taxonomy of parameter setting.

### 2.2.1.5 Parameter tuning

In it good parameter values are found before an algorithm is run, and then are not changed during a run, that is, all the parameter values are static during the search process. However, the main disadvantage of parameter tuning is its lack of flexibility during this process [55]. Some of the work using static parameter values is discussed below.

It was recommended by Storn and Price [56] that $N P$ s should be between $5 \times D$ to $20 \times D$, and suggested that a good initial choice of $F$ could be 0.5 . Gamperle et al. [57] claimed that choosing the proper parameters for DE is challenging. In [57], different parameter settings for DE are evaluated and it was found that NPs of between $3 D$ and $8 D$, with $F=0.6$ and $C r$ in the range of $[0.3,0.9]$, are good choices. Ronkkonen et al. [58] advised using $F \in[0.4,0.95]$ and $C r \in[0,0.2]$ for separable functions and $C r \in[0.9,1]$ for non-separable ones. However, the selection of DE's appropriate parameter is yet an open question.

### 2.2.1.6 Parameter control

In these methods, the parameter values change during the running of the algorithm, can be classified as deterministic, adaptive and self-adaptive, as shown in 2.1.

Deterministic methods: the values of the parameters are updated based on some deterministic rules, regardless of any feedback from the algorithm, i.e., a rule is applied when a number of generations has passed since the last time that rule was triggered [59]. As an example, Qian and Li [60] proposed a strategy for adapting $F$ using the diversity of the current population and the number of members of the current Pareto-front. However, a fixed value was used for Cr .

Adaptive methods: parameter values are updated based on some form of feedback from the search, which is used to define the magnitude of the changes to the parameters and/or its direction [54, 61-68]. For example, Zhang and Sanderson [64] introduced an adaptive DE algorithm with an external archive, known as JADE. In it, for each $\vec{x}_{i}, C r$ and $F$ are generated according to normal and Cauchy distributions of the means, $\mu C r, \mu F$, respectively, and a standard deviation of 0.1.

Self-adaptive methods: parameters are coded into chromosomes, and their values are updated by applying evolutionary steps (mutation, crossover and selection) [69].

For example, Brest et al. [69] presented a self-adaptive DE algorithm, known as jDE , in which the control parameters $C r$ and $F$ are determined using a selfadaptive mechanism, by first encoding them into each solution vector and by then adapting them by means of evolution. In it, the values of $C r$ and $F$ are randomly initialized for every individual in the population, and then they are randomly adjusted in subsequent generations based on two probabilities of $\tau_{1}$ and $\tau_{2}$. These new values are used to generate new solutions.

Abbas [70] developed self-adaptive operators for solving Multi-objective Optimization Problems (MOPs). Its crossover and mutation rates are initialized from a uniform distribution in $[0, l]$ and then the parameters are updated using the same concept as its mutation strategy equation. Later this work was extended [71, 72]. Teo [73] developed a DE algorithm with a self-adaptive population size based on self-adaptive Pareto DE algorithm [70]. Tirronen and Neri [74] proposed a technique to adapt NP based on fitness diversity, while population diversity is used to adapt the $F$ and $C r$ values. Fan and Yan [66] presented a self-adaptive DE (SDE) algorithm, in which $F$ and $C r$ can be updated by zoning the evolution.

In summary, DE algorithms with adaptive and self-adaptive techniques have often been more successful than classical ones [66, 69, 71, 72]. However, as no single parameter has been proved to be the best for all kinds of test problems [22, 75, 76], researchers have begun using ensembles of operators, such as mutation and crossover strategies, along with their associated parameter values. Ali et al. [76] developed a new DE algorithm, sTDE-dR, in which a different adaptive method is used to define the values of $F$ and $C r$. The population is divided into $k$ tribes, with a different adaptive mechanism used for each one to update these control parameters.

### 2.2.2 Genetic algorithm (GA)

A GA is one of the most popular population-based algorithms for solving optimization problems. Like DE, GA uses different operators, including crossover, mutation and elitism-preserving techniques [15]. Crossover is the process for generating a new solution by exchanging genes among chromosomes, while elitism ensures the best so far found solution is kept and a mutation operator is used to maintain diversity to escape local solution. GA has been successfully used for solving many difficult real-world problems. However, it faces more difficulties than DE when handling multimodal problems [77]. Its primary operators are described below.

### 2.2.2.1 Genetic representation

Due to variations in the nature of problems, different genetic representations are required, such as binary, permutation and real-value, to represent individuals [43, 78].

### 2.2.2.2 Selection

This is the process of selecting individuals from a population according to their fitness function values (FVs), which are evaluated with respect to a given objective function. Generally speaking, the highest-ranked chromosome will have a greater possibility of being selected than the others and the worst will be eliminated. Several selection methods, such as roulette wheel, rank and tournament [43], have been introduced.

### 2.2.2.3 Crossover:

Once the selection process is completed, a crossover operator is triggered to generate new offspring by exchanging sub-parts of two parent candidates. Several crossover operators have been introduced [43]. Some crossover operators suitable for discrete problems are the uniform, single-point and multi-point [79]. Others for continuous problems are the average [80], flat [81], blend (BLX- $\alpha$ ) [82], simulated binary (SBX) [83], unimodal distribution (UNDX) [84], parent-centric (PCX) [85], simplex (SPX) [86], and triangular (TC) [87]. Elsayed et al. [88] compared the performances of 10 GA variants for solving COPs, with results that showed SBX with non-uniform mutation was the best, and also none of them was suitable to solve all kind of problems defined in the literature.

SBX was originally proposed by Agrawal and Deb [83]. It has been widely used in practice and has been found to work better for test problems with a continuous search space, where the optimum point has unknown bounds [88]. It has also been successfully applied to solve COPs [43, 88, 89]. To generate new individuals using SBX, firstly, two parents, $\vec{x}_{j}^{1}=\left(x_{1}^{1}, x_{2}^{1}, \ldots, x_{D}^{1}\right)$ and $\vec{x}_{j}^{2}=\left(x_{1}^{2}, x_{2}^{2}, \ldots, x_{D}^{2}\right)$, are chosen from the entire population and then two offspring, $\vec{y}_{j}^{1}=\left(y_{1}^{1}, y_{2}^{1}, \ldots, y_{D}^{1}\right)$ and $\vec{y}_{j}^{2}=\left(y_{1}^{2}, y_{2}^{2}, \ldots, y_{D}^{2}\right)$ are generated as follows. Firstly $\beta_{q j}$ is calculated by
equating the area under the probability curve equal to $u_{j}$ as:

$$
\beta_{q j}= \begin{cases}\left(2 u_{j}\right)^{1 / \eta_{c}+1} & \text { if } u_{j} \leq 0.5  \tag{2.7}\\ \left(\frac{1}{2\left(1-u_{j}\right)}\right)^{1 / \eta_{c}+1} & \text { otherwise }\end{cases}
$$

where $u_{i}$ is a random number uniformly generated in the range of $[0,1]$, and $\eta_{c}$ is a user-defined parameter, called the SBX distribution index.

After obtaining the value of $\beta_{q j}$, the offspring is calculated as:

$$
\begin{gather*}
y_{j}^{1}=0.5\left[\left(1+\beta_{q j}\right) x_{j}^{1}+\left(1-\beta_{q j}\right) x_{j}^{2}\right], \forall j=1,2, \cdots, N_{x}  \tag{2.8}\\
y_{j}^{2}=0.5\left[\left(1-\beta_{q j}\right) x_{j}^{1}+\left(1+\beta_{q j}\right) x_{j}^{2}\right] j=1,2, \cdots, N_{x} \tag{2.9}
\end{gather*}
$$

### 2.2.2.4 Mutation:

a mutation operator can be considered a random deformation of strings with a certain probability. Its primary purpose is to preserve genetic diversity over generations, and as a result, avoid local optima. There are many mutations for both discrete and continuous problems, such as Gaussian [90], logarithmic, uniform [91], non-uniform [91] and polynomial [44]. As in [92], non-uniform mutation functions performed well in solving COPs, its main steps are described below.

A child is mutated as [43]:

$$
\begin{array}{r}
y_{j}^{\prime}(G)=y_{j}(G)+\delta_{j}(G) \\
\delta_{j, G}= \begin{cases}\left(U_{j}-y_{j}(G)\right)\left(1-r(G)^{\left(1-\frac{G}{N_{G}}\right)^{b_{q}}}\right) & \text { if } r \leq 0.5 \\
\left(L_{j}-y_{j}(G)\right)\left(1-r(G)^{\left.\left(1-\frac{G}{N_{G}}\right)^{b_{q}}\right)}\right. & \text { if } r>0.5\end{cases} \tag{2.11}
\end{array}
$$

where $L_{j}$ and $U_{j}$ are the lower and upper bounds of variable $x_{j}$, respectively,
$r(G) \in[0,1]$ is a random number, and $G$ and $N_{G}$ are the current generation number and maximum number of generations, respectively. ' $b_{q}^{\prime}$ values are used to control the speed of the step length [43].

### 2.2.3 Evolution strategy (ES)

ES is a type of EA, in which operators of variation and selection are applied to a population of solutions to solve an optimization problem [92]. It has been found to be superior to many other common optimization method [92-96] and also has a strong theoretical background [95, 97, 98]. Of the different variants of ES introduced over the years, such as $(1+1)-\mathrm{ES},(\mu+1)-\mathrm{ES},(\mu, \mathrm{l})$-ES, $(\mu, \lambda)$-ES, CMA-ES [99]. CMA-ES has shown its capability to efficiently solve diverse types of optimization problems [99] and its superiority to other ES algorithms [100, 101]. It uses the following steps [99].

```
Algorithm 1 CMA-ES algorithm
    Generate an initial individual \(\vec{x}_{m}\) and calculate its fitness function value;
    Sample new solutions, such that \(\vec{x}_{z, G+1}=\vec{x}_{m}+\sigma N\left(0, C_{G}\right) \forall z=1: N P\);
    Evaluate and sort the new offspring.
    Select \(\mu\) individuals as a parental vector. Then calculate their center using
    \(\vec{x}_{m, G+1}=\sum_{k=1}^{\mu} w_{k} \vec{x}_{k, G}\) where \(\sum_{k=1}^{\mu} w_{k}=1\) and \(w_{1} \geq w_{2} \geq \ldots \geq w_{\mu}\).
    5: Update the evolution path \(p_{G+1}^{s}\) and \(p_{G+1}^{\sigma}\).
    6: Adapt the covariance matrix \(\left(C_{G+1}\right)\).
    7: Update the global step size \(\left(\sigma_{G+1}\right)\).
    8: Go to steps 2, and repeat theses steps until a stopping criterion is met.
```


### 2.3 Ensembles of EAs

As there is no one algorithm and/or operator capable of consistently solving a wide range of test problems, several methods that use different algorithms or search operators in a single framework, such as ensemble-based (a mix of operators) [75], hyper-heuristics (heuristics selecting from heuristics) [102], mutli-methods (using more than one optimization algorithm) [103, 104], multi-operators (using more
than one search operator in a single optimization algorithm) [23] and heterogeneous (using different algorithms with different behaviors) [105] approaches, have been developed.

These approaches need a selection mechanism to choose or put more emphasis on the best-performing one during the evolutionary process. The following subsection briefly described the adaptive operator selection mechanism.

### 2.3.1 Adaptive operator selection (AOS)

As previously stated, no single operator and/or algorithm is capable of solving a wide range of optimization problems. Therefore, researchers and practitioners have used frameworks that contain more than one search operator or algorithm in a single algorithmic framework, called multi-operator or multi-methods. The selection procedures of these algorithms, which are usually called AOSs, rely on different criteria, such as improvement in the feasibility rate and/or solution quality and/or constraint violations [24], convergence differences and progress ratios [106], a re-enforcement learning mechanism [107, 108] and pheromone updates of the Ant Colony Optimization Meta-Heuristic (ACO-MH) [109]. A comprehensive review of AOS is introduced by Maturana et al. [110], who divides it into its major components of credit assignment and operator selection. The former term defines how to reward an operator and/or algorithm based on its recent performance during a run and the latter uses these rewards to choose one operator and/or algorithm from a pool.

Credit assignment The feedback provided by operators and/or algorithms is used to calculate their rewards, which are maintained in a memory and are then used by the selection component to select the next operator and/or algorithm to be used by the framework.

Operator selection Using the reward values, operator selection methods choose operators and/or algorithms to produce offspring through two mechanisms: 1) probability-based methods, such as Probability Matching PM [111] and Adaptive Pursuit (AP) [112]; and 2) bandit-based methods [113].

- Probability matching and adaptive pursuit methods: often use a roulette wheel-like process to select an operator and/or algorithm. Some AOS methods based on probabilities, such as those used in the ZEPDE [114], DMPSADE [66], JADE [51], and jDE [69] algorithms, can be found in the literature.
- Bandit based methods: are based on the Multi-Armed Bandit (MAB) paradigm [108] [115] , in which each operator is viewed as one arm of a MAB problem, with the rewards based mainly on the fitness improvement brought by the corresponding operator to the individual to which it is applied. In the literature, there are a number of MAB methods, such as the Upper Confidence Bound (UCB) algorithm [107, 116], the Area Under the Curve (AUC), and the Sum-of-Ranks (SoR) [117]. More details can be found in [118].

Selection of operators and/or algorithms based on the characteristics of a problem or its features is rarely investigated in the literature. The fitness landscape analysis (FLA) is usually helpful to judge function complexity [25, 40]. The use of FLA in the selection of operators/algorithms, may boost the performance of the algorithm, if it is carefully incorporated. In the next section, an overview of the landscape measures is provided.

### 2.4 Landscape Analysis

Generally, a fitness landscape consists of a set of solutions (populations of individuals), each solution has a fitness function value (FV) and a neighborhood operator which may be a distance measure [25, 119]. Measuring the fitness landscape of a problem helps researchers to classify a problem as an easy or difficult one to solve [120].

### 2.4.1 Landscape measures

Many landscape measures for understanding and analyzing the different characteristics of optimization problems have been proposed [25, 27]. They are classified in two groups [121], statistical- and information-based, which are briefly reviewed below.

### 2.4.1.1 Statistical-based measures

- Auto-correlation is a method that measures the degree of correlation between neighboring points on a landscape path and is often used to measure the ruggedness of a fitness function [26, 27]. Given a series of points generated by a random walk method, the auto-correlation value can be calculated by:

$$
\begin{equation*}
\rho(a)=\frac{1}{\sigma^{2}(f) \times(k-a)} \times \sum_{t=1}^{k-a}\left(f\left(x_{t}\right)-\bar{f}\right) \times\left(f\left(x_{t+a}\right)-\bar{f}\right) \tag{2.12}
\end{equation*}
$$

where $a$ is the step size between two points, $k$ the number of random walk points, $\sigma^{2}$ the variance of the objective values and $\bar{f}$ the mean fitness. If the auto-correlation value is low, the landscape is considered rugged. There is also another measure
called correlation length [26], which is computed as:

$$
\begin{equation*}
l=\frac{1}{\ln (|\rho(1)|)} \quad \text { for } \rho(1)>1 \tag{2.13}
\end{equation*}
$$

where $\rho(1)$ is the auto-correlation between two points when $a=1$. Smaller values of $l$ indicate more rugged search landscapes and larger ones more smoother landscape.

- The Fitness Distance Correlation (FDC), which was proposed by Jones and Forrest [28], is another landscape method used to realize a problem's difficulty [122]. It measures the correlation between the objective FV and the distance to the nearest optimal solution in the search domain. Given a number of individuals, $X=\left\{\vec{x}_{1}, \vec{x}_{2}, \ldots, \vec{x}_{N P}\right\}$ and their objective FV, $F=\left\{f_{1}, f_{2}, \ldots, f_{N P}\right\}$, the FDC value is computed by:

$$
\begin{equation*}
F D C=\frac{\sum_{i=1}^{N P}\left(f_{i}-\bar{f}\right) \times\left(d_{i}-\bar{d}\right)}{n \times \sigma_{f} \times \sigma_{d}} \tag{2.14}
\end{equation*}
$$

where $d_{i}$ is the distance between the $i^{t h}$ candidate and best one in the population, and $\sigma_{f}, \sigma_{d}, \bar{f}$, and $\bar{d}$, are the standard deviation and average of the fitness function and distance, respectively. In case of minimization, values of $F D C$ near 1 and 0 indicates that the search is easy and difficult, respectively.

- The searchability measure assesses the searchability of a problem, which is the capability of an operator/algorithm to move to an area of the search region with a better FV. It is computed by subtracting the problem information landscape vector from a reference one, which is the landscape of an easy function that is easy to be optimized by any algorithm, regardless of dimension [123].

An information matrix, $M=\left[a_{i, j}\right]$, for a minimization problem is formed using

$$
a_{i, j}= \begin{cases}1 & \text { if } f\left(x_{i}\right)<f\left(x_{j}\right)  \tag{2.15}\\ 0.5 & \text { if } f\left(x_{i}\right)=f\left(x_{j}\right) \\ 0 & \text { otherwise }\end{cases}
$$

Not all the entries in the information landscape are necessary for defining the information landscape [123, 124]. As due to matrix symmetry, the lower triangle can be omitted, the values on the diagonal are always 0.5 , and the row and column of the optimal solution are also unnecessary. Therefore, an information matrix can be decreased to a vector, $L s=\left(l s 1, l s_{2}, \ldots, l s_{|L s|}\right)$, where the number of values is $|L S|=\frac{(N P-1) \times(N P-2)}{2}$.

Given two landscapes, $L s_{f}$ and $L s_{r e f}$, the difference value between them is computed by:

$$
\begin{equation*}
L D=\frac{1}{\left|L s_{f}\right|} \times \sum_{i=1}^{\left|L s_{f}\right|}\left|l s_{1 i}-l s_{2 i}\right| \tag{2.16}
\end{equation*}
$$

When $L D$ is close to 1 , the problem is assumed to be difficult and when it is close to 0 , easy.

- The Dispersion Metric (DM) was introduced by Lunacek and Whitley [20] to predict the existence of funnels, which are global basin shapes consisting of grouped local solutions in a landscape [29]. It measures the mean distance between two high-quality solutions, and is calculated by:

$$
\begin{equation*}
D I S_{\phi \%}=\frac{1}{(\phi \times n) \times(\phi \times n-1)} \times \sum_{i=1}^{\phi \times n-1} \sum_{j=i+1}^{\phi \times n}\left\|x_{i}-x_{j}\right\| \tag{2.17}
\end{equation*}
$$

where $\phi$ represents the top $\phi \%$ of the population. Given a sample of solution points, DM is calculated as the difference between the dispersion of all individuals in the sample and that of the set of best solutions. Negative and positive values of DM indicate the absence and presence of multiple funnels, respectively.

- The Length Scale (LS) is a landscape measure that can be used to reflect the ruggedness, smoothness and neutrality of a problem [30, 125]. It is calculated as:

$$
\begin{equation*}
L S=\frac{\left|f_{1}-f_{2}\right|}{\left\|x_{1}-x_{2}\right\|} \tag{2.18}
\end{equation*}
$$

For more information regarding the fitness landscape analysis measures, readers are referred to $[25,40]$

### 2.4.1.2 Information-based measure

To determine the modality of a function, information characteristics analysis (ICA) may be used. It was proposed by Vassilev et al. [31] to determine the characteristics of the fitness landscapes of discrete problems and was later adapted by Steer et al. [126] and Malan and Engelbrecht [127] to characterize those of continuous ones. Given a sample of individuals generated by a random walk, $X=\left\{\vec{x}_{1}, \vec{x}_{2}, \ldots, \vec{x}_{n}\right\}$, and their FVs, $F=\left\{f_{1}, f_{2}, \ldots, f_{n}\right\}$, the difference between consecutive FVs is used to produce a string, $\prod_{k}(\varepsilon)=\pi_{1}, \pi_{2}, \ldots, \pi_{n}$, where $\pi_{k} \in$ $\{-1,0,1\}$. The value of $\pi_{k}$ is computed by:

$$
\pi_{k}(\varepsilon)= \begin{cases}-1 & \text { if } f_{k}-f_{k-1}<-\varepsilon  \tag{2.19}\\ 0 & \text { if }\left|f_{k}-f_{k-1}\right| \leq \varepsilon \\ 1 & \text { if } f_{k}-f_{k-1}>\varepsilon\end{cases}
$$

where $\varepsilon$ is a sensitivity parameter. The entropic measure, $H(\varepsilon)$, of the string, $\pi_{k}(\varepsilon)$, is calculated by:

$$
\begin{equation*}
H(\varepsilon)=\sum_{d \neq e} P_{[d e]} l o g_{6} P_{[d e]} \tag{2.20}
\end{equation*}
$$

where $d$ and $d$ are elements in the string $\{-1,0,1\}$ and $P_{[d e]}$ is the probability of the occurrence of the sub-blocks, $d e$. The result is a value in the range of $[0,1]$, which is an estimate of a problem's ruggedness. The Partial Information Content (PIC), a measure proposed by Vassilev et al. [31] to measure a function's modality, is calculated by producing a new string, $\prod_{k}^{\prime}(\varepsilon)$, from the old one, $\prod_{k}(\varepsilon)$ by removing all zeroes and repeated digits, $\prod_{k}^{\prime}(\varepsilon)=\pi_{1}, \pi_{2}, \ldots, \pi_{\mu}$, where $\pi_{k} \neq 0$ and $\pi_{k} \neq \pi_{k-1}$. It is computed by:

$$
\begin{equation*}
\operatorname{PIC}(\varepsilon)=\frac{\mu}{n} \tag{2.21}
\end{equation*}
$$

where $\mu$ is the length of $\prod_{k}^{\prime}(\varepsilon)$. PIC determines changes in the slopes in the random walk, which is an indication of local optima, with the number of local optima computed by:

$$
\begin{equation*}
N \approx \frac{P I C(\varepsilon) \times n}{2} \tag{2.22}
\end{equation*}
$$

### 2.5 Constraint Handling Techniques with EAs

In this section, a number of constraint-handling techniques (CHTs) are discussed.

When solving constrained optimization problems with EAs, solutions that satisfy all the constraints are called feasible and those that fail to satisfy at least one of them are called infeasible. As dealing with infeasible solutions in COPs is a big issue, researchers have proposed a number of CHTs for coping with their constraints. These have been incorporated with EAs which have a good history of solving unconstrained optimization problems. One simple way of dealing with infeasible solutions is to completely reject them and continue the search with only feasible ones. However, this has the large drawback that some of the information contained in an infeasible solution may be lost [128]. Mezura-Montes and Coello Coello classify CHTs into two groups [128], early and current CHTs. The former group consists of the following techniques: 1) Penalty methods; 2) decoders; 3) special operators; and 4) separation of objective function and constraints. While the later group includes the following methods: 1) feasibility rules; 2) $\epsilon$-constraint method; 3) stochastic ranking (SR); 4) novel special operators; 5) novel penalty methods; 6) methods using MOP techniques; and 7) hybrid methods. The following section discusses the most popular CHTs.

### 2.5.1 Penalty methods (PMs)

PM is the most common technique used by evolutionary computation (EC) researchers to handle constraints [92]. It is considered the simplest way of adapting an EA to Constrained Evolutionary Optimization (CEO) and can be performed without needing to re-implement the three basic evolutionary procedures (i.e., selection, crossover, mutation). It does this by penalizing infeasible solutions by summing a penalty to their objective function. Generally, penalty functions can
be formulated as:
$f(\vec{x})= \begin{cases}f(\vec{x}) & \text { if all constraints are feasible } \\ f(\vec{x})=f(\vec{x}) \pm\left[\sum_{k=1}^{s} \varrho_{k} \times G_{k}+\sum_{e=1}^{q} \theta_{e} \times H_{e}\right] & \text { otherwise }\end{cases}$
where $G_{k}$ and $H_{e}$ are functions of constraints $g_{k}(\vec{x})$ and $h_{e}(\vec{x})$, respectively, and $\varrho_{k}$ and $\theta_{e}$ penalty factors. In the literature, there are different types of penalty methods [129], such as death penalty [128], static penalty [130]. Some of the recently methods are discussed in the following subsections.

Dynamic Penalty: this technique assumes that the penalty factors depend on the number of generations and vary from generation to generation [131]. It needs fewer parameters [128, 131]. However, in practice, it is difficult to develop good dynamic penalty functions for static functions.

Adaptive Penalty: in it, the values of the penalty parameters are determined, based on information gathered from the search process [92]. Therefore, the value of each penalty parameter is adapted every generation and varies according to the quality of the solutions in the population. These functions are easy to implement and do not require any interaction from the user to define their values [130]. For some methods proposed in this category, a reader can refer to [128].

### 2.5.2 Separation of objective function and constraints

In this approach, the search space is divided into two steps in which constraints and objective function are handled separately. The aim of the first step is to find feasible solutions regardless of their objective FV, while the second is to optimize objective FV.

- Superiority of feasible solutions approach [132]- This method is based on the following heuristic: "every feasible solution is better than any other infeasible solution" [132]. Its main purpose is to provide feasible solutions with an advantage in the selection process by using the following rules when two solutions are compared: i) every feasible solution is better than every infeasible one; ii) of two feasible solutions, the one with the best fitness is preferred; and iii) of two infeasible solutions, the one with the smallest total constraint violations is better. In this approach, the selection mechanism performs only pair-wise comparisons. Thus, no penalty factor is needed. However, this method may lead to loss of diversity [131].
- Multi-objective optimization approach- In this category, COPs are solved as MOPs, whereby their constraints and objective functions are optimized using a multi-objective concept [133-139]. Although this is attractive to many researchers, it has the drawback that, in many cases, solving a COP in this way is more difficult than solving it as an essentially a single-objective optimization problem.


### 2.5.3 $\epsilon$-Constraint method

This method converts a COP into unconstrained one [140]. In its process, it is used to compare two solutions, when the constraints violations of them are smaller than $\epsilon$ value, the fittest one is selected. Otherwise, the solution with small constraint violation is preferred. Several methods have been proposed to control the $\epsilon$-level [140-143].

### 2.5.4 Stochastic ranking (SR)

This method [144] was proposed to strike the right balance between objective and penalty functions stochastically, which is very difficult to achieve in a penalty function technique. In it, a probability, $P_{f}$, was proposed either to select infeasible solutions based on either only their objective functions, or their sum of constraint violations. Although SR is simple, it cannot guarantee diversity as its ranking is stochastic.

### 2.5.5 Specialized operators

These methods help an EA to evolve solutions in the feasible region by either including special techniques to search for feasible solutions [44]; i.e., using special operators to transform infeasible solutions into feasible ones, or searching the boundaries between feasible and feasible regions [35, 36, 145].

### 2.5.6 Hybrid methods

In this category, an ensemble of CHTs is used to handle constraints. In [146], four CHTs: feasibility rules, stochastic ranking, a self-adaptive penalty function and the $\epsilon$-constrained method, which are used in an ensemble way to solve COPs. Elsayed et al. [147] proposed a DE algorithm, which uses four mutations, two crossover and two CHTs (Superiority of Feasible Solutions and $\epsilon$-constrained method).

### 2.6 EAs Review

In this section, the literature on solving unconstrained and constrained optimization problems with EAs as well as, the landscape analysis techniques used with EAs, is reviewed.

### 2.6.1 EAs for unconstrained optimization problems

In this section, EAs used to solve unconstrained optimization problems were briefly reviewed.

### 2.6.1.1 Single algorithms for unconstrained problems

Zhang et al. [64] proposed an ADE algorithm with an optional external memory (JADE), in which the $C r_{i}$ and $F_{z}$ of each individual $\overrightarrow{x_{z}}$ at each generation was independently generated according to a normal and Cauchy distribution, respectively. A repair mechanism is used to handle the value falling outside range as: when the value of $C r_{z}$ fell outside the range of $[0,1]$, it was repaired to a value within it. If the value of $F_{i}$ was greater than 1 , it was truncated to 1 or re-generated if $F_{z}<0$. Tanabe and Fukunage [148] proposed a success-history-based parameter adaptation for $\mathrm{DE}(\mathrm{SHADE})$ in which instead of using a single pair $\left(\mu_{C R}, \mu_{F}\right)$ to guide parameter adaptation as in JADE, the mean values of $S_{C R}$ and $S_{F}$ for each generation were stored in memory as $\mu_{C R}$ and $\mu_{F}$, respectively. Later, Tanabe and Fukunage [67] improved SHADE algorithm by using a linear population size reduction (LPSR) to dynamically re-size the population $N P$ during a run as the number of fitness evaluations increases, which is called L-SHADE. It showed good performance in comparison with other algorithms for solving a set of unconstrained optimization problems. Later many improved versions of L-SHADE have been proposed [149-153].

### 2.6.1.2 Ensembles of operators for unconstrained problems

In this subsection, a brief review of different algorithms that use ensembles of different operators, as well as the selection mechanisms, is provided.

A new version of $\mathrm{DE}, j D E_{N P, M M}$, for solving optimization problems, where

MM stands for multiple mutation strategies because two are incorporated, was proposed by Zamuda and Brest [154]. It is also uses a methodology for reducing its population size. Each new solution is generated by one of the two mutation strategies by using the following selection mechanism. The first mutation strategy is used when $N P \geq 100$ or 2 ) when rand $<0.75$, and rand is a uniform random number $\in[0,1]$, otherwise the second was used. $j D E_{N P, M M}$ was tested on 22 real world applications and demonstrated better performances than two other algorithms.

Wang et al. [68] developed a composite DE (CoDE), in which three mutation strategies are randomly combined with three fixed control parameter settings to generate a new trial vector. At each generation, three vectors are generated for each target vector, with the one with the best objective FV surviving to the next generation. It was inferred from their experimental results, that CoDE obtained better results when compared with state-of-the-art algorithms.

A self-adaptive $\mathrm{DE}(\mathrm{SaDE})$ for solving unconstrained real-parameter optimization problems was proposed by Qin et al. [155]. In it, both the strategies for generating the trial vector and its associated control parameter values, are gradually self-adapted according to a success rate calculated based on previous learning experiences. Firstly, all the mutation strategies have equal probabilities of generating a new solution. However the probabilities are updated after the initial $L P$ generations as follows: the updated probability for each mutation strategy is the number of successful individuals divided by the number of all the individuals generated by that strategy in the previous $L P$. This algorithm performed much better than both traditional DE and several state-of-the-art DE variants with adaptive parameters.

Mallipeddi et al. [156] proposed an ensemble of mutation strategies and control
parameters in DE (EPSDE) for solving unconstrained optimization problems. In it, each solution in the initial population is randomly assigned a mutation strategy with its associated parameter values taken from pools of different mutation strategies and the values of each control parameter. The process for selecting the next generation of parent individuals is as follows: if the generated solution 1) is fittest than its parent in the previous generation, its mutation strategy and parameter values are stored; or 2) is worse than its parent, the parent vector is reinitialized with a new mutation strategy and associated parameter values. The performance of EPSDE compared favorably with a set of well-known DE methods.

A multi-population-based framework in which three mutation strategies are combined in a novel DE variant called MPEDE, was proposed by Wu et al. [22]. Its initial population is dynamically divided into several sub-populations, three small indicator ones of equal sizes and one larger reward one. Each mutation strategy is used to evolve one indicator sub-population, with the reward sub-population assigned to the current best-performing mutation strategy. That selection based on the ratios between the fitness improvements and consumed function evaluations. MPEDE was tested on the suite of CEC 2005 benchmark functions and was shown to be competitive with other state-of-the-art algorithms. For more information regarding multi-operator algorithms, readers are referred to [17].

A new adaptive multi-population DE with dynamic population reduction, sTDE-dR, in which the initial population is divided into multiple tribes, was proposed by Ali et al. [76]. A distinct mutation strategy and crossover operator, selected from pools of different ones is used to evolve one sub-population, and a different adaptive method is used to determine the values of $F$ and $C r$ for each tribe. The mean success of each tribe in each generation is used to calculate the
ratio of its participation in the next generation. The proposed algorithm was validated by solving a challenging set of benchmarks from the CEC2014 real-parameter single-objective competition, and when compared with several state-of-the-art algorithms, showed superior performance.

Ali et al. [21] introduced a multi-population DE (mDE-bES) for solving largescale optimization problems, in which the initial population is divided into subpopulations of equal sizes, which are evolved using different DE mutation strategies for a specified number of generations. An information-sharing method, in which some individuals are randomly selected, based on a neighborhood structure to migrate between sub-populations, is also used. mDE-bES was tested on a set of 19 large-scale continuous optimization problems. Its results showed that its performance and scalability behavior were competitive with those of state-of-theart algorithms.

### 2.6.1.3 Ensembles of algorithms for unconstrained problems

Over the last few years, the concept of multi-method algorithms, which uses the strengths of different EAs, has emerged. Vrugt and Robinson [157] introduced the multi-algorithm genetically adaptive multi-objective (AMALGAM) algorithm that has demonstrated to be a robust algorithm for solving MOPs. Later, this work was extended [157] by proposing an algorithm known as AMALGAM for singleobjective optimization (AMALGAM-SO) which uses the strengths of CMA-ES, a GA and a particle swarm optimizer (PSO) in a single algorithm for evolving a population. The number of offspring for each algorithm are dynamically updated by a self-adaptive learning strategy. When experimented on a number of unconstrained optimization problems, it similarly performed to existing algorithms for small dimension problems but was superior to the existing ones for higher-dimensional multi-modal and more complex optimization problems.

Peng et al. [158] proposed a new approach, called the population-based algorithm portfolio (PAP), which exploits the advantages of four existing populationbased algorithms (the self-adaptive DE with neighborhood search (SaNSDE), PSO with inertia weight (wPSO), generalized generation gap (G3) model with a PCX operator (G3PCX) and CMA-ES). Each single algorithm is run for a portion of the specified resources (time and cost) and an information-sharing scheme is used to encourage interaction among them. PAP was comprehensively evaluated by investigating 11 instances of it applied on 27 benchmark functions, with the results showing that it outperforms its constituent algorithms.

Olorunda and Engelbrecht[159] proposed a heterogeneous cooperative algorithm which uses the strengths of a GA, DE and PSO, to evolve each subpopulation in a single algorithmic framework. It was shown to perform consistently and competitively on all the considered problems. Grobler et al. [160], introduced six methods for controlling heuristic space diversity (HSD) during the optimization process. In their experiments, a heterogeneous meta-hyper-heuristic (HMHH) method with four common meta-heuristic algorithms as its set of constituent algorithms (a GA, guaranteed convergence PSO (GCPSO), SaNSDE and CMA-ES) is used as a basis for investigating the management of HSD. Their proposed algorithm showed good performance when compared with a popular PAP one.

Li et al. [161] proposed a new multi-method algorithm which combined the advantages of both modified CoDE (MCoDE) and modified JADE (MJADE) in a single evolutionary framework which they called HMJCDE. In it, an adaptive mechanism, based on the rate of improvement in objective FVs, is employed to determine which algorithm to use to evolve the entire population. The performance of HMJCDE was assessed by solving well-known unconstrained problems
and was shown to be better than those of JADE, CoDE and other state-of-the-art algorithms.

Zhao et al. [162] introduced an algorithm which combines the search capabilities of both the SaDE algorithm and a modified multiple trajectory search (MMTS), called SaDE-MMTS, for solving large-scale optimization problems. As previously explained, in SaDE , the DE mutation strategies used and their associated control parameter values, are self-adapted by learning from their successes, while MMTS adopts a clearing procedure to select its search agents while using self-adaptive step sizes. Switching between these algorithms is implemented, based on their success rates in previous generations.

Elsayed et al. [104] proposed a united multi-operator EAs (UMOEAs) approach for solving unconstrained optimization problems. The algorithm starts with an initial population that is then divided into sub-populations, each of which is evolved using a different multi-operator EA, with the best-performing one determined based on its success rate. Later, Elsayed et al. [163] proposed an improved version of UMOEAs, called UMOEAsII, in which each multi-operator EA runs with multiple search operators. In it, an adaptive operator selection (AOS) mechanism, based on the quality of solutions produced and the diversity of the population, places emphasis on the better-performing multi-operator algorithm and its search operators. UMOEAsII was tested on the CEC2016 competition's single-objective real-parameter optimization problems, which demonstrating its capability to obtain better results than those of other state-of-the-art algorithms. In doing so it won the competition.

### 2.6.1.4 EAs utilizing landscape techniques for unconstrained problems

Recently, researchers have utilized fitness landscapes to decide and choose appropriate algorithms and/or operators for solving optimization problems.

Merz and Freisleben [164] performed a fitness landscape analysis of a number of Quadratic Assignment Problems (QAP), with the results used to classify problem instances according to the difficulty of their local searches. An autocorrelation analysis is used to examine the suitability of a local search and the global structure is investigated by employing a FDC analysis. Bischl et al. [165] suggested using a model to select the best-performing algorithm from a set of four for solving Black-Box optimization Benchmarking (BBOB) problems [166, 167], based on Exploratory Landscape Analysis (ELA) techniques. Then, the modality, separability, and global structure of an optimization problem are determined as the first step in identifying the landscape (performed off-line). Next, to select the best-performing algorithm a machine-learning model is constructed and validated based on two different cross-validation schemes. Nevertheless, the results may not be generalizable for problems with different dimensions. Because the low-level features are obtained in a separate step, the authors did not add the computational cost for calculating them to the number of function evaluations. Also, as the selection of the algorithm pool is manual, its validation on unobserved problems is weakened.

Garden and Engelbrecht [168] employed a self-organizing feature map to cluster and analyze the landscapes of two commonly used benchmark problems. They concluded that while there are functions that represent a wide range of properties, some other properties are not fully covered in these benchmarks. In [169], a prediction model for predicting when a PSO algorithm will fail to solve a particular
optimization problem is developed, with decision trees used to predict the failures of seven different PSOs, by utilizing a number of fitness landscape measures.

Munoz et al.[170] used a regression model (multi-layer feed-forward neural network) to determine the best of 8 parameter combinations for the CMA-ES algorithm. A knowledge base of 1800 problem instance drawn from the Comparing Continuous Optimization (COCO) benchmark [167], were used to train the model. Data from the CEC2005 competition [171] was then used to validate the model and the seven ELA measures that were used to analyze and characterize each problem. However, all the landscape analyzes were performed off-line and the sample size of $15 \times 10^{3} \times D$ that was used to calculate the ELA measurement is too expensive to be practical. Also, during the validation phase, the accuracy of the model was compared with only random configurations of unseen problems. Munoz et al. [172] proposed a new version of information content of fitness sequences (ICoFiS), in which a Latin hypercube design (LHD) was used to generate initial samples and also the distance between two solutions in the analysis was included. COCO was used as the testing functions and the lower and upper bounds for the sample size were set at values of $10^{2} \times D$ and $10^{3} \times D$, respectively, which is still computationally expensive in terms of the number of fitness evaluations.

Sun et al. [173] proposed a novel exploratory landscape analysis (ELA) method, called Maximum Entropic Epistasis (MEE), to measure the level of the interactions between variables in continuous domain. It determines interactions between two solutions $\vec{x}_{1}$ and $\vec{x}_{2}$, by calculating the maximal information coefficient (MIC) between $\vec{x}_{2}$ and the partial derivative of the fitness function with respect to $\vec{x}_{1}$. Interestingly, MEE was investigated to examine its possibility to guide the evolutionary search process for an optimal solution to a specified problem. It showed equal or better performance than the algorithm designed in [174]. However, as

MEE uses the partial derivative of the fitness function, it may be computationally expensive.

As the area covered by the points generated by the random walk-based methods is limited and not enough for landscape analysis, Jana et al. [175] proposed a chaos-based random walk algorithm to quantify the complexity and deception of a problem. The accuracy of determining the ruggedness of a problem was compared to those obtained from simple and progressive random walk-based algorithms, with the results were slightly better.

### 2.6.2 EAs for constrained optimization problems

As previously mentioned, due to the success of EAs in solving unconstrained optimization problems and the importance of solving COPs in many scientific area, researchers have used CHTs with EAs to solve COPs. Some recent significant advances in this direction are discussed in the following subsections.

### 2.6.2.1 Single algorithm for solving COPs

Takahama and Sakai [176] proposed $\varepsilon$ DE, which incorporates the the $\varepsilon$ constrained method with DE. In it, a feasible-elite preserving strategy and gradientbased mutation were used. Later, to handle COPs with many equality constraints, an improved $\varepsilon \mathrm{DE}[141]$ was proposed. It adopted faster reduction of the relaxation of the equality constraints and a higher gradient-based mutation rate. Takahama and Sakai [140] extended their previous work [141, 176], by introducing an archive which stored solutions and maintained population diversity. Their algorithm is called $\epsilon$ DEag and it achieved excellent performances, in cases in which many infeasible solutions needed to be repaired. However, it consumed a great deal of time.

Wang and Cai [177] developed a DE algorithm, that is combined with multiobjective optimization to solve COPs, called CMODE. It was tested on CEC2006 benchmark problems, with very competitive performance to state-of-art algorithms. However, when the offspring is feasible and parents are infeasible, the idea of dominance might not be effective. Ning Dong et al. [178] transformed COP into a bi-objective optimization problem by using a novel unbiased bi-objective optimization model, in which Pareto ranking was used as a selection method.

An adaptive ranking mutation operator (ARMOR), based on DE, was introduced by Gong et al. [179]. In it the individuals were adaptively ranked based on three situations: 1) infeasible, the constraint violations were used to rank the solutions; 2) semi-feasible, the individuals were ordered based on the transformed objective function; and 3) feasible, the solutions were ranked based on objective function value.

Elsayed et al. [180], introduced a multi-parent crossover GA (GAMPC) for solving the real-application problems introduced in [181]. A randomized operator was applied as mutation, and also an archive of good solutions was used to maintain population diversity. It was the winner of the CEC2011 competition. Later, it was enhanced by using a diversity operator, instead of mutation, for quicker convergence [182].

### 2.6.2.2 Ensembles of operators for COPs

Mallipeddi and Suganthan [183] proposed an algorithm that uses four CHTs with DE (ECHT-DE) to solve COPs. In its internal process, four population were randomly initialized with each CHT was used with one sub-population with an information sharing method which shared offspring among them. It was tested by solving CEC2010 CEC2010 competition for COPs, and it came second in the
rank. However, it was expensive in terms of computational time.

Da Silva et al. [184] used an adaptive penalty method with DE for solving a set of COPs. In it, a mechanism for automatically choosing one of four DE mutation strategies is introduced. This occurs as: 1) for the first $10 \%$ of the total number of generations allowed, four individuals are generated and the best chosen; 2) for the next $30 \%$ new individuals are generated by only the variant which produced the best individual in the current population; 3) all the variants are used again to generate new individuals for another 10\%. 4) the best strategy is used to generate new solutions for the next $30 \%$; and 5) a third evaluation stage is performed using all the operators, with the best-performing variant chosen for the remaining generations. Based on the results obtained from solving several structural and mechanical engineering optimization problems, it was claimed that the algorithm performs better than certain GA techniques used in the continuous domain.

Elsayed et al. [185] introduced an improved version on SAMODE [24], called ISAMODE-CMA, in which CMA-ES was periodically applied to enhance its local search capability, and a dynamic penalty is used to handle constraints. In their method, a mix of modified versions of binomial and exponential crossovers is adopted. A restart mechanism is used to escape local solution. Also, the subpopulation sizes are updated based on an improvement index that considers both feasibility ratio and solution quality. ISAMODE-CMA was compared with different state-of-the-art approaches and showed superior performance. Elsayed et al. [147] developed a DE algorithm, called SAS-DE, in which four DE mutation, two crossover operators, and two CHTs, are used. The performance of SAS-DE was tested by solving a set of benchmark problems [186], with consistently better performance than other well-known algorithms.

Wang et al. [187] introduced a new algorithm, that uses two mutation strategies each of which was used with equal probability of 0.5 . In it, an infeasible solution archiving and replacement mechanism are presented. For this, during an entire evolution process, if an offspring dominates its parent, the parent solution may be replaced. The experimental results showed that their proposed method was superior to state-of-the-art algorithms.

A DE algorithm (DE-AOPS), that uses a new technique for dynamically choosing the best combinations of parameters, from given continuous ranges, as well as DE operators, is proposed [188]. Also, a new CHT is proposed in which DE-AOPS starts with handling some constraints, with the largest sum of the constraint violations till a pre-defined number of generations, and gradually considers all of them. The performance of DE-AOPS is judged using a well-known set of COPs, with consistently better performance than other state-of-the-art algorithms.

### 2.6.2.3 Hybrid and Ensembles of Algorithms for COPs

Elsayed et al. [189] proposed an algorithm that utilizes four EAs (DE, GA, ES and EP) with each one has two different operators (EAwAC). It uses information sharing procedure to replace the worst four individuals in each sub-population with the best four individuals (the best one from each sub-population). The number of individuals in each sub-population as well as the number assigned to each operator are dynamically updated, based on both the objective FV and feasibility rate. The experimental results showed that EAwAC was competitive to, if not better than, well-known algorithms.

Zaman et al. [190] developed a new multi-method EA which adaptively places more emphasis on the most suitable EA, based on each algorithm's performance during previous generations. It uses the strengths of both a GA and DE (GA-DE)
to solve dynamic economic dispatch (DED) problems. To enhance its convergence rate, a repair technique is used to move infeasible solutions towards feasible ones. Its effectiveness was tested by solving a number of dynamic economic dispatch (DED) problems. In this it was superior to state-of-the-art algorithms, in terms of its quality of solutions and reliability.

### 2.6.2.4 EAs utilizing landscape techniques for COPs

As previously stated, FLA techniques can be used to measure the relative complexity of a problem. However, many studies using FLA measures have been limited to combinatorial problems, with a few studies done on constrained optimization problems [25, 164, 191].

Tayarani and Prugel-Bennett [192] used auto-correlation measure to study the ruggedness of the quadratic assignment problem (QAP). In their study, they showed how the similarity and difference between real-world problems and the random problems. In [193], an AOS mechanism, based on a set of four fitness landscape analysis techniques, is used to train an on-line regression learning model (dynamic weighted majority) to predict the weight of each operator in each generation. It determines the most suitable of four crossover operators for solving a set of capacitated arc-routing problem (CARP) instances. It uses an instantaneous reward, which is considered the value computed in the last evaluation. However, compared with some well-known algorithms, this algorithm did not show significant benefits.

Poursoltan and Neumann [194] build a model to predict the best-performing algorithm from (DE, ES and PSO) for a specific COP. Its inputs are the features of a given COP instance, these features are constraint coefficients relationships such as number of constraints, feasibility ratio in vicinity of optimum, angle between
constraint hyperplanes and standard deviation. The experimental results show that prediction model is able to give a good prediction. However, as a training and testing mechanism is used, the algorithm may be limited to the test problems considered and its performance deteriorate when solving another set of problems.

### 2.7 Boundary-based Methods and Search Space Reduction

In the literature, a number of evolutionary approaches have been developed, that consider the fact that for most practical problems the optimal solution exists on the boundary of feasible space. Michalwicz [37] was the first to propose a GA, known as Numerical Optimization for Constrained Optimization (GENOCOP), that used three mutation strategies (uniform, boundary and non-uniform), where the boundary operator generates random points on the boundary of the feasible region, and it also incorporated three different crossover operators (arithmetical, simple and heuristic). In [195], for searching the edge of feasibility, a geometrical crossover was presented. It is a complicated crossover mechanism which transforms an infeasible solution to become feasible. This crossover is suitable to solve COPs with linear equality constraints. However, it has some drawbacks, including that: 1) it may fail in solving COP with nonlinear constraints; and 2) the design of an efficient geometrical crossover technique is dependent on the problem.

To continue the research direction in [195], different sphere-based operators were designed to restrict the search to the boundary of the feasible region [145]. These operators were used with different optimization algorithms, such as GA and ES, with the sphere function adopted in the design of search operators because of its simplicity and attractive symmetrical proprieties. However, these operators only work on certain types of problems, and it would be difficult to design a specific
operator to solve each individual problem. In [196], a self-adaptive boundary search GA was proposed and applied to solve a water distribution problem. The approach is able to reduce the computational effort required to in reach high quality solutions, in comparison to traditional GA.

Based on the boundary search concept introduced in [37], a new ant colony optimization (ACO) algorithm was proposed by Leguizamon and Coello Coello [36] for solving nonlinear COPs. It is well-known that any line segment that connects a feasible point with an infeasible point will intersect the boundary of the feasible region at some point. A binary search method, such as bisection, can be used to search the line segment to locate points on the boundary of feasibility space. This assists the convergence of the proposed ACO algorithm. Although this algorithm shows superior performance, it has some limitations, such as 1) it requires both feasible and infeasible points to conduct the search, and this could be problematic for many problems at the beginning of the evolutionary process; and 2) it could be computationally expensive because of the bisection process.

According to [35], it needs at least one active constraint to start the search process and the edges of the feasible space is represented by a new function that determines the thicknesses of the edges around the active constraints. The thickness enables the search process to focus on the boundary of the feasible region. However, the main drawback of this approach, is that it assumes that the active and inactive constraints are known. In another study, a GA that utilizes infeasible solutions that are near to a constraint boundary was proposed by Singh et al. [89]. As when these solutions are used with the feasible solutions, new solutions may be generated either on, or near to, the constraint boundary. However, this can not be done unless some feasible solutions are present.

In [41], a search space reduction technique (SSRT) is proposed, as an initial
step of GA for solving COPs. Its main idea, is to direct some of the randomly selected infeasible solutions in the initial population, to move towards the feasible space. Due to the fact, that the optimal solution of COPs must lie on each and every equality constraint, Barkat Ullah et al. [38] proposed a heuristic technique to emphasis the search process on the landscape of equality constraints. From the current location of an individual solution, this heuristic is able to reach a solution on the equality constraint, and then search the constraint landscape. However, it may encounter problems when there are many variables, especially when many of them are nonlinear; this is because it needs to apply numerical search methods to find out the values of nonlinear variables [197]. Also, it assumes that the equality constraint function must contain all variables. If this is not the case, it needs to explore the landscape of other constraints.

### 2.8 Chapter Summary and Research Directions

Solving optimization problems is deemed a vital research area that assists decision-making processes in several practical applications. This chapter presented an introduction to unconstrained and constrained optimization problems and how EAs are used to solve them. Also, different constraint handling techniques was presented. The landscape analysis measures and search space reduction along with current well-known methods which uses FLA methods and search space reduction with EAs were discussed.

Of the many solution approaches developed, EAs have demonstrated great success in solving both unconstrained and constrained problems with a wide variety of properties. However, their performances were highly dependent on the algorithms design, selection of its operators and parameter settings. Also, no single algorithm and/or search operator performed consistently well for all the types of
optimization problems defined in the literature. Although, ensemble-based methods have shown success in tackling these shortcomings, finding an appropriate design of these approaches still challenging, for example, it is difficult to determine (a) which algorithm and/or operators should be used in the pool, (b) which algorithm and/or operator should be chosen during the evolutionary process, and based on which selection criteria. Moreover, existing selection approaches do not utilize any information about function's/ problem's landscape. This motivates us to develop algorithms that utilizes problem's landscape information to select the best-performing operators and/or algorithms, as will be discussed in Chapters 3, 4 and 6.

Also, in a COP, the feasible space, which is bounded by the constraint functions, may represent a relatively small portion of the search space, and the existence of the equality constrains make this feasible space tiny. Also in many real-world application, the optimal solution lies in the boundary of the feasible region, which is the intersection of the active constraints. Although EAs have been successfully used to solve COPs, they still suffer from the drawback of wasting a considerable amount of time (fitness evaluations) searching ineffective areas in the search space. So this motivates us to develop a mechanism that may efficiently be able to to find that intersection, or a nearer point, as will be discussed in Chapters 5 and 6.

## Chapter 3

# Landscape-based Algorithm for Unconstrained Problems 

In this chapter, a new landscape-based DE algorithm is proposed for solving unconstrained optimization problems. After a brief introduction, the descriptions of the benchmark problems which are solved using the proposed algorithms, is described. Then the proposed algorithm and its main components are presented. Then, the effects of the proposed algorithm's components on its performance are discussed. Finally, the experimental results from using it to solve different sets of unconstrained optimization problems are analyzed and then compared with those from state-of-the-art algorithms.

### 3.1 Introduction

As previously reported, optimization problems can be divided into many different classes, based on their characteristics and mathematical properties. Therefore,

[^0]an algorithm with certain operators and/or parameters and/or CHTs may work efficiently on one set of test problems, but poorly on another.

To tackle this problem, researchers have proposed many different methods that use different algorithms or search operators in a single framework, such as ensemble-based (a mix of operators) [75], hyper-heuristics (heuristics selecting from heuristics) [102], mutli-methods (using more than one optimization algorithm) $[103,104]$, multi-operators (using more than one search operator in a single optimization algorithm) [23] and heterogeneous (using different algorithms with different behaviors) [105] approaches. To clarify, each of these algorithms uses a pool of different algorithms/operators and a selection mechanism to determine the best-performing one/s during the search process. Their selection procedures are based on different criteria, such as a re-enforcement learning mechanism [107, 108], improvement in the solution quality and/or constraint violations and/or feasibility rate [24], and convergence differences and progress ratios [106]. However, none of these approaches considers any function characteristics in the process of selecting the best-performing operator and/or algorithm.

Landscape information is usually helpful to judge the function complexity. The carefully incorporating it in the selection of operators may improve the performance of an algorithm. However, selection methods based on a landscape analysis are very rare $[165,193]$ and have some limitations, such as: (1) a landscape analysis was performed using an off-line mode, i.e., with the initial experiments independently conducted, to calculate the values of the landscape statistics obtained from the evolutionary process in order to solve a problem; (2) calculating landscape measures is computationally expensive; and (3) as the training and testing mechanism used may restrict an/the algorithm to the test problems considered, its performance can deteriorate when solving another set of problems.

The aim in this chapter is to propose a new algorithm, that is capable of solving a wide range of unconstrained optimization problems. To achieve this objective, a nulti-operator DE algorithm is proposed. Its novel design utilizes landscape information with an adaptive operator selection (AOS) mechanism, which is used to give more importance to the best-performing operator during the run.

The performance of the proposed approach is tested by solving 45 unconstrained optimization problems taken from CEC2014 [198] and CEC2015 [199]. Several experiments are designed and carried out to analyze the effects of different parameters and components on its performance, and the results from the final variant of the proposed algorithm compered with those from well-known algorithms in the literature.

This chapter is organized as follows: the next section presents the benchmark problems; the proposed algorithm and its components are described in Section 3.3, the experimental results and analysis are discussed in Section 3.4; and, finally, the chapter summary is presented in Section 3.5.

### 3.2 Benchmark Problems

To judge the performances of the proposed algorithms, a total of 45 widely used test functions (introduced in the CEC2014 and CEC2015 competitions) are employed.

The sets of the CEC2014 and CEC2015 benchmark problems $[198,199]$ contain 30 and 15 test functions, respectively, as detailed in Tables 3.1 and 3.2, respectively. The criterion for both these competitions was that each problem was independently run 51 times, with the stopping condition $10000 \times D$ fitness function evaluation (FEs), where $D$ is the number of decision variables.

Table 3.1: Properties of the CEC2014 test problems

|  | No. | Functions | Optimal solution |
| :---: | :---: | :---: | :---: |
| Unimodal Functions | 1 | Rotated High Conditioned Elliptic Function | 100 |
|  | 2 | Rotated Bent Cigar Function | 200 |
|  | 3 | Rotated Discus Function | 300 |
| Simple <br> Multimodal <br> Functions | 4 | Shifted and Rotated Rosenbrock'sFunction | 400 |
|  | 5 | Shifted and Rotated Ackley's Function | 500 |
|  | 6 | Shifted and Rotated Weierstrass Function | 600 |
|  | 7 | Shifted and Rotated Griewank's Function | 700 |
|  | 8 | Shifted Rastrigin's Function | 800 |
|  | 9 | Shifted and Rotated Rastrigin's Function | 900 |
|  | 10 | Shifted Schwefel's Function | 1000 |
|  | 11 | Shifted and Rotated Schwefel's Function | 1100 |
|  | 12 | Shifted and Rotated Katsuura Function | 1200 |
|  | 13 | Shifted and Rotated HappyCat Function | 1300 |
|  | 14 | Shifted and Rotated HGBat Function | 1400 |
|  | 15 | Shifted and Rotated ExpandedGriewank's plus Rosenbrock's Function | 1500 |
|  | 16 | Shifted and Rotated Expanded Scaffer's F6 Function | 1600 |
| Hybrid <br> Functions | 17 | Hybrid Function $1(\mathrm{~N}=3)$ | 1700 |
|  | 18 | Hybrid Function $2(\mathrm{~N}=3)$ | 1800 |
|  | 19 | Hybrid Function 3 ( $\mathrm{N}=4$ ) | 1900 |
|  | 20 | Hybrid Function 4 ( $\mathrm{N}=4$ ) | 2000 |
|  | 21 | Hybrid Function $5(\mathrm{~N}=5)$ | 2100 |
|  | 22 | Hybrid Function $6(\mathrm{~N}=5)$ | 2200 |
| Composition Functions | 23 | Composition Function $1(\mathrm{~N}=5)$ | 2300 |
|  | 24 | Composition Function $2(\mathrm{~N}=3)$ | 2400 |
|  | 25 | Composition Function $3(\mathrm{~N}=3)$ | 2500 |
|  | 26 | Composition Function $4(\mathrm{~N}=5)$ | 2600 |
|  | 27 | Composition Function $5(\mathrm{~N}=5)$ | 2700 |
|  | 28 | Composition Function 6 ( $\mathrm{N}=5$ ) | 2800 |
|  | 29 | Composition Function $7(\mathrm{~N}=3)$ | 2900 |
|  | 30 | Composition Function $8(\mathrm{~N}=3)$ | 3000 |
| Search Range $[-100,100]^{D}$ |  |  |  |

### 3.3 Multi-operator DE Algorithm with Landscapebased AOS

In this section, a landscape-based AOS algorithm for DE (LSAOS-DE), is presented. It uses more than one DE mutation strategy in a single algorithmic framework. Also, it has an adaptive operator selection process, based on both

Table 3.2: Properties of the CEC2015 test problems

|  | No. | Functions | Optimal solution |
| :---: | :---: | :---: | :---: |
| Unimodal Functions | 1 | Rotated High Conditioned Elliptic Function | 100 |
|  | 2 | Rotated CigarFunction | 200 |
| Simple <br> Multimodal <br> Functions | 3 | Shiftedand Rotated Ackley's Function | and |
|  | 4 | Shifted and Rotated Rastrigin's Function | 400 |
|  | 5 | Shifted and Rotated Schwefel's Function | 500 |
| Hybrid <br> Functions | 6 | Hybrid Function $1(\mathrm{~N}=3)$ | 600 |
|  | 7 | Hybrid Function 2 ( $\mathrm{N}=4$ ) | 700 |
|  | 8 | Hybrid Function 3( $\mathrm{N}=5$ ) | 800 |
| Composition Functions | 9 | Composition Function $1(\mathrm{~N}=3)$ | 900 |
|  | 10 | Composition Function $2(\mathrm{~N}=3)$ | 1000 |
|  | 11 | Composition Function 3 ( $\mathrm{N}=5$ ) | 1100 |
|  | 12 | Composition Function $4(\mathrm{~N}=5)$ | 1200 |
|  | 13 | Composition Function $5(\mathrm{~N}=5)$ | 1300 |
|  | 14 | Composition Function 6 ( $\mathrm{N}=7$ ) | 1400 |
|  | 15 | Composition Function 7 ( $\mathrm{N}=10$ ) | 1500 |
| Search Range [ $-100,100]^{D}$ |  |  |  |

the (1) problem landscape and (2) performances of operators, to choose the bestperforming DE mutation strategy during the run.

### 3.3.1 LSAOS-DE

As previously discussed, existing multi-operator algorithms usually use an AOS mechanism because of its successful generation of new offspring. The basic steps in the proposed LSAOS-DE algorithm, which uses both the problem's landscape information and also operators' performances to adaptively choose the most suitable DE operator, are presented in Algorithm 2 and Figure 3.1.

To fully cover the search space, it is initiated using the Latin Hyper-cube Design (LHD) [200] as described in section 3.3.1.1 and a pool of $m$ DE mutation strategies with diverse characteristics is defined. Each operator is assigned to the same number of individuals and a new solution generated according to its assigned
mutation strategy. At the same time, the information landscape metric and performance history of each operator are calculated using Algorithm 3 and equation 3.4 , respectively. This process continues for CS generations, after which the normalized average values of the landscape metric and performance history measure are computed for each operator. Based on these values, the best-performing operator is selected to evolve the entire population in the subsequent cycle (for $C S$ generations). Once this step is completed, and owing to the fact that the performance of one operator may change during the evolutionary process, i.e., it may perform well in early generations but poorly in later ones or vice versa, all the $m$ operators are re-used to evolve the entire population and the landscape measure is calculated and recorded again. Note that, after every $C S$ generation, the success rate is set to a value of zero, as is the landscape metric. This process is continued until a pre-defined number of fitness evaluations (limit) is reached, and then the best-performing operator found so far is used to evolve the entire population until a stopping criterion is met.

At the same time, during the evolutionary process, $N P$ is adaptively re-sized using linear population size reduction [67], it has a large value at the start of the evolutionary process which is then linearly reduced (by deleting the worst individual from the population) until $N P^{m i n}$ is reaches, as:

$$
\begin{equation*}
N P_{t+1}=\operatorname{round}\left[\left(\frac{N P^{\min }-N P^{i n i t}}{M A X_{F E S}}\right) \times F E S+N P^{i n i t}\right] \tag{3.1}
\end{equation*}
$$

where $N P^{\text {min }}$ is the smallest number of individuals the proposed algorithm will use, $F E S$ and $M A X_{F E S}$ the current and maximum numbers of fitness evaluations. The purpose of adapting NP is to maintain diversity during the early stages of the evolutionary process while placing greater emphasis on the intensification process in later stages [67].

```
Algorithm 2 Proposed LSAOS-DE algorithm
    Counter \(\leftarrow 0\); Generate an initial population \((X)\) of size \(N P\) using Latin
    Hypercube Design; FES \(\leftarrow 0\);
    Calculate the fitness values of \(X\);
    \(F E S \leftarrow F E S+N P ;\)
    while \(F E S \leq M A X_{F E S}\) do
        \(C \leftarrow C+1 ;\)
        if \(F E S \leq\) limit then
            \(C \leftarrow C+1 ;\)
            if \(C<C S\) then
                Randomly assign each operator to ( \(\left[\frac{N P}{m}\right]\) ) solutions;
                Generate new population using the assigned operators.
                Calculate the \(L D_{\text {op }}\) considering those individuals updated by operator
                \(o p\);
                Calculate the success rate \(S R_{o p}\) (Equation 3.4) considering those indi-
                viduals updated by operator \(o p\);
            end if
            if \(\bmod (C, C S==0)\) then
                Measure the performance of every \(m\) using Equation 4.5;
                Determine the best-performing operator, i.e., the one with the maxi-
                mum value of \(N P M\);
            end if
            if \(C>C S\) and \(C<2 C S\) then
                Evolve the current entire population using best DE mutation strategy;
            end if
            if \(C==2 C S\) then
                Counter \(\leftarrow 0\), reset \(m, S R_{o p}=[], L D_{o p}=[] ;\)
            end if
        else
            Evolve the population using the best DE operator;
        end if
        \(F E S \leftarrow F E S+N P ;\)
        Update \(N P\) using equation (Equation 3.1);
    end while
```

It is worth mentioning that the proposed algorithm has the same structure as multi-method/multi-operator, heterogeneous and ensemble-based ones while its pool consists of several different DE mutation strategies and its selection mechanism relies on both the information landscape and the performance history of each DE strategy.


Figure 3.1: The general structure of LSAOS-DE

### 3.3.1.1 Initialization phase

In this phase, the LHD, which is a type of stratified sampling, is used to generate the initial population as it is capable of producing a sample of points that efficiently covers a search region.

The initialization is performed by:

$$
\begin{gather*}
x_{i, j, 0}=x_{j, \text { min }}+\operatorname{lhd}(1, N P) \times\left(x_{j, \text { max }}-x_{j, \text { min }}\right)  \tag{3.2}\\
i=1,2, \ldots ., N P \text { and } j=1,2, \ldots, D
\end{gather*}
$$

where $l h d$ is a LHD function that generates random numbers from independent standard Normal distributions [200, 201].

### 3.3.1.2 Selection phase

In this section, the two selection criteria, landscape method and performance history measure, are discussed.

Information landscape negative searchability (ILNS) measure This is based on the difference between the information landscape vector of the problem to be solved and the well-known spherical function used as a reference landscape due to its simplicity and scalability [202] which is constructed by:

$$
\begin{equation*}
f_{r e f}(\vec{x})=\sum_{j=1}^{D}\left(x_{j}-x_{j}^{b}\right)^{2} \tag{3.3}
\end{equation*}
$$

where $\vec{x}_{i}^{b}$ is the best individual in the sample.

After constructing the vector landscapes of the problem to be optimized and the reference function ( $L S_{f}$ and $L S_{r e f}$, respectively), the ILNS measure is computed using Algorithm 3 and the information landscape measure using equation 4.3 .

Normalized performance measure (NPM) In this section, the overall $N P M$ of each operator is computed using the operator's searchability index ( $L D$ ) and success rate $S R_{o p}$ which is defined as the number of successful offspring generated

```
Algorithm 3 Algorithm for computing ILNS index.
    Input: population of individuals \((X)\) updated by operator op;
    Determine the location of the best individual in the sample, \(\vec{x}^{b}\);
    Construct the pairwise comparison matrix \(M\) using equation 2.15;
    Construct vector \(L S_{f}\) that represent the information matrix of the problem;
    Construct the reference function, \(f_{r e f}\), by using equation 3.3;.
    Construct the vector \(L S_{\text {ref }}\) that represent the information landscape of the
    reference function;
7: Compute the value of the Information Landscape negative searchability index using equation 4.3;
```

by an operator ( $o p$ ) divided by the number of individuals assigned to that $o p$ as:

$$
\begin{equation*}
S R_{o p}=\frac{\text { Number of improved offsprings }}{\text { Number of all individuals evolved by operator } o p} \tag{3.4}
\end{equation*}
$$

The capability of each operator to explore the landscape is calculated by Algorithm 3. The normalized values of the $S R$ and $L D$ metrics are calculated respectively by:

$$
\begin{gather*}
N M_{S R_{o p}}=\frac{M_{S R_{O P}}}{\sum_{O P=1}^{m} M_{S R_{O P}}}  \tag{3.5}\\
N M_{L D_{o p}}=\frac{1-M_{L D_{o p}}}{\sum_{O P=1}^{m}\left(1-M_{L D_{o p}}\right)} \tag{3.6}
\end{gather*}
$$

where $\{o p=1,2, \ldots, m\}$ and $M_{S R}$ and $M_{L D}$ are the mean values of the SR and landscape information, respectively.

Subsequently, the overall normalized performance of each operator is computed by:

$$
\begin{equation*}
N P M_{O P}=N M_{S R_{O P}}+N M_{L D_{o p}} \tag{3.7}
\end{equation*}
$$

### 3.3.2 Parameter adaptation

To calculate the values of the crossover rate $\left(C r_{i}\right)$ and control $\left(F_{i}\right)$ parameters, the same adaptation procedure as reported in [67] is used, in which a historical memory of length $H$ for both $F$ and $C r$, is used with their values denoted as $\mu_{F}$ and $\mu_{C R}$, and initially set to 0.5 . Each individual $\vec{X}_{i}$ is associated with its $\left(F_{i}\right)$ and $\left(C R_{i}\right)$, the values of which are respectively created by:

$$
\begin{align*}
C r_{i} & =\operatorname{randni}\left(\mu_{C R, r_{i}}, 0.1\right)  \tag{3.8}\\
F_{i} & =\operatorname{randci}\left(\mu_{F, r_{i}}, 0.1\right) \tag{3.9}
\end{align*}
$$

where $r_{i}$ is randomly selected from $[1, H]$, randni and randci randomly selected from normal and Cauchy distributions with mean $\mu_{C R, r_{i}}$ and $\mu_{F, r_{i}}$, respectively, and variance of 0.1 . If the values of $C r_{i}$ and $F_{i}$ are outside [0,1], a repair mechanism is used as follows: if $C R_{i}$ is outside the range, it is replaced by the limit value ( 0 or 1 ) closest to the generated value and if $F_{i}>1$, it is replaced by 1 , and if $F_{i} \leq 0$, equation 3.9 is repeatedly executed until a valid value is generated.

At the end of each generation, the $\left(C r_{i}\right)$ and $\left(F_{i}\right)$ used by the successful individuals are recorded in $S_{C R}$ and $S_{F}$, and then the contents of the historical memories are updated as:

$$
\begin{align*}
\mu_{C R, h, g+1} & =\left\{\begin{array}{cc}
\operatorname{meanw}_{L}\left(S_{C r}\right) & \text { if } S C R \neq \phi \\
\mu_{C R, h, g} & \text { otherwise }
\end{array}\right.  \tag{3.10}\\
\mu_{F, h, g+1} & =\left\{\begin{array}{cc}
\operatorname{meanw}_{L}\left(S_{F}\right) & \text { if } S F \neq \phi \\
\mu_{F, h, g} & \text { otherwise }
\end{array}\right. \tag{3.11}
\end{align*}
$$

where $1 \leq h \leq H$ is the position in the memory to be updated. It is initialized to 1 and then incremented whenever a new element is inserted into the history, and if it is greater than $H$, it is set to 1 and $\operatorname{meanw}_{L}(S F)$ the Lehmer mean computed by:

$$
\begin{equation*}
\operatorname{meanw}_{L}(S F)=\frac{\sum_{h=1}^{|S F|} w_{h} \cdot S_{F_{h}}^{2}}{\sum_{h=1}^{|S F|} w_{h} \cdot S_{F_{h}}} \tag{3.12}
\end{equation*}
$$

where $w_{h}$ is the weight computed using equation 3.13

$$
\begin{equation*}
w_{h}=\frac{\left|\left(f\left(u_{h, g+1}\right)-f\left(x_{h, g}\right)\right)\right|}{\sum_{h=1}^{\left|S_{F}\right|}\left|\left(f\left(u_{h, g+1}\right)-f\left(x_{h, g}\right)\right)\right|} \tag{3.13}
\end{equation*}
$$

### 3.4 Experimental Setup and Results

To judge the performance of the proposed algorithm, experiments were conducted by solving the set of benchmark problems presented in Section 3.2.

To verify the performance of the proposed algorithm, comparisons are carried out with three DE-based single operator algorithms (LSHADE [67], SHADE [148], and JADE [64]), four multioperator-based ones (CoDE [68], SaDE [155], EPSDE [156], and MPEDE [22]), and two powerful multi-method based ones (UMOEAs [104] and AMALGAM-SO [103]). Also, to test the effectiveness of the proposed selection mechanism LSAOS-DE was also compared with seven of its variants (AOSDE-LS, AOSDE-SR, AOSDE-FIR, AOSDE-PR, AOSDE-PBM, AOSDE-RD, and AOSDE-PAOC), in each of which only the selection mechanisms were different as will be described in Section Heuristics chapter3.

All the algorithms proposed in this thesis were coded in Matlab, and were run on a PC with a 3.4 GHz Core I7 processor, 16 GB RAM, and Windows 7. For the state-of-the-art algorithms, all the parameters were set at those values recommended in their corresponding papers, and for a fair comparison, all the algorithms started from the same seed. As the original JADE paper only reported population sizes for $10 D, 30 D$, and $100 D$, an approximate value of 185 individuals for $50 D$ was used. For more comprehensive comparisons, each comparative algorithm was run 51 times for all the optimization functions with $10 D, 30 D$, and $50 D$, to a maximum number of fitness function evaluations of $10000 D$, with the best, mean and standard deviation results recorded. Note that, for any run, if the deviation from the optimal solution of the best fitness value was less than or equal to $1.0 e-8$, it was considered to be zero.

In this thesis, to compare different algorithms, two non-parametric tests (the Wilcoxon signed-rank [203] and Friedman's ranking [204]) were conducted. The Wilcoxon signed-rank test assigns one of three signs (,+- , and $\approx$ ) for the comparison of any two algorithms, where the "+" sign means the first algorithm was significantly better than the second, the " -" that it was significantly worse, and the " $\approx$ " that there was no significant difference between the two algorithms. A 5\% significance level was used to judge the difference between any pair of algorithms. A Friedman test was also used to rank the algorithms.

To compare the performance of the proposed algorithm graphically, performance profiles $[205,206]$, which are a tool to compare performance, of a number of algorithms $(S)$ using a set of problems $(P)$, and a comparison goal such as the computational time and the average number of fitness evaluations to obtain a certain level, of a performance indicator (such as optimal fitness), are plotted. For an algorithm (s), the performance profile $R h o_{s}$ is given by

$$
\begin{equation*}
\operatorname{Rho}_{s}(\tau)=\frac{1}{n_{p}} \times\left|p \in P: r_{p, s} \leq \tau\right| \tag{3.14}
\end{equation*}
$$

$R h o_{s}(\tau)$ is the probability for an algorithm $s \in S$ that a performance ratio $r_{p, s}$ is within a factor $\tau \in R$ of the best possible ratio. The function $R h o_{s}$ is the (cumulative) distribution function for the performance ratio.

### 3.4.1 Parameters analysis

In this section, analysis of the algorithm's components, to determine the final version of the proposed algorithm, are discussed. The effect of the following parameters: 1) the effect of the number of DE operators $m ; 2$ ) the effect of reducing $m ; 3)$ the effect of $\left.N P^{\text {init }} ; 4\right)$ the effect of $C S$; and 5) the effect of $N P^{\text {min }}$, are examined.

### 3.4.1.1 Default values

As for parameters settings, $N P^{\text {init }}$ was set to $18 D, N P^{\text {min }}$ to 7 . The $C S$ parameter to $25 . \varphi$ to 0.5 for $\mathrm{DE} / \varphi$ best/ $/ 1$ was used to maintain diversity, and 0.1 for all other variants, to speed up convergence rate. The archive rate $(A)$ was 1.4, memory size $(H)$ was 5 , and limit, which was the limit for running the multioperator, was $\frac{1}{2} \times M A X_{F E S}$, after which the best-performing operator evolved the population until the end of the run.

### 3.4.1.2 Analyzing the number of operators in LSAOS-DE (m)

To design a multi-operator DE algorithm, one can first analyze and determine the mutation strategies that should be used. 11 variants of the standard DE algorithm ( $\mathrm{DE} / \varphi$ best/1, $\mathrm{DE} /$ current-to- $\varphi$ best/ $/$ / with archive, $\mathrm{DE} /$ current-to$\varphi$ best/ $/$ / without archive, $\mathrm{DE} /$ rand/1, $\mathrm{DE} /$ rand $/ 2$, $\mathrm{DE} /$ current-to-rand/ $/ 1 /$ with

Table 3.3: Friedman's test results

| Algorithm | Mean rank | Order |
| :---: | :---: | :---: |
| $\mathrm{DE} /$ current-to- $\varphi$ best $/ 1$ without archive | 4.22 | 1 |
| $\mathrm{DE} /$ current-to- $\varphi$ best $/ 1$ archive | 4.63 | 2 |
| $\mathrm{DE} / \varphi$ best/ $/ 1$ | 5.57 | 3 |
| $\mathrm{DE} /$ rand-to- $\varphi$ best $/ 1$ without archive | 5.6 | 4 |
| $\mathrm{DE} /$ rand $/ 1$ | 6.07 | 5 |
| $\mathrm{DE} /$ rand-to- $\varphi$ best 1 with archive | 6.17 | 6 |
| $\mathrm{DE} /$ current-to-rand $/ 1$ | 6.35 | 7 |
| $\mathrm{DE} /$ rand-to- $\varphi$ best $/ 2$ with archive | 6.37 | 8 |
| $\mathrm{DE} /$ current-to-rand $/ 1$ without archive | 6.48 | 9 |
| $\mathrm{DE} / \varphi$ best $/ 2$ | 7.02 | 10 |
| $\mathrm{DE} /$ rand $/ 2$ | 7.53 | 11 |

archive, $\mathrm{DE} /$ current-to-rand $/ 1 /$ without archive, $\mathrm{DE} /$ rand-to- $\varphi$ best/ $/ 1$ with archive, $\mathrm{DE} /$ rand-to- $\varphi$ best $/ 1$ without archive, $\mathrm{DE} / \varphi$ best/2, and $\mathrm{DE} /$ rand-to- $\varphi$ best $/ 2 /$ with archive) were tested by solving CEC2014 problems with $30 D$, and the average results were recorded. Based on this, the variants were ranked by a Friedman test and their mean values are presented in Table 3.3.

The number of DE mutation strategies $(m)$ required for LSAOS-DE was analyzed, by conducting different experiments using $m=3,4,5,6$, and 7 (best variants based on results obtained in Table 3.3) to solve the 30 D problems, with the remaining parameters set as mentioned in Section 3.4.1.1. Note that increasing the number of operators does not necessarily mean achieving better performance [24]. One reason for this, is that operators may not be complementary, which may cause loss of fitness evaluations and/or a biased search process.

Summary of the results are presented in Table 3.4. To understand it, for example, row 4 , which compares $m=3$ and $m=7$, indicates that $m=3$ was superior for 15 test problems, obtained the same results for 9 , but was inferior for 6 , which means that $m=3$ was better than $m=7$.

Regarding the Wilcoxon signed-rank test, it is clear that $m=5$ is better than

Table 3.4: Summary of comparison of different variants of proposed algorithm with different $m$ values ( $3,4,5,6$ and 7 ) is based on average results

|  | Algorithms | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Mean | $m=3$ Vs. $m=4$ | 12 | 7 | 11 | $\approx$ |
|  | $m=3$ vs. $m=5$ | 10 | 8 | 12 | $\approx$ |
|  | $m=3$ vs. $m=6$ | 13 | 8 | 9 | $\approx$ |
|  | $m=3$ vs. $m=7$ | 15 | 9 | 6 | + |
|  | $m=4$ vs. $m=5$ | 7 | 11 | 12 | - |
|  | $m=4$ vs. $m=6$ | 16 | 7 | 7 | + |
|  | $m=4$ vs. $m=7$ | 15 | 7 | 8 | + |
|  | $m=5$ vs. $m=6$ | 17 | 7 | 6 | + |
|  | $m=5$ vs. $m=7$ | 15 | 9 | 6 | + |
|  | $m=6$ vs. $m=7$ | 13 | 8 | 9 | $\approx$ |

* Note Dec. is based on the Wilcoxon signed test
the others, as confirmed by the Friedman test, the results of which are shown in Figure 3.2(a).

Furthermore, the performance profiles are depicted in Figure 3.3(a), in which, one can observe from the figure, that the variant with $m=5$ outperforms other variants.

### 3.4.1.3 Analyzing the reduction mechanism

In this section, the effect of reducing $m$ during a run was analyzed. To do this, four different variants of the proposed algorithm (Ver1, Ver2, Ver3 and Ver4) were run. In Ver1, $m$ was reduced from 5 to 1 ; in Ver2 $m$ was reduced from 5 to 4 to 3 to 2 to $1, m$ was reduced from 5 to 3 to 1 in Ver3 and reduced from 5 to 3 to 2 to 1 in Ver4. To show the benefit of reducing $m$ over generations, another variant (Ver5) with no reduction was run. In Ver5, all the five search operators were used in each generation and the number of individuals evolved by each mutation strategy was updated based on the proposed selection mechanism. All the parameters setting are set as those in the previous section. The detailed results (average, St.d) are presented in Appendix A, Table A.11.


Figure 3.2: Average rankings of (a) different variants for $m=3,4,5,6$, and 7 mutation strategies (b) five different variants, (c) different values of $N P^{i n i t}$, (d) different values of $C S$, (e) different values of $N P^{\min }$ and (f) LSAOS-DE and seven other variants

Table 3.5: Summary of comparisons of different variants of proposed algorithm with different variants for reducing $m$ based on average results, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results

| Algorithms | Better | Equal | Worse | Prob. | Dec. $\alpha=0.05$ | Dec. $\alpha=0.10$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ver 1 vs. Ver 2 | 19 | 7 | 4 | 0.002 | + | + |
| Ver 1 vs. Ver 3 | 17 | 8 | 5 | 0.026 | + | + |
| Ver 1 vs. Ver 4 | 12 | 10 | 8 | 0.332 | $\approx$ | $\approx$ |
| Ver 1 vs. Ver 5 | 14 | 8 | 8 | 0.042 | + | + |
| Ver 2 vs. Ver 3 | 11 | 7 | 12 | 0.891 | $\approx$ | $\approx$ |
| Ver 2 vs. Ver 4 | 8 | 7 | 15 | 0.097 | $\approx$ | - |
| Ver 2 vs. Ver 5 | 11 | 6 | 13 | 0.909 | $\approx$ | $\approx$ |
| Ver 3 vs. Ver 4 | 8 | 6 | 16 | 0.103 | $\approx$ | $\approx$ |
| Ver 3 vs. Ver 5 | 10 | 7 | 13 | 0.761 | $\approx$ | $\approx$ |
| Ver 4 vs. Ver 5 | 15 | 7 | 8 | 0.059 | $\approx$ | + |

Table 3.6: Friedman test results

| Algorithm | Mean rank | Order |
| :---: | :---: | :---: |
| Ver1 | 2.38 | 1 |
| Ver2 | 3.42 | 5 |
| Ver3 | 3.37 | 4 |
| Ver4 | 2.70 | 2 |
| Ver5 | 3.13 | 3 |

Table 3.5 presents shows the summary of the obtained results, based on the average results. Regarding the Wilcoxon signed-rank test, Ver1 is the best. The overall rankings for the different five variants are presented in Table 3.6 and Figure 3.2(b), in which Ver1 has the best performance. These results are also confirmed by the plots of the performance profiles depicted in Figure 3.3(b). From the above comparison, it is clear that Ver1 is the best among the variants which used a reduction mechanism for m . Comparing Ver1 with Ver5, Ver1 is better, which means that reducing the number of DE mutations strategy is better than, fixing the number of DE mutation strategies during the search process.

### 3.4.1.4 Effect of $N P^{\text {init }}$

The influence of $N P^{\text {init }}$ on the performance of LSAOS-DE was investigated by conducting several experiments with $N P^{\text {init }}=5 D, 10 D, 18 D, 20 D, 25 D$, and $30 D$ for solving the $30 D$ problems. The remaining parameters were fixed as mentioned in Section 3.4.1.1, detailed results are shown in Appendix A, Table A.12. Table 3.7 shows the summary of comparisons for different $N P^{\text {init }}$ values, based on the average obtained results. Regarding the Wilcoxon signed-rank test results, it is clear that $N P=25 D$ was the best for all variants. Further analysis based on the Friedman test for different values of $N P^{\text {init }}$ was conducted. The mean ranks depicted in Figure 3.2(c) also show that $N P^{\text {init }}=25 D$ was the best.

Furthermore, the performance profiles graph is depicted in Figure 3.3(c). From which, it is clear that the variant with $N P^{i n i t}=25 D$ was better than all the others.

### 3.4.1.5 Effect of $C S$

The effect of $C \mathrm{~S}$, which determines the timing of reductions in the number of mutation strategies, was analyzed. This is done by utilizing different numbers of generations, $25,50,75,100,150$, and 200 for $C S$, while all other parameters were set as in previous sections (detailed results are shown in Appendix A, Table A.13). The overall rankings for all the different $C S$ values, based on the Friedman test are depicted in Figure 3.2(d), in which it is clear that higher values of $C S$ had good impacts on performance, with $C S=150$ preferred.

Table 3.8 presents a summary of the comparisons of six different $C S$ values. Regarding the statistical test, it was found that $C S=150$ better than the others.

From the performance profiles of the six different CS values depicted in Figure

Table 3.7: Summary of comparisons of different variants of proposed algorithm with different $N P^{\text {init }}$ values $(5 D, 10 D, 18 D, 20 D, 25 D$ and $30 D)$ based on average results, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results

| Algorithms | Better | Equal | Worse | Prob. | Dec. $\alpha=0.05$ | Dec. $\alpha=0.10$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $5 D$ vs. $10 D$ | $\mathbf{4}$ | $\mathbf{8}$ | $\mathbf{1 8}$ | $\mathbf{0 . 0 0 6}$ | - | - |
| $5 D$ vs. $15 D$ | $\mathbf{5}$ | $\mathbf{6}$ | $\mathbf{1 9}$ | $\mathbf{0 . 0 0 2}$ | - | - |
| $5 D$ vs. $18 D$ | $\mathbf{4}$ | $\mathbf{6}$ | $\mathbf{2 0}$ | $\mathbf{0 . 0 0 1}$ | - | - |
| $5 D$ vs. $20 D$ | $\mathbf{7}$ | $\mathbf{5}$ | $\mathbf{1 8}$ | $\mathbf{0 . 0 1 3}$ | - | - |
| $5 D$ vs. $25 D$ | $\mathbf{6}$ | $\mathbf{4}$ | $\mathbf{2 0}$ | $\mathbf{0 . 0 0 5}$ | - | - |
| $5 D$ vs. $30 D$ | $\mathbf{9}$ | $\mathbf{4}$ | $\mathbf{1 7}$ | $\mathbf{0 . 0 2 8}$ | - | - |
| $10 D$ vs. $15 D$ | $\mathbf{6}$ | $\mathbf{7}$ | $\mathbf{1 7}$ | $\mathbf{0 . 0 0 1}$ | - | - |
| $10 D$ vs. $18 D$ | $\mathbf{6}$ | $\mathbf{8}$ | $\mathbf{1 6}$ | $\mathbf{0 . 0 0 2}$ | - | - |
| $10 D$ vs. $20 D$ | $\mathbf{9}$ | $\mathbf{6}$ | $\mathbf{1 5}$ | $\mathbf{0 . 0 3 4}$ | - | - |
| $10 D$ vs. $25 D$ | $\mathbf{7}$ | $\mathbf{5}$ | $\mathbf{1 8}$ | $\mathbf{0 . 0 0 5}$ | - | - |
| $10 D$ vs. $30 D$ | $\mathbf{9}$ | $\mathbf{5}$ | $\mathbf{1 6}$ | $\mathbf{0 . 0 4 8}$ | - | - |
| $15 D$ vs. $18 D$ | $\mathbf{8}$ | $\mathbf{7}$ | $\mathbf{1 5}$ | $\mathbf{0 . 0 5 2}$ | $\approx$ | - |
| $15 D$ vs. $20 D$ | 11 | 6 | 13 | 0.376 | $\approx$ | $\approx$ |
| $15 D$ vs. $25 D$ | $\mathbf{8}$ | $\mathbf{4}$ | $\mathbf{1 8}$ | $\mathbf{0 . 0 3 2}$ | - | - |
| $15 D$ vs. $30 D$ | 11 | 6 | 13 | 0.230 | $\approx$ | $\approx$ |
| $18 D$ vs. $20 D$ | 16 | 5 | 9 | 0.122 | $\approx$ | $\approx$ |
| $18 D$ vs. $25 D$ | 11 | 5 | 14 | 0.451 | $\approx$ | $\approx$ |
| $18 D$ vs. $30 D$ | 13 | 5 | 12 | 0.936 | $\approx$ | $\approx$ |
| $20 D$ vs. $25 D$ | 9 | 6 | 15 | 0.119 | $\approx$ | $\approx$ |
| $20 D$ vs. $30 D$ | 11 | 8 | 11 | 0.709 | $\approx$ | $\approx$ |
| $25 D$ vs. $30 D$ | 15 | 6 | 9 | 0.141 | $\approx$ | $\approx$ |

$3.3(\mathrm{~d})$, it is clear that the variant with $C S=150$ was the first to reach a probability of 1 , with $\tau$ between 4 and 5 .

### 3.4.1.6 Effect of $N P^{\text {min }}$

As previously mentioned, the number of individuals in the whole population was initially $N P^{i n i t}$ which was then linearly reduced to $N P^{m i n}$. To analyze the effect of $N P^{\text {min }}$, different experiments were conducted using different $N P^{m i n}$ values of $7,10,20,30,40$, and 50 , while all the other parameters were fixed, as previously discussed (detailed results are shown in Appendix A, Table A.14). All the variants were ranked based on the Friedman test and their results depicted in

Table 3.8: Summary of comparisons of different variants of proposed algorithm with different $C S$ values ( $25,50,75,100,150$ and 200) based on average results, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results

| Algorithms | Better | Equal | Worse | Prob. | Dec. $\alpha=0.05$ | Dec. $\alpha=0.10$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $C S=25$ vs. $C S=50$ | 12 | 9 | 9 | 0.566 | $\approx$ | $\approx$ |
| $C S=25$ vs. $C S=75$ | 13 | 9 | 8 | 0.313 | $\approx$ | $\approx$ |
| $C S=25$ vs. $C S=100$ | 10 | 9 | 11 | 0.741 | $\approx$ | $\approx$ |
| $C S=25$ vs. $C S=150$ | $\mathbf{8}$ | $\mathbf{9}$ | $\mathbf{1 3}$ | $\mathbf{0 . 0 9 5}$ | $\approx$ | - |
| $C S=25$ vs. $C S=200$ | 10 | 8 | 12 | 0.256 | $\approx$ | $\approx$ |
| $C S=50$ vs. $C S=75$ | 9 | 10 | 11 | 0.709 | $\approx$ | $\approx$ |
| $C S=50$ vs. $C S=100$ | 7 | 9 | 14 | 0.251 | $\approx$ | $\approx$ |
| $C S=50$ vs. $C S=150$ | $\mathbf{8}$ | $\mathbf{7}$ | $\mathbf{1 5}$ | $\mathbf{0 . 0 8 9}$ | $\approx$ | - |
| $C S=50$ vs. $C S=200$ | 10 | 7 | 13 | 0.140 | $\approx$ | $\approx$ |
| $C S=75$ vs. $C S=100$ | 8 | 8 | 14 | 0.168 | $\approx$ | $\approx$ |
| $C S=75$ vs. $C S=150$ | $\mathbf{3}$ | $\mathbf{8}$ | $\mathbf{1 9}$ | $\mathbf{0 . 0 0 4}$ | - | - |
| $C S=75$ vs. $C S=200$ | $\mathbf{6}$ | $\mathbf{8}$ | $\mathbf{1 6}$ | $\mathbf{0 . 0 2 0}$ | - | - |
| $C S=100$ vs. $C S=150$ | $\mathbf{8}$ | $\mathbf{9}$ | $\mathbf{1 3}$ | $\mathbf{0 . 0 7 6}$ | $\approx$ | - |
| $C S=100$ vs. $C S=200$ | 9 | 10 | 11 | 0.232 | $\approx$ | $\approx$ |
| $C S=150$ vs. $C S=200$ | 10 | 10 | 10 | 1 | $\approx$ | $\approx$ |

Table 3.9: Summary of comparisons of different variants of proposed algorithm with different $N P^{\text {min }}$ values ( $7,10,20,30,40$ and 50 ) based on average results, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results

| Algorithms | Better | Equal | Worse | Prob. | Dec. $\alpha=0.05$ | Dec. $\alpha=0.10$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| $N P^{\text {min }}=7$ vs. $N P^{\text {min }}=10$ | 14 | 8 | 8 | 0.961 | $\approx$ | $\approx$ |
| $N P^{\text {min }}=7$ vs. $N P^{\text {min }}=20$ | $\mathbf{1 9}$ | $\mathbf{8}$ | $\mathbf{3}$ | $\mathbf{0 . 0 0 2}$ | + | + |
| $N P^{\text {min }}=7$ vs. $N P^{\text {min }}=30$ | $\mathbf{1 9}$ | $\mathbf{7}$ | $\mathbf{4}$ | $\mathbf{0 . 0 0 6}$ | + | + |
| $N P^{\text {min }}=7$ vs. $N P^{\text {min }}=40$ | $\mathbf{1 8}$ | $\mathbf{6}$ | $\mathbf{6}$ | $\mathbf{0 . 0 6 3}$ | $\approx$ | + |
| $N P^{\text {min }}=7$ vs. $N P^{\text {min }}=50$ | $\mathbf{1 8}$ | $\mathbf{5}$ | $\mathbf{7}$ | $\mathbf{0 . 0 4 2}$ | + | + |
| $N P^{\text {min }}=10$ vs. $N P^{\text {min }}=20$ | $\mathbf{1 8}$ | $\mathbf{7}$ | $\mathbf{5}$ | $\mathbf{0 . 0 0 6}$ | + | + |
| $N P^{\text {min }}=10$ vs. $N P^{\text {min }}=30$ | $\mathbf{1 7}$ | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{0 . 0 0 5}$ | + | + |
| $N P^{\text {min }}=10$ vs. $N P^{\text {min }}=40$ | $\mathbf{2 1}$ | $\mathbf{7}$ | $\mathbf{2}$ | $\mathbf{0 . 0 0 0}$ | + | + |
| $N P^{\text {min }}=10$ vs. $N P^{\text {min }}=50$ | $\mathbf{1 8}$ | $\mathbf{6}$ | $\mathbf{6}$ | $\mathbf{0 . 0 0 1}$ | + | + |
| $N P^{\text {min }}=20$ vs. $N P^{\text {min }}=30$ | 15 | 6 | 9 | 0.265 | $\approx$ | $\approx$ |
| $N P^{\text {min }}=20$ vs. $N P^{\text {min }}=40$ | 16 | 7 | 7 | 0.191 | $\approx$ | $\approx$ |
| $N P^{\text {min }}=20$ vs. $N P^{\text {min }}=50$ | 15 | 6 | 9 | 0.130 | $\approx$ | $\approx$ |
| $N P^{\text {min }}=30$ vs. $N P^{\text {min }}=40$ | $\mathbf{1 7}$ | $\mathbf{9}$ | $\mathbf{4}$ | $\mathbf{0 . 0 6 8}$ | $\approx$ | + |
| $N P^{\text {min }}=30$ vs. $N P^{\text {min }}=50$ | $\mathbf{1 8}$ | $\mathbf{5}$ | $\mathbf{7}$ | $\mathbf{0 . 0 1 3}$ | + | + |
| $N P^{\text {min }}=40$ vs. $N P^{\text {min }}=50$ | $\mathbf{1 4}$ | $\mathbf{7}$ | $\mathbf{9}$ | $\mathbf{0 . 0 9 7}$ | $\approx$ | + |

Figure 3.2(e). Also, a Wilcoxon signed-rank test of the different variants of the proposed algorithm, with different $N P^{\text {min }}$ values was conducted and the summary of the results presented in Table 3.9 indicates that the setting of $N P^{\min }=7$ was slightly better than those of other variants, with small values preferred.

The performance profiles for different values of $N P^{\text {min }}$ are depicted in Figure $3.3(\mathrm{e})$, which shows that the variant with $N P^{\min }=7$ had the highest probability at the beginning, and was the first to reach a probability of 1 , with $\tau$ between 70 and 80 .

### 3.4.2 Comparisons of proposed algorithm and other heuristicbased selection methods

In this section, to assess the effect of the proposed selection mechanism, a comparison of LSAOS-DE and seven of its variants, namely AOSDE-LS, AOSDESR, AOSDE-FIR, AOSDE-PR, AOSDE-PBM, AOSDE-RD, and AOSDE-PAOC, in each of which only the selection mechanisms were different, and below is a description of the selection mechanism in every variant:

1. In AOSDE-LS, a landscape information is used to select the best-performing DE mutation strategy as in Equation 3.6.
2. In ASODE-SR, to select the best-performing operator, a success rate was used as in Equation 3.4.
3. In ASODE-FIR, fitness improvement rate, which is used to evaluate the difference in quality between the parent solution and its offspring in a normalized manner [108], is used and is computed by

$$
\begin{equation*}
F I R_{o p}=\frac{p f-c f}{p f} \tag{3.15}
\end{equation*}
$$

where $p f$ and $c f$ are the best fitness value for parent and child solution, respectively.


Figure 3.3: Performance profiles for (a) $m$ with different values, (b) five different variants, (c) $N P^{\text {init }}$ with different values, (d) $C S$ with different values, (e) $N P^{\min }$ with different values and (f) LSAOS-DE and other seven variants, where $R h o_{s}(\tau)$ is the fraction of problems that a solver was able to solve within a factor of $\tau \geq 1$ of the best observed performance.
4. In AOSDE-PR, progress ratio [106], which is used to evaluate the ability of an operator to improve its best solution, is computed by

$$
\begin{equation*}
P R=\left|l n \sqrt{\frac{f_{\min }(t-1)}{f_{\min }(t)}}\right| \tag{3.16}
\end{equation*}
$$

5. In AOSDE-PBM, in each generation the difference between the best fitness found by each operator, and the best known solution is calculated. An exponential function, $\left(a e^{b x}\right)$, is fitted to these values. Then this model is used to calculate the expected absolute error after $C S$ subsequent generations, and the DE mutation strategy that has the minimum expected absolute error is chosen as the best-performing operator [104].
6. In AOSDE-RD, one of the DE mutation strategies is randomly selected every $C S$ generation to evolve the entire population for the subsequent $C S$ generations.
7. In AOSDE-PAOC, DE mutation strategies are given probabilities in proportion to the improvement of fitness over two iterations [109]. This probability is computed by

$$
\begin{equation*}
P b(t)=P b(t-1)+\sum_{i=1}^{S_{o p}}\left(f\left(x_{i}(t-1)\right)-f\left(x_{i}(t)\right)\right. \tag{3.17}
\end{equation*}
$$

where $S_{o p}$ is the number of individuals evolved by operator op and $P b_{o p}(0)$ is the initial probability and is calculated by:

$$
\begin{equation*}
P b_{o p}(0)=\frac{1}{S_{o p}} \tag{3.18}
\end{equation*}
$$

Detailed results are shown in Appendix A, Tables A.8, A.9, A.10. A Friedman test was carried out to rank all the algorithms based on their average results

Table 3.10: Friedman test results obtained from comparing LSAOS-DE and seven variants

|  | 10 D |  | 30 D |  | 50 D |  | Overall rank |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Algorithm | Mean rank | Order | Mean rank | Order | Mean rank | Order |  |
| LSAOS-DE | $\mathbf{3 . 4 2}$ | 1 | $\mathbf{3 . 3 8}$ | 1 | $\mathbf{3 . 1 8}$ | 1 | 1 |
| AOSDE-LS | 4.86 | 6 | 4.74 | 6 | 5.03 | 5 | 8 |
| AOSDE-SR | 5.07 | 7 | 4.13 | 2 | 4.28 | 2 | 2 |
| AOSDE-FIR | 4.79 | 5 | 4.98 | 7 | 4.28 | 2 | 6 |
| AOSDE-PR | 4.50 | 4 | 4.66 | 5 | 4.69 | 4 | 4 |
| AOSDE-PBM | 4.27 | 3 | 4.47 | 3 | 5.22 | 6 | 5 |
| AOSDE-RD | 4.26 | 2 | 5.00 | 8 | 5.11 | 7 | 7 |
| AOSDE-PAOC | 4.86 | 6 | 4.64 | 4 | 4.21 | 3 | 3 |

* Overall rank is based on the sum of the orders for $10 \mathrm{D}, 30 \mathrm{D}$, and 50D
as shown in Table 3.10 and Figure 3.2(e), in which LSAOS-DE was ranked first for the $10 D, 30 D$ and $50 D$ test problems, with AOSDE-RD second for the $10 D$, AOSDE-SR second for the $30 D$, and AOSDE-SR and AOSDE-FIR equal second for the 50 D ones.

Considering the quality of solutions obtained, a comparison was carried out of LSAOS-DE and all the other variants, with the results shown in Table 3.11. It is clear that, LSAOS-DE is better than all other algorithms.

Regarding Wilcoxon signed-rank test, for the $10 D$, LSAOS-DE is significantly better than all other algorithms and it is significantly better than all other algorithms, except AOSDE-SR and AOSDE-PAOC, for $30 D$ and $50 D$ problems, respectively. Generally speaking, it is evident that the proposed algorithm was better than its variants.

Also, the average total computational time and FEs is presented in Table 3.12, which shows that the proposed LSAOS-DE requires the least average computational time and FEs. That means the propos LSAOS-DE saves computational time by $15.45 \%, 14.87 \%, 15.14 \%, 15.20 \%, 15.40 \%, 14.57 \%$ and $13.94 \%$, and FEs by $13.81 \%, 14.34 \%, 15.73 \%, 14.28 \%, 13.29 \%, 13.55 \%$ and $15.45 \%$ in comparison to AOSDE-LS, AOSDE-SR, AOSDE-FIR, AOSDE-PR, AOSDE-PBM, AOSDE-RD

Table 3.11: Summary of comparisons of proposed algorithm and seven variants, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results

|  | Algorithms | Better | Equal | Worse | p-value | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10D | LSAOS-DE vs. AOSDE-LS | 24 | 11 | 10 | 0.004 | + |
|  | LSAOS-DE vs. AOSDE-SR | 27 | 8 | 10 | 0.017 | $+$ |
|  | LSAOS-DE vs. AOSDE-FIR | 25 | 9 | 11 | 0.010 | $+$ |
|  | LSAOS-DE vs. AOSDE-PR | 27 | 8 | 10 | 0.006 | $+$ |
|  | LSAOS-DE vs. AOSDE-PBM | 24 | 10 | 11 | 0.007 | $+$ |
|  | LSAOS-DE vs. AOSDE-RD | 21 | 10 | 14 | 0.047 | $+$ |
|  | LSAOS-DE vs. AOSDE-PAOC | 25 | 10 | 10 | 0.004 | $+$ |
| 30D | LSAOS-DE vs. AOSDE-LS | 32 | 3 | 10 | 0.003 | + |
|  | LSAOS-DE vs. AOSDE-SR | 25 | 4 | 16 | 0.141 | $\approx$ |
|  | LSAOS-DE vs. AOSDE-FIR | 29 | 2 | 14 | 0.038 | + |
|  | LSAOS-DE vs. AOSDE-PR | 28 | 4 | 13 | 0.035 | $+$ |
|  | LSAOS-DE vs. AOSDE-PBM | 31 | 2 | 12 | 0.009 | $+$ |
|  | LSAOS-DE vs. AOSDE-RD | 28 | 3 | 14 | 0.037 | + |
|  | LSAOS-DE vs. AOSDE-PAOC | 28 | 4 | 13 | 0.015 | + |
| 50D | LSAOS-DE vs. AOSDE-LS | 35 | 1 | 9 | 0.000 | $+$ |
|  | LSAOS-DE vs. AOSDE-SR | 29 | 3 | 13 | 0.043 | + |
|  | LSAOS-DE vs. AOSDE-FIR | 28 | 2 | 15 | 0.036 | + |
|  | LSAOS-DE vs. AOSDE-PR | 29 | 2 | 14 | 0.033 | $+$ |
|  | LSAOS-DE vs. AOSDE-PBM | 32 | 1 | 12 | 0.001 | + |
|  | LSAOS-DE vs. AOSDE-RD | 37 | 1 | 7 | 0.000 | + |
|  | LSAOS-DE vs. AOSDE-PAOC | 28 | 2 | 15 | 0.070 | $\approx$ |

Table 3.12: Comparison among LSAOS-DE and seven of its variants based on the average computational time and FEs

| \{Algorithms | Total average time | Total average FEs |
| :---: | :---: | :---: |
| LSAOS-DE | $\mathbf{2 3 1 . 2 8}$ | $\mathbf{7 5 6 7 1 8 4}$ |
| AOSDE-LS | 273.56 | 8779867 |
| AOSDE-SR | 271.68 | 8833511 |
| AOSDE-FIR | 272.56 | 8979867 |
| AOSDE-PR | 272.72 | 8827440 |
| AOSDE-PBM | 273.39 | 8726557 |
| AOSDE-RD | 270.73 | 8752952 |
| AOSDE-PAOC | 268.75 | 8950416 |

and AOSDE-PAOC, respectively.

Furthermore, from the graphs of the performance profiles depicted in Figure $3.3(\mathrm{f})$, it is clear that LSAOS-DE had the highest probability at the start, and reached a probability of 1 first at $\tau=2.5$, while AOSDE-SR was second.

As a further illustration, the convergence plots of the best results obtained during 51 runs of LSAOS-DE, AOSDE-SR, AOSDE-LS for the 30 D problems, for four different functions, F01, F06, F20 and F30, are shown in Figure 3.4, in which it is clear that the convergence speed of LSAOS-DE was the best. It can be concluded that, a balance between the success rate and landscape information leads to good performances, in comparison to the other cases.

### 3.4.3 Comparisons of proposed and state-of-the-art algorithms

Experiments were conducted to compare the performance of the proposed algorithm with those of state-of-the-art ones using the best set of previously determined parameter values, that is, $N P^{i n i t}=25 D, N P^{\text {min }}=7, C S=150$ and $N P$ updated using equation 3.1.

Details of the computational results $\left(f\left(x_{\text {best }}\right)-f\left(x^{*}\right)\right)$ obtained from the proposed algorithm for $10 \mathrm{D}, 30 \mathrm{D}$, and 50 D problems are shown in Appendix A, (Tables A.1, A.2, A.3, A.4, A.5, A.6, A.7), in which the average values and standard deviations of the solutions are compared with those obtained from the state-of-the-art algorithms.

The proposed method obtained better results than all the other algorithms for more $10 D$ test problems. For the $30 D$ ones, LSAOS-DE obtained better results than all the other algorithms although AMALGAM-SO was competitive in terms of its average results. For the 50 D problems, the proposed method performed better than all the other algorithms except LSHADE, which was competitive in terms of its average values but there was a bias towards LSAOS-DE.

The results based on the average fitness values obtained from the Wilcoxon


Figure 3.4: Convergence graphs which compares LSAOS-DE with both AOSDE-LS and AOSDE-SR, with the values of SR and LS (a,b,c) F01, (d,e,f) F06, (g,h,i) F20 and (j,k,l) F30

Table 3.13: Summary of comparisons of proposed algorithm and nine state-of-the-art algorithms based on mean results, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results.

|  | Algorithms | Better | Equal | Worse | p-value | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 D | LSAOS-DE vs. LSHADE | 20 | 12 | 13 | 0.057 | $\approx$ |
|  | LSAOS-DE vs. JADE | 35 | 8 | 2 | 0.000 | + |
|  | LSAOS-DE vs. SHADE | 33 | 9 | 3 | 0.000 | + |
|  | LSAOS-DE vs. CoDE | 25 | 8 | 12 | 0.022 | + |
|  | LSAOS-DE vs. SaDE | 32 | 8 | 5 | 0.000 | + |
|  | LSAOS-DE vs. EPSDE | 29 | 8 | 8 | 0.011 | + |
|  | LSAOS-DE vs. UMOEAs | 28 | 8 | 9 | 0.001 | + |
|  | LSAOS-DE vs. MPEDE | 28 | 9 | 8 | 0.001 | + |
|  | LSAOS-DE vs. AMALGAM-SO | 31 | 2 | 12 | 0.006 | + |
|  | LSAOS-DE vs. LSHADE | 23 | 5 | 17 | 0.125 | $\approx$ |
|  | LSAOS-DE vs. JADE | 33 | 4 | 8 | 0.000 | + |
|  | LSAOS-DE vs. SHADE | 36 | 3 | 6 | 0.000 | + |
|  | LSAOS-DE vs. CoDE | 35 | 1 | 9 | 0.000 | + |
|  | LSAOS-DE vs. SaDE | 40 | 1 | 4 | 0.000 | + |
|  | LSAOS-DE vs. EPSDE | 36 | 0 | 9 | 0.001 | + |
|  | LSAOS-DE vs. UMOEAs | 31 | 4 | 10 | 0.001 | + |
|  | LSAOS-DE vs. MPEDE | 32 | 4 | 9 | 0.000 | + |
|  | LSAOS-DE vs. AMALGAM-SO | 31 | 0 | 14 | 0.019 | + |
|  | LSAOS-DE vs. LSHADE | 23 | 5 | 17 | 0.125 | $\approx$ |
| LSAOS-DE vs. JADE | 33 | 4 | 8 | 0.000 | + |  |
|  | LSAOS-DE vs. SHADE | 36 | 3 | 6 | 0.000 | + |
|  | LSAOS-DE vs. CoDE | 35 | 1 | 9 | 0.000 | + |
|  | LSAOS-DE vs. SaDE | 40 | 1 | 4 | 0.000 | + |
|  | LSAOS-DE vs. EPSDE | 36 | 0 | 9 | 0.001 | + |
|  | LSAOS-DE vs. UMOEAs | 31 | 4 | 10 | 0.001 | + |
|  | LSAOS-DE vs. MPEDE | 32 | 4 | 9 | 0.000 | + |
|  | LSAOS-DE vs. AMALGAM-SO | 31 | 0 | 14 | 0.019 | + |

signed-rank test presented in Table 3.13 demonstrate that the proposed algorithm was statistically better than all the state-of-the-art ones in terms of both the average and best results for the $10 D, 30 D$ and $50 D$ problems,except for LSHADE and AMALGAM-SO for the means of the 50 D and 30 D ones, respectively, where there was no significant difference.

For further analysis, a Friedman test was performed to rank all algorithms based on the average fitness values they achieved. The results shown in Table 3.14

Table 3.14: Friedman test results obtained from comparisons of LSAOS-DE and state-of-the-art algorithms

|  | 10 D |  | 30 D |  | 50 D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Algorithm | Mean rank | Order | Mean rank | Order | Mean rank | order | Overall rank |
| LSAOS-DE | $\mathbf{3 . 3 8}$ | 1 | $\mathbf{3 . 1 2}$ | 1 | $\mathbf{3 . 0 1}$ | 1 | 1 |
| LSHADE | 4.02 | 2 | 3.90 | 2 | 3.91 | 2 | 2 |
| JADE | 5.96 | 5 | 6.59 | 8 | 6.34 | 7 | 8 |
| SHADE | 5.49 | 4 | 5.72 | 5 | 5.64 | 6 | 4 |
| CoDE | 4.87 | 3 | 5.88 | 7 | 6.52 | 8 | 7 |
| SaDE | 6.40 | 7 | 7.27 | 10 | 7.41 | 10 | 9.5 |
| EPSDE | 6.93 | 9 | 7.17 | 9 | 7.27 | 9 | 9.5 |
| UMOEAs | 6.37 | 6 | 5.84 | 6 | 5.47 | 5 | 6 |
| MPEDE | 4.87 | 3 | 4.11 | 3 | 4.53 | 3 | 3 |
| AMALGAM-SO | 6.72 | 8 | 5.40 | 4 | 4.89 | 4 | 5 |

* Overall rank is based on the sum of the orders for 10D, 30D, and 50D
indicate that, generally, LSAOS-DE ranked $1^{\text {st }}$ followed by LSHADE, MPEDE, SHADE, AMALGAM-SO, UMOEAs, JADE, CoDE, SaDE and EPSDE.

As a further illustration, the convergence plots of the average results obtained during 51 runs of all the algorithms for the 30 D problems are shown in Figure 3.5, in which it is evident that the convergence speed of LSAOS-DE was the best.

### 3.4.4 Relative time complexity

This section describes the algorithmic complexity of the proposed LSAOS-DE code in which, as defined in [198, 199]. As defined in [198, 199], $T_{0}$ is the time calculated for running the code :

$$
\begin{aligned}
& \text { for } i=1: 1000000 \\
& x=0.55+(\text { double }) i ; x=x+x ; x=x / 2 ; x=x * x \\
& x=\operatorname{sqrt}(x) ; x=\log (x) ; x=\exp (x) ; x=x /(x+2) ;
\end{aligned}
$$

end
where $T_{1}$ is the time to execute 200,000 evaluations of the benchmark functions


Figure 3.5: Convergence plots of proposed algorithm and state-of-the-art-algorithm for (a) F01, (b) F07, (c) F23 and (d) F30.
$F 18$ for CEC2014 and $F 31$ for CEC2015, respectively, with $D$ dimensions, and $T_{2}$ is the time to execute LSAOS-DE with 200,000 evaluations of both functions in $D$ dimensions. $\hat{T}_{2}$ is the mean of the $T_{2}$ values of 5 runs. Table 3.15 shows the time complexity of LSAOS-DE computed for $10 D, 30 D$, and $50 D$ in CEC2014 [198] and CEC2015 [199].

The correlation coefficient $(R)$ in Table 3.15 is computed to observe the relationship between dimensions and $\frac{\left(\hat{T_{2}}-T_{1}\right)}{T_{0}}$, which for both CEC2014 and CEC2015, is a strong positive linear one (i.e., $\frac{\left(\hat{T_{2}}-T_{1}\right)}{T_{0}}$ scaled linearly with the number of dimensions).

Table 3.15: Algorithm's complexity

|  |  | $T_{0}$ | $T_{1}$ | $\hat{T}_{2}$ | $\frac{\left(\hat{T}_{2}-T_{1}\right)}{T_{0}}$ | $R$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CEC2014 | $D=10$ | 0.110568 | 0.307946 | 0.926645 | 5.59565064 | 0.981004 |
|  | $D=30$ |  | 0.288033 | 1.176284 | 8.033201288 |  |
|  | $D=50$ |  | 0.559683 | 1.943288 | 12.51798893 |  |
|  | $D=100$ |  | 2.55944 | 4.424032 | 16.86744809 |  |
| CEC2015 | $D=10$ | 0.110568 | 0.117537 | 0.932886 | 7.374186021 | 0.946601 |
|  | $D=30$ |  | 0.382173 | 1.276088 | 8.084753274 |  |
|  | $D=50$ |  | 0.789205 | 2.218334 | 12.92534006 |  |
|  | $D=100$ |  | 2.463938 | 4.172859 | 15.45583713 |  |

### 3.5 Chapter Summary

During the last few decades, several EAs have been introduced to solve unconstrained optimization problems. However, no single EA is able to solve a wide range of these problems. As a result, the concept of multi-method and multioperator has been emerged to tackle this issue. An AOS mechanisms are used in these designs, to choose the best-performing operator and/or algorithm. Utilizing a problem's landscape to design an efficient AOS mechanism has not been comprehensively explored. In this chapter, a novel multi-operator DE algorithm was designed. In its process, more than one DE mutation strategies with diverse characteristics are used. Also, to put more emphasis on the best-performing operator during the evolutionary process, a problem's landscape information is adopted within an AOS.

The performance of the proposed algorithms were tested by solving 45 bound constrained numerical optimization problems, taken from CEC2014 and CEC2015. LSAOS-DE was compared to seven of its variants, with the results showing that it was better in the quality of solutions obtained.

Then, based on the quality of solutions obtained, the results from LSAOS-DE were compared with those from existing state-of-the-art algorithms such as three
well-known DE-based single operator algorithms (LSHADE, SHADE, and JADE), four multi-operator-based algorithms (CoDE, SaDE, EPSDE, and MPEDE); and two multi-method based algorithms (UMOEAs and AMALGAM-SO). The experimental results show that the proposed algorithm is able to obtain better solutions, and its overall performance outperforms the state-of-the-art algorithms.

Motivated by the encouraging results presented in this chapter on unconstrained optimization problems, the next chapter attempts to also use the landscape information to efficiently solve COPs.

## Chapter 4

## Landscape-based Algorithm for

## Constrained Problems

In this chapter, a modified landscape measure is used in AOS to select the bestperforming DE mutation strategy from a pool of ones to solve constrained optimization problems (COPs). After a brief introduction, this chapter provides a description of the used benchmark problems. A proposed framework and the modified landscape method is presented. After that, an analysis of algorithm components is provided. Finally comparisons with state-of-art algorithms are provided.

### 4.1 Introduction

Constrained optimization problems play an important role in many scientific areas: such as computer science and operations research. As stated in chapter 2, the solution of COPs using EAs requires the satisfaction of all of a problem's constraints. To do this, many constrained handling techniques (CHTs) have been proposed and integrated with EAs, as reviewed in Chapter 2.

During the past few decades, many EAs and CHTs have been integrated to solve constrained optimization problems. However, no single algorithm is the best
for all kind of problems. As stated in the previous chapters, researchers and practitioners have developed many different methods that use different algorithms or search operators in a single framework. In Chapter 3, landscape measures were used in an adaptive operator selection mechanism, to put emphasis on the best-performing DE operators from a pool of operators. The results were very promising in solving unconstrained optimization problems.

Motivated by the encouraging results obtained in chapter 3, for solving unconstrained optimization problem, in this chapter two landscape measures are modified to deal with COPs. This is because landscape measures were originally designed for unconstrained optimization problems. Moreover, a multi-operator DE algorithm is proposed, in which these modified landscape measures are used to put more emphasis on the best-performing operator, with the aim of solving a wide range of COPs.

The performance of the proposed algorithm is judged by solving a set of constrained optimization problems, 24 from CEC2006 [207], 36 test problems from CEC2010 [186] (18 with $10 D$ and 18 with $30 D$ ) and 10 problems from CEC2011 [181]. Several experiments were designed and carried out to analyze the effects of different parameters on its performance, and the results from the final variant of the algorithm is compared with different variants of the same algorithm with different selection criteria. Subsequently, the best variant found after analyzing the algorithm's components, is compared to a number of state-of-the-art algorithms.

This chapter is organized as follows: the next section presents the benchmark problems; the proposed algorithm and the landscape modifications are discussed in Section 3.3; the experimental results and analysis are discussed in Section 3.4; and the chapter summary is presented in Section 3.5.

### 4.2 Benchmark Problems

To judge the performance of the proposed method, three sets of problems are used. These problems were introduced in the CEC2006, and the CEC2010 special competition sessions on constrained optimization problems, and CEC2011 special completion on real-world problems, they are known as the CEC2006 [207], CEC2010 [186], and CEC2011 benchmark problems.

The CEC2006 benchmark problems [207] contains 24 test problems, as detailed in Table 4.1 presents the details of these 24 test functions. In it $\rho=\frac{N F}{N P}$ is the feasibility ratio, where $N F$ is the number of feasible solutions in the initial population, generated by the test case developers, $L I, N I, L E$ and $N E$ are the number of linear inequality, nonlinear inequality, linear equality and nonlinear equality constraints, respectively, and $\alpha$ is the number of active constraints in the optimal solution. These test problems have different types of objective functions, such as linear, nonlinear, polynomial, quadratic and cubic. They have different numbers of decision variables, $D$, as seen in column 2 of the table.

CEC2010 contains 36 test problems(18 with 10 and 18 with 30 dimensions), as detailed in Table 4.2. Similar to the CEC2006 test problems, they have different mathematical properties, such as either linear or non-linear objective functions and/or constraints, either equality or inequality constraints and either uni-modal or multi-modal objective functions, with the feasible space possibly very tiny compared with the search space.

Real-application Test Problems: These problems come from CEC2011, in that benchmark, there are a number of real-world engineering problems. This chapter considers the 10 of them that are constrained problems. They have different mathematical characteristics, such as having different types and numbers of constraints

Table 4.1: Details of CEC2006 benchmark constrained test functions

| Problem | Variables | $\rho(\%)$ | LI | NI | LE | NE | $\alpha$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| g01 | 13 | 0.0111 | 9 | 0 | 0 | 0 | 6 |
| g02 | 20 | 99.9971 | 0 | 2 | 0 | 0 | 1 |
| g03 | 10 | 0.0000 | 0 | 0 | 0 | 1 | 1 |
| g04 | 5 | 52.1230 | 0 | 6 | 0 | 0 | 2 |
| g05 | 4 | 0.0000 | 2 | 0 | 0 | 3 | 3 |
| g06 | 2 | 0.0066 | 0 | 2 | 0 | 0 | 2 |
| g07 | 10 | 0.0003 | 3 | 5 | 0 | 0 | 6 |
| g08 | 2 | 0.8560 | 0 | 2 | 0 | 0 | 0 |
| g09 | 7 | 0.5121 | 0 | 4 | 0 | 0 | 2 |
| g10 | 8 | 0.0010 | 3 | 3 | 0 | 0 | 6 |
| g11 | 2 | 0.0000 | 0 | 0 | 0 | 1 | 1 |
| g12 | 3 | 4.7713 | 0 | 1 | 0 | 0 | 0 |
| g13 | 5 | 0.0000 | 0 | 0 | 0 | 3 | 3 |
| g14 | 10 | 0.0000 | 0 | 0 | 3 | 0 | 3 |
| g15 | 3 | 0.0000 | 0 | 0 | 1 | 1 | 2 |
| g16 | 5 | 0.0204 | 4 | 34 | 0 | 0 | 4 |
| g17 | 6 | 0.0000 | 0 | 0 | 0 | 4 | 4 |
| g18 | 9 | 0.0000 | 0 | 13 | 0 | 0 | 6 |
| g19 | 15 | 33.4761 | 0 | 5 | 0 | 0 | 0 |
| g21 | 7 | 0.0000 | 0 | 1 | 0 | 5 | 6 |
| g23 | 9 | 0.0000 | 0 | 2 | 3 | 1 | 6 |
| g24 | 2 | 79.6556 | 0 | 2 | 0 | 0 | 2 |

and variables, being static or dynamic in nature, and of different modalities. $r f_{1-}{ }^{-}$ $r f_{5}$, are static economic load dispatch (ELD) ones with dimensions of $6,13,15,40$ and 140 , respectively, problems $r f_{6}$ and $r f_{7}$ are dynamic economic dispatch (DED) ones with dimensions of 120 and 216, respectively, and problems $r f_{8^{-}} r f_{10}$ are Hydrothermal Scheduling Problems, all with 96 dimensions. Detailed descriptions of these problems can be found in [181].

Table 4.2: Details of CEC2010 (N-S indicates a function is non-separable, I-S that a function is separable, I- the number of inequality constraints, E- the number of equality constraints and feasibility ratio is estimated ratio between
feasible region and the search space)

| Problem | Search range | Objective type | Number of constraints |  | Feasibility rate |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | E | I | 10D | 30D |
| C01 | $[0,10]^{D}$ | N-S | 0 | $2 \mathrm{~N}-\mathrm{S}$ | 0.997689 | 1.0000 |
| C02 | $[5.12,5.12]^{D}$ | I-S | 1 I-S | 2 I-S | 0.0000 | 0.0000 |
| C03 | $[-1000,1000]^{D}$ | N-S | 1 I-S | 0 | 0.0000 | 0.0000 |
| C04 | $[-50,50]^{D}$ | I-S | $2 \mathrm{~N}-\mathrm{S}, 2 \mathrm{I}-\mathrm{S}$ | 0 | 0.0000 | 0.0000 |
| C05 | $[-600,600]^{D}$ | I-S | 2 I-S | 0 | 0.0000 | 0.0000 |
| C06 | $[-600,600]^{D}$ | I-S | 2 Rotated | 0 | 0.0000 | 0.0000 |
| C07 | $[-140,140]^{D}$ | N-S | 0 | 1 I-S | 0.505123 | 0.503725 |
| C08 | $[-140140]^{D}$ | N-S | 0 | 1 Rotated | 0.505123 | 0.503725 |
| C09 | $[-500,500]^{D}$ | N-S | 1 I-S | 0 | 0.0000 | 0.0000 |
| C10 | $[-500,500]^{D}$ | N-S | 1 Rotated | 0 | 0.0000 | 0.0000 |
| C11 | $[-100,100]^{D}$ | Rotated | $1 \mathrm{~N}-\mathrm{S}$ | 0 | 0.0000 | 0.0000 |
| C12 | $[-1000,1000]^{D}$ | I-S | $1 \mathrm{~N}-\mathrm{S}$ | 1 I-S | 0.0000 | 0.0000 |
| C13 | $[-500,500]^{D}$ | I-S | 0 | 2 I-S, 1 N-S | 0.0000 | 0.0000 |
| C14 | $[-1000,1000]^{D}$ | N-S | 0 | 3 I-S | 0.003112 | 0.006123 |
| C15 | $[-1000,1000]^{D}$ | N-S | 0 | 3 Rotated | 0.003210 | 0.006023 |
| C16 | $[-10,10]^{D}$ | N-S | 2 I-S | 1 I-S, 1 N-S | 0.0000 | 0.0000 |
| C17 | $[-10,10]^{D}$ | N-S | 1 I-S | $2 \mathrm{~N}-\mathrm{S}$ | 0.0000 | 0.0000 |
| C18 | $[-50,50]^{D}$ | N-S | 1 I-S | 1 I-S | 0.00001 | 0.0000 |

### 4.3 Modified Landscape Measure Combined with MODE

As previously described, existing multi-operator algorithms use an adaptive operator selection mechanism, which is usually based on the success of generating new offspring. In this section, the MODE algorithm, which uses modified problem's landscape information, to adaptively choose the most suitable DE operator, is proposed to solve a wide range of COPs. This section presents modified landscape measures, the general framework, and it components.

### 4.3.1 Modified landscape measures

In the previous chapters, the Information Landscape Negative Searchability (ILNS) measure was used in an AOS, to put more emphasis on the best-performing operator, from a pool of $m$ operators, and was used to solve unconstrained optimization problems. Dealing with constrained optimization problems is different from unconstrained ones, as all the functional constraints must be satisfied. Therefore, ILNS must be modified to be able to deal with COPs.

### 4.3.1.1 Modified ILNS (MILNS)

This section proposes a modified ILNS.

First, an information matrix $M=\left[a_{i, j}\right]$ for a minimization problem is constructed using:

$$
a_{i j}= \begin{cases}1 \quad & \text { if }\left(\psi\left(x_{i}\right)=\psi\left(x_{j}\right)=0 \text { and } f\left(x_{i}\right)<f\left(x_{j}\right)\right) \text { or }  \tag{4.1}\\ & \left(\text { if }\left(\psi\left(x_{i}\right) \neq 0 \text { and } \psi\left(x_{j}\right) \neq 0 \text { and } \psi\left(x_{i}\right)<\psi\left(x_{j}\right)\right)\right. \text { or } \\ & \left(\psi\left(x_{i}\right)=0 \text { and } \psi\left(x_{j}\right) \neq 0\right. \\ 0 \quad & \text { if }\left(\psi\left(x_{i}\right)=\psi\left(x_{j}\right)=0 \text { and } f\left(x_{i}\right)>f\left(x_{j}\right)\right) \text { or } \\ & \left(\text { if }\left(\psi\left(x_{i}\right) \neq 0 \text { and } \psi\left(x_{j}\right) \neq 0 \text { and } \psi\left(x_{i}\right)>\psi\left(x_{j}\right)\right)\right. \text { or } \\ & \psi\left(x_{i}\right) \neq 0 \text { and } \psi\left(x_{j}\right)=0\end{cases}
$$

0.5 otherwise
where $\psi\left(x_{i}\right)$ is the total degree of constrain violations for individual $x_{i}$. To construct the information landscape, as described in the previous chapter, not all entries in the information matrix $M$ are necessary. As, there is a duplicate in the entries due to symmetry (the lower triangle should be omitted), the entries on the diagonal are always 0.5 (and should be omitted), and the row and column of the optimum solution should be omitted. So the information matrix can be reduced to a vector $L S=\left(l s 1, l s_{2}, \ldots, l s_{|L S|}\right)$, where the number of elements in LS, $|L S|=\frac{(N P-1) \times(N P-2)}{2}$, and $N P$ is the population size.

Here, an example is given to understand how $L S$ is constructed for COPs. Consider the following COP:

$$
\begin{equation*}
\text { Minimize } f(x, y)=-(x-10)^{3}+(y-20)^{3} \tag{4.2}
\end{equation*}
$$

subject to: $g_{1}(x, y)=-(x-5)^{2}-(y-5)^{2}+100 \leq 0$

$$
\begin{array}{r}
g_{2}(x, y)=(x-6)^{2}+(y-5)^{2}-82.81 \leq 0 \\
13 \leq x \leq 100 \text { and } 0 \leq y \leq 100
\end{array}
$$

and the values of $(x, y)=\{(15.9997,4.1173),(14.4503,2.1789),(14.4354,1.4401)$, $(15.0003,4.3179)\}$, then $f_{1}=f\left(x_{1}, y_{1}\right)=-6321.1, f_{2}=f\left(x_{2}, y_{2}\right)=-5571.7$, $f_{3}=f\left(x_{3}, y_{3}\right)=-6310.8$, and $f_{4}=f\left(x_{4}, y_{4}\right)=-3731.7, \psi_{1}=\psi\left(x_{1}, y_{1}\right)=2.6024$, $\psi_{2}=\psi\left(x_{2}, y_{2}\right)=2.7325, \psi_{3}=\psi\left(x_{3}, y_{3}\right)=0$ and $\psi_{4}=\psi\left(x_{4}, y_{4}\right)=0$. Then the
pairwise matrix $M$ is:

$M=$|  | $f_{1}$ | $f_{2}$ | $f_{3}$ | $f_{4}$ |
| :---: | :---: | :---: | :---: | :---: |
| $f_{1}$ | 0.5 | 1 | 0 | 0 |
| $f_{2}$ | 0 | 0.5 | 0 | 0 |
| $f_{3}$ | 1 | 1 | 0.5 | 1 |
| $f_{4}$ | 1 | 1 | 0 | 0.5 |

To construct the vector $L S$ from matrix $M$, the lower triangular, main diagonal, third row and third column are deleted. So, $L S=\left(a_{12}, a_{14}, a_{24}\right)=(1,0,0)$. Given two landscape $L S_{f}=\left(l s_{f, 1}, l s_{f, 2}, \ldots, l s_{f,\left|L S_{f}\right|}\right)$ and $L S_{\text {ref }}=\left(l s_{r e f, 1}, l s_{r e f, 2}, \ldots\right.$, $\left.l s_{r e f,\left|L S_{r e f}\right|}\right)$, the difference value between the two given landscapes is computed using equation 4.3.

$$
\begin{equation*}
L D=\frac{1}{\left|L S_{f}\right|} \times \sum_{z=1}^{\left|L S_{f}\right|}\left|l s_{f, z}-l s_{r e f, z}\right| \tag{4.3}
\end{equation*}
$$

where $z=1,2, \ldots,\left|L S_{f}\right|$. When $L D$ is close to 0 or 1 , the problem is considered easy or difficult, respectively.

### 4.3.1.2 Modified FDC

In this section, a modified FDC is proposed to deal with COPs. As previously stated in chapter 2, FDC measures the correlation between objective function of $\vec{x}$ and its distance to its nearest best solution $\left(x^{o p t}\right)$. As this chapter deals with COPs, the $\left(x^{o p t}\right)$ is determined based on both the objective value and sum of constraint violations using the feasibility rule, that is between wo individuals $\vec{x}_{1}$ and $\vec{x}_{2}$, the fittest one is determined by:

1. if $\psi\left(\vec{x}_{1}\right)=\psi\left(\vec{x}_{2}\right)=0$ and $f\left(\vec{x}_{1}\right)<f\left(\vec{x}_{2}\right)$, then $\vec{x}_{1}$ is better;
2. if $\psi\left(\vec{x}_{1}\right)=0$ and $\psi\left(\vec{x}_{1}\right) \neq 0$, then $\vec{x}_{1}$ is better, or if $\psi\left(\vec{x}_{1}\right) \neq 0$ and $\psi\left(\vec{x}_{1}\right)=0$, then $\vec{x}_{2}$ is better; and
3. if $\psi\left(\vec{x}_{1}\right) \neq 0$ and $\psi\left(\vec{x}_{2}\right) \neq 0$ and $\psi\left(\vec{x}_{1}\right)<\psi\left(\vec{x}_{2}\right)$, then $\vec{x}_{1}$ is better.

### 4.3.2 MODE combined with modified landscape for COPs

In this section, details of the proposed modified landscape-based multi-operator DE (MLS-MODE) are discussed.

The general framework of the proposed algorithm is presented in Algorithm 4. It starts with a random initial population of size $N P$, generated using LHD. Then, each individual is evaluated, and the number of current fitness evaluations ( $F E S$ ) is updated. Subsequently, each DE operator generates the same number of individuals. At the end of each generation, the information landscape metric is calculated for each operator using Algorithm 3. After a predefined number of generations (CS), the best-performing DE operator is selected based on the normalized landscape value (NLD) (see Section 4.3.3.1), and then used to evolve the entire population for the subsequent $C S$ generations. Then, as the performance of one operator may be good at the later generations, all the DE operators are reused to evolve the current entire population. This process is continued until a pre-defined number of fitness evaluations $\left(F E s_{p r e}\right)$ is reached and then the bestperforming operator found so far is used to evolve the entire population until a stopping criterion is reached.

### 4.3.3 The selection phase

In this section, the selection phase, which uses the the modified landscape to select the best-performing operator, is described.

```
Algorithm 4 Proposed algorithm
    Counter \(\leftarrow 0\); Generate an initial population \((X)\) of size \(N P\) using Latin
    Hypercube Design; FES \(\leftarrow 0\);
    Calculate the fitness values of \(X\), and total constraint violation \(\psi\);
    \(F E S \leftarrow F E S+N P ;\)
    while \(F E S \leq M A X_{F E S}\) do
        \(C \leftarrow C+1 ;\)
        if \(F E S \leq F E s_{\text {pre }}\) then
            \(C \leftarrow C+1 ;\)
            if \(C<C S\) then
                Randomly assign each operator to ( \(\left[\frac{N P}{m}\right]\) ) solutions;
                Generate new population using the assigned operators.
                Calculate \(L D_{o p}\) by considering those individuals updated by operator
                \(o p\);
            end if
            if \(\bmod (C, C S==0)\) then
                Measure the normalized landscape value of every \(m\) using Equation 4.5;
                Determine the best-performing operator, i.e., the one with the maxi-
                mum value of \(O N_{L D_{o p}}\);
            end if
            if \(C>C S\) and \(C<2 C S\) then
                Evolve the current entire population using the best DE mutation strat-
                    egy;
            end if
            if \(C==2 C S\) then
                Counter \(\leftarrow 0\), reset \(m, L D_{o p}=[] ;\)
            end if
        else
            Evolve the population using the best DE operator;
        end if
        \(F E S \leftarrow F E S+N P ;\)
        Update \(N P\) using equation 3.1;
    end while
```


### 4.3.3.1 Normalized average Landscape measure

In this section, the overall normalized average landscape measure ( $O N_{L D_{\text {op }}}$ ) of each operator op is computed, by utilizing the MILNS measure (see Section 4.3.1.1).

The normalized value $N_{L D_{o p}}$ metrics of operator $o p$ is calculated using by:

$$
\begin{equation*}
N_{L D_{o p}}=\frac{1-M_{L D_{o p}}}{\sum_{O P=1}^{m}\left(1-M_{L D_{o p}}\right)} \tag{4.4}
\end{equation*}
$$

where $\{o p=1,2, \ldots, m\}, M_{L D}$ is the mean value of the landscape information measure.

Subsequently, the overall normalized performance $O N_{L D_{o p}}$ of operator op is computed by equation 4.5 :

$$
\begin{equation*}
O N_{L D_{o p}}=\frac{N_{L D_{o p}}}{\sum_{O P=1}^{m}\left(N_{L D_{o p}}\right)} \tag{4.5}
\end{equation*}
$$

### 4.3.4 Adaptation of $F$ and $C r$

As previously mentioned, a DE's performance depends on its search operators and control parameters. However, selecting them is not an easy task. Therefore, a self-adaptive mechanism is used in this chapter [67, 208].

A historical memory of length $H$ for both $F$ and $C r$ is used. The parameter values in this historical memory are denoted as $\mu_{F}$ and $\mu_{C r}$, and initially were set to 0.5. Each individual $\vec{x}_{z}$ is associated with its own $\left(F_{z}\right)$ and $\left(C r_{z}\right)$, and their values are created using the following equations:

$$
\begin{array}{r}
C r_{z}=\operatorname{randni}\left(\mu_{C r, r_{z}}, 0.1\right) \\
F_{z}=\operatorname{randci}\left(\mu_{F, r_{z}}, 0.1\right) \tag{4.7}
\end{array}
$$

where $r_{z}$ is randomly selected from $[1, H]$, randni and randci are randomly selected from normal and Cauchy distributions with mean $\mu_{C r, r_{z}}$ and $\mu_{F, r_{z}}$ respectively, with variance 0.1. A repair mechanism is used to handle any values of $C r_{z}$ and $F_{z}$, if their values are outside $[0,1]$. They are repaired as follows. If $C r_{z}$ is out of the
range, it is replaced by the limit value ( 0 or 1 ) closest to the generated value. If $F_{z}>1$, it is replaced by 1 , and if $F_{z} \leq 0$, equation 4.7 is repeatedly executed until a valid value is generated.

At the end of each generation, the $\left(C r_{z}\right)$ and $\left(F_{z}\right)$ used by the successful individuals are recorded in $S_{C r}$ and $S_{F}$, and then the contents of the historical memory are updated as follows:

$$
\begin{align*}
\mu_{C R, h, G+1} & =\left\{\begin{array}{cc}
\operatorname{meanw}_{L}\left(S_{C r}\right) & \text { if } S C R \neq \phi \\
\mu_{C R, h, G} & \text { otherwise }
\end{array}\right.  \tag{4.8}\\
\mu_{F, h, G+1} & =\left\{\begin{array}{cc}
\operatorname{meanw}_{L}\left(S_{F}\right) & \text { if } S F \neq \phi \\
\mu_{F, h, G} & \text { otherwise }
\end{array}\right. \tag{4.9}
\end{align*}
$$

$$
\begin{equation*}
\operatorname{meanw}_{L}(S F)=\frac{\sum_{h=1}^{|S F|} \omega_{h} \cdot S_{F_{h}}^{2}}{\sum_{h=1}^{|S F|} \omega_{h} \cdot S_{F_{h}}} \tag{4.10}
\end{equation*}
$$

where $\omega_{h}$ is the weight computed using:

$$
\begin{equation*}
\omega_{h}=\frac{\beta_{h}}{\sum_{h=1}^{\left|S_{C r}\right|} \beta_{h}} \tag{4.11}
\end{equation*}
$$

where $1 \leq h \leq H$ is the position of the memory to update. It is initialized with a value of 1 and is consequently incremented whenever a new element is inserted into the history. If $h>H, h$ is reset to 1 . The value of $\beta_{h}$ is computed, based on one of the following cases [208]:

1. Infeasible to infeasible: the best solution in the population is infeasible in both generations $G-1$ and $G$;
2. Infeasible to feasible: the best solution in the population is infeasible at generation $G-1$ and becomes feasible at $G$; and
3. Feasible to feasible: the best solution is feasible at both generations $G-1$ and $G$.

Firstly, for every successful solution $\left(h \in 1,2, \ldots,\left|S_{C r}\right|\right)^{2}$ which falls in case 1, its $\beta_{h}$ is computed as:

$$
\begin{equation*}
\beta_{h}=I_{h}=\max \left(0, \frac{\psi_{h, G-1}-\psi_{h, G}}{\psi_{h, G-1}}\right)+\max \left(0, \frac{f_{h, G-1}-f_{h, G}}{f_{h, G-1}}\right) \tag{4.12}
\end{equation*}
$$

Then, for every successful solution $\left(h \in 1,2, \ldots,\left|S_{C r}\right|\right)^{2}$ which exist in case 2 or 3 , its $\beta_{h}$ is calculated as:

$$
\begin{equation*}
\beta_{h}=\max \left(0, I_{h}\right)+\frac{\psi_{h, G-1}-\psi_{h, G}}{\psi_{h, G-1}}+\max \left(0, \frac{f_{h, G-1}-f_{h, G}}{f_{h, G-1}}\right) \tag{4.13}
\end{equation*}
$$

### 4.3.5 Constraints handling

In this method, the feasibility rule is used to select between any individual and its parent, as: 1) from two feasible solutions, the one with the lowest fitness value is selected; 2) from two infeasible solutions, the one with the smallest sum of constraint violation $(\psi)$ is chosen, where $\psi$ is calculated using Equation 4.14; and 3) a feasible solution as always better than infeasible one.

$$
\begin{equation*}
\psi\left(\vec{x}_{z}\right)=\sum_{k=1}^{s} \max \left(0, g_{k}\left(\vec{x}_{z}\right)\right)+\sum_{e=1}^{q} \max \left(0,\left|h_{e}\left(\vec{x}_{z}\right)\right|-\delta_{e}\right) \tag{4.14}
\end{equation*}
$$

where $g_{k}\left(\vec{x}_{z}\right)$ and $h_{e}\left(\vec{x}_{z}\right)$ are the $k^{\text {th }}$ inequality and $e^{t h}$ equality constraints, respectively. For every equality constraint $h_{e}, \delta_{e}$ is initialized with a large value and then reduced gradualy to 0.0001 , and its initial value is problem dependent [208-210].

### 4.4 Experimental Setup and Results

In this section, the performance of the proposed algorithm is tested by solving the set of benchmark problems presented in Section 4.2. For more comprehensive comparisons, each comparative algorithm was run 25 times for all the optimization functions to a maximum number of fitness function evaluations of 200000 for CEC2006, $20000 \times D$ for CEC2010 and 150000 for CEC2011, with the best, mean and standard deviation results recorded.

Considering parameters settings, the $C S$ parameter was set to $25, \varphi$ to 0.5 for $\mathrm{DE} / \varphi$ best $/ 1$ to maintain diversity, and 0.1 for all other variants, to speed up the convergence rate. The archive rate $(A)$ to 1.4 , the memory size $(H)$ to 5 , and $F E s_{p r e}$, which was the limit for running the multi-operator, to $\frac{1}{2} \times M A X_{F E S}$, after which the best-performing operator evolved the population until the end of the run. A linear population size reduction mechanism [67] is used as previously described in the previous chapter in which $N P^{\text {init }}$ set at a value of 180 and $N P^{\text {min }}$ was set at a value of 4 .

In the following sections, the effect of the parameters and each component of the proposed algorithm, is examined. After which,the comparison between the best variants of the proposed algorithm and the other state-of-the-art algorithms is conducted.

Table 4.3: Computational time and average FEs of different variants for adapting $F$ and $C r$

| Algorithms | Total average time | Total average FEs |
| :---: | :---: | :---: |
| V1 | 2.65 | 163861 |
| V2 | 1.93 | 123725 |
| V3 | $\mathbf{1 . 0 7}$ | $\mathbf{6 7 0 6 6}$ |

### 4.4.1 Parameter analysis

In this section, the effect of the following parameters: 1) the effect of different adaptation rates of $F$ and $C r ; 2$ ) the effect of cycle ( $C S$ ); 3) the effect of linear reduction; 4) the effect of the $N P^{i n i t}$ that are used as the maximum population size; 5) the effect of $N P^{\text {min }}$ that is the minimum population size; and 6) the effect of using landscape method in the selection method; on the performance of the proposed algorithm are examined.

### 4.4.1.1 Effect of Self-adaptation

In this section, to see the effect of the self-adaptation strategy used in this chapter, two variants of the proposed algorithm, with two different mutation and crossover rates, are considered. Their results are compared with those obtained from the proposed algorithm with the self-adaptive mechanism. V1 uses $F=$ 0.9 and $C r=0.1$, while V2 uses $F=0.5$ and $C r=0.5$ uses, and V3 uses the self-adaptive mechanism described in Section 4.3.4. The best, average and standard deviation results, obtained from 25 runs for each variant, are presented in Appendix B, Table B.1.

When comparing the computational time and FEs of the different variants, V3 which uses the self-adaptive approach, is the best. This is shown in Table 4.3.

Also, the performance profiles for both computational time and FEs are depicted in Figure 4.1. From these graphs, the variant with self-adaptation is the


Figure 4.1: Comparison of performance profiles of different variants for adapting $F$ and $C r$ (a) based on computational time; and (b) based on FEs
best, for both average computational time and average FEs.

Regarding the quality of solutions, Table 4.4 shows a comparison summary

Table 4.4: Comparison summary between different variants for adapting $F$ and Cr

| Variants | Best Results |  |  |  |  | Average results |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Better | Equal | Worse | Dec. | P-value | Better | Equal | Worse | Dec. | P-value |
| V3 vs. V1 | 13 | 8 | 1 | + | 0.005 | 15 | 6 | 1 | + | 0.003 |
| V3 vs. V2 | 10 | 11 | 1 | + | 0.049 | 11 | 10 | 1 | + | 0.001 |

Table 4.5: Computational time and average FEs of different $C S$ values

| Variants | Total average time | Total average FEs |
| :---: | :---: | :---: |
| $C S=25$ | 1.065 | 67066 |
| $C S=50$ | 1.109 | 68570 |
| $C S=75$ | 0.978 | 68407 |
| $C S=100$ | 0.996 | 66988 |
| $C S=125$ | $\mathbf{0 . 9 6 3}$ | $\mathbf{6 6 0 7 4}$ |
| $C S=150$ | 0.981 | 66469 |

between V3 and the other two variants (V1 and V2). From the results, the performance of V3 with self-adapting $F$ and $C r$ is better than the two other variants for both the best and average results obtained. In regards to the Wilcoxon test, V3 is statistically better than both V1 and V2 for the both best and average results.

### 4.4.1.2 Effect of CS

In this section, MLS-MODE is tested while using the self-adaptation of $F$ and $C r$, as it was better than both of the fixed values, but with different values of $C S$. $C S$ represents the number of generations at which MLS-MODE selects the best-performing operator. A number of experiments are conducted by using $C S=25,50,75,100,125$ and 150 generations, with detailed results presented in Appendix B, Tables B.2, B.3.

Table 4.5 presents the total average time and total average number of fitness evaluations. From the results, the variant with $C S=125$ is slightly better than all other variants in both average time and FEs. Also, the overall rank based on the Friedman test is presented in Table 4.6, from which it is clear, that the variant with $C S=125$ has the best rank, for both the best and average results.

Table 4.6: Ranks of different values for $C S$, based on Friedman rank test, based on both best and average results

| Variants | Average rank based on <br> best results obtained | Average rank based on <br> average results obtained |
| :---: | :---: | :---: |
| $C S=25$ | 3.52 | 3.48 |
| $C S=50$ | 3.61 | 3.70 |
| $C S=75$ | 3.48 | 3.61 |
| $C S=100$ | 3.57 | 3.48 |
| $C S=125$ | $\mathbf{3 . 3 9}$ | $\mathbf{3 . 2 5}$ |
| $C S=150$ | 3.43 | 3.48 |

Table 4.7: Computational time and average FEs of different $N P^{\text {init }}$ values

| Variants | Total average time | Total average FEs |
| :---: | :---: | :---: |
| $N P^{\text {init }}=50$ | 1.513 | 51912 |
| $N P^{\text {init }}=75$ | 1.068 | 57134 |
| $N P^{\text {init }}=100$ | 0.977 | 55279 |
| $N P^{\text {init }}=125$ | 0.942 | 61032 |
| $N P^{\text {init }}=150$ | $\mathbf{0 . 9 1 3}$ | $\mathbf{5 0 4 7 5}$ |
| $N P^{\text {init }^{\text {in }}=200}$ | 0.963 | 68297 |

### 4.4.1.3 Effect of $N P^{\text {init }}$

To see the effect of the initial population size $N P^{i n i t}$, different experiments with $N P^{\text {init }}=50,75,100,125,150$ and 200 were conducted. The detailed results are presented in the Appendix B, Tables B.4, B.5. The total average time and FEs are presented in Tables 4.7, from which it is clear that the variant with $N P=150 \mathrm{D}$ is slightly better. This is proofed by the performance profiles graphs depicted in Figure 4.2, from which it is clear that the variant with $N P^{\text {init }}=150$ is the best for both average computational time and FEs.

Regarding the quality of solutions, Table 4.8 shows the summary of the obtained results, based on the average results. It is clear that $N P=150 D$ was better than all of the other variants. Regarding the Wilcoxon test, there is no significant difference between the variants. However, there is a bias towards the variant of $N P=150 D$.


Figure 4.2: Comparison of performance profiles of proposed algorithm with different values of $N P^{\text {init }}$ different variants for adapting $F$ and $C r$ (a) based on computational time; and (b) based on FEs

### 4.4.1.4 Effect of $N P^{\text {min }}$

For this analysis, the proposed algorithm was run with different $N P^{\text {min }}$ values, such that $N P^{\text {min }}=4,10,20,30,40$ and 50 individuals. The detailed results are

Table 4.8: Comparison summary between different variants of the proposed algorithm with different $N P^{\text {init }}$ values

| Variants | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: |
| $N P^{\text {init }}=150$ vs. $N P^{\text {init }}=50$ | 5 | 16 | 1 | $\approx$ |
| $N P^{\text {init }}=150$ vs. $N P^{\text {init }}=75$ | 4 | 17 | 1 | $\approx$ |
| $N P^{\text {init }}=150$ vs. $N P^{\text {init }}=100$ | 4 | 17 | 1 | $\approx$ |
| $N P^{\text {init }}=150$ vs. $N P^{\text {init }}=125$ | 4 | 17 | 1 | $\approx$ |
| $N P^{\text {init }}=150$ vs. $N P^{\text {init }}=200$ | 3 | 17 | 2 | $\approx$ |

Table 4.9: Computational time and average FEs of different $N P^{\text {min }}$ values

| Variants | Total average time | Total average FE |
| :---: | :---: | :---: |
| $N P^{\text {min }}=4$ | 1.038 | $\mathbf{5 5 5 1 5}$ |
| $N P^{\text {min }}=10$ | 1.176 | 57173 |
| $N P^{\text {min }}=20$ | 0.961 | 56496 |
| $N P^{\text {min }}=30$ | 0.936 | 57678 |
| $N P^{\text {min }}=40$ | $\mathbf{0 . 8 8 0}$ | 56384 |
| $N P^{\text {min }}=50$ | 0.935 | 57240 |

Table 4.10: Average ranks of proposed algorithm with different $N P^{\text {min }}$ values

| Variants | Mean rank |
| :---: | :---: |
| $N P^{\text {min }}=4$ | 3.73 |
| $N P^{\text {min }}=10$ | 3.77 |
| $N P^{\text {min }}=20$ | 3.73 |
| $N P^{\text {min }}=30$ | 3.32 |
| $N P^{\text {min }}=40$ | $\mathbf{3 . 0 7}$ |
| $N P^{\text {min }}=50$ | 3.39 |

shown in Appendix B, Tables B.6, B.7. The average total computational time and FEs is presented in Table 4.9, which shows that the variant with $N P^{\text {min }}=40$ requires the least average computational time, and the second least in average FEs.

A Friedman test was carried out to rank all the variants. From the results shown in Table 4.10, it was found that the variant with $N P^{\min }=40$ was ranked first, while the one with $N P^{\text {min }}=30$ and $N P^{\text {min }}=50$ came second and third, respectively.

Table 4.11: Comparison summary between different variants of the proposed algorithm with different $N P^{\text {min }}$ values

| Variants | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: |
| $N P^{\text {min }}=40$ vs. $N P^{\text {min }}=4$ | $\mathbf{5}$ | $\mathbf{1 7}$ | $\mathbf{0}$ | + |
| $N P^{\text {min }}=40$ vs. $N P^{\text {min }}=10$ | $\mathbf{5}$ | $\mathbf{1 7}$ | $\mathbf{0}$ | + |
| $N P^{\text {min }}=40$ vs. $N P^{\text {min }}=20$ | 4 | 17 | 1 | $\approx$ |
| $N P^{\text {min }}=40$ vs. $N P^{\text {min }}=30$ | 4 | 17 | 1 | $\approx$ |
| $N P^{\text {min }}=40$ vs. $N P^{\text {min }}=50$ | 4 | 17 | 1 | $\approx$ |

As a further step in comparison, a Wilcoxon test was carried out with the summary of its results are presented in Table 4.11. It is clear that, $N P^{\min }=40$ is significantly better than $N P^{\text {min }}=4$ and $N P^{\text {min }}=10$, while there is no significant difference with the others.

### 4.4.1.5 Comparing MLS-MODE with different selection mechanisms

In this section, the effect of the modified landscape method in the selection mechanism is analyzed. To do this, a comparison of MLS-MODE is compared with 4 of its variants (Q-MODE, D-MODE, QD-MODE and MFDC-MODE), in each of which only the selection mechanisms were different, and below is a description of the selection mechanism in every variant:

- In D-MODE, population diversity is used to select the best-performing DE operator, as:

$$
\begin{equation*}
D_{o p, G}=\frac{\sum_{i=1}^{N P_{o p}} \operatorname{dis}\left(\overrightarrow{x^{o p}}{ }_{i}, \overrightarrow{x p}_{b}\right)}{N P_{o p}}, \forall o p=1,2, \ldots, m \tag{4.15}
\end{equation*}
$$

where $\operatorname{dis}\left({\overrightarrow{x^{o p}}}_{i},{\overrightarrow{x^{0 p}}}_{b}\right)$ is the distance between the $i^{\text {th }}$ individual and the best individual generated by operator $o p, N P_{o p}$ is the number of individuals evolved by operator op, $\vec{x}_{b}$ the best solution in the individuals evolved by operators $o p$, and $m$ is the number of operators.

Table 4.12: Ranks of 5 different variants, based on Friedman rank test

| Algorithm | Mean rank | Order |
| :---: | :---: | :---: |
| MLS-MODE | $\mathbf{2 . 5 9}$ | $\mathbf{1}$ |
| D-MODE | 3.29 | 5 |
| Q-MODE | 3.07 | 3 |
| QD-MODE | 3.09 | 4 |
| MFDC-MODE | 2.96 | 2 |

- In Q-MODE, the selection mechanism is based on the improvement rates in objective function values [163], as:

$$
\begin{equation*}
Q_{o p, G}=\frac{\sum_{z=1}^{N P_{o p}} \max \left(0, f_{G+1, z}-f_{G, z}\right)}{\sum_{z=1, o p}^{N P_{o p}} f_{G, z}}, \forall o p=1,2, \ldots, m \tag{4.16}
\end{equation*}
$$

where $f_{G+1, z}$ and $f_{G, z}$ are the new and old objective FVs, respectively.

- QD-MODE: the selection mechanism is based on both the population diversity and the quality of solutions, as:

$$
\begin{equation*}
Q D_{o p, G}=D_{o p, G}+Q_{o p, G} \tag{4.17}
\end{equation*}
$$

- MFDC-MODE: the selection mechanism is based on the modified FDC, as previously described in section 4.3.1.2.

The detailed results obtained from these five variants are presented in Appendix B, Tables B.8, B.9, B.10, B.11, B.12.

A Friedman's ranks test was carried out to rank all the variants for all problems in CEC2006 and CEC2011. From the results shown in Table 4.12, it was found that MLS-MODE was ranked first, while MFDC-MODE came second.

Table 4.13: Comparison summary between MLS-MODE, D-MODE, Q-MODE, QD-MODE and MFDC-MODE

| Variants | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: |
| MLS-MODE vs. D-MODE | $\mathbf{1 1}$ | $\mathbf{1 7}$ | $\mathbf{4}$ | $\approx$ |
| MLS-MODE vs. Q-MODE | $\mathbf{1 1}$ | $\mathbf{1 5}$ | $\mathbf{6}$ | $\approx$ |
| MLS-MODE vs. QD-MODE | 12 | 16 | 4 | $\approx$ |
| MLS-MODE vs. MFDC-MODE | 10 | 16 | 6 | $\approx$ |

Table 4.14: Comparison among MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE based on the average computational time and FEs

| Variants | Total average time | Total average FE |
| :---: | :---: | :---: |
| MLS-MODE | $\mathbf{0 . 9 9 9}$ | $\mathbf{5 3 3 7 7}$ |
| Q-MODE | 1.519 | 76420 |
| D-MODE | 1.530 | 79659 |
| QD-MODE | 3.200 | 65906 |
| MFDC-MODE | 1.209 | 70939 |

A comparison summary between MLS-MODE and the other four variants is presented in Table 4.13. MLS-MODE is better than D-MODE, Q-MODE, QDMODE and MFDC-MODE for 11, 11, 12, and 10 test problems respectively, while MLS-MODE is inferior to D-MODE, Q-MODE, QD-MODE and MFDC-MODE in $4,6,4$ and 6 test problems respectively.

In addition to judging the quality of solution, the average computational time and the number of fitness evaluations required to reach the optimal solution with an error of 0.0001 , i.e., the stopping condition is $\left(f(x)-f\left(x^{*}\right) \leq 0.0001\right)$, where FEs $f\left(x^{*}\right)$ is the best known solution. Table 4.14 shows the comparison. From this table, it is clear that MLS-MODE saves computational time by $34 \%, 35 \%, 69 \%$ and $17 \%$ in comparison to Q-MODE, D-MODE, QD-MODE and MFDC-MODE, respectively. Regarding FEs, MLS-MODE saves it by $30 \%, 33 \%, 19 \%$ and $24 \%$ in comparison to Q-MODE, D-MODE, QD-MODE and MFDC-MODE, respectively.

Further more, performance profiles for both computational time and FEs are depicted in Figure 4.3. From these figures, the proposed MLS-MODE is the best,


Figure 4.3: Performance profiles comparing MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE, based on (a) the average computational time and (b) the average number of FEs.
for both computational time and FEs.

### 4.4.2 Comparisons with state-of-the-art algorithms

From the above-mentioned analyzes, it was found that, MLS-MODE with $C S=125, N P^{\text {init }}=150$ and $N P^{\text {min }}=40$ is the best variant. So, this variant will be compared to the state-of-the-art algorithms by solving the benchmark problems previously described in Section 4.1.

### 4.4.2.1 Comparison to the state-of-the-art algorithms for CEC2006

In this section, to verify the performance of the proposed (MLS-MODE) algorithm, comparisons are carried out with: an adaptive hybrid DE algorithm (AHDEa) [211], a self-adaptive multi-operator genetic algorithm (SAMO-GA) [24], a self-adaptive algorithm with multi-operator strategy (SAMO-DE) [24], an improved version of SAMO-DE (ISAMODE-CMA) [47], the adaptive penalty formulation with GA (APF-GA) [130], an evolutionary programming based on ensemble of constraint-handling techniques ECHT-EP2 [146], a DE based on ensemble of constraint-handling techniques ECHT-DE [146], a rank based multi-operator DE algorithm (rank-iMDDE) [212], $\epsilon \mathrm{DEg}$ with Gradient-Based Mutation $\epsilon \mathrm{DE}[141]$ and an artificial immune system based approach for COPs (AIS-ZYH) [213], which they were used in solving CEC2006 test problems. The detailed results of MLSMODE, based on 200000 FEs, along with those obtained from the state-of-the-art algorithms are presented in Appendix B, Tables B.13, B.14, B.15, B.16, B.17, B.18. The table shows the mean and standard deviation (Std.) results obtained from 25 runs.

It must be mention here that MLS-MODE used 200000 fitness evaluations (FEs), while ISAMODE-CMA, SAMO-DE, ECHT-EP2, ECHT-DE, SAMO-GA, rank-iMDDE, AH-DEa used 240000 FEs, and APF-GA, MDE, and $\epsilon$ DEg used 500000 FEs. It should mentioned here that all algorithms solved 22 out 24 test

Table 4.15: Summary of comparisons of the proposed MLS-MODE against AH-DEa, SAMO-GA, SAMO-DE, AIS-ZHY, ECHT-EP2, ECHT-DE, APF-GA, ISAMODE-CMA, $\epsilon$ DEg, and rank-iMDDE based on the average results, where
'Dec.' statistical decision is based on Wilcoxon signed-rank test results

| Algorithms | Better | Equal | Worse | Dec. $\alpha=0.05$ | Dec. $\alpha=0.10$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MLS-MODE vs. AH-DEa | 7 | 15 | 0 | + | + |
| MLS-MODE vs. SAMO-GA | 11 | 9 | 2 | + | + |
| MLS-MODE vs. SAMO-DE | 8 | 14 | 0 | + | + |
| MLS-MODE vs. AIS-ZHY | 6 | 16 | 0 | + | + |
| MLS-MODE vs. ECHT-EP2 | 6 | 16 | 0 | + | + |
| MLS-MODE vs. ECHT-DE | 6 | 16 | 0 | + | + |
| MLS-MODE vs. APF-GA | 10 | 11 | 1 | $\approx$ | + |
| MLS-MODE vs. ISAMODE-CMA | 2 | 20 | 0 | $\approx$ | $\approx$ |
| MLS-MODE vs. $\epsilon$ DEg | 1 | 21 | 0 | $\approx$ | $\approx$ |
| MLS-MODE vs. rank-iMDDE | 3 | 19 | 0 | $\approx$ | $\approx$ |

problems. Thus, the analysis is based on 22 test problems. The proposed MLSMODE algorithm is able to obtain the optimal solutions for all test problems, with feasibility and success rates equal to $100 \%$.

Table 4.15 presents a summary of the comparison between MLS-MODE and the state-of-the-art algorithms. MLS-MODE is better than AH-DEa, SAMO-GA, SAMO-DE, AIS-ZHY, ECHT-EP2, APF-GA, ECHT-DE, ISAMODE-CMA, $\epsilon$ DE, and rank-iMDDE for $7,11,8,6,6,10,6,2,1$ and 3 test problems, respectively, while MLS-MODE is inferior to SAMO-GA and APF-GA in 2 and 1 test problems, respectively. Regarding the Wilcoxon test results, MLS-MODE was significantly better than AH-DEa, SAMO-GA, SAMO-DE, AIS-ZHY, ECHT-EP2, ECHT-DE, and APF-GA. Although there is no significant difference between MLS-MODE and ISAMODE-CMA, $\epsilon$ DEg and rank-iMDDE, there is a bias towards MLS-MODE in the number of better functions. One advantage of MLS-MODE, is its ability to reach optimal solution faster than ISAMODE-CMA, $\epsilon \mathrm{DEg}$ and rank-iMDDE. In summary, the average number of FEs that are consumed by MLS-MODE are 53377, while ISAMODE-CMA, $\epsilon$ DEg and rank-iMDDE consumed 76420, 79659, and 65,906 FEs respectively, which means that MLS-MODE is able to save $30.15 \%$,

Table 4.16: Average ranking of MLS-MODE, EHCT-DE, AIS-ZHY,ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE by the Friedman test for the 22 functions in terms of mean value

| Algorithm | Mean rank |
| :---: | :---: |
| MLS-MODE | $\mathbf{4 . 7 0}$ |
| EHCT-DE | 6.45 |
| AIS-ZHY | 5.84 |
| ISMOADE-CMA | 5.14 |
| SAMO-DE | 6.59 |
| ECHT-EP2 | 5.80 |
| $\epsilon$ DEg | 7.75 |
| AH-DEa | 6.55 |
| SAMO-GA | 7.86 |
| APF-GA | 7.07 |
| rank-iMDDE | 5.25 |

$32.99 \%$, and $19.01 \%$ of FEs in comparison to ISAMODE-CMA, $\epsilon \mathrm{DEg}$ and rankiMDDE, respectively.

Furthermore, a Friedman test was used to rank all the algorithms according to the mean results obtained, with the mean rank presented in Table 4.16 and Figure 4.4. From Table 4.16, MLS-MODE gets the first rank among the 11 algorithms on 22 test functions.

### 4.4.2.2 Comparison to the state-of-the-art algorithms for CEC2010

In this section, the proposed MLS-MODE is tested by solving CEC2010 [186] constrained optimization competition. MLS-MODE is compared with the state-of-the-art algorithms: constrained DE with an archive and gradient-based mutation ( $\epsilon \mathrm{DEag}$ ) [214], which won the CEC2010 COP competition, self-adaptive multioperator DE (SAMODE) [39], DE combined with DE-DBmax (DE-DBmax) [215], co-evolutionary comprehensive learning particle swarm optimizer (Co-CLPSO) [216], adaptive ranking mutation operator-based DE (ECHT-ARMOR-DE) [179], elitist artificial bee colony (eABC) [217], multi-operator GA (SAMO-GA) [39]


Figure 4.4: Average ranking of MLS-MODE, EHCT-DE, AIS-ZHY,ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE by the Friedman test for the 22 functions in terms of mean value
and constraint-consensus mutation based DE (DEbavCC) [218]. Detailed results obtained from MLS-MODE and the state-of-the-art algorithms are presented in Appendix B, Tables B.19, B.20, B.21, B.22, B.23, B. 24 .

MLS-MODE, SAMODE, DEbavDBmax and DE-DBmax were able to achieve a $100 \%$ feasibility rate for the $10-\mathrm{D}$ and $30-\mathrm{D}$ test functions, while $\epsilon \mathrm{DEag}$ attained $100 \%$ feasibility ratio for only 35 out of 36 test instances, while it only obtained a $12 \%$ feasibility ratio for C12 with 30-D. Co-CLPSO was able to obtain a $94.4 \%$ feasibility ratio for the $10-\mathrm{D}$ and $87.3 \%$ for the $30-\mathrm{D}$ test problems, and the other algorithms were also not able to achieve the $100 \%$ feasibility rate

Table 4.17 shows the summary of the quality of solutions obtained. From


Figure 4.5: Convergence graph for (a) g02, g03 and g05, (b) g06, g07 and g09, (c) g10, g12 and g14 and (d) g19, g21 and g23.
this table, it is clear that MLS-MODE was able to obtain better results for many problems of both $10 D$ and $30 D$ test problems.

Based on the Wilcoxon test results, for 10D test problems, MLS-MODE is significantly better than DEbavDBmax, DE-DBmax, eABC, Co-CLPSO and SAMOGA for the average results obtained, and better than eABC and Co-CLPSO for the best results obtained. Based on 30D test problems, MLS-MODE was found to be significantly better than all the algorithms for the best results obtained,

Table 4.17: Summary of comparison of MLS-MODE and state-of-the-art algorithms CEC2010

|  | Algorithms | Criteria | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10D | MLS-MODE vs. DEbavDBmax | Best | 3 | 12 | 3 | $\approx$ |
|  |  | Average | 13 | 5 | 0 | + |
|  | MLS-MODE vs. SAMODE | Best | 2 | 12 | 4 | $\approx$ |
|  |  | Average | 12 | 2 | 4 | $\approx$ |
|  | MLS-MODE vs. $\epsilon$ DEag | Best | 5 | 10 | 3 | $\approx$ |
|  |  | Average | 8 | 6 | 4 | $\approx$ |
|  | MLS-MODE vs. DE-DBmax | Best | 5 | 10 | 3 | $\approx$ |
|  |  | Average | 16 | 2 | 0 | + |
|  | MLS-MODE vs. eABC | Best | 16 | 1 | 1 | + |
|  |  | Average | 17 | 0 | 1 | + |
|  | MLS-MODE vs. Co-CLPSO | Best | 14 | 3 | 1 | + |
|  |  | Average | 16 | 0 | 2 | + |
|  | MLS-MODE vs. SAMO-GA | Best | 10 | 5 | 3 | $\approx$ |
|  |  | Average | 14 | 0 | 4 | + |
|  | MLS-MODE vs. ECHT-ARMOR-DE | Best | 6 | 10 | 2 | $\approx$ |
|  |  | Average | 8 | 5 | 5 | $\approx$ |
| 30D | MLS-MODE vs. DEbavDBmax | Best | 7 | 9 | 2 | $\approx$ |
|  |  | Average | 11 | 3 | 4 | $\approx$ |
|  | MLS-MODE vs. SAMODE | Best | 13 | 2 | 3 | + |
|  |  | Average | 12 | 1 | 5 | $\approx$ |
|  | MLS-MODE vs. $\epsilon$ DEag | Best | 15 | 1 | 2 | + |
|  |  | Average | 15 | 0 | 3 | + |
|  | MLS-MODE vs. DE-DBmax | Best | 8 | 8 | 2 | $\approx$ |
|  |  | Average | 11 | 3 | 4 | $\approx$ |
|  | MLS-MODE vs. eABC | Best | 16 | 0 | 2 | + |
|  |  | Average | 17 | 0 | 1 | + |
|  | MLS-MODE vs. Co-CLPSO | Best | 15 | 1 | 2 | + |
|  |  | Average | 16 | 0 | 2 | + |
|  | MLS-MODE vs. SAMO-GA | Best | 13 | 1 | 4 | + |
|  |  | Average | 13 | 0 | 5 | + |
|  | MLS-MODE vs. ECHT-ARMOR-DE | Best | 11 | 4 | 3 | + |
|  |  | Average | 14 | 1 | 3 | + |

except DEbavDBmax and DE-DBmax which were statistically similar. Regarding the average fitness values, MLS-MODE was statistically better than $\epsilon$ DEag, eABC, Co-CLPSO, SAMO-GA and ECHT-ARMOR-DE, and statistically similar to DEbavDBmax, SAMODE, and DE-DBmax.

Furthermore, a Friedman test was conducted to rank all algorithms based on the best and average results. Table 4.18 and Figure 4.6 shows the results, from which it is clear that MLS-MODE is ranked first for 10D and 30D.

Table 4.18: Average Ranking achieved by Friedman test for CEC2010

|  |  | Average rank based on best results obtained | Average rank based on average results obtained | Over all rank |
| :---: | :---: | :---: | :---: | :---: |
| 10D | MLS-MODE | 3.86 | 2.67 | 3.27 |
|  | DEbavDBmax | 3.81 | 4.39 | 4.10 |
|  | SAMODE | 3.47 | 4.11 | 3.79 |
|  | $\epsilon$ DEag | 4.22 | 4.00 | 4.11 |
|  | DE-DBmax | 4.31 | 5.47 | 4.89 |
|  | eABC | 8.36 | 8.42 | 8.39 |
|  | Co-CLPSO | 6.81 | 6.78 | 6.80 |
|  | SAMO-GA | 5.47 | 5.33 | 5.40 |
|  | ECHT-ARMOR-DE | 4.69 | 3.83 | 4.26 |
| 30D | MLS-MODE | 2.83 | 2.72 | 2.78 |
|  | DEbavDBmax | 2.97 | 2.94 | 2.96 |
|  | SAMODE | 4.47 | 3.81 | 4.14 |
|  | $\epsilon$ DEag | 6.81 | 5.47 | 6.14 |
|  | DE-DBmax | 3.11 | 3.67 | 3.39 |
|  | eABC | 7.94 | 8.39 | 8.17 |
|  | Co-CLPSO | 6.89 | 7.08 | 6.99 |
|  | SAMO-GA | 5.50 | 5.00 | 5.25 |
|  | ECHT-ARMOR-DE | 4.47 | 5.92 | 5.20 |

### 4.4.2.3 Comparison to the state-of-the-art algorithms for CEC2011

In this section the proposed MLS-MODE is judged by solving 10 real-world application problems taken from the CEC2011 [181] competition on real-world optimization problems.

The performance of the proposed MLS-MODE is compared with the state-of-the-art algorithms, known as: continuous DE ant-stigmergy algorithm (CDASA) [219], an adaptive DE algorithm (ADE) [220], ensemble DE algorithm (EPSDE) [221], SAMODE [23], DE with adaptive crossover rate (DE-Acr) and a competitive DE with local search [222], (CDELS) [223], with their detailed results are presented in Appendix B, Tables B.25, B.26. All these algorithm solve these test problems as unconstrained optimization problems, and there is no information about whether the optimal solution obtained is feasible or not.

In order to compare the performance of the proposed MLS-MODE with the state-of-the-art algorithms, a Friedman test is conducted. Table 4.19 and Figure

(a)

(b)

Figure 4.6: Average Ranking achieved by Friedman test for CEC2010 (a) 10D and (b) 30D.
4.7 shows the average ranking of the seven algorithms. The highest ranking is shown in boldface. As seen, MLS-MODE and DE-Acr obtained the best ranking.

Table 4.19: Average Ranking achieved by Friedman test for CEC2011

| Algorithm | Mean rank |
| :---: | :---: |
| MLS-MODE | $\mathbf{2 . 2 0}$ |
| ADE | 4.40 |
| EPSDE | 3.70 |
| SAMODE | 3.10 |
| DE-Acr | $\mathbf{2 . 2 0}$ |
| CDELS | 6.20 |
| CDASA | 6.20 |



Figure 4.7: Average ranking of MLS-MODE against ADE, EPSDE, SAMODE, DE-ACr, CDELS and CDASA, by the Friedman test for the 10 functions in terms of mean value

Table 4.20: Comparison summary of MLS-MODE against ADE, EPSDE, SAMODE, DE-ACr, CDELS and CDASA for CEC2011

| Algorithm | Better | Equal | Worse | $p$-value | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MLS-MODE vs. ADE | 8 | 0 | 2 | 0.037 | + |
| MLS-MODE vs. EPSDE | 8 | 0 | 2 | 0.017 | + |
| MLS-MODE vs. SAMODE | 7 | 0 | 3 | 0.203 | $\approx$ |
| MLS-MODE vs. DE-Acr | 5 | 0 | 5 | 0.575 | $\approx$ |
| MLS-MODE vs. CDELS | 10 | 0 | 0 | 0.05 | + |
| MLS-MODE vs. CDASA | 10 | 0 | 0 | 0.05 | + |

Regarding the quality of solutions, a summary has been reported in Table 4.20. MLS-MODE was better than ADE, EPSDE, SAMODE, DE-ACr, CDELS and CDASA for $8,8,7,5,10$ and 10 test problems, respectively, While ADE, EPSDE, SAMODE, DE-ACr, CDELS and CDASA are better than MLS-MODE in $2,2,3,5,0$, and 0 test problems, respectively. Based on the Wilcoxon test, it was found that MLS-MODE is significantly better than ADE, EPSDE, CDELS and CDASA, while there is no significance difference with SAMODE and DE-Acr.

### 4.5 Chapter Summary

Motivated by the promising results obtained from LSAOS-DE in Chapter 3, for solving unconstrained optimization problems, in this chapter, a modified landscape method, called MLS-MODE, is proposed, and is used in an AOS to put more weight to the best-performing DE mutation strategy. MLS-MODE is used to solve constrained optimization problems.

MLS-MODE was tested by solving 22 test problems taken from CEC2006, 36 test problems taken from CEC2010, and 10 test problems taken from CEC2011. MLS-MODE was compared to four of its variants, which all share the same structure with the only difference being in the selection mechanism. The impact of MLS-MODE was significant, as it also consumed $34.0 \%, 35.0 \%, 69.0 \%$ and $17.0 \%$ less computational time than Q-MODE, D-MODE, QD-MODE and

MFDC-MODE, respectively, and regarding to the number of fitness evaluation, MLS-MODE consumed $30.0 \%, 33.0 \%, 19.0 \%$ and $25.0 \%$ less than Q-MODE, DMODE, QD-MODE and MFDC-MODE, respectively.

The results from MLS-MODE were then compared with those from state-of-the-art algorithms, and based on the quality of solutions obtained and nonparametric statistical testing, the results showed the superiority of MLS-MODE.

In solving COPs some constraints, known as active constraints, are more important than others. As of the optimization literature, the optimal solution often lies at the intersection of active constraints. This has served as motivation to develop a mechanism that may efficiently be able to to find that intersection, or a nearer point, as will be discussed in Chapter 5.

## Chapter 5

## Reduced Search Space Mechanism for Constrained Problems

In this chapter, a reduced search space mechanism with an active constraint determination procedure is combined with several state-of-the-art algorithms to solve constrained optimization problems (COPs). The experimental results from, and analysis of, the proposed method are presented and discussed by solving benchmark problems. Finally, detailed results obtained from the proposed algorithms and comparisons with those from state-of-the-art algorithms are presented.

### 5.1 Introduction

In solving COPs, some constraints are more important than others, they are known as active constraints. As of the optimization literature [35-37, 195], the optimal solution often lies at the intersection of active constraints. So the purpose of the search process can be find that intersection, or a nearer point. If the active constraints are known in some way, finding the optimal solution will almost always be easier.

The aim of this chapter is to identify promising reduced search space for COPs. To achieve this objective, new mechanism has been proposed, which identifies the

[^1]promising boundary region, based on an analysis of the individuals in the current population. To do that, a mechanism for automatically identifying the active constraints, based on the current solutions, is proposed. After that, using the information of the active constraints, the promising boundary zone for searching is determined. However, for effective searching using DE, this approach incorporates small regions from both feasible and infeasible spaces around the identified boundary region. As a simple example, suppose the promising boundary is a ring (circle) in a two dimensional search space. Then a smaller and a bigger ring are created for search space, that is the area between the smaller and bigger rings. The distance between the two rings can be varied depending on the nature of the problems and the stage of the evolution process. Note that the promising boundary can also be a part of the ring (an arc) in which the reduced search space (R2S) is created by joining the inner and outer arcs.

In order to evaluate the performance of the proposed R2S mechanism, it is incorporated with a number of state-of-the-art algorithms. The mechanism was tested by solving a set of COPs, 24 from CEC2006 [207], 36 from CEC2010 [186] (18 with $10 D$ and 18 with $30 D$ ) and 10 from CEC2011 [181] defined in the previous chapter. Also, several experiments have been designed and carried out to analyze the effects of different parameters on the performance of the proposed algorithm. Moreover, the proposed algorithm is also able to handle the case where the optimal solution lies well inside the feasible region, by using the whole search space. The proposed concept can also easily be applied with other evolutionary search algorithms. This chapter also uses the same test problems as Chapter 4 ( Section 4.2).

The chapter is organized as follows: Section 5.2 discusses the proposed framework; the simulation results for the benchmark problems are provided in Section
5.3; and finally, section 5.4 presents the chapter summary.

### 5.2 Proposed Algorithm

In this section, the proposed active constraints determination (ACD) and R2S mechanisms are described. Then, the general framework of the proposed algorithm that combines R2S with the basic DE algorithm, is discussed.

### 5.2.1 Active constraint determination (ACD) mechanism

As previously mentioned, some constraints are active at the optimum points in many real-world COPs. According to the definition, at any point $\vec{x}$, the constraints $g_{k}(\vec{x})$ that satisfy $g_{k}(\vec{x})=0$ are considered active at $\vec{x}$, as equality constraints are active for all points of decision space. Note that if $\vec{x}$ is feasible and at least one of the constraints is active at $\vec{x}$, then $\vec{x}$ lies on the boundary between the feasible and infeasible regions of the search space. Algorithm 5 describes the main steps of the ACD mechanism, in which a predefined number of fitness evaluations ( $F E S_{A C D}$ ) is spent in every $C S$ (which is the number of generation for evaluating whether or not constraints are active) generations, to check if the value of $g_{k}(\vec{x}) \leq$ Val for a randomly chosen individual from the $m$ best individuals. In such a case, $g_{k}(\vec{x})$ is an active constraint, otherwise it is not.

```
Algorithm 5 ACD mechanism
    Input: iter, cfe, \(F E S_{A C D}, g_{j}\) is the constraint values of individual \(j\);
    if \(\bmod (\) iter,\(C S==0)\) AND \(c f e \leq F E S_{A C D}\) then
        if \(g_{j} \leq V a l\) then
            constraint \(j\) is an active constraint.
        else
            constraint \(j\) is not an active constraint.
        end if
    end if
```


### 5.2.2 R2S

As of the literature, equality constraints are always converted to inequality ones using

$$
\begin{equation*}
g_{k}(\vec{x})=\left|h_{k}(\vec{x})\right|-\Delta \leq 0, \text { for } k=s+1, \ldots, q \tag{5.1}
\end{equation*}
$$

where $\Delta$ is a small positive tolerance parameter for relaxing the equality constraints. Therefore, the degree of constraint violation of solution $\vec{x}$ on the $j^{\text {th }}$ constraint can be calculated by

$$
\begin{equation*}
G_{k}(\vec{x})=\max \left\{0, g_{k}(\vec{x})\right\}, k=1, \ldots, q \tag{5.2}
\end{equation*}
$$

Then $\psi(\vec{x})=\sum_{k=1}^{q} G_{k}(\vec{x})$ is the total degree of constraint violation of solution $x$.

For each individual active constraint, the width or thickness of the boundary area is given by

$$
\begin{equation*}
-\delta_{\text {in }} \leq g_{k}(\vec{x}) \leq \delta_{\text {out }} \tag{5.3}
\end{equation*}
$$

where $g_{k}(\vec{x})$ is the $k^{\text {th }}$ constraint, $\delta_{\text {in }}$ and $\delta_{\text {out }}$ are the inner-delta and outer-delta values, respectively.

Equation (5.3) is used to define the new search space, R2S, that is smaller than the search space defined by the variable bounds, and is also different from the feasible space.
$\delta_{\text {out }}$ is used to include the infeasible regions around the selected boundary. For a problem when its number of feasible solutions is less than $0.2 * N P$ individuals, the initial $\delta_{\text {out }}$ value $\delta_{\text {out }}(0)$ is set to the total constraint violation $(\psi)$ of the top
$0.2 * N P$ individuals in the population, and for other problems, to 1 . The $\delta_{\text {out }}$ value is updated when the number of $c f e$ is less than $F E S_{c}$, after which it is set to zero to obtain solutions with minimum constraint violations, as:

$$
\delta_{\text {out }}(t)= \begin{cases}\delta_{\text {out }}(0) \times\left(1-\left(\frac{c f e}{F E S_{c}}\right)\right)^{z} & 0<c f e \leq F E S_{c}  \tag{5.4}\\ 0 & c f e>F E S_{c}\end{cases}
$$

The $\delta_{\text {out }}$ value is controlled by parameter z, the value of which is updated using

$$
\begin{equation*}
z=\frac{-5-\ln \left(\delta_{\text {out }}(0)\right)}{\ln (0.05)} \tag{5.5}
\end{equation*}
$$

To avoid a too-small value, a predefined value of $z_{\text {min }}=3$ is assigned and is then controlled as

$$
\begin{equation*}
z=0.3 \times z+0.7 \times z_{\text {min }} \tag{5.6}
\end{equation*}
$$

$\delta_{i n}$ is used to reduce a feasible region from the inside to be closer to the boundary. $\delta_{\text {in }}(0)$ is set to a large value to initially consider all of the feasible region, and is then updated every consecutive generation using the linear reduction mechanism computed by:

$$
\begin{equation*}
\delta_{i n}(t)=\delta_{i n}^{i n i t}-c f e \times \frac{\delta_{i n}^{i n i t}-\delta_{i n}^{m i n}}{M A X_{F E S}} \tag{5.7}
\end{equation*}
$$

where $\delta_{i n}^{\text {init }}=a b s(\max (\min (g)))$ is its initial value, $\delta_{i n}^{\min }=0.002 \times \delta_{i n}^{\text {init }}$ its minimum value, and $c f e$ is the current number of fitness evaluations and and $M A X_{F E S}$ is the maximum numbers of fitness evaluations.

As previously described, the degree of constraint violation of solution $\vec{x}$ on the $k^{\text {th }}$ constraint is computed using equation 5.2, and the total degree of constraint violation is computed by

$$
\begin{equation*}
\psi(\vec{x})=\sum_{k=1}^{q} G_{k}(\vec{x}) . \tag{5.8}
\end{equation*}
$$

In this chapter, if the problem has an active constraint and $\vec{x}$ satisfies both $L$ and $K$ in equations 6.8 and 6.9 , the violation is zero. Otherwise, the total degree of constraint violation is calculated using equations 6.8-6.7.

$$
\begin{align*}
L & =-\delta_{\text {in }}-g_{k}(\vec{x}) \leq 0  \tag{5.9}\\
R & =g_{k}(\vec{x})-\delta_{\text {out }} \leq 0 \tag{5.10}
\end{align*}
$$

The total degree of constraint violation is calculated as

$$
\begin{equation*}
\psi_{R 2 S}(\vec{x})=\sum_{i=1}^{m} \max (0, \max (L, R)) \tag{5.11}
\end{equation*}
$$

By using equation 6.7, any individual which lies inside the space formed by the intersection of the active constraint's boundary region is feasible, and ones outside this region are infeasible. On the other hand, if the problem does not have any active constraints, the total degree of constraint violation is computed using equation 5.8.

Figure 5.1 shows an example of how R2S is constructed, Figure 5.1(a) shows the original search space and feasible region. At the start of the initial evolutionary process, a boundary is constructed for each individual constraint $\left(g_{k}(\vec{x})\right)$ by using equation 5.3, as depicted in Figure 5.1(b), where the shaded area represents the
new reduced search space for all constraints, i.e., if any solution, $\vec{x}_{z}$, lies inside the shaded region and satisfies all the constraints boundaries, it is feasible and its violation is zero, while if it lies outside, or inside this region and did not satisfy all constraints, it is considered infeasible and its violation is calculated using equation 6.7. After the active constraints are determined by Algorithm 5.1(c), the search space is reduced to cover the boundary regions for only the active constraints, that is, $g_{1}$ and $g_{2}$ in the given example, with 5.1(c) showing the new reduced search space. Figure 5.1(d) shows the area of interest (intersection of the active constraints), which is the reduced feasible region.

The following example is used to show how the population of individuals is evolved, based on the R2S mechanism.

$$
\begin{aligned}
& \operatorname{minimize} f(y)=\left(y_{1}-2\right)^{2}+\left(y_{2}-1\right)^{2} \\
& \text { subject to: } g_{1}(y)=y_{1}+y_{2}-2 \leq 0 \\
& g_{2}(y)=y_{1}^{2}-y_{2}+2 \leq 0 \\
& -5 \leq y_{1}, y_{2} \leq 5
\end{aligned}
$$

The optimal solution of this problem is located at $y^{*}=(0,2)$ with $f\left(y^{*}\right)=5$. The feasible space of this problem occupies roughly $0.25 \%$ of the whole search space and both constraints are active at the optimal solution. Figure ?? shows the population progress of one run. As depicted in Figure 5.2, in Figure 5.2(a) it is observed that the initially created individuals are uniformly distributed in the search space, but none of them is feasible. While in Figure 5.2(b), it is observed that some of the individuals are considered as feasible with respect to the new feasible space constructed by R2S. From generation to generation, the constructed


Figure 5.1: Example of Reduced Search Space for (a) Original Search Space, (b) All Constraints, (c) Active Constraints and (d) Feasible region, which is the intersection of the active constraints.
search space is reduced to reach the boundary of the feasible region, as noted in Figures $5.2(\mathrm{c}), 5.2(\mathrm{~d}), 5.2(\mathrm{e})$, and $5.2(\mathrm{f})$. It is clear from this graphic illustration, that R2S is very effective in guiding the generation of solutions to the boundary of the feasible region.

To show the effectiveness of the proposed R2S mechanism, a comparison between MJADE, which is different from the original JADE [64] algorithm in only


Figure 5.2: The distribution of (a) initial population without R2S mechanism, (b) initial population with R2S mechanism, (c) population at gen 8 with R2S mechanism, (d) population at gen 16 with R2S mechanism (e) population at gen 20 with R2S mechanism and (f) population at gen 30 with R2S mechanism
that a feasibility rule [224] is used to handle the constraint, and MJADE-R2S for g11, which has 2 variables and one equality constraint, are depicted in Figure 5.3. Plots 5.3(a), 5.3(c) and 5.3(e) in Figure 5.3, depict the distribution of population for MJADE without R2S at initialization, and at the 15th, and 40th generation, respectively, while, Plots $5.3(\mathrm{~b}), 5.3(\mathrm{~d})$ and $5.3(\mathrm{f})$ in Figure 5.3, depict the distribution of population for MJADE-R2S at initialization, and at the 15th, and 40th generation, respectively. With R2S, the population converges to the global optimum (plot 5.3(f)). Therefore, Fig. 5.3 for problem g11 indicates that the proposed R2S can enhance an algorithm's search ability when incorporated with a state-of-the-art algorithm.

### 5.2.3 General framework

Algorithm 6 presents the general framework for the proposed algorithm using ACD and R2S with DE (DE-R2S).

This algorithm starts with an initial population of size $N P$, generated randomly within the bounds of each decision variable. Then, the objective value and $(\psi)$ of each individual is computed using equation 5.8 , and based on these $(\psi)$, the initial values for $\delta_{\text {in }}$ and $\delta_{\text {out }}$ are automatically determined for each function. Equation 6.7 is then used to compute $\left(\psi_{R 2 S}\right)$ of the boundary region. A boundary is constructed for every single constraint $\left(g_{k}(\vec{X})\right)$, as explained in Figure ??. Then, a trial population is generated via the processes of mutation and crossover, the two populations are compared point by point, based on their fitness values and constraint violations, and a new population is formed according to Deb's feasibility rule [224], whereby one of the following rules is used: 1) of two feasible solutions $\left(\vec{x}_{1}, \vec{x}_{2}\right)$, the fittest is selected, i.e. $\left.f\left(\vec{x}_{1}\right) \leq f\left(\vec{x}_{2}\right), 2\right)$ a feasible solution is always better than an infeasible one, 3) of two infeasible solutions, the one with the smaller sum of its constraint violations is selected, i.e. $\psi\left(\vec{x}_{1}\right) \leq \psi\left(\vec{x}_{2}\right)$. As


Figure 5.3: The distribution of the population of MJADE algorithm (a) initial population without R2S mechanism, (b) initial population with R2S mechanism, (c) population at gen 15 without R2S mechanism, (d) population at gen 15 with R2S mechanism (e) population at gen 40 without R2S mechanism and (f) population at gen 40 with R2S mechanism

```
Algorithm 6 The proposed framework
    In generation iter \(=0\), generate an initial random population of size NP.
    Evaluate objective/constraint function values and the \(\psi\) for each individual of
    the population \(N P\) using equation 5.2.
    Determine the initial values of \(\delta_{\text {in }}\) and \(\delta_{\text {out }}\) based on original total constraint
    violation as described in Sec 5.2.2.
    Construct a boundary region for every constraint based on the determined
    values \(\delta_{\text {in }}\) and \(\delta_{\text {out }}\) as described in Figure 5.1.
    Update fitness evaluations \(c f e \leftarrow N P\);
    At each generation (iter): Evolve entire population using any algorithm.
    Update fitness evaluations \(c f e \leftarrow c f e+N P\);
    Determine the active constraints using Algorithm 5.
    if active constraint are present then
        Remove boundary for non-active constraints;
        Update values of \(\delta_{\text {in }}\) and \(\delta_{\text {out }}\) for active constraints by using equations 5.7
        and 5.4 , respectively.
        Update values of total constraint violations based on the updated values of
        \(\delta_{\text {in }}\) and \(\delta_{\text {out }}\) by using equation 6.7.
    else
        Use entire search space
    end if
    Compare child solutions with parent solutions, and the fittest between them
    will enter the new population.
17: Stop if the termination criterion is met; else set iter \(=i\) iter +1 , and go to
    STEP 6.
```

the ACD algorithm runs, at predefined numbers of fitness evaluations, whether or not there are active constraints is determined. If active constraints are present, the values of $\delta_{\text {in }}$ and $\delta_{\text {out }}$ are computed and updated, as described in section 5.2.2, otherwise $\delta_{i n}$ is set to a maximum value (to search the whole inside feasible region), which is done by deleting the inner boundary. The processes of mutation, crossover and acceptance are repeated until a stopping condition is met.

### 5.3 Experimental Results and Analysis

This section reports comprehensive experiments that were conducted to evaluate the performances of the R2S and ACD methods when combined with modified JADE [64], modified CoDE [68], modified OXDE [225] (MJADE, MCoDE and

MOXDE all are similar to their original algorithm but to be able to solve COPs, Deb's feasibility rule was incorporated in each algorithm), GAMPC [180], SaDE [65] and FRORI [187]. The combinations are referred to as MJADE-R2S, MCoDER2S, GAMPC-R2S, SaDE-R2S, MOXDE-R2S and FRORI-R2S, respectively, and were used to optimize the 32 functions presented in CEC2006 [207] and CEC2011 [181].

### 5.3.1 Experimental setup

In this section, the obtained computational results are presented and analyzed.

To fairly compare the results obtained from the different algorithms, each problem is optimized over 25 independent runs, each algorithm starts from the same initial population for corresponding runs. The algorithms are implemented using Matlab and all experiments were performed on a computer with a 3.4 GHz Core (TM) i7 processor, 16.0G RAM and Windows 7. For all the test functions in CEC2006 and CEC2011, their maximum numbers of fitness evaluations ( $F E S_{\text {max }}$ ) are set to 200000 and 150000 , respectively. Val is set to small value. It was set to 0.01 . $m$ was set to a value of 10 .

### 5.3.2 Comparison between state-of-the-art algorithms, with and without R2S, for solving CEC2006 and CEC2011

This subsection, briefly discusses the results obtained from six state-of-the-art algorithms, with and without, R2S. Unless otherwise stated, for each algorithm, the following parametric setup was used, based on the relevant guidelines in the literature:

- MJADE with $p=0.05, c=0.1$ and $N P=100$.

Table 5.1: Summary of comparison of results obtained from different algorithms with and without R2S for CEC2006 and CEC2011

| Algorithms | Criteria | $R^{+}$ | $R^{-}$ | $p$-value | $\alpha=0.05$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MJADE-R2S vs. MJADE | Best | 84 | 7 | 0.007 | Yes |
|  | Average | 246 | 30 | 0.001 | Yes |
| MCoDE-R2S vs MCoDE | Best | 252 | 1 | 0.000 | Yes |
|  | Average | 297 | 3 | 0.000 | Yes |
| MOXDE-R2S vs MOXDE | Best | 79 | 12 | 0.019 | Yes |
|  | Average | 175 | 56 | 0.039 | Yes |
| FRORI-R2S vs FRORI | Best | 189 | 1 | 0.000 | Yes |
|  | Average | 177 | 13 | 0.001 | Yes |
| SaDE-R2S vs SaDE | Best | 156 | 15 | 0.002 | Yes |
|  | Average | 229 | 47 | 0.006 | Yes |
| GAMPC-R2S vs GAMPC | Best | 67 | 11 | 0.028 | Yes |
|  | Average | 233 | 43 | 0.004 | Yes |

- MCoDE with $N P=30$,
- MOXDE with $N P=100, F=0.9$ and $C r=0.9$.
- GAMPC with $N P=90, c r=1, p=0.1$, maximum number of generations $T_{\max }=1667$, the number of individuals that are selected to fill the archive pool $m=0.5 \times N P$, and the tournament pool size is selected randomly as 2 or 3.
- $\operatorname{SaDE}$ with $N P=50$,
- $\operatorname{FRORI}$ with $N P=80$, maximum replacement number $M R N=\max (5, D / 2)$,

$$
F_{\text {pool }}=[0.6,0.8,0.1], \text { and } C r_{\text {pool }}=[0.1,0.2,1.0]
$$

The detailed results (best, mean and standard deviation values) are shown in Appendix C, Tables C.1, C.2. .

The comparison summaries among the algorithms, with and without R2S, are presented in Table 5.1. From this table, it is clear that the number of problems in which the average fitness values obtained by algorithms with R 2 S is higher

Table 5.2: Comparison of performances of algorithms with and without R2S regarding best and mean computational times and savings in FEs

| Algorithms | Saving in Computational <br> Time | Saving in FEs |
| :---: | :---: | :---: |
| MJADE-R2S vs. MJADE | $17.64 \%$ | $8.34 \%$ |
| MCoDE-R2S vs. MCoDE | $10.60 \%$ | $10.66 \%$ |
| MOXDE-R2S vs. MOXDE | $36.69 \%$ | $11.88 \%$ |
| FRORI-R2S vs. FRORI | $18.19 \%$ | $2.37 \%$ |
| SaDE-R2S vs. SaDE | $30.29 \%$ | $5.04 \%$ |
| GAMPC-R2S vs. GAMPC | $13.37 \%$ | $11.12 \%$ |

than those obtained by algorithms without R2S. In regards to best fitness values obtained, algorithms with R2S, are also better in terms of the number of best values obtained. To understand Table 5.1, for example the first row compares MJADE-R2S with MJADE, in regards to best values obtained. It shows that MJADE-R2S, is better than MJADE, as $R^{+}=84, R^{-}=7$ and $p$-value $=0.007$, which means that MJADE-R2S is significantly better than MJADE.

In addition to the quality of solutions, the computational effort (the number of fitness evaluations (FES)) and times required by these algorithms to obtain optimal solutions within an error of 0.0001 , i.e., the stopping condition is $(f(\vec{x})-$ $f\left(\overrightarrow{x^{*}}\right) \leq 0.0001$ ), where $f\left(\overrightarrow{x^{*}}\right)$ indicates the best-known solutions, are compared. A summary of the comparison of the algorithms, with and without R2S, is provided in Table 5.2, in which it is clear that those with R2S are the fastest. This means that this method is capable of improving the performances of the state-of-the-art algorithms, in terms of both computational time and effort. To understand these results, as an example, the second row shows that MCoDE-R2S takes $10.66 \%$ fewer FEs and $10.60 \%$ less computational time than MCoDE, to reach the known best solutions.

Regarding the Wilcoxon signed-rank test, for both the best and average results obtained, the algorithms with R2S are significantly better than those without it.

The reasons why algorithms with R2s perform better than algorithms without R2s, can be explained as follows. Firstly, ACD works well and is able to distinguish between active and in-active constraints, as will be shown later in Section 5.3.3.1. Secondly, the R2S mechanism helps the solutions to move very fast to the boundary between feasible and infeasible regions, which means it will reach the optimal solution very fast, as is clear from Figure 5.3.

To determine the best-performing algorithm (to be used in the following parametric analysis), MJADE, MCoDE, MOXDE, GAMPC, FRORI and SaDE are compared, and their rankings obtained from the Friedman test and their mean values, are depicted in Figure 5.4. The figure includes the mean rankings of MJADER2S, MCoDE-R2S, MOXDE-R2S, GAMPC-R2S, FRORI-R2S and SaDE-R2S. It is clear that MJADE, both with and without R2S, is the best.

Furthermore, the performance profiles for the average and best results obtained by the MJADE algorithms, with and without R2S, are depicted in Figure 5.5. It is clear that MJADE-R2S is better than MJADE in both cases.

Finally, as a sample, a convergence plot for MJADE and MJADE-R2S, for problems g02, g03, g13, and r01, is presented in Figure 5.6. In the figure, the x -axis represents the number of fitness evaluations and the y -axis represents the fitness value. This figure shows that MJADE-R2S converges much faster than MJADE.

### 5.3.3 Parametric analysis

This section analyzes the R2S mechanism and its parameters.

(a)

(b)

Figure 5.4: Average rankings for (a) MJADE, MCoDE, MOXDE, GAMPC, FRORI, and SaDE, and (b) MJADE-R2S, MCoDE-R2S, MOXDE-R2S, GAMPC-R2S, FRORI-R2S, and SaDE-R2S

### 5.3.3.1 Active constraints

As previously mentioned, by their nature equality constraints are active constraints, and so they do not require any mechanism for identification. So the ACD mechanism is only tested on the CEC2006 problems that have inequality

(b)

Figure 5.5: Plots of performance profiles for MJADE-R2S and MJADE based on (a) best results, and (b) average results
constraints. Table 5.3 shows the actual numbers of active constraints reported in [207], the predicted numbers of active constraints determined by the proposed ACD mechanism, and the number of FEs required for each problem to determine the active constraints. It is clear that, ACD was able to identify all the active constraints successfully, with the last column indicating its success rate (SRs),


Figure 5.6: Convergence plots of MJADE-R2S and MJADE for (a) g02 (b) g03 (c) g13 and (d) r01
calculated by:

$$
\begin{equation*}
S R=\frac{\# \text { of predicted }}{\# \text { of actual }} \times 100 \tag{5.12}
\end{equation*}
$$

Therefore, based on the FES_active_required column in Table 5.3, $F E S_{A C D}$ is set to the maximum value (35200). For every problem except g07, the ACD

Table 5.3: Number of active constraints determined by ACD

| Problem | Actual | Predicted | FES_active_required | SR |
| :---: | :---: | :---: | :---: | :---: |
| g01 | 6 | 6 | 30200 | 100 |
| g04 | 2 | 2 | 15200 | 100 |
| g06 | 2 | 2 | 15200 | 100 |
| g07 | 6 | 5 | 35200 | 83.3 |
| g09 | 2 | 2 | 20200 | 100 |
| g10 | 3 | 3 | 20200 | 100 |
| g16 | 4 | 4 | 5200 | 100 |
| g18 | 6 | 6 | 25200 | 100 |
| g24 | 2 | 2 | 5200 | 100 |

mechanism was able to obtain the same number of active constraints as the actual number.

### 5.3.3.2 Effect of CS

The effect of CS, which is an interval that is the number of generations for evaluating whether constraints are active or not, is analyzed using different numbers of generations, namely $1,25,50,75$ and 100 . The detailed results (mean and standard deviation values) are shown in Appendix C, Table C.7. The overall rankings, based on the Friedman test, are presented in Table 5.4. The table shows that $C S=25$ is the best. The Wilcoxon signed-rank test results are presented in Table 5.5, in which for example row 6 , which compares $C S=25$ and $C S=75$, indicates that $C S=25$ is superior for 2 test problems, obtains the same results for 20 and is inferior for 0 , which means that it is slightly better than $C S=75$, although the difference between them is not significant. Also, it is clear that CS values equal to or greater than 25 are significantly better than $C S=1$, and while those of $C S=25,50,75$, and 100 do not greatly affect the results, $C S=25$ is slightly better.

Table 5.4: Mean ranks of different CS values based on Friedman test

| Algorithms | Mean rank | Order |
| :---: | :---: | :---: |
| $\mathrm{CS}=1$ | 3.55 | 5 |
| $\mathrm{CS}=25$ | $\mathbf{2 . 7 5}$ | $\mathbf{1}$ |
| $\mathrm{CS}=50$ | 2.89 | 2.5 |
| $\mathrm{CS}=75$ | 2.89 | 2.5 |
| $\mathrm{CS}=100$ | 2.93 | 4 |

Table 5.5: Summary of comparisons of different variants of proposed algorithm with different CS values (1, 25, 50, 75 and 100) based on average results, where 'Dec.' statistical decision is based on Wilcoxon rank-sum test

| Algorithms | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{CS}=1$ vs. $\mathrm{CS}=25$ | 0 | 16 | 6 | - |
| $\mathrm{CS}=1$ vs. $\mathrm{CS}=50$ | 0 | 16 | 6 | - |
| $\mathrm{CS}=1$ vs. $\mathrm{CS}=75$ | 0 | 16 | 6 | - |
| $\mathrm{CS}=1$ vs $\mathrm{CS}=100$ | 0 | 16 | 6 | - |
| $\mathrm{CS}=25$ vs $\mathrm{CS}=50$ | 1 | 21 | 0 | $\approx$ |
| $\mathrm{CS}=25$ vs. $\mathrm{CS}=75$ | 2 | 20 | 0 | $\approx$ |
| $\mathrm{CS}=25$ vs. $\mathrm{CS}=100$ | 2 | 20 | 0 | $\approx$ |
| $\mathrm{CS}=50$ vs. $\mathrm{CS}=75$ | 1 | 20 | 1 | $\approx$ |
| $\mathrm{CS}=50$ vs. $\mathrm{CS}=100$ | 1 | 20 | 1 | $\approx$ |
| $\mathrm{CS}=75$ vs $\mathrm{CS}=100$ | 1 | 21 | 0 | $\approx$ |

### 5.3.3.3 Effect of $F E S_{c}$

As previously mentioned, $\delta_{\text {out }}$ and $\delta_{\text {in }}$ are updated using equations (5.4) and (5.7), respectively up to a predefined number of $\mathrm{FEs}\left(F E s_{c}\right)$. To analyze the effect of $F E S_{c}$, experiments were conducted using different values for it of $0.3 \times F E S_{\max }$, $0.5 \times F E S_{\max }, 0.7 \times F E S_{\max }$, and $0.9 \times F E S_{\max }$ while all other parameters are fixed. The detailed results (mean and standard deviation values) are shown in Appendix C, Table C.8. The variants were ranked based on the Friedman test and their results are presented in Table 5.6, which shows that $F E S_{c}=0.7 \times$ $F E S_{\max }$ is slightly better than the others. Also, a Wilcoxon rank-sum test of the different variants of the proposed algorithm with different values was conducted. A summary of its results is presented in Table 5.7. It indicates that $F E S_{c}=$ $0.7 \times F E S_{\max }$ is slightly better than the other variants.

Table 5.6: Mean ranks of different $F E S_{c}$ values, based on Friedman test

| Algorithms | Mean rank | Order |
| :---: | :---: | :---: |
| $F E S_{c}=0.3 \times F E S_{\max }$ | 2.66 | 3 |
| $F E S_{c}=0.5 \times F E S_{\max }$ | 2.07 | 2 |
| $F E S_{c}=0.7 \times F E S_{\max }$ | $\mathbf{1 . 9 8}$ | $\mathbf{1}$ |
| $F E S_{c}=0.9 \times F E S_{\max }$ | 3.30 | 4 |

Table 5.7: Summary of comparisons of different variants of proposed algorithm with different values ( $0.3,0.5,0.7$ and 0.9 ) based on average results, where 'Dec.' indicates statistical decisions based on Wilcoxon rank-sum test

| Algorithms | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: |
| $F E S_{c}=0.3 F E S$ vs. $F E S_{c}=0.5 F E S$ | 0 | 14 | 8 | - |
| $F E S_{c}=0.3 F E S$ vs. $F E S_{c}=0.7 F E S$ | 1 | 14 | 7 | - |
| $F E S_{c}=0.3 F E S$ vs. $F E S_{c}=0.9 F E S$ | 11 | 7 | 4 | $\approx$ |
| $F E S_{c}=0.5 F E S$ vs. $F E S_{c}=0.7 F E S$ | 1 | 18 | 3 | $\approx$ |
| $F E S_{c}=0.5 F E S$ vs. $F E S_{c}=0.9 F E S$ | 14 | 7 | 1 | + |
| $F E S_{c}=0.7 F E S$ vs. $F E S_{c}=0.9 F E S$ | 15 | 7 | 0 | + |

### 5.3.4 Comparison between state-of-the-art algorithms, with and without R2S, for solving CEC2010

From the above-mentioned analysis, it was found that, FES_active_required $=125, C S=25$ and $F E S_{c}=0.7 \times F E S_{\max }$ are the best parameters. So, these parameters will be used in the comparison in this section.

A set of 36 test instances ( 18 problems each with 10 and 30 dimensions) that were introduced in CEC2010 [186] has been solved. The algorithm was run 25 times for each test problem, where the stopping criterion was to run for up to $200 K$ FEs for $10 D$ instances, and $600 K$ FEs for $30 D$. The detailed results (best, mean and standard deviation values) are shown in Appendix C, Tables C.3, C.4, C.5, C.6.

Considering both the best and average results, a comparative analysis is presented in Table 5.8. To explain the results, for example for MJADE-R2S vs

Table 5.8: Summary of comparison of results obtained from different algorithms with and without R2S for CEC2010

|  |  | 10 D |  |  |  | 30 D |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Algorithms | Criteria | $R^{+}$ | $R^{-}$ | $p$-value | Dec. | $R^{+}$ | $R^{-}$ | $p$-value | Dec. |
| MJADE-R2S vs. MJADE | Best | 78 | 0 | 0.002 | + | 119 | 1 | 0.001 | + |
|  | Average | 110 | 26 | 0.043 | + | 135 | 15 | 0.004 | + |
| MCoDE-R2S vs MCoDE | Best | 143 | 28 | 0.012 | + | 166 | 5 | 0.000 | + |
|  | Average | 140 | 31 | 0.018 | + | 140 | 31 | 0.018 | + |
| MOXDE-R2S vs MOXDE | Best | 149 | 4 | 0.001 | + | 162 | 9 | 0.001 | + |
|  | Average | 144 | 47 | 0.011 | + | 139 | 32 | 0.020 | + |
| FRORI-R2S vs FRORI | Best | 10 | 7 | 0.842 | $\approx$ | 35 | 1 | 0.017 | + |
|  | Average | 48 | 30 | 0.480 | $\approx$ | 78 | 42 | 0.307 | $\approx$ |
| SaDE-R2S vs SaDE | Best | 104 | 1 | 0.001 | + | 151 | 20 | 0.004 | + |
|  | Average | 153 | 18 | 0.003 | + | 149 | 22 | 0.006 | + |
| GAMPC-R2S vs GAMPC | Best | 43 | 2 | 0.015 | + | 66 | 12 | 0.034 | + |
|  | Average | 87 | 4 | 0.004 | + | 88 | 17 | 0.026 | + |

MJADE, it can be observed that MJADE-R2S provides higher $R^{+}$values than $R^{-}$for MJADE, for both best and average values for $10 D$ and $30 D$. Moreover, the p-values of all the cases are less than 0.05 , which indicates that algorithms with R2S exhibit statistically superior convergence performance against the algorithms without R2S, except for FRORI.

Furthermore, as an example, the performance profile comparing MJADE and GAMPC with and without R2S, is presented in Figure 5.7. This figure shows that MJADE-R2S and GAMPC-R2S are better than MJADE and GAMPC, as MJADE-R2S and GAMPC-R2S reach a probability of 1 (when $\tau=37$ and $\tau=1$, respectively) before their corresponding MJADE and GAMPC.

Since there is no significance different between FRORI with and without R2S, the complexity of these two algorithms is computed followed the guidelines in [186] for both 10D and 30D. This complexity is presented in Table 5.9. It can be concluded, that the time complexity of FRORI-R2S is less than the time complexity of FRORI, and that means R2S did not add any additional complexity to the original algorithms.


Figure 5.7: Performance profiles comparing MJADE and GAMPC, with and without R2S, for CEC2010 for 30D (a) MJADE and (b) GAMPC

### 5.4 Chapter Summary

As of the optimization literature, the optimal solution of COPs often lies on the intersection of the active constraints. Therefore, in this chapter, the R2S mechanism is proposed, which searches the boundary area between the feasible

Table 5.9: Comparison between FRORI and FRORI-R2S based on algorithm complexity

|  | FRORI |  |  |  | FRORI-R2S |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $T_{0}$ | $T_{1}$ | $\widehat{T}_{2}$ | $\frac{\widehat{T}_{2}-T_{1}}{T_{0}}$ | $T_{0}$ | $T_{1}$ | $\widehat{T}_{2}$ | $\frac{\widehat{T}_{2}-T_{1}}{T_{0}}$ |
| 10D | 0.14293 | 0.121451 | 4.1496266 | 28.18286 | 0.14293 | 0.121451 | 3.60050308 | $\mathbf{2 4 . 3 4 0 9 5}$ |
| 30D | 0.14293 | 0.312842 | 5.28531388 | 34.78956 | 0.14293 | 0.312842 | 4.93899166 | $\mathbf{3 2 . 3 6 6 5 4}$ |

and infeasible regions. R2S comprises two components. The first is an ACD mechanism which enables the algorithm to distinguish between active and nonactive constraints. The second performs a boundary construction, in which after determining active constraints, the algorithm defines the thickness of the boundary area between the feasible and infeasible regions for active constraints, while this boundary area is removed for non-active ones. Also, it deals with the case in which the optimal solution lies inside the feasible region, by searching the original search space by increasing the value for the inner delta.

This new method is incorporated in six state-of-the-art algorithms that were tested on the CEC'2006 and CEC'2010 single-objective COPs, as well as a number of real-application constrained problems, with the results demonstrating that it is capable of improving the performances of these algorithms.

Motivated by the encouraging results obtained in this and the previous chapters, a new multi-method algorithm incorporating both landscape information and R 2 S , is proposed for solving COPs in the next chapter.

## Chapter 6

## Multi-EAs Framework for Constrained Problems

This chapter introduces a novel multi-method algorithm to solve COPs. It incorporates both landscape methods and the reduced search space mechanism proposed in Chapters 4 and 5. The experimental results from, and analysis of, the proposed method are presented and discussed by solving the previously used benchmark problems. Finally, detailed results obtained from the proposed algorithm, and comparisons with those from state-of-the-art algorithms, are presented.

### 6.1 Introduction

As previously mentioned, no single algorithm is able to solve a wide range of optimization problems. Also, in COPs, some constraints are much more important than others.

As a consequence, a new landscape-based DE algorithm was proposed in Chapter 4 for solving COPs. It used information about a problem's landscape to attempt to put more emphasis on the best DE operator, from a pool of them. It showed better performance than other state-of-the-art algorithms in both quality of solutions and computational time. Also, the proposed reduced search space

Part of this work has previously appeared in

1. K. M. Sallam, S. M. Elsayed, R. A. Sarker, and D. L. Essam, "Multi-method based orthogonal experimental design algorithm for solving cec2017 competition problems," in Evolutionary Computation (CEC), 2017 IEEE Congress on. IEEE, 2017, pp. 1350-1357.
mechanism in Chapter 5, demonstrated its capability to enhance state-of-the-art algorithms. So, a framework that can utilize both a problem's landscape and reduced search space in one single framework, may result in better performance.

Therefore, the main aim of this chapter is to propose a new multi-EA algorithm, that utilizes the benefits of both a problem's landscape and the search space reduction mechanism. In its entire process, information from the objective function and constraints landscapes are used to choose the best algorithm during the evolutionary process. Concurrently the reduced search space mechanism focuses the search process around the active constraints. The performance of the proposed algorithm has been tested by solving the CEC2006 [207], CEC2010 [186] and CEC2011 [181] problems defined in Chapter 3. Also, several experiments were designed and carried out to analyze the effects of different parameters on the performance of the proposed algorithm. The results from the final variant of the proposed algorithm are compared with those from well-known algorithm in the literature.

The organization of this chapter is as follows: the next section describes the proposed framework; the experimental results and analysis are reported in Section 6.3; and a chapter summary is presented in Section 6.4.

### 6.2 Proposed Algorithm

The general algorithmic framework of multi-EA, using a problem's landscape and reduced search space (MEA-LS-R2S) is described in this section.

### 6.2.1 MEA-LS-R2S

The main steps of MEA-LS-R2S are shown in Algorithm 7. Initially, a random population of size $N P$ individuals is generated where each variable of each
individual must be within the boundaries. Then, the initial population is divided into $m$ sub-populations of sizes, $N P_{1}, N P_{2}, \ldots, N P_{m}$ respectively. The individuals in each population are evolved by different EAs (DE, GA and CMA-ES). Each algorithm is applied based on its probability $\left(\operatorname{prob}_{E A}\right)$. Initially, the probabilities of all EAs are equal to 1 . Once a half cycle ( $C S$ generations) is finished, all $p r o b_{E A}$ are dynamically updated based on the landscape measure, as discussed in Section 6.2.1.2. In the subsequent cycle, in each generation, $m$ random numbers, between 0 and 1 are generated, based on which the corresponding EA is used to evolve its own sub-population. After another $C S$ generations, an information sharing mechanism is executed, and $\operatorname{prob}_{E A}$ for every EA, is set to a value of 1 . This cycle is repeated until the algorithm finishes.

```
Algorithm 7 Proposed MEA-LS-R2S algorithm
    Define \(N P \leftarrow N P_{1}+N P_{2}+\ldots+N P_{m}\), count \(\leftarrow 0, \operatorname{prob}_{p} \leftarrow 1, \forall p=1,2, \ldots, m\),
    \(F E S_{\text {max }} \leftarrow 10,000 D\), and all other parameters required.
    Generate an initial \(N P\) random individuals \((X)\), with the variables of each one \(\left(\vec{x}_{z}\right)\)
    must be within their boundaries;
    Assign random \(N P_{1}, N P_{2}, \ldots, N P_{m}\) individuals from \(X\) to \(X_{p}, \forall p=1,2, \ldots, m\),
    respectively.
    while \(F E S \leq F E S_{\text {max }}\) do
        count \(\leftarrow\) count +1
        if count \(==C S\) then
            Update \(\operatorname{prob}_{p}, \forall p=1,2, \ldots, m\), as described in 6.2.1.2;
        end if
        if count \(==2 \times C S\) then
            Execute the information sharing mechanism as in section 6.2.1.3 and prob \(_{p} \leftarrow\)
            \(1, \forall p=1,2, \ldots, m\) and count \(\leftarrow 1\);
        end if
        if \(\operatorname{rand}(p) \in[0,1] \leq \operatorname{prob}_{p}\) then
            Evolve the corresponding sub-population using the assigned EA, update FES
            and sort \(X_{1}\);
        end if
        Go to step 4;
    end while
```


### 6.2.1.1 The used Algorithms

In this section, the description of the EA algorithms used in the framework, are given.

Multi-operator DE (MODE): starts with $N P_{1}$ individuals which are randomly taken from the entire $N P$ individuals. It uses the following three DE mutation strategies.

- $\mathrm{DE} /$ current-to- $\phi$ best with archive/1/bin

$$
u_{i, j}=\left\{\begin{array}{r}
x_{i, j}+F_{i} \cdot\left(x_{\phi, j}-x_{i, j}+x_{r 1, j}-x_{r 2, j}\right)  \tag{6.1}\\
\text { if }\left(\text { rand } \leq c r_{i} \text { or } j=j_{r a n d}\right) \\
x_{i, j} \quad \text { otherwise }
\end{array}\right.
$$

- $\mathrm{DE} /$ rand-to- $\phi$ best with archive/ $/$ /bin

$$
u_{i, j}=\left\{\begin{array}{r}
x_{r 1, j}+F_{i} \cdot\left(x_{\phi, j}-x_{r 1, j}+x_{r 3, j}-x_{r 2, j}\right)  \tag{6.2}\\
\text { if }\left(\text { rand } \leq c r_{i} \text { or } j=j_{\text {rand }}\right) \\
x_{i, j} \quad \text { otherwise }
\end{array}\right.
$$

- DE/ $\phi$ best $/ 1 /$ bin

$$
u_{i, j}= \begin{cases}x_{\phi, j}+F_{i \cdot} \cdot\left(x_{r 1, j}-x_{r 3, j}\right) &  \tag{6.3}\\ \quad \text { if }\left(\text { rand } \leq c r_{i} \text { or } j=j_{\text {rand }}\right) \\ x_{i, j} & \text { otherwise }\end{cases}
$$

where $r_{1} \neq r_{2} \neq r_{3} \neq i$ are random integer numbers, $\vec{x}_{r 1}$ and $\vec{x}_{r 3}$ are randomly selected from the entire population, $x_{\phi, j}$ was selected from the
best $10 \%$ individuals from entire populations, while $x_{r 2, j}$ was selected from the union of the entire population and an archive.

Each variant evolves the same number of individuals, and for each individual in the entire sub-population, a new offspring individual is generated using the assigned DE operator. Then, for each offspring the objective value and the total constraint violation is calculated (see Section 6.2.1.3). A selection process is carried out between every offspring and its parent, and the fittest enters the new population, as discussed in Section 6.2.1.3. Concurrently the landscape index for each DE is calculated. Once a half cycle $(C S)$ is finished, the best-performing DE operator is selected based on the normalized measure, to evolve the entire whole sub-population for the subsequent half cycle. Again, this cycle is repeated while the algorithm runs.

Multi-operator GA (MOGA): like MODE, it starts with $N P_{2}$ individuals randomly selected from the whole population $N P$ individuals. In its entire process, two effective GA variants are used, GA with simulated binary crossover (SBX) and a non-uniform mutation (NU-M), as well as MPC-GA as in [226]. The entire process of MOGA is similar to MODE, with the only difference being that the two GA algorithms are always used, based on the effectiveness of each one of them. To generate an offspring, a random number (rand $\in[0,1]$ ) is generated, then if it is greater than a predefined probability $(P(1))$, two new individuals are generated by SBX-NU, otherwise three individuals are produced by MPC-GA. Then the number of successful individuals (entered the next population) generated by MPC-GA is saved in $S_{1}$, while the successful ones produced by SBX-NU are saved in $S_{2}$. Then $(P(1))$ is updated every generation by $P(1)=\frac{S_{1}}{S 1+S_{2}}$.

CMA-ES: has shown its capability to solve different types of optimization problems [99] successfully. It originated from the concept of self-adaptation in ES, which adapts the covariance matrix of a multivariate normal search distribution. In it, the new individuals are created by a sampling of a Gaussian distribution, and rather than using a single step mutation; it depends on the path that the population takes over generations [227]. Algorithm 8 shows the main steps of CMA-ES.

```
Algorithm 8 CMA-ES algorithm
    Generate an initial individual \(\vec{x}_{m}\) and calculate its fitness function value;
    Sample new solutions, such that \(\vec{x}_{z, G+1}=\vec{x}_{m}+\sigma N\left(0, C_{G}\right) \forall z=1: N P\);
    Evaluate and sort the new offspring.
    Select \(\mu\) individuals as a parental vector. Then calculate their center using
    \(\vec{x}_{m, G+1}=\sum_{k=1}^{\mu} w_{k} \vec{x}_{k, G}\) where \(\sum_{k=1}^{\mu} w_{k}=1\) and \(w_{1} \geq w_{2} \geq \ldots \geq w_{\mu}\).
    Update the evolution path \(p_{G+1}^{s}\) and \(p_{G+1}^{\sigma}\).
    Adapt the covariance matrix \(\left(C_{G+1}\right)\).
    Update the global step size \(\left(\sigma_{G+1}\right)\).
    Go to steps 2, and repeat theses steps until a stopping criterion is met.
```


### 6.2.1.2 Normalized landscape measure

In this chapter, the overall normalized average landscape measure, for each algorithm is computed as in Chapter 4 (Section 3.3.1.2). The normalized value $N_{L D_{E A}}$ of algorithm $E A$ is calculated by:

$$
\begin{equation*}
N_{L D_{E A}}=\frac{1-M_{L D_{E A}}}{\sum_{O P=1}^{m}\left(1-M_{L D_{E A}}\right)} \tag{6.4}
\end{equation*}
$$

where $\{E A=1,2, \ldots, m\}$, and $M_{L D}$ is the mean value of the landscape information measure.

Subsequently, the overall normalized performance, $O N_{L D_{E A}}$, of each $E A$ is computed by equation 4.5 :

$$
\begin{equation*}
O N_{L D_{E A}}=\frac{N_{L D_{E A}}}{\sum_{E A=1}^{m}\left(N_{L D_{E A}}\right)} \tag{6.5}
\end{equation*}
$$

Then, each probability is updated as:

$$
\begin{equation*}
\operatorname{prob}_{E A}=\max \left(0.1, \min \left(0.9, \frac{O N_{L D_{E A}}}{\sum_{E A=1}^{m}\left(O N_{L D_{E A}}\right)}\right), \forall E A=1,2, \ldots, m\right. \tag{6.6}
\end{equation*}
$$

Note: Equation 6.5 is used to determine the best-performing operator in MODE.

### 6.2.1.3 Selection process

The selection process between any offspring and its parent according to a modified form of Deb's feasibility rule [224], whereby one of the following rules is used: 1) of two feasible solutions $\left(\vec{x}_{1}, \vec{x}_{2}\right)$, the fittest is selected, i.e. $f\left(\vec{x}_{1}\right) \leq$ $f\left(\vec{x}_{2}\right), 2$ ) a feasible solution is always better than an infeasible one, 3) of two infeasible solutions, the one that has a smaller value of $\psi_{R 2 S}$ is preferred, i.e. $\psi_{R 2 S}\left(\vec{x}_{1}\right) \leq \psi_{R 2 S}\left(\vec{x}_{2}\right) . \psi_{R 2 S}$ of an individual $\left(\overrightarrow{x_{z}}\right)$ is calculated based on the reduced search space mechanism proposed in Chapter 5, as:

$$
\begin{equation*}
\psi_{R 2 S}(\vec{x})=\sum_{i=1}^{m} \max (0, \max (L, R)) \tag{6.7}
\end{equation*}
$$

where L and R are computed the following equations as:

$$
\begin{align*}
& L=-\delta_{\text {in }}-g_{k}(\vec{x}) \leq 0  \tag{6.8}\\
& R=g_{k}(\vec{x})-\delta_{\text {out }} \leq 0 \tag{6.9}
\end{align*}
$$

where $\delta_{\text {in }}$ and $\delta_{\text {out }}$ are are the inner-delta and outer-delta values, respectively, and their values are updated using the mechanism developed in Chapter 5 (Section 5).

### 6.2.1.4 Information sharing

The information sharing method in MEA-LS-R2S is simple. At the end of every cycle (count $=2 \times C S$ ), all the $m$ sub-populations are grouped together in the whole entire population. Then the sup-populations are filled with $\left(N P_{1}\right.$, $\left.N P_{2}, \ldots, N P_{m}\right)$ random individuals from the whole entire population. Then, the parameters of CMA-ES are reset to their initial values, except for $\sigma$, which is updated as $\sigma=\sigma_{\text {initial }} \times\left(1-\frac{F E S}{F E S_{\max }}\right)$.

### 6.3 Experimental Results and Analysis

This section discusses the performances of the proposed algorithm when tested by solving the sets of benchmark problems presented in Chapter 4 (Section 4.2). To obtain comprehensive comparisons, each algorithm was run 25 times for all the optimization functions to a maximum number of FEs of 200000 for CEC2006, $20000 \times D$ for CEC2010 and 150000 for CEC2011, with the best, mean and standard deviation results recorded.

Regarding parameter settings, the values of $\varphi, A, H$ were set to the same values as in Chapter 4, Section 4.4. The linear population size reduction mechanism [67] previously described in Chapter 3 is used, in which $N P_{E A}^{i n i t}$ was set at a value of $\left(N P-N P_{3}\right) / 2$ and $N P_{E A}^{\min }$ was set at a value of 4 . Note, the linear reduction mechanism is used for only DE and GA. The population size used for CMA-ES is set to 10 . The $C S$ parameter was set to 25 , while the values of $\delta_{\text {in }}$ and $\delta_{\text {out }}$ were set to the same values as in Chapter 5, Section 5.3.

### 6.3.1 Parameter analysis

In this subsection, the effects of the following parameters on the performance of the proposed algorithm are examined: 1) the number of EAs used; 2) $C S ; 3$ )

Table 6.1: Comparisons of summary of Var1, Var2 and Var3

| Algorithms | Best results |  |  |  |  | Average results |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Better | Equal | Worse | Dec. | Better | Equal | Worse | Dec. |  |
| Var1 vs. Var2 | 10 | 7 | 1 | + | 13 | 1 | 4 | $\approx$ |  |
| Var1 vs. Var3 | 2 | 7 | 9 | $\approx$ | 3 | 3 | 12 | $\approx$ |  |
| Var2 vs. Var3 | 2 | 6 | 10 | $\approx$ | 3 | 1 | 14 | - |  |

Table 6.2: Average ranks of Var1, Var2 and Var3, obtained from Friedman test based on both best and average results

| Algorithms | Average rank based on <br> best results obtained | Average rank based on <br> average results obtained |
| :---: | :---: | :---: |
| Var1 | 2.00 | 1.94 |
| Var2 | 2.56 | 2.47 |
| Var3 | $\mathbf{1 . 4 4}$ | $\mathbf{1 . 5 8}$ |

linear reduction 4) $N P_{E A}^{i n i t}$; and 5) $N P_{E A}^{\min }$. To do this, the $10 D$ test problems from CEC2010 are considered.

### 6.3.1.1 Effect of the number of the EAs, $m$

The number of EA algorithms $(m)$ required for MEA-LS-R2S was analyzed. To do this, three different variants of the proposed algorithm (Var1, Var2 and Var3) were run. Var1 uses MODE, MOGA and CMA-EA, while for Var2 MODE and MOGA are used and Var3 utilizes MODE and CMA-ES. All the parameter settings are set as those in the previous section. The detailed results (best, average, St.d) are presented in Appendix D, Table D.1.

Regarding the quality of solutions, Table 6.1 shows of a summary of comparisons of these variants. It indicates that there was a bias towards Var3. Based on Wilcoxon signed-rank test results, Var1 was significantly better than Var2 for the best results, while Var3 was significantly better than Var2 for the average results. Also, a Friedman test was conducted to rank these variants, with the results presented in Table 6.2 showing that Var3 was the best variant.

Table 6.3: Computational times and average FEs for Var1, Var2 and Var3

| Algorithms | Total average time | Total average FEs |
| :---: | :---: | :---: |
| Var1 | 9.54 | 155974 |
| Var2 | 8.84 | 163799 |
| Var3 | $\mathbf{5 . 2 5}$ | $\mathbf{1 2 8 8 4 1}$ |



Figure 6.1: Comparison of performance profiles of proposed algorithm with different $m$ values, based on average (a) computational time; and (b) FEs

Also, the total average time and number of FEs needed to reach the optimal solution with an error of 0.0001 were compared. Table 6.3 presents the total average time and number of FEs for each variant, for both of which it is clear that Var3 was better than all the others.

Furthermore, the performance profiles depicted in Figure 6.1 show that Var3 was the best for both average computational time and FEs.

### 6.3.1.2 Effect of $C S$

To determine the effect of the cycle half $C S$, MEA-LS-R2S was tested using Var3 (MODE and CMA-ES), which was better than the other two variants from the previous section, but with different values of $C S$ of $25,50,75$ and 100 generations, with the detailed results are presented in Appendix D, Table D.2. CS specifies how often MEA-LS-R2S selects the best algorithm, and how often MODE

Table 6.4: Comparisons of summary of different variants of the proposed algorithm with different $C S$ values

| Algorithms | Best results |  |  |  | Average results |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Better | Equal | Worse | Dec. | Better | Equal | Worse | Dec. |
| $C S=25$ vs. $C S=50$ | 1 | 15 | 2 | $\approx$ | 11 | 7 | 0 | + |
| $C S=25$ vs. $C S=75$ | 3 | 14 | 1 | $\approx$ | 12 | 6 | 0 | + |
| $C S=25$ vs. $C S=100$ | 4 | 13 | 1 | $\approx$ | 11 | 6 | 1 | + |

Table 6.5: Average ranks of different values of $C S$, obtained from Friedman test based on both best and average results

| Algorithms | Average rank based on <br> best results obtained | Average rank based on <br> average results obtained |
| :---: | :---: | :---: |
| $C S=25$ | 2.39 | $\mathbf{1 . 5 8}$ |
| $C S=50$ | $\mathbf{2 . 3 6}$ | 2.58 |
| $C S=75$ | 2.58 | 2.67 |
| $C S=100$ | 2.67 | 3.17 |

selects the best DE operator.

Table 6.4 presents a comparison of different variants of the proposed MEA-LS-R2S with different $C S$ values. Regarding the best results, the variant with $C S=25$ was better than, inferior to, and obtained similar results with, the variants $C S=50, C S=75$ and $C S=100$ for 1,3 and 4, and 2,1 and 1 , and 15 , 14 and 13 , respectively, while for the average results obtained MEA-LS-R2S with $C S=25$ was superior to $C S=50, C S=75$ and $C S=100$ in 11,12 and 11 , test problems respectively, but inferior to these variants for 0,0 , and 1 test problems.

Regarding the Wilcoxon signed-rank test, for the average results obtained, the proposed MEA-LS-R2S with $C S=25$ was significantly better than the others, while there is no significance difference between these variants for the best results.

For further analysis, a Friedman test was conducted with the results presented in Table 6.5 and Figure 6.2, from which it is clear the overall rank of $C S=25$ performed best.


Figure 6.2: Average ranks of different values of $C S$, obtained from Friedman test based on (a) best results; and (b) average results

### 6.3.1.3 Effect of linear population size reduction mechanism

To judge the effect of the linear population size mechanism used, two variants of the proposed MEA-LS-R2S algorithm, with linear reduction V1, and without linear reduction V2, were tested. The detailed results are presented in Appendix D, Table D.3.

Regarding the quality of solutions, Table 6.6 shows comparisons of these two variants, which indicate that V1 with the population size linear reduction mechanism was best. Based on a Wilcoxon singed-rank test, V1 was statistically better than V 2 in terms of best and average results obtained. The average computational time and FEs consumes by V1 to reach the optimal solution with an error equal to 0.0001 was 7.33 s and 128318, respectively, while for V2 it was 8.32 s and 140189, respectively.

Table 6.6: Comparisons of summary between the proposed algorithm with and without linear reduction

| Algorithms | Criteria | Better | Equal | Worse | Dec |
| :---: | :---: | :---: | :---: | :---: | :---: |
| V1 vs. V2 | Best | 12 | 6 | 0 | + |
|  | Mean | 14 | 4 | 0 | + |

Table 6.7: Comparisons of summary of different variants of the proposed algorithm with different $N P^{\text {init }}$ values

| Algorithms | Best results |  |  |  |  | Average results |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Better | Equal | Worse | Dec. | Better | Equal | Worse | Dec. |  |
| $N P^{\text {init }}=50$ vs. $N P^{\text {init }}=75$ | 0 | 17 | 1 | $\approx$ | 4 | 6 | 8 | $\approx$ |  |
| $N P^{\text {init }}=50$ vs. $N P^{\text {init }}=100$ | 1 | 16 | 1 | $\approx$ | 3 | 6 | 9 | - |  |
| $N P^{\text {init }}=50$ vs. $N P^{\text {init }}=125$ | 2 | 15 | 1 | $\approx$ | 3 | 6 | 9 | - |  |
| $N P^{\text {init }}=50$ vs. $N P^{\text {init }}=150$ | 3 | 14 | 1 | $\approx$ | 5 | 5 | 8 | - |  |
| $N P^{\text {init }}=75$ vs. $N P^{\text {init }}=100$ | 2 | 16 | 0 | $\approx$ | 3 | 10 | 5 | $\approx$ |  |
| $N P^{\text {init }}=75$ vs. $N P^{\text {init }}=125$ | 3 | 15 | 0 | $\approx$ | 4 | 11 | 3 | $\approx$ |  |
| $N P^{\text {init }}=75$ vs. $N P^{\text {init }}=150$ | 4 | 14 | 0 | $\approx$ | 9 | 7 | 2 | $\approx$ |  |
| $N P^{\text {init }}=100$ vs. $N P^{\text {init }}=125$ | 3 | 15 | 0 | $\approx$ | 7 | 11 | 0 | + |  |
| $N P^{\text {init }}=100$ vs. $N P^{\text {init }}=125$ | 4 | 14 | 0 | $\approx$ | 9 | 9 | 0 | + |  |
| $N P^{\text {init }}=125$ vs. $N P^{\text {init }}=150$ | 4 | 14 | 0 | $\approx$ | 8 | 8 | 2 | $\approx$ |  |

### 6.3.1.4 Effect of $N P^{\text {init }}$

To observe the effect of the initial population size of MODE, different experiments with $N P^{\text {init }}=50,75,100,125$ and 150 were conducted, with the detailed results presented in Appendix D, Table D.4.

Regarding the quality of solutions in terms of the best and average results obtained (Table 6.7), it is clear that $N P^{\text {init }}=100$ was better than all the other variants. The Wilcoxon signed-rank test showed that $N P^{\text {init }}=100$ was significantly better than $N P^{\text {init }}=50, N P^{\text {init }}=125$ and $N P^{\text {init }}=150$, but there was no significance difference with $N P^{\text {init }}=75$.

Also, a Friedman test was carried out to rank all the variants. From the results shown in Table 6.8, it is clear that those with $N P^{\text {init }}=100$ and $N P^{\text {init }}=75$, ranked first and second respectively.

Furthermore, the performance profiles is presented in Figure 6.3, to compare

Table 6.8: Average ranks of different values of $N P^{\text {init }}$, obtained from Friedman test based on both best and average results

| Algorithms | Average rank based on <br> best results obtained | Average rank based on <br> average results obtained | Overall rank |
| :--- | :---: | :---: | :---: |
| $N P^{\text {init }}=50$ | 2.94 | 3.35 | 6.29 |
| $N P^{\text {init }}=75$ | $\mathbf{2 . 7 2}$ | 2.72 | 5.44 |
| $N P^{\text {init }}=100$ | 2.86 | $\mathbf{2 . 3 3}$ | $\mathbf{5 . 1 9}$ |
| $N P^{\text {init }}=125$ | 3.08 | 2.89 | 5.97 |
| $N P^{\text {init }}=150$ | 3.39 | 3.53 | 6.92 |



Figure 6.3: Comparison of performance profiles of proposed algorithm with different $N P^{\text {init }}$ values, based on average (a) computational time; and (b) FEs
the different variants based on both the average computational time and FEs, from which it is clear that the variant with $N P^{i n i t}=100$ is the best.

### 6.3.1.5 Effect of $N P^{\text {min }}$

For this analysis, the proposed MEA-LS-R2S was run with different $N P^{\text {min }}$ values of $4,10,20,30$ and 40 individuals, with the detailed results shown in Appendix D, Table D.5. The average total computational times and FEs presented in Table 6.9 show that $N P^{\text {min }}=4$ required the least average computational time and the fewest average FEs.

Table 6.9: Computational times and average FEs of different values for $N P^{\text {min }}$

| Algorithms | Total average time | Total average FEs |
| :---: | :---: | :---: |
| $N P^{\text {min }}=4$ | $\mathbf{7 . 3 8}$ | $\mathbf{1 1 0 5 4 9}$ |
| $N P^{\text {min }}=10$ | 7.68 | 112180 |
| $N P^{\text {min }}=20$ | 7.75 | 111082 |
| $N P^{\text {min }}=30$ | 7.47 | 112196 |
| $N P^{\text {min }}=40$ | 7.40 | 112920 |

Table 6.10: Average ranks of different values of $N P^{\text {min }}$, obtained from Friedman test based on both best and average results

| Algorithms | Average rank based on <br> best results obtained | Average rank based on <br> average results obtained |
| :--- | :---: | :---: |
| $N P^{\text {min }}=4$ | $\mathbf{2 . 9 2}$ | $\mathbf{2 . 4 4}$ |
| $N P^{\text {min }}=10$ | 3.06 | 3.06 |
| $N P^{\text {min }}=20$ | 3.06 | 3.11 |
| $N P^{\text {min }}=30$ | $\mathbf{2 . 9 2}$ | 3.31 |
| $N P^{\text {min }}=40$ | 3.06 | 3.08 |

Table 6.11: Comparisons of summary of different variants of the proposed algorithm with different $N P^{m i n}$ values

| Algorithms | Best results |  |  |  | Average results |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Better | Equal | Worse | Dec. | Better | Equal | Worse | Dec. |
| $N P^{\text {min }}=4$ vs. $N P^{\text {min }}=10$ | 1 | 17 | 0 | $\approx$ | 7 | 9 | 2 | + |
| $N P^{\text {min }}=4$ vs. $N P^{\text {min }}=20$ | 1 | 17 | 0 | $\approx$ | 5 | 11 | 2 | $\approx$ |
| $N P^{\text {min }}=4$ vs. $N P^{\text {min }}=30$ | 0 | 18 | 0 | $\approx$ | 7 | 11 | 0 | + |
| $N P^{\text {min }}=4$ vs. $N P^{\text {min }}=40$ | 1 | 17 | 0 | $\approx$ | 6 | 11 | 1 | $\approx$ |

For further analysis, a Friedman test was done to rank all the different variants. The results are shown in Table 6.10. From which it is clear that $N P^{\min }=4$ ranked first.

Considering the quality of solutions, Table 6.11 presents a comparison between the proposed MEA-LS-R2S with $N P^{\text {min }}=4$ and all other variants, in which it is clear that $N P^{\min }=4$ is better than all the other variants, especially in terms of average results obtained. Regarding the Wilcoxon signed-rank test, the proposed algorithm with $N P^{\text {min }}=4$, was significantly better than $N P^{\text {min }}=10$ and $N P^{\text {min }}=30$, but was not significantly better than $N P^{\text {min }}=20$ and $N P^{\text {min }}=$ 40. Based on the above analysis, the proposed MEA-LS-R2S with $N P^{\text {min }}=4$ is
slightly better than all other variants.

### 6.3.2 Comparisons of MEA-LS-R2S and state-of-the-art algorithms

As, from the above-mentioned analyzes, it was found that MEA-LS-R2S with linear population size reduction, $C S=25, N P^{\text {init }}=100$ and $N P^{\text {min }}=4$ was the best variant, its performance for solving the benchmark problems described in Chapter 4, Section 4.2, was compared with several state-of-the-art algorithms.

### 6.3.2.1 Comparisons of MEA-LS-R2S and state-of-the-art algorithms for CEC2006

To judge the performance of the the proposed (MEA-LS-R2S) algorithm, comparisons were carried out using the state-of-the-art algorithms to solve CEC2006, namely, adaptive hybrid DE algorithm (AH-DEa) [211], self-adaptive multi-operator genetic algorithm (SAMO-GA) [24], self-adaptive algorithm with multi-operator strategy (SAMO-DE) [24], improved version of SAMO-DE (ISAMODE-CMA) [47], adaptive penalty formulation with GA (APF-GA) [130], EP based on ensemble of constraint-handling techniques ECHT-EP2 [146], DE based on ensemble of constraint-handling techniques ECHT-DE [146], rank based multi-operator DE algorithm (rank-iMDDE) [212], $\epsilon$ DEg with Gradient-Based Mutation $\epsilon$ DE [141], artificial immune system based approach for COPs (AIS-ZYH) [213], modified JADE with R2S (MJADE-R2S) described in Chapter 5, and modified landscapebased multi-operator DE (MLS-MODE) described in Chapter 4.

Detailed results obtained from MEA-LS-R2S, based on 200000 FEs and the state-of-the-art algorithms, are presented in Appendix D, (Tables D.6, D.7, D.8, D.9, D.10, D.11), which shows the known optimal solutions for each problem and
the mean and standard deviation (Std.) results obtained from 25 runs.

It must be mentioned, that whereas MEA-LS-R2S used 200000 FEs, ISAMODECMA, SAMO-DE, ECHT-EP2, ECHT-DE2, SAMO-GA, rank-iMDDE and AHDEa used 240000, and APF-GA, MDE and $\epsilon \mathrm{DEg}$ used 500000. Also, as all the algorithms solved 22 of the 24 test problems, the analysis is based on those 22 . The proposed MEA-LS-R2S algorithm was able to obtain optimal solutions for all of these 22 problems with $100 \%$ feasibility and success rates.

Table 6.12 presents a comparison of these algorithms. MEA-LS-R2S was better than AH-DEa, SAMO-GA, SAMO-DE, AIS-ZHY, ECHT-EP2, APF-GA, ECHTDE, ISAMODE-CMA, $\epsilon$ DEg, rank-iMDDE, MJADE-R2S and MLS-MODE for 7, 11, $8,6,6,10,6,2,1,2,8$ and 7 test problems, respectively, but inferior to SAMO-GA and APF-GA for 2 and 1, respectively.

Considering the Wilcoxon signed-rank test, MEA-LS-R2S was significantly better than AH-DEa, SAMO-GA, SAMO-DE, AIS-ZHY, ECHT-EP2, ECHT-DE, APF-GA, MJADE-R2S and MLS-MODE. Although there was no significant difference between it and ISAMODE-CMA, DEg and rank-iMDDE, there was a bias towards it in terms of its number of better functions. One advantage of MEA-LSR2S was its capability to reach optimal solutions faster than ISAMODE-CMA, $\epsilon \mathrm{DEg}$ and rank-iMDDE. In summary, the average numbers of FEs consumed by MEA-LS-R2S, MLS-MODE, ISAMODE-CMA, DEg and rank-iMDDE were 42332, 53377, 76420, 79659 and 65,906, respectively, which means that MEA-LS-R2S took $20.69 \%, 44.61 \%, 46.86 \%$ and $35.77 \%$ fewer FEs than MLS-MODE, ISAMODECMA, $\epsilon \mathrm{DEg}$ and rank-iMDDE, respectively.

For further analysis, a Friedman test is carried out to rank all algorithms, with their rank is presented in Table 6.13. The highest ranking is shown in boldface.

Table 6.12: Summary of comparisons of the proposed MEA-LS-R2S and the state-of-the-art algorithms, where 'Dec.' statistical decision based on Wilcoxon signed-rank test results

| Algorithms | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: |
| MEA-LS-R2S vs. AH-DEa | 7 | 15 | 0 | + |
| MEA-LS-R2S vs. SAMO-GA | 11 | 9 | 2 | + |
| MEA-LS-R2S vs. SAMO-DE | 8 | 14 | 0 | + |
| MEA-LS-R2S vs. AIS-ZHY | 6 | 16 | 0 | + |
| MEA-LS-R2S vs. ECHT-EP2 | 6 | 16 | 0 | + |
| MEA-LS-R2S vs. ECHT-DE | 6 | 16 | 0 | + |
| MEA-LS-R2S vs. APF-GA | 10 | 11 | 1 | + |
| MEA-LS-R2S vs. ISAMODE-CMA | 2 | 20 | 0 | $\approx$ |
| MEA-LS-R2S vs. $\epsilon$ DEg | 1 | 21 | 0 | $\approx$ |
| MEA-LS-R2S vs. rank-iMDDE | 2 | 20 | 0 | $\approx$ |
| MEA-LS-R2S vs. MJADE-R2S | 8 | 14 | 0 | + |
| MEA-LS-R2S vs. MLS-MODE | 7 | 15 | 0 | + |

Table 6.13: Average ranking of MEA-LS-R2S, EHCT-DE, AIS-ZHY,ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA, rank-iMDDE, MJADE-R2S and MLS-MODE by the Friedman test for the 22 functions in terms of mean value

| Algorithms | Mean rank |
| :---: | :---: |
| MEA-LS-R2S | $\mathbf{5 . 4 3}$ |
| EHCT-DE | 7.43 |
| AIS-ZYH | 6.82 |
| ISAMODE-CMA | 5.98 |
| SAMODE | 7.66 |
| ECHT-EP2 | 6.80 |
| $\epsilon$ DE | 5.50 |
| AH-DEa | 7.61 |
| SAMO-GA | 8.95 |
| APF-GA | 8.25 |
| Rank-iMDDE | 5.89 |
| MJADE-R2S | 6.91 |
| MLS-MODE | 7.61 |

As seen, MEA-LS-R2S obtained the best ranking, while $\epsilon \mathrm{DE}$ came the second.

### 6.3.2.2 Comparisons of MEA-LS-R2S and state-of-the-art algorithms for CEC2010

The proposed MEA-LS-R2S was also compared with the state-of-the-art algorithms for solving CEC2010, namely, constrained DE with an archive and gradientbased mutation ( $\epsilon$ DEag) [214], which won the CEC2010 COP competition, selfadaptive multi-operator DE (SAMODE), DE combined with DE-DBmax (DEDBmax) [215], co-evolutionary comprehensive learning particle swarm optimizer (Co-CLPSO) [216], adaptive ranking mutation operator-based DE (ECHT-ARMORDE) [179], elitist artificial bee colony (eABC) [217], multi-operator GA (SAMOGA) [39], constraint-consensus mutation based DE (DEbavCC) [218], modified JADE with R2S described in Chapter 5, and modified landscape-based multioperator DE (MLS-MODE) described in Chapter 4.

Detailed results obtained from them based on $20000 \times D$ FEs, shown in Appendix D, Tables D.12, D.13, D.14, D.15, D.16, D.17.

Regarding the feasibility rate, MEA-LS-R2S, SAMO-DE, DE-DBmax and DEbavDBmax were able to obtain a $100 \%$ feasibility rate for the $10 D$ and $30 D$ test problems while $\epsilon$ DEag achieved a $100 \%$ feasibility ratio for the $10 D$ and for only 35 of 36 for $30 D$ test problems, with only a $12 \%$ rate for C12 with $30 D$. CoCLPSO was able to achieve $94.4 \%$ and $87.3 \%$ for the $10 D$ and $30 D$ test problems respectively, with the others were also unable to produce a $100 \%$ ratio.

In terms of the quality of solutions, a summary of the results is presented in Table 6.14. For $10 D$, MEA-LS-R2S was better than DEbavDBmax, SAMODE, $\epsilon$ DEag, DE-DBmax, Co-CLPSO, eABC, SAMO-GA, ECHT-ARMOR-DE, MJADER2S and MLS-MODE for $4,1,5,6,13,16,10,7,8$ and 4 test problems respectively, but inferior to these algorithms for $0,1,1,0,0,1,1,0,0$ and 0 , respectively for
the best results. In terms of the average results for $10 D$, MEA-LS-R2S was better than DEbavDBmax, SAMODE, $\epsilon$ DEag, DE-DBmax, Co-CLPSO, eABC, SAMOGA, ECHT-ARMOR-DE, MJADE-R2S and MLS-MODE for $11,10,7,15,17,17$, $15,9,13$ and 5 test problems, respectively, but inferior to these algorithms for 2 , $5,3,1,1,1,3,4,2$ and 2 , respectively.

For $30 D$, in terms of the best results, MEA-LS-R2S was superior to DEbavDBmax, SAMODE, $\epsilon$ DEag, DE-DBmax, eABC, Co-CLPSO, SAMO-GA, ECHT-ARMOR-DE, MJADE-R2S and MLS-MODE for $6,12,16,7,16,15,13,11,8$ and 5 test problems, respectively, but inferior to these algorithms for 3, 4, 1, 3, $2,2,4,33$ and 1, respectively, while for the average results MEA-LS-R2S was better than DEbavDBmax, SAMODE, $\epsilon$ DEag, DE-DBmax, eABC, Co-CLPSO, SAMO-GA, ECHT-ARMOR-DE, MJADE-R2S and MLS-MODE for 12, 13, 16, $13,17,16,14,14,14$ and 19 , respectively, but inferior to these algorithms for 4, $5,2,3,1,2,4,3,3$ and 4 , respectively.

Regarding the Wilcoxon signed-rank test, for the $10 D$ test problems, MEA-LS-R2S was significantly better than DEbavDBmax, DE-DBmax, eABC, CoCLPSO, SAMO-GA and MJADE-R2S in terms of best and average results obtained and ECHT-ARMOR-DE and MLS-MODE in terms of best results obtained, while there is no significance difference between MEA-LS-R2S and SAMODE and $\epsilon$ DEag. For the $30 D$ test problems, MEA-LS-R2S was significantly better than $\epsilon$ DEag, eABC, Co-CLPSO, ECHT-ARMOR-DE and MJADE-R2S in terms of both the best and average results obtained, and DE-DBmax and SAMO-GA for average results obtained, while there is no significance difference in the remaining cases.

For further analysis, a Friedman test was used to rank all the algorithms according to their best and averages results, presented in Table 6.15 and Figure

Table 6.14: Summary of comparison of MEA-LS-R2S and state-of-the-art algorithms for CEC2010

|  | Algorithms | Criteria | Better | Equal | Worse | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10D | MEA-LS-R2S vs. DEbavDBmax | Best | 4 | 14 | 0 | + |
|  |  | Average | 11 | 5 | 2 | + |
|  | MEA-LS-R2S vs. SAMODE | Best | 1 | 16 | 1 | $\approx$ |
|  |  | Average | 10 | 3 | 5 | $\approx$ |
|  | MEA-LS-R2S vs. $\epsilon$ DEag | Best | 5 | 12 | 1 | $\approx$ |
|  |  | Average | 7 | 8 | 3 | $\approx$ |
|  | MEA-LS-R2S vs. DE-DBmax | Best | 6 | 12 | 0 | + |
|  |  | Average | 15 | 2 | 1 | + |
|  | MEA-LS-R2S vs. eABC | Best | 16 | 1 | 1 | + |
|  |  | Average | 17 | 0 | 1 | + |
|  | MEA-LS-R2S vs. Co-CLPSO | Best | 14 | 4 | 0 | + |
|  |  | Average | 17 | 0 | 1 | + |
|  | MEA-LS-R2S vs. SAMO-GA | Best | 10 | 7 | 1 | + |
|  |  | Average | 15 | 0 | 3 | + |
|  | MEA-LS-R2S vs. ECHT-ARMOR-DE | Best | 7 | 11 | 0 | + |
|  |  | Average | 9 | 5 | 4 | $\approx$ |
|  | MEA-LS-R2S vs. MJADE-R2S | Best | 8 | 10 | 0 | + |
|  |  | Average | 13 | 3 | 2 | + |
|  | MEA-LS-R2S vs. MLS-MODE | Best | 4 | 14 | 0 | + |
|  |  | Average | 5 | 11 | 2 | $\approx$ |
| 30D | MEA-LS-R2S vs. DEbavDBmax | Best | 6 | 9 | 3 | $\approx$ |
|  |  | Average | 12 | 2 | 4 | $\approx$ |
|  | MEA-LS-R2S vs. SAMODE | Best | 12 | 2 | 4 | $\approx$ |
|  |  | Average | 13 | 0 | 5 | $\approx$ |
|  | MEA-LS-R2S vs. $\epsilon$ DEag | Best | 16 | 1 | 1 | + |
|  |  | Average | 16 | 0 | 2 | + |
|  | MEA-LS-R2S vs. DE-DBmax | Best | 7 | 8 | 3 | $\approx$ |
|  |  | Average | 13 | 2 | 3 | + |
|  | MEA-LS-R2S vs. eABC | Best | 16 | 0 | 2 | + |
|  |  | Average | 17 | 0 | 1 | + |
|  | MEA-LS-R2S vs. Co-CLPSO | Best | 15 | 1 | 2 | + |
|  |  | Average | 16 | 0 | 2 | + |
|  | MEA-LS-R2S vs. SAMO-GA | Best | 13 | 1 | 4 | $\approx$ |
|  |  | Average | 14 | 0 | 4 | + |
|  | MEA-LS-R2S vs. ECHT-ARMOR-DE | Best | 11 | 4 | 3 | + |
|  |  | Average | 14 | 1 | 3 | + |
|  | MEA-LS-R2S vs. MJADE-R2S | Best | 8 | 7 | 3 | + |
|  |  | Average | 14 | 1 | 3 | + |
|  | MEA-LS-R2S vs. MLS-MODE | Best | 5 | 12 | 1 | $\approx$ |
|  |  | Average | 10 | 4 | 4 | $\approx$ |

Table 6.15: Average rankings of MEA-LS-R2S, DEbavDBmax, SAMODE, $\epsilon$ DEag, DE-DBmax, eABC, Co-CLPSO, SAMO-GA and ECHT-ARMOR-DE, MLS-MODE and MJADE-R2S obtained from Friedman test

|  | Algorithms | Average rank based on best results obtained | Average rank based on, average results obtained | Overall rank |
| :---: | :---: | :---: | :---: | :---: |
| 10D | MEA-LS-R2S | 4.25 | 3.42 | 3.84 |
|  | DEbavDBmax | 5.11 | 5.42 | 5.27 |
|  | SAMODE | 4.44 | 4.92 | 4.68 |
|  | $\epsilon$ DEag | 5.47 | 4.67 | 5.07 |
|  | DE-DBmax | 5.69 | 6.78 | 6.24 |
|  | eABC | 10.19 | 10.25 | 10.22 |
|  | Co-CLPSO | 8.14 | 8.22 | 8.18 |
|  | SAMO-GA | 6.92 | 6.39 | 6.66 |
|  | ECHT-ARMOR-DE | 5.92 | 4.75 | 5.34 |
|  | MJADE-R2S | 4.86 | 7.83 | 6.35 |
|  | MLS-MODE | 5.00 | 3.36 | 4.18 |
| 30D | MEA-LS-R2S | 4.00 | 3.08 | 3.54 |
|  | DEbavDBmax | 4.03 | 3.86 | 3.95 |
|  | SAMODE | 5.67 | 4.78 | 5.23 |
|  | $\epsilon$ DEag | 8.53 | 6.64 | 7.59 |
|  | DE-DBmax | 4.22 | 4.64 | 4.43 |
|  | eABC | 9.83 | 10.22 | 10.03 |
|  | Co-CLPSO | 8.50 | 8.58 | 8.54 |
|  | SAMO-GA | 7.03 | 6.11 | 6.57 |
|  | ECHT-ARMOR-DE | 5.78 | 7.03 | 6.41 |
|  | MJADE-R2S | 4.61 | 7.75 | 6.18 |
|  | MLS-MODE | 3.81 | 3.70 | 3.76 |

6.4 in which it can be seen that MEA-LS-R2S ranked first of the 9 algorithms for both $10 D$ and $30 D$.

### 6.3.2.3 Comparisons of MEA-LS-R2S and state-of-the-art algorithms for CEC2011

In this section the proposed MEA-LS-R2S algorithm is judged by solving the 10 real-world application problems taken from the CEC2011 [181] competition on real-world optimization problems. Its performance is compared with the state-of-the-art algorithms, namely, continuous DE ant-stigmergy algorithm (CDASA) for solving CEC2011 competition problems [219], adaptive DE algorithm (ADE) for solving CEC2011 competition problems [220], ensemble DE algorithm (EPSDE)


Figure 6.4: Overall rankings of MEA-LS-R2S, DEbavDBmax, SAMODE, $\epsilon$ DEag, DE-DBmax, eABC, Co-CLPSO, SAMO-GA, ECHT-ARMOR-DE, MJADE-R2S and MLS-MODE obtained from Friedman test (a) based on 10D; and (b) based on $30 D$
for solving CEC2011 competition problems [221], DE with multi-population strategies (SAMODE) for solving CEC2011 competition problems [23], DE with adaptive crossover rate (DE-Acr) and a competitive DE with local search for solving CEC2011 competition problems [223], modified DE with local search (CDELS)
for solving CEC2011 competition problems [222], hybrid EA-DE-Memetic Algorithm (EA-DE-MA) for solving CEC2011 competition problems [228], improved version of SAMO-DE (ISAMODE-CMA) [47], modified JADE with R2S described in Chapter 5, and modified landscape-based multi-operator DE (MLS-MODE) described in Chapter 4.

Detailed results obtained from them based on 150000 FEs shown in Appendix D, Tables D.18, D.19, D.20. Note that all the state-of-the-art algorithms used in this comparison, solve these test problems as unconstrained optimization problems, and there are no details about whether the optimal solution obtained is feasible or not.

Considering the quality of solutions, a summary of the results is presented in Table 6.16. In terms of the best results, MEA-LS-R2S was better than CDASA, ADE, EPSDE, SAMODE, DE-Acr, CDELS, EA-DE-MA, ISAMODE-CMA, MJADER2S and MLS-MODE for $10,10,7,8,8,10,10,8,7$ and 6 , respectively, but inferior to these algorithms for $0,0,2,2,2,0,0,2,3$ and 3 , respectively. In regards to the mean results, MEA-LS-R2S was superior to CDASA, ADE, EPSDE, SAMODE, DE-Acr, CDELS, EA-DE-MA, ISAMODE-CMA, MJADE-R2S and MLS-MODE for $10,10,8,8,7,10,10,8,7$ and 7 , respectively, but worse than these algorithms for $0,0,2,2,3,0,0,2,2$ and 2 , respectively.

Based on the Wilcoxon signed-rank test, it was clear that MEA-LS-R2S was significantly better than all algorithms, except SAMODE, ISAMODE-CMA and MLS-MODE for best results and DE-Acr and MJADE-R2S for both best and average results.

Also, a Friedman test was conducted to rank all the algorithms in terms of both best and average results, with the ranks presented in Table 6.17 and Figure

Table 6.16: Summary of comparison of MEA-LS-R2S and state-of-the-art algorithms CEC2011

| Algorithms | Best results |  |  |  | Mean results |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Better | Equal | Worse | Dec. | Better | Equal | Worse | Dec. |
| MEA-LS-R2S vs. CDASA | 10 | 0 | 0 | + | 10 | 0 | 0 | + |
| MEA-LS-R2S vs. ADE | 10 | 0 | 0 | + | 10 | 0 | 0 | + |
| MEA-LS-R2S vs. EPSDE | 7 | 1 | 2 | + | 8 | 0 | 2 | + |
| MEA-LS-R2S vs. SAMODE | 8 | 0 | 2 | $\approx$ | 8 | 0 | 2 | + |
| MEA-LS-R2S vs. DE-Acr | 8 | 0 | 2 | $\approx$ | 7 | 0 | 3 | + |
| MEA-LS-R2S vs. CDELS | 10 | 0 | 0 | + | 10 | 0 | 0 | + |
| MEA-LS-R2S vs. EA-DE-MA | 10 | 0 | 0 | + | 10 | 0 | 0 | + |
| MEA-LS-R2S vs. ISAMODE-CMA | 8 | 0 | 2 | $\approx$ | 8 | 0 | 2 | + |
| MEA-LS-R2S vs. MJADE-R2S | 7 | 0 | 3 | $\approx$ | 7 | 1 | 2 | $\approx$ |
| MEA-LS-R2S vs. MLS-MODE | 6 | 1 | 3 | $\approx$ | 7 | 1 | 2 | + |

Table 6.17: Average rankings of MEA-LS-R2S, CDASS, ADE, EPSDE, SAMODE, DE-Acr, CDELS, EA-DE-MA, ISAMODE-CMA, MJADE-R2S and MLS-MODE obtained from Friedman test

| Algorithms | Average rank based on <br> best results obtained | Average rank based on <br> average results obtained |
| :---: | :---: | :---: |
| MEA-LS-R2S | $\mathbf{2 . 6 0}$ | $\mathbf{2 . 3 5}$ |
| CDASA | 9.10 | 9.40 |
| ADE | 6.90 | 7.50 |
| EPSDE | 6.40 | 6.50 |
| SAMODE | 4.95 | 5.50 |
| DE-Acr | 4.05 | 3.50 |
| CDELS | 10.15 | 9.25 |
| EA-DE-MA | 10.20 | 10.40 |
| ISAMODE-CMA | 4.25 | 3.90 |
| MJADE-R2S | 3.30 | 3.35 |
| MLS-MODE | 4.10 | 4.35 |

6.5. From which it is clear that the proposed MEA-LS-R2S was ranked first.

Furthermore, the performance profiles depicted in Figure 6.6 show that MEA-LS-R2S was the best for both best and average results.

Also, the proposed MEA-LS-R2S is able to obtain better solutions faster than MJADE-R2S and MLS-MODE. In summary, the average computational time that are taken by MEA-LS-R2S is 61.7, while MJADE-R2S and MLS-MODE take 73.29 and 87.97 , respectively, which means that MEA-LS-R2S is able to save $15.70 \%$ and $29.77 \%$ of computational time in comparison to MJADE-R2S and MLS-MODE,

(b)

Figure 6.5: Rankings of MEA-LS-R2S, CDASS, ADE, EPSDE, SAMODE, DE-Acr, CDELS, EA-DE-MA, ISAMODE-CMA, MJADE-R2S and MLS-MODE obtained from Friedman test (a) based on best results; and (b) based on average results


Figure 6.6: Comparison of performance profiles of MEA-LS-R2S, CDASA, ADE, EPSDE, SAMODE, DE-Acr, CDELS, EA-DE-MA, ISAMODE-CMA, MJADE-R2S and MLS-MODE (a) based on best results; and (b) based on average results
respectively. The performance profiles depicted in Figure 6.7 show that MEA-LS-
R2S was the best in terms of computational time.

(a)

Figure 6.7: Comparison of performance profiles of MEA-LS-R2S, MJADE-R2S and MLS-MODE based on the average computational time

### 6.4 Chapter Summary

Motivated by the encouraging results obtained from the proposed landscape based algorithms in Chapters 3 and Chapter 4, and the proposed search space reduction mechanism in Chapter 5, in this chapter, a new multi-EA algorithms, which utilizes information from the problem's landscape and search space, namely MEA-LS-R2S, was proposed.

MEA-LS-R2S was tested by solving 22 test problems taken from CEC2006, 36 test problems taken from CEC2010, and 10 test problems taken from CEC2011. The results from MEA-LS-R2S were compared with those from state-of-the-art algorithms, and based on the quality of solutions obtained and non-parametric statistical testing, the results showed the superiority of the proposed MEA-LSR2S.

Finally, based on the quality of solutions obtained, and the non-parametric statistical test results, MEA-LS-R2S was compared with the proposed methods in Chapter 4 and Chapter 5 (JADE-R2 and MLS-MODE, respectively), which demonstrated its superiority in all cases.

## Chapter 7

## Conclusions and Future Research

## Directions

The research conducted and discussed in this thesis is summarized in this chapter, and its conclusions and suggestions for possible future work presented.

### 7.1 Summary of Research Conducted

In this section, a summary of the research conducted in this thesis is presented.

### 7.1.1 summary of research conducted in chapters one and two

As discussed in Chapters 1 and 2, optimization problems, which can be classified as unconstrained or constrained, have different characteristics and mathematical properties that make the process of finding optimal solutions to them difficult. Of the existing solutions techniques developed, evolutionary algorithms (EAs) have demonstrated great success. However, researchers and practitioners acknowledged that, the performances of such methods are highly dependent on an algorithm's design, and the choice of its search operators and control parameters. Also, the most suitable EA and/or its search operators for solving a particular problem is often determined using a trail-and-error approach rather than any useful information about the problems landscape. Furthermore, one EA, search operator and/or set of parameters well suited for a certain set of problems may not work well for another, as is evident in the literature. Although fitness landscape analysis (FLA)
has been widely used to judge a problem's complexity, it has not been fully explored in relation the designs of algorithms. Also, in most COPs, the optimal solution lies on the intersection of its active constraints. This basic information may help to concentrate the search process in certain regions instead of the entire search space and speed up the process of locating the optimal solution.

As discussed in Chapter 1, the main objective of this study was to use information from the problem landscape and search space to boost the performances of EAs. To achieve this main goal, four related aspects were introduced as follows: the first one was to propose a new algorithm that uses landscape information to select the most suitable DE , from a pool of them, during the evolutionary process for solving unconstrained optimization problems. The second was to propose an algorithm which utilizes the strength of more than one DE and choose the best one based on the objective function and constraints landscapes for solving COPs. The third was to propose a mechanism for reducing the search space by focusing the search on the area around the active constraints. The fourth was to propose an algorithm that uses multiple EAs and both a reduced search space mechanism and landscape information to solve COPs. These four goals have been achieved in Chapters 3 to 6 .

### 7.1.2 summary of research conducted in chapter three

In Chapter 3, an algorithm that uses the function landscape to choose the best-performing differential evolution (DE) from a set was developed. In it, several different DE operators are used to evolve the entire population for a pre-defined number of generations ( $C S$ ). Concurrently, the function landscape and success rate of each DE operator are calculated and stored in every generation, with the best-performing one based on their normalized measures used to evolve the entire population for the subsequent cycle, a process which continues until the stopping
criteria are satisfied. The proposed algorithm was used to solve two specialized sets of unconstrained optimization problems and an analysis of its components undertaken. Its results were presented and compared with those of seven of its variants as well as several state-of-the-art algorithms.

### 7.1.3 summary of research conducted in chapter four

In Chapter 4, a landscape-based algorithm for solving COPs, in which information from the objective function and constraint landscapes is used to choose the best operator from a pool during the evolutionary process, was proposed. It starts with a random population generated by the Latin hyper-cube design mechanism and then several DE mutation strategies are used to evolve the entire population. After a certain number of generations, the best strategy based on the problems landscape is selected to evolve subsequent populations, a process that continues until the stopping condition is met. Its different components were analyzed and then the experimental results obtained from it and several state-of-the-art algorithms for solving different sets of COPs were compared.

### 7.1.4 Summary of research conducted in chapter five

In Chapter 5, a new reduced search space (R2S) mechanism, which automatically identifies the active constraints based on the current solutions and uses this information to determine the most promising boundary zone for searching, was proposed. Its different components were analyzed and it was integrated in six state-of-the-art algorithms for solving COPs, with the experimental results obtained from algorithms both with and without it compared.

### 7.1.5 Summary of research conducted in chapter six

In Chapter 6, a new multi-EA algorithm that uses information from the search space and problem's landscape was proposed. Its different components were analyzed and then the experimental results obtained from it and other state-of-the-art algorithm for solving different sets of COPs compared.

### 7.2 Summary of Conclusions

The conclusions drawn from this study can be summarized as follows.

### 7.2.1 Landscape-based algorithm for unconstrained problems

In chapter 3,11 variants of DE mutation strategies were tested by solving 30 unconstrained optimization problems. The results obtained showed that there was no single one was able to attain the best results for all test problems. However, the $\mathrm{DE} /$ current-to- $\varphi$ best/ 1 without archive was better than all others, with the $\mathrm{DE} /$ current-to- $\varphi$ best $/ 1$ archive ranked second and $\mathrm{DE} / \varphi$ best $/ 1$ third.

Based on the five parametric analysis performed in this chapter, the best parameters were set as follows: the number of DE operators $(m)$ initially of 5 and reduced from 5 to 1 every two cycles, $N P^{\text {init }} 25 \times D, N P^{\min }$ of 7 and $C S 150$.

The results obtained from the proposed LSAOS-DE and seven of its variants, with the only difference among them their selection mechanisms, were compared. LSAOS-DE was shown to perform competitively against the others and be capable of saving $15.1 \%$ of computational time and $15.7 \%$ of the number of fitness evaluations (FEs). Also, compared with several state-of-the-art algorithms, it was either competitive or better.

### 7.2.2 Landscape-based algorithm for constrained problems

In Chapter 4, the results obtained by MLS-MODE for solving three specialized COPs were presented and analyzed.

Based on the parametric analysis, the best parameters were set as $N P^{\text {init }} 150$, $N P^{\min } 40, C S 125$, with the self-adaptation of the control parameters proven to be better than using fixed values.

MLS-MODE showed its superiority over four of its variants, the only differences among which were their selection mechanisms, by obtaining savings in computational time and the number of FEs of up to $69 \%$ and $33 \%$, respectively. Compared with several state-of-the-art algorithms, it was more competent and capable of reaching $100 \%$ feasibility ratios for all the test problems.

### 7.2.3 Reduced search space mechanism for constrained problems

In Chapter 5, a R2S mechanism for constrained problems, which was easily incorporated in six well-known algorithms, was proposed.

It was capable of determining the active constraints with a $96 \%$ success rate and helped the algorithms improve the quality of solutions, with savings in computational time and the number of FEs of up to $36.69 \%$ and $11.88 \%$, respectively. Also, it could be easily integrated in other algorithms used to solve COPs.

### 7.2.4 Multi-EA framework for constrained problems

In Chapter 6, to take advantage of the benefits of both a problem's landscape and the R2S mechanism, a new multi-EA (MEA-LS-R2S) algorithm was proposed.

MEA-LS-R2S was tested and analyzed by solving three specialized COPs.

Firstly, based on a parametric analysis, it was concluded that it is better to use a $N P^{\text {init }}$ of $100, N P^{\min }$ of $4, C S$ of $25, m$ of 2 and mechanism for linearly reducing the population than a fixed population size.

Secondly, based on the results obtained from three variants of the proposed algorithm, it was found that Var3 (that used MODE and CMA-ES) was better than Var2 (that used MODE, MOGA and CMA-ES) and Var1 (that used MOGA and CMA-ES). Also, Var3 was able to save up to $44.5 \%$ of computational time and $21.3 \%$ of the number of FEs compared with those of the other two variants.

Finally, the proposed MEA-LS-R2S was either competitive with or better than several state-of-the-art algorithms and capable of reaching $100 \%$ feasibility ratios for all the test problems.

### 7.3 Link to Real-World Applications

In chapters 4,5 and 6 , the performance of the proposed algorithms were tested on 10 real-world applications problems, in which the proposed algorithms were either competitive with or better than many state-of-the-art algorithms. Also, in another work, not included in this thesis, an algorithm that uses the landscape information to choose the best-performing DE operators, among many, was proposed and used to solve a set of real-world applications problems (TP-MODE). The results obtained from TP-MODE was compared with those obtained from many of the state-of-the-art algorithms, showing that the performance of TP-MODE was better. The whole paper is presented in Appendix E.

### 7.4 Future Research Directions

The algorithms developed in this thesis could be extended by:

1. testing LSAOS-DE on more unconstrained optimization problems;
2. using more than one landscape measure to choose the most suitable EA and/or its search operators during the evolutionary process;
3. developing other landscape-based CI algorithms, such as GA and particle swarm optimization;
4. applying all the algorithms to solving large-scale optimization problems using decomposition techniques;
5. adopting all the algorithms to solve multi- and many-objective problems in which interest is increasing;
6. enhancing the performances of the algorithms by using local and/or multilocal search approaches;
7. incorporating the R2S mechanism in other EAs;
8. applying the proposed algorithms to solving dynamic optimization problems;
9. implementing surrogate models in all the proposed algorithms to reduce their numbers of FEs;
10. using a problems landscape to choose the best surrogate model from a set; and/or
11. proposing an algorithm that utilizes more than one mutation strategies, more than one crossover operators and more than one parameter adaptation techniques;

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## Appendices

In this section, detailed results from all the proposed algorithms are presented in four appendices, each containing different tables.

1. Appendix A: computational results from proposed landscape-based algorithm for solving unconstrained optimization problems.
2. Appendix B: computational results from proposed landscape-based algorithm for solving constrained optimization problems.
3. Appendix C: computational results from proposed reduced search space mechanism for solving constrained optimization problems.
4. Appendix D: computational results from proposed multi-EAs framework for solving constrained optimization problems.
5. Appendix E: published paper entitled "Two-phase Differential Evolution Framework for Solving Optimization Problems".

## Appendix A

Table A.1: Error values obtained by LSAOS-DE for 10D, 30D, and 50D

| Prob. | 10D |  |  | 30D |  |  | 50D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. |
| F01 | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $6.560 \mathrm{E}+01$ | $2.062 \mathrm{E}+03$ | $2.499 \mathrm{E}+03$ |
| F02 | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $7.021 \mathrm{E}-08$ | $2.053 \mathrm{E}-07$ |
| F03 | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ |
| F04 | $0.000 \mathrm{E}+00$ | $1.654 \mathrm{E}+01$ | $1.739 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $7.186 \mathrm{E}-05$ | $3.060 \mathrm{E}-04$ | $0.000 \mathrm{E}+00$ | $1.924 \mathrm{E}+01$ | $3.934 \mathrm{E}+01$ |
| F05 | $1.123 \mathrm{E}+00$ | $1.376 \mathrm{E}+01$ | $7.896 \mathrm{E}+00$ | $2.000 \mathrm{E}+01$ | $2.025 \mathrm{E}+01$ | $8.289 \mathrm{E}-02$ | $2.000 \mathrm{E}+01$ | $2.000 \mathrm{E}+01$ | $2.302 \mathrm{E}-03$ |
| F06 | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $4.491 \mathrm{E}-02$ | $1.648 \mathrm{E}-01$ | $9.308 \mathrm{E}-02$ | $1.198 \mathrm{E}+00$ | $7.815 \mathrm{E}-01$ |
| F07 | $0.000 \mathrm{E}+00$ | $1.014 \mathrm{E}-03$ | $3.311 \mathrm{E}-03$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $3.093 \mathrm{E}-03$ | $4.645 \mathrm{E}-03$ |
| F08 | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ |
| F09 | $0.000 \mathrm{E}+00$ | $8.418 \mathrm{E}-01$ | $1.294 \mathrm{E}+00$ | $1.285 \mathrm{E}+00$ | $4.686 \mathrm{E}+00$ | $1.618 \mathrm{E}+00$ | $9.950 \mathrm{E}+00$ | $1.632 \mathrm{E}+01$ | $2.962 \mathrm{E}+00$ |
| F10 | $0.000 \mathrm{E}+00$ | $2.449 \mathrm{E}-03$ | $1.749 \mathrm{E}-02$ | $2.070 \mathrm{E}-08$ | $9.175 \mathrm{E}-03$ | $1.590 \mathrm{E}-02$ | $1.222 \mathrm{E}-01$ | $1.730 \mathrm{E}+00$ | $1.486 \mathrm{E}+00$ |
| F11 | $1.458 \mathrm{E}+00$ | $5.147 \mathrm{E}+01$ | $4.879 \mathrm{E}+01$ | $1.028 \mathrm{E}+03$ | $1.603 \mathrm{E}+03$ | $4.422 \mathrm{E}+02$ | $2.654 \mathrm{E}+03$ | $3.992 \mathrm{E}+03$ | $7.883 \mathrm{E}+02$ |
| F12 | 5.808E-03 | $1.493 \mathrm{E}-01$ | $9.303 \mathrm{E}-02$ | 4.091E-02 | $3.020 \mathrm{E}-01$ | $1.229 \mathrm{E}-01$ | $3.558 \mathrm{E}-02$ | $6.974 \mathrm{E}-02$ | $2.275 \mathrm{E}-02$ |
| F13 | $1.550 \mathrm{E}-02$ | $5.062 \mathrm{E}-02$ | $1.337 \mathrm{E}-02$ | $8.075 \mathrm{E}-02$ | $1.215 \mathrm{E}-01$ | $1.754 \mathrm{E}-02$ | $1.423 \mathrm{E}-01$ | $1.942 \mathrm{E}-01$ | $2.041 \mathrm{E}-02$ |
| F14 | $2.559 \mathrm{E}-02$ | $1.055 \mathrm{E}-01$ | $3.073 \mathrm{E}-02$ | $1.677 \mathrm{E}-01$ | $2.180 \mathrm{E}-01$ | $2.384 \mathrm{E}-02$ | $2.478 \mathrm{E}-01$ | $2.915 \mathrm{E}-01$ | $1.881 \mathrm{E}-02$ |
| F15 | $2.537 \mathrm{E}-01$ | $4.033 \mathrm{E}-01$ | $6.565 \mathrm{E}-02$ | $1.954 \mathrm{E}+00$ | $2.489 \mathrm{E}+00$ | $2.390 \mathrm{E}-01$ | $3.173 \mathrm{E}+00$ | $4.674 \mathrm{E}+00$ | $8.364 \mathrm{E}-01$ |
| F16 | $2.857 \mathrm{E}-01$ | $1.265 \mathrm{E}+00$ | $3.423 \mathrm{E}-01$ | $8.141 \mathrm{E}+00$ | $9.244 \mathrm{E}+00$ | $5.547 \mathrm{E}-01$ | $1.673 \mathrm{E}+01$ | $1.815 \mathrm{E}+01$ | $9.651 \mathrm{E}-01$ |
| F17 | $0.000 \mathrm{E}+00$ | $1.044 \mathrm{E}+00$ | $1.010 \mathrm{E}+00$ | $4.414 \mathrm{E}+01$ | $1.358 \mathrm{E}+02$ | $7.155 \mathrm{E}+01$ | $4.355 \mathrm{E}+02$ | $1.044 \mathrm{E}+03$ | $3.560 \mathrm{E}+02$ |
| F18 | $2.015 \mathrm{E}-03$ | $1.298 \mathrm{E}-01$ | $1.431 \mathrm{E}-01$ | $2.206 \mathrm{E}+00$ | $6.345 \mathrm{E}+00$ | $2.562 \mathrm{E}+00$ | $6.496 \mathrm{E}+01$ | $8.604 \mathrm{E}+01$ | $1.057 \mathrm{E}+01$ |
| F19 | $2.147 \mathrm{E}-02$ | $7.844 \mathrm{E}-02$ | $5.921 \mathrm{E}-02$ | $1.888 \mathrm{E}+00$ | $3.251 \mathrm{E}+00$ | $5.955 \mathrm{E}-01$ | $7.720 \mathrm{E}+00$ | $1.059 \mathrm{E}+01$ | $8.509 \mathrm{E}-01$ |
| F20 | $6.715 \mathrm{E}-03$ | $1.751 \mathrm{E}-01$ | $1.673 \mathrm{E}-01$ | $1.439 \mathrm{E}+00$ | $3.856 \mathrm{E}+00$ | $1.294 \mathrm{E}+00$ | $5.075 \mathrm{E}+00$ | $1.126 \mathrm{E}+01$ | $3.977 \mathrm{E}+00$ |
| F21 | $1.227 \mathrm{E}-05$ | $2.879 \mathrm{E}-01$ | $2.435 \mathrm{E}-01$ | $1.606 \mathrm{E}+00$ | $3.223 \mathrm{E}+01$ | $4.474 \mathrm{E}+01$ | $1.338 \mathrm{E}+02$ | $4.149 \mathrm{E}+02$ | $1.200 \mathrm{E}+02$ |
| F22 | 4.203E-02 | $1.220 \mathrm{E}-01$ | $4.574 \mathrm{E}-02$ | $2.320 \mathrm{E}+01$ | $3.361 \mathrm{E}+01$ | $1.711 \mathrm{E}+01$ | $2.231 \mathrm{E}+01$ | $1.497 \mathrm{E}+02$ | $8.477 \mathrm{E}+01$ |


| ¢L－H679 ${ }^{\text {I }}$ |  | 70＋H000＇I | \＆L－马Scz： | 70＋年000＊ | 70＋ $3000 \cdot \mathrm{~L}$ | 00＋ 0 H000．0 | 70＋ 3000 I |  | 9\％臬 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ¢0＋${ }^{\text {¢ }} 066 \varepsilon^{-} \mathrm{C}$ | ㄷ0＋旦 886.9 |  | 70＋䛼LL6．9 |  | モ0＋G7LI＇¢ |  | $80+4 \pm ¢ 6.7$ |  | 玨直 |
| 80－GLze＇t | 70－H298：8 | 70－HE88： 2 | モ0－乌tモc．9 | 70－H8¢9 \％ | 70－H899． 7 | ¢0－－ $8897 \times$ | 70－H8ฑ0＇¢ | 70－H7币0＇¢ | 8も号 |
| L0－HE08 7 | 70＋4790． | 70＋ | L0－G966． |  | 70＋号670＊ | 10－gzel $\%$ | 70＋ $7800{ }^{\text {I }}$ |  | 7ヵ二 |
| L0＋G7cr．${ }^{\text {\％}}$ | 70＋唯97だも | 70＋G600＇ォ | 00＋斗9969 | 70＋早800＇ォ | 70＋马 $000{ }^{\text {² }}$ | z0＋G2ti．L | 10＋G7Lİ9 | L0－G99\％L | Lも， |
| L0＋早979＊6 | 70＋足978．8 |  | 70＋GLE7． | 70＋足959 | 70＋鸟年09． | \＆I－HEZI＇I | 70＋G991．$\%$ | z0＋马99I＇ 7 | H |
| L0－H2I9 I | 70＋号0ฑ0 5 | 70＋鸟880． I | L0－GL币0＇I | 70＋G $2760^{\circ}$ I | 70＋岛も $70 \cdot \mathrm{~L}$ | 70－408\％ Z |  | 70＋鸟L00＇L | 68， |
| 10＋㘴987．8 | 70＋示6Iた | L0＋马g98． |  | 10＋马868 | 00＋马88¢ $\cdot 8$ | 10－ษ667．$\%$ | L0－H9t\＆$\%$ | 90－HzLZ＇9 | 88， |
| $00+48 L 2 \cdot 6$ | 10＋星660＇ஏ | L0＋GL06． 8 | 10－G0L2．9 | $00+$ 田LEF 9 | 00＋走006 ${ }^{\text {¢ }}$ | 70－H029＊6 | L0－H7ヵI＇I | 70－Ģte | 28． |
| 70＋勿モモ8． 7 | 80＋边矿 | z0＋号矿 9 | L0＋H9sc： 9 | 70＋过LEE L | 20＋早998． 7 | 00＋ |  | 00＋H000．0 | 98， |
| 70＋甶9¢\％ 9 | ¢0＋ HzEt f |  | 70＋ 789 ¢ ${ }^{\text {c }}$ | ¢0＋田L¢T | 70＋早07\％ 6 | L0＋Ggzc 9 | L0＋ $4897 \cdot \varepsilon$ | L0－ษ6㸬6 | 98， |
| 00＋ 2 LZだ 8 | L0＋ $\mathrm{H} 788{ }^{\text {．}}$ I |  |  | 00＋ | $00+$ 年 $600 \cdot 7$ | $00+$ H0Lf＇ | 00＋GLII ${ }^{\text {a }}$ | 00＋${ }^{\text {a }} 00000$ | モ\＆ |
| モ0－g¢70 9 | L0＋ 0 H000 7 | L0＋H000 z |  |  | L0＋ 0 H000 $\%$ | 00＋ $\mathrm{HELL} \cdot \mathrm{S}$ | L0＋G8LL． | $00+$ H6もt 7 | \＆\＆， |
| 00＋具000．0 | 00＋号000＊ | 00＋马 00000 | 00＋G000：0 |  | 00＋年000．0 | 00＋H000：0 | 00＋ $4000{ }^{\circ}$ | 00＋ 0 ［000 0 | 784 |
| $80+$ ge 98.1 | 70＋号L19．8 | L0＋ H 7 LI E | 00＋ $0^{\text {a }} 0000^{\circ}$ | 00＋ $0^{\text {a }} 0000^{\circ}$ | 00＋ $0^{-1000} 0$ | 00＋ 0 ［000．0 | 00＋ | 00＋ 0 H000．0 | L\＆ |
| 70＋自981．も |  | $80+$ ¢п70 8 |  |  | 70＋ $8829 \cdot 8$ |  | 70＋ 3779 च | z0＋ | 08， |
| L0＋男998．$\dagger$ | 70＋号矿 2 | 70＋Gt¢0 2 | 70＋GzLz＇ | 70＋可も989 | 70＋鸟209 ${ }^{\text {－}}$ | 20－Ģi0 $\%$ |  | 70＋G9LZ 7 | 67， |
| 70＋身LEE［ | 80＋ $200^{\circ} \mathrm{L}$ | $20+$ H000 $z$ | L0＋号965＇6 | 70＋号785：8 | 70＋ $7000 \cdot 7$ |  |  | 20＋ $7899^{\circ} \mathrm{E}$ | 87， |
| L0＋島L9 \％ 7 | 70＋ $28.7 \%$ ¢ | z0＋ $2900 \cdot 8$ | 70－3TL29 z | 70＋走000＇8 | 20＋ $7000 \cdot 8$ | 10－HzL0＇\＆ |  | 10－G60T•8 | 27H |
| 70－GceL | 70＋过 $700{ }^{\circ} \mathrm{I}$ | 70＋边 $200 \cdot \mathrm{~L}$ | 70－Hz99－ | 70＋匀L00 I | 70＋因L00 ${ }^{\text {I }}$ |  | 70＋ 7000 I | 70＋H000 ${ }^{\text {L }}$ | 97 H |
| $00+$ gez9 ${ }^{\text {\％}}$ | 70＋马L80 ${ }^{\circ}$ | $20+$ H000 7 | L0－－ 7689 | 70＋马970 7 | $20+$ 年 $000 \cdot 7$ | 00＋号LLE．9 | 70＋马660 ${ }^{\text {I }}$ |  | 9\％ |
|  | 70＋ $777 \mathrm{c}^{\circ} 7$ | z0＋H000 $\%$ | L0＋H091．${ }^{\text {I }}$ |  | 70＋ $7000 \cdot 7$ | $00+$ He09 7 | 70＋ $3080 \cdot \mathrm{I}$ | 70＋ $7000 \cdot \mathrm{~L}$ | モて， |
| L0＋GLE0 $\%$ | 70＋马80才 ¢ | 70＋马 $000{ }^{\circ} \mathrm{z}$ | L0＋G67t＇¢ | 70＋示 $790 \cdot 8$ | \％ $0+$ 鸟 $000{ }^{\circ} \mathrm{z}$ | \＆L－G028．7 | 70＋島967＇¢ | 70＋马G67．$¢$ | 86， |

Table A.2: Error values achieved by the proposed LSAOS-DE, LSHADE, SHADE, JADE, CoDE and SaDE for $10 D$

| problem | LSHADE | SHADE | JADE | CoDE | SaDE | LSAOSDE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)=$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F02 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $3.21 \mathrm{E}+01(9.16 \mathrm{E}+00)$ | $3.08 \mathrm{E}+01(1.11 \mathrm{E}+01)$ | $3.21 \mathrm{E}+01(9.44 \mathrm{E}+00)$ | $8.95 \mathrm{E}+00(1.46 \mathrm{E}+01)$ | $1.95 \mathrm{E}+01(1.70 \mathrm{E}+01)$ | $1.65 \mathrm{E}+01(1.74 \mathrm{E}+01)$ |
| F05 | $1.78 \mathrm{E}+01(5.64 \mathrm{E}+00)$ | $1.82 \mathrm{E}+01(4.67 \mathrm{E}+00)$ | $1.81 \mathrm{E}+01(3.70 \mathrm{E}+00)$ | $1.88 \mathrm{E}+01(4.76 \mathrm{E}+00)$ | $1.88 \mathrm{E}+01(4.78 \mathrm{E}+00)$ | $1.38 \mathrm{E}+01(7.90 \mathrm{E}+00)$ |
| F06 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.24 \mathrm{E}-06(8.84 \mathrm{E}-06)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $2.18 \mathrm{E}-10(1.55 \mathrm{E}-09)$ | $2.19 \mathrm{E}-05(1.15 \mathrm{E}-04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F07 | $1.70 \mathrm{E}-03(5.27 \mathrm{E}-03)$ | $4.02 \mathrm{E}-03(5.75 \mathrm{E}-03)$ | $8.78 \mathrm{E}-03(7.77 \mathrm{E}-03)$ | $3.70 \mathrm{E}-02(2.68 \mathrm{E}-02)$ | $1.00 \mathrm{E}-03(3.06 \mathrm{E}-03)$ | $1.01 \mathrm{E}-03(3.31 \mathrm{E}-03)$ |
| F08 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $2.54 \mathrm{E}+00(9.18 \mathrm{E}-01)$ | $3.04 \mathrm{E}+00(7.93 \mathrm{E}-01)$ | $3.26 \mathrm{E}+00(8.81 \mathrm{E}-01)$ | $4.00 \mathrm{E}+00(2.18 \mathrm{E}+00)$ | $7.27 \mathrm{E}+00(1.73 \mathrm{E}+00)$ | $8.42 \mathrm{E}-01(1.29 \mathrm{E}+00)$ |
| F10 | $2.45 \mathrm{E}-03(1.22 \mathrm{E}-02)$ | 8.57E-03(2.17E-02) | $1.10 \mathrm{E}-02(2.71 \mathrm{E}-02)$ | $3.43 \mathrm{E}-02(3.81 \mathrm{E}-02)$ | $1.22 \mathrm{E}-03(8.75 \mathrm{E}-03)$ | $2.45 \mathrm{E}-03(1.75 \mathrm{E}-02)$ |
| F11 | $2.86 \mathrm{E}+01(3.21 \mathrm{E}+01)$ | $5.68 \mathrm{E}+01(4.61 \mathrm{E}+01)$ | $8.63 \mathrm{E}+01(4.22 \mathrm{E}+01)$ | $9.08 \mathrm{E}+01(9.05 \mathrm{E}+01)$ | $3.84 \mathrm{E}+02(1.17 \mathrm{E}+02)$ | $5.15 \mathrm{E}+01(4.88 \mathrm{E}+01)$ |
| F12 | $6.50 \mathrm{E}-02(1.70 \mathrm{E}-02)$ | $1.34 \mathrm{E}-01(2.84 \mathrm{E}-02)$ | $3.23 \mathrm{E}-01(5.99 \mathrm{E}-02)$ | $4.70 \mathrm{E}-02(5.54 \mathrm{E}-02)$ | $4.29 \mathrm{E}-01(9.11 \mathrm{E}-02)$ | $1.49 \mathrm{E}-01(9.30 \mathrm{E}-02)$ |
| F13 | $5.14 \mathrm{E}-02(1.24 \mathrm{E}-02)$ | $7.70 \mathrm{E}-02(1.74 \mathrm{E}-02)$ | $7.56 \mathrm{E}-02(1.77 \mathrm{E}-02)$ | $8.25 \mathrm{E}-02(3.12 \mathrm{E}-02)$ | $1.38 \mathrm{E}-01(2.55 \mathrm{E}-02)$ | $5.06 \mathrm{E}-02(1.34 \mathrm{E}-02)$ |
| F14 | $7.06 \mathrm{E}-02(2.28 \mathrm{E}-02)$ | $9.28 \mathrm{E}-02(2.63 \mathrm{E}-02)$ | $9.22 \mathrm{E}-02(3.29 \mathrm{E}-02)$ | $1.01 \mathrm{E}-01(3.17 \mathrm{E}-02)$ | $1.87 \mathrm{E}-01(4.81 \mathrm{E}-02)$ | $1.06 \mathrm{E}-01(3.07 \mathrm{E}-02)$ |
| F15 | $3.81 \mathrm{E}-01(8.30 \mathrm{E}-02)$ | $4.87 \mathrm{E}-01(9.05 \mathrm{E}-02)$ | $5.50 \mathrm{E}-01(8.09 \mathrm{E}-02)$ | $6.22 \mathrm{E}-01(1.69 \mathrm{E}-01)$ | $1.23 \mathrm{E}+00(1.67 \mathrm{E}-01)$ | $4.03 \mathrm{E}-01(6.57 \mathrm{E}-02)$ |
| F16 | $1.26 \mathrm{E}+00(2.51 \mathrm{E}-01)$ | $1.64 \mathrm{E}+00(2.23 \mathrm{E}-01)$ | $1.55 \mathrm{E}+00(3.67 \mathrm{E}-01)$ | $1.20 \mathrm{E}+00(6.33 \mathrm{E}-01)$ | $2.25 \mathrm{E}+00(2.39 \mathrm{E}-01)$ | $1.26 \mathrm{E}+00(3.42 \mathrm{E}-01)$ |
| F17 | $7.92 \mathrm{E}-01(7.82 \mathrm{E}-01)$ | $3.49 \mathrm{E}+00(1.68 \mathrm{E}+01)$ | $1.39 \mathrm{E}+01(4.12 \mathrm{E}+01)$ | $2.76 \mathrm{E}+00(4.42 \mathrm{E}+00)$ | $1.11 \mathrm{E}+01(6.42 \mathrm{E}+00)$ | $1.04 \mathrm{E}+00(1.01 \mathrm{E}+00)$ |
| F18 | $2.35 \mathrm{E}-01(1.80 \mathrm{E}-01)$ | $2.00 \mathrm{E}-01(1.81 \mathrm{E}-01)$ | $1.98 \mathrm{E}-01(2.22 \mathrm{E}-01)$ | $3.67 \mathrm{E}-01(6.13 \mathrm{E}-01)$ | $3.73 \mathrm{E}-01(4.76 \mathrm{E}-01)$ | $1.30 \mathrm{E}-01(1.43 \mathrm{E}-01)$ |
| F19 | $1.11 \mathrm{E}-01(1.17 \mathrm{E}-01)$ | $2.07 \mathrm{E}-01(1.56 \mathrm{E}-01)$ | $2.35 \mathrm{E}-01(2.61 \mathrm{E}-01)$ | $8.59 \mathrm{E}-02(7.55 \mathrm{E}-02)$ | $2.20 \mathrm{E}-01(7.54 \mathrm{E}-02)$ | $7.84 \mathrm{E}-02(5.92 \mathrm{E}-02)$ |
| F20 | $1.47 \mathrm{E}-01(1.24 \mathrm{E}-01)$ | $2.89 \mathrm{E}-01(1.45 \mathrm{E}-01)$ | $2.40 \mathrm{E}-01(1.67 \mathrm{E}-01)$ | $2.42 \mathrm{E}-02(3.21 \mathrm{E}-02)$ | $2.49 \mathrm{E}-01(1.00 \mathrm{E}-01)$ | $1.75 \mathrm{E}-01(1.67 \mathrm{E}-01)$ |
| F21 | $3.36 \mathrm{E}-01(2.60 \mathrm{E}-01)$ | $3.91 \mathrm{E}-01(2.85 \mathrm{E}-01)$ | $4.06 \mathrm{E}-01(2.89 \mathrm{E}-01)$ | $2.35 \mathrm{E}-01(2.48 \mathrm{E}-01)$ | $3.37 \mathrm{E}-01(2.33 \mathrm{E}-01)$ | $2.88 \mathrm{E}-01(2.43 \mathrm{E}-01)$ |
| F22 | $9.18 \mathrm{E}-02(4.03 \mathrm{E}-02)$ | $2.75 \mathrm{E}-01(1.45 \mathrm{E}-01)$ | $1.67 \mathrm{E}-01(5.46 \mathrm{E}-02)$ | $6.70 \mathrm{E}-02(6.53 \mathrm{E}-02)$ | $3.36 \mathrm{E}-01(1.46 \mathrm{E}-01)$ | $1.22 \mathrm{E}-01(4.57 \mathrm{E}-02)$ |
| F23 | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ |
| F24 | $1.08 \mathrm{E}+02(1.29 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(2.22 \mathrm{E}+00)$ | $1.08 \mathrm{E}+02(2.53 \mathrm{E}+00)$ | $1.12 \mathrm{E}+02(3.22 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(4.16 \mathrm{E}+00)$ | $1.08 \mathrm{E}+02(2.60 \mathrm{E}+00)$ |
| F25 | $1.47 \mathrm{E}+02(4.40 \mathrm{E}+01)$ | $1.53 \mathrm{E}+02(4.44 \mathrm{E}+01)$ | $1.37 \mathrm{E}+02(4.06 \mathrm{E}+01)$ | $1.41 \mathrm{E}+02(4.12 \mathrm{E}+01)$ | $1.20 \mathrm{E}+02(9.21 \mathrm{E}+00)$ | $1.10 \mathrm{E}+02(6.57 \mathrm{E}+00)$ |
| F26 | $1.00 \mathrm{E}+02(1.64 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.32 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.82 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.16 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.49 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.66 \mathrm{E}-02)$ |
| F27 | $5.60 \mathrm{E}+01(1.20 \mathrm{E}+02)$ | $1.15 \mathrm{E}+02(1.57 \mathrm{E}+02)$ | $1.60 \mathrm{E}+02(1.86 \mathrm{E}+02)$ | $2.74 \mathrm{E}+01(8.85 \mathrm{E}+01)$ | $1.02 \mathrm{E}+01(5.57 \mathrm{E}+01)$ | $1.52 \mathrm{E}+00(3.01 \mathrm{E}-01)$ |
| F28 | $3.83 \mathrm{E}+02(3.60 \mathrm{E}+01)$ | $3.98 \mathrm{E}+02(4.69 \mathrm{E}+01)$ | $4.06 \mathrm{E}+02(5.09 \mathrm{E}+01)$ | $3.60 \mathrm{E}+02(1.41 \mathrm{E}+01)$ | $3.64 \mathrm{E}+02(2.40 \mathrm{E}+01)$ | $3.65 \mathrm{E}+02(1.63 \mathrm{E}+01)$ |
| F29 | $2.22 \mathrm{E}+02(5.82 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(5.80 \mathrm{E}-01)$ | $2.20 \mathrm{E}+02(1.27 \mathrm{E}+01)$ | $2.20 \mathrm{E}+02(1.26 \mathrm{E}+01)$ | $2.12 \mathrm{E}+02(2.71 \mathrm{E}+01)$ | $2.22 \mathrm{E}+02(2.02 \mathrm{E}-01)$ |
| F30 | $4.68 \mathrm{E}+02(1.73 \mathrm{E}+01)$ | $4.68 \mathrm{E}+02(1.30 \mathrm{E}+01)$ | $4.77 \mathrm{E}+02(2.42 \mathrm{E}+01)$ | $4.64 \mathrm{E}+02(7.66 \mathrm{E}+00)$ | $4.85 \mathrm{E}+02(2.41 \mathrm{E}+01)$ | $4.62 \mathrm{E}+02(1.63 \mathrm{E}+00)$ |


| （00＋号00＊0） $70+$ H00 ${ }^{\text {I }}$ | （00＋H00．0） $70+$ H $00{ }^{\circ} \mathrm{I}$ | （00＋H00．0） $20+$ 岛00．I | （もL－Ģ9．も） $70+$ H00 ${ }^{\text {a }}$ | （00＋H00＊0） $20+$ H00 ${ }^{\text {I }}$ | （00＋H00＊0） $20+$ 式00．I | 9ヵt |
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|  |  |  | （ $80+$ H 20.7 ） $80+$ 示69 ${ }^{\circ}$ |  |  | 伍且 |
|  | （90－H0L 8） $70-$－ $90{ }^{\circ} \mathrm{E}$ | （ $90-\mathrm{H} 8 L^{\circ} \mathrm{G}$ ） $70-\mathrm{H} 90{ }^{\circ} \mathrm{C}$ | （ $90-\mathrm{G} 6 L^{\circ} \mathrm{8}$ ） $70-\mathrm{G} 90 \cdot \mathrm{E}$ |  |  | EもH |
|  |  |  |  |  |  | 7ヵH |
|  |  |  |  |  |  | H |
| （8L－HZİI） $20+$ HLI＇ |  |  | （ $\mathrm{L} 0+\mathcal{H} 67^{\circ} \mathrm{E}$ ） $70+$ H $27 \cdot \%$ |  |  | 0才年 |
|  | （ $70-\mathrm{G} 9 \mathrm{E}^{\circ} \mathrm{E}$ ） $70+$ H00 ${ }^{\text {I }}$ |  |  | （ $70-$－g60 6 ） $70+$ H00 I |  | 68E |
|  |  |  | （ $10-\mathrm{H} 8 \varepsilon^{\circ} 9$ ） $\mathrm{L} 0-\mathrm{Hg} 0^{\circ} \mathrm{G}$ |  |  | 88H |
|  |  | （ $70-\mathrm{H} 08^{\circ} \mathrm{C}$ ） $70-\mathrm{y} 9 \mathrm{E}^{\circ} \mathrm{L}$ | （ $\mathrm{L}-$－HE才 ${ }^{\circ}$ ） $\mathrm{L} 0-\mathrm{H} 0 \mathrm{c}^{\circ} \mathrm{C}$ | （ $70-\mathrm{H} 02 \cdot 6$ ） L 0 －島LI＇Z |  | LEH |
| （00＋HIL $\cdot$ ） $00+$ 出 $8 \% \cdot$ I |  | （00＋G69．L）L0－号LI＇9 | （ $10+$ H8\＆\％$) 00+$ HSL 9 |  |  | 98古 |
|  |  | （L0＋G9才 $\left.{ }^{\circ} \mathrm{8}\right) \mathrm{L} 0+9$［ $89^{\circ} \mathrm{L}$ | （L0＋HLI｀G） 0 （0＋ 486.2 | （ $\mathrm{L} 0+$ HS $2 \cdot \mathrm{G}$ ） $\mathrm{L} 0+4788^{\circ} 9$ | （L0＋H68．\％） 0 ＋凫 $99^{\circ} \mathrm{L}$ | 98日 |
|  |  |  | （ $10-\mathrm{g} 06.8$ ） $00+$ H99．8 | （20－马0才6） $00+$ 岛 $0^{\circ} \mathrm{E}$ |  | 7\＆日 |
|  |  |  | （00＋H\＆9 \％） 0 ＋ 486. I | （00＋马LL＇t） $0+$＋ $36 L^{\prime}$ I |  | 88J |
| （00＋马00\％0）00＋子200．0 | （00＋H00＊） $00+$ H 0000 | （00＋H00．0）00＋马或000 | （00＋H00：0）00＋出00．0 | （00＋H00\％0）00＋号00．0 | （00＋H00\％） $00+$＋ 4000 | 78S |
| （00＋马00\％） $00+$ H00．0 | $(00+$ 鸟00＊0） $00+$ 年 0000 |  |  | $(00+马 00 \%) 00+$ 早00＊0 |  | LEH |


| problem | EPSDE | MPEDE | UMOEAs | AMALGAM-SO | LSAOSDE |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $4.24 \mathrm{E}-05(1.41 \mathrm{E}-05)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F02 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $7.75 \mathrm{E}-05(2.11 \mathrm{E}-05)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $6.40 \mathrm{E}-05(4.10 \mathrm{E}-05)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.61 \mathrm{E}+01(1.71 \mathrm{E}+01)$ | $1.42 \mathrm{E}+01(1.68 \mathrm{E}+01)$ | $2.28 \mathrm{E}+01(1.58 \mathrm{E}+01)$ | $1.65 \mathrm{E}+01(1.74 \mathrm{E}+01)$ |
| F05 | $2.01 \mathrm{E}+01(1.22 \mathrm{E}-02)$ | $1.16 \mathrm{E}+01(9.88 \mathrm{E}+00)$ | $2.00 \mathrm{E}+01(8.36 \mathrm{E}-02)$ | $1.76 \mathrm{E}+01(6.53 \mathrm{E}+00)$ | $1.38 \mathrm{E}+01(7.90 \mathrm{E}+00)$ |
| F06 | $3.01 \mathrm{E}+00(5.56 \mathrm{E}-01)$ | $4.07 \mathrm{E}-04(1.92 \mathrm{E}-03)$ | $1.60 \mathrm{E}-01(2.65 \mathrm{E}-01)$ | $1.53 \mathrm{E}-02(8.55 \mathrm{E}-02)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F07 | $1.49 \mathrm{E}-02(1.11 \mathrm{E}-02)$ | $3.62 \mathrm{E}-03(6.35 \mathrm{E}-03)$ | $1.45 \mathrm{E}-04(1.04 \mathrm{E}-03)$ | $2.35 \mathrm{E}-04(6.28 \mathrm{E}-05)$ | $1.01 \mathrm{E}-03(3.31 \mathrm{E}-03)$ |
| F08 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $6.00 \mathrm{E}-04(3.95 \mathrm{E}-03)$ | $1.99 \mathrm{E}-03(3.79 \mathrm{E}-03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $3.86 \mathrm{E}+00(9.87 \mathrm{E}-01)$ | $3.51 \mathrm{E}+00(1.22 \mathrm{E}+00)$ | $3.73 \mathrm{E}+00(2.11 \mathrm{E}+00)$ | $2.07 \mathrm{E}-01(4.04 \mathrm{E}-01)$ | $8.42 \mathrm{E}-01(1.29 \mathrm{E}+00)$ |
| F10 | $4.90 \mathrm{E}-02(6.88 \mathrm{E}-02)$ | $2.45 \mathrm{E}-03(1.22 \mathrm{E}-02)$ | $1.95 \mathrm{E}+00(2.27 \mathrm{E}+00)$ | $3.35 \mathrm{E}+00(4.29 \mathrm{E}+00)$ | $2.45 \mathrm{E}-03(1.75 \mathrm{E}-02)$ |
| F11 | $3.40 \mathrm{E}+02(1.11 \mathrm{E}+02)$ | $9.31 \mathrm{E}+01(8.68 \mathrm{E}+01)$ | $3.80 \mathrm{E}+02(1.96 \mathrm{E}+02)$ | $1.39 \mathrm{E}+01(1.30 \mathrm{E}+01)$ | $5.15 \mathrm{E}+01(4.88 \mathrm{E}+01)$ |
| F12 | $3.14 \mathrm{E}-01(5.55 \mathrm{E}-02)$ | $2.58 \mathrm{E}-01(8.37 \mathrm{E}-02)$ | $3.79 \mathrm{E}-03(1.67 \mathrm{E}-02)$ | $7.06 \mathrm{E}-02(4.88 \mathrm{E}-02)$ | $1.49 \mathrm{E}-01(9.30 \mathrm{E}-02)$ |
| F13 | $1.21 \mathrm{E}-01(2.44 \mathrm{E}-02)$ | 8.03E-02(2.66E-02) | $1.85 \mathrm{E}-02(1.38 \mathrm{E}-02)$ | $1.10 \mathrm{E}-02(4.83 \mathrm{E}-03)$ | $5.06 \mathrm{E}-02(1.34 \mathrm{E}-02)$ |
| F14 | $1.32 \mathrm{E}-01(3.51 \mathrm{E}-02)$ | $7.65 \mathrm{E}-02(2.38 \mathrm{E}-02)$ | $1.69 \mathrm{E}-01(4.06 \mathrm{E}-02)$ | $2.65 \mathrm{E}-01(5.97 \mathrm{E}-02)$ | $1.06 \mathrm{E}-01(3.07 \mathrm{E}-02)$ |
| F15 | $7.11 \mathrm{E}-01(1.17 \mathrm{E}-01)$ | $5.87 \mathrm{E}-01(1.65 \mathrm{E}-01)$ | $8.50 \mathrm{E}-01(1.85 \mathrm{E}-01)$ | $6.80 \mathrm{E}-01(1.14 \mathrm{E}-01)$ | $4.03 \mathrm{E}-01(6.57 \mathrm{E}-02)$ |
| F16 | $2.46 \mathrm{E}+00(2.69 \mathrm{E}-01)$ | $1.47 \mathrm{E}+00(3.55 \mathrm{E}-01)$ | $2.77 \mathrm{E}+00(2.54 \mathrm{E}-01)$ | $1.21 \mathrm{E}+00(4.63 \mathrm{E}-01)$ | $1.26 \mathrm{E}+00(3.42 \mathrm{E}-01)$ |
| F17 | $4.93 \mathrm{E}+01(3.90 \mathrm{E}+01)$ | $5.34 \mathrm{E}+00(5.38 \mathrm{E}+00)$ | $3.12 \mathrm{E}+01(3.54 \mathrm{E}+01)$ | $3.99 \mathrm{E}+01(4.08 \mathrm{E}+01)$ | $1.04 \mathrm{E}+00(1.01 \mathrm{E}+00)$ |
| F18 | $1.21 \mathrm{E}+00(7.66 \mathrm{E}-01)$ | $5.28 \mathrm{E}-01(4.36 \mathrm{E}-01)$ | $1.04 \mathrm{E}+00(6.71 \mathrm{E}-01)$ | $2.73 \mathrm{E}+00(4.02 \mathrm{E}+00)$ | $1.30 \mathrm{E}-01(1.43 \mathrm{E}-01)$ |
| F19 | $1.42 \mathrm{E}+00(2.29 \mathrm{E}-01-)$ | $1.40 \mathrm{E}-01(7.57 \mathrm{E}-02)$ | 7.16E-01(4.69E-01) | $5.94 \mathrm{E}-01(3.93 \mathrm{E}-01)$ | $7.84 \mathrm{E}-02(5.92 \mathrm{E}-02)$ |
| F20 | $1.55 \mathrm{E}-01(7.26 \mathrm{E}-02)$ | $1.73 \mathrm{E}-01(1.12 \mathrm{E}-01)$ | $9.11 \mathrm{E}-01(3.90 \mathrm{E}-01)$ | $1.43 \mathrm{E}+00(1.26 \mathrm{E}+00)$ | $1.75 \mathrm{E}-01(1.67 \mathrm{E}-01)$ |
| F21 | $5.25 \mathrm{E}+00(2.00 \mathrm{E}+01)$ | 4.93E-01(2.82E-01) | $1.84 \mathrm{E}+00(3.04 \mathrm{E}+00)$ | $9.50 \mathrm{E}+00(2.03 \mathrm{E}+01)$ | $2.88 \mathrm{E}-01(2.43 \mathrm{E}-01)$ |
| F22 | $1.96 \mathrm{E}+01(2.23 \mathrm{E}+00)$ | $2.76 \mathrm{E}-01(1.93 \mathrm{E}-01)$ | $9.64 \mathrm{E}+00(6.42 \mathrm{E}+00)$ | $4.03 \mathrm{E}+00(5.90 \mathrm{E}+00)$ | $1.22 \mathrm{E}-01(4.57 \mathrm{E}-02)$ |
| F23 | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(1.79 \mathrm{E}-04)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ |
| F24 | $1.12 \mathrm{E}+02(2.10 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(2.66 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(3.33 \mathrm{E}+00)$ | $1.06 \mathrm{E}+02(3.00 \mathrm{E}+00)$ | $1.08 \mathrm{E}+02(2.60 \mathrm{E}+00)$ |
| F25 | $1.93 \mathrm{E}+02(2.28 \mathrm{E}+01)$ | $1.17 \mathrm{E}+02(6.52 \mathrm{E}+00)$ | $1.43 \mathrm{E}+02(3.14 \mathrm{E}+01)$ | $1.39 \mathrm{E}+02(1.87 \mathrm{E}+01)$ | $1.10 \mathrm{E}+02(6.57 \mathrm{E}+00)$ |
| F26 | $1.00 \mathrm{E}+02(2.86 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.59 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.84 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(5.89 \mathrm{E}-03)$ | $1.00 \mathrm{E}+02(1.66 \mathrm{E}-02)$ |
| F27 | $3.32 \mathrm{E}+02(1.41 \mathrm{E}+02)$ | $1.71 \mathrm{E}+00(3.63 \mathrm{E}-01)$ | $4.56 \mathrm{E}+01(1.09 \mathrm{E}+02)$ | $2.19 \mathrm{E}+02(1.33 \mathrm{E}+02)$ | $1.52 \mathrm{E}+00(3.01 \mathrm{E}-01)$ |
| F28 | $3.06 \mathrm{E}+02(1.23 \mathrm{E}-02)$ | $3.67 \mathrm{E}+02(2.32 \mathrm{E}+01)$ | $3.61 \mathrm{E}+02(4.06 \mathrm{E}+01)$ | $3.33 \mathrm{E}+02(8.60 \mathrm{E}+01)$ | $3.65 \mathrm{E}+02(1.63 \mathrm{E}+01)$ |
| F29 | $2.02 \mathrm{E}+02(3.04 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(8.22 \mathrm{E}-02)$ | $2.11 \mathrm{E}+02(2.79 \mathrm{E}+01)$ | $2.23 \mathrm{E}+02(2.75 \mathrm{E}+00)$ | $2.22 \mathrm{E}+02(2.02 \mathrm{E}-01)$ |
| F30 | $2.32 \mathrm{E}+02(6.15 \mathrm{E}+00)$ | $4.64 \mathrm{E}+02(5.00 \mathrm{E}+00)$ | $4.84 \mathrm{E}+02(4.69 \mathrm{E}+01)$ | $4.91 \mathrm{E}+02(4.27 \mathrm{E}+01)$ | $4.62 \mathrm{E}+02(1.63 \mathrm{E}+00)$ |


| （00＋ | （10） | （00＋ | （6L | （00＋800 0） $20+$ 边 00 L | $\underline{\text { g }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | （ $81-$ 马g $¢ \cdot \varepsilon$ ） $70+$ H9I $¢$ | 旺回 |
|  |  |  |  |  | H |
|  | （ $\mathrm{L} 0-\mathrm{GLI} \cdot \mathrm{L}$ ） $70+$ 鸟L0 I | （10－769 | （ $\mathrm{L} 0-\mathrm{G} 67^{\circ} \mathrm{E}$ ） $70+$ 岛L0 I |  | H |
|  |  |  | （ $10+480 \cdot 8$ ） $0+$＋ 889.7 |  | H |
| （8L－g7I＇L） $20+$ HLI＇Z |  | $\left(00+马 788^{\circ} \mathrm{E}\right) \mathrm{z} 0+$ |  |  | H |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
| （ $70-$－ 296 ） ） $0-$－早 |  |  |  |  | 28H |
| （00＋马TL＇L）00＋马HE\％I | （ $\mathrm{L} 0+\mathrm{H} 86^{\circ} \mathrm{C}$ ） $\mathrm{L} 0+$ 过 $00{ }^{\circ} \mathrm{C}$ |  |  |  | H |
|  |  |  | （ $\mathrm{L} 0+$ H 29.9 ） $\mathrm{L} 0+$ 号 90.9 |  | 98E |
|  |  |  | （00＋ $\left.767^{\circ} \mathrm{L}\right) 00+$ He $5^{\circ} \mathrm{E}$ |  | H |
|  |  |  |  |  | 88E |
| （ $00+$＋ 0000 ） $00+$ 式 0000 | （90－G89\％）$¢ 0-\mathrm{G} 67^{\circ} 8$ |  | （ $00+$ H00＊0） $00+$ 年 0000 | （ $00+$ H $00 \cdot 0$ ） $00+$ 年00＊ | 78E |
|  |  |  |  |  | I\＆ |

Table A.4: Error values achieved by the proposed LSAOS-DE, LSHADE, SHADE, JADE, CoDE and SaDE for 30D

| problem | LSHADE | SHADE | JADE | CoDE | SaDE | LSAOSDE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $2.84 \mathrm{E}+04(2.05 \mathrm{E}+04)$ | $1.48 \mathrm{E}+04(3.03 \mathrm{E}+04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F02 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $4.30 \mathrm{E}-09(1.44 \mathrm{E}-08)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.09 \mathrm{E}-06(7.78 \mathrm{E}-06)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.27 \mathrm{E}+00(9.10 \mathrm{E}+00)$ | $1.94 \mathrm{E}+01(2.94 \mathrm{E}+01)$ | $7.19 \mathrm{E}-05(3.06 \mathrm{E}-04)$ |
| F05 | $2.01 \mathrm{E}+01(2.35 \mathrm{E}-02)$ | $2.04 \mathrm{E}+01(3.47 \mathrm{E}-02)$ | $2.04 \mathrm{E}+01(4.21 \mathrm{E}-02)$ | $2.00 \mathrm{E}+01(6.19 \mathrm{E}-02)$ | $2.06 \mathrm{E}+01(5.02 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01(8.29 \mathrm{E}-02)$ |
| F06 | $2.19 \mathrm{E}-02(1.09 \mathrm{E}-01)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.07 \mathrm{E}+01(5.38 \mathrm{E}+00)$ | $2.39 \mathrm{E}+00(1.70 \mathrm{E}+00)$ | $1.23 \mathrm{E}+00(3.36 \mathrm{E}+00)$ | $4.49 \mathrm{E}-02(1.65 \mathrm{E}-01)$ |
| F07 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $5.80 \mathrm{E}-04(2.39 \mathrm{E}-03)$ | $4.82 \mathrm{E}-04(3.44 \mathrm{E}-03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F08 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.02 \mathrm{E}+01(1.25 \mathrm{E}+00)$ | $1.21 \mathrm{E}-05(1.08 \mathrm{E}-05)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.27 \mathrm{E}+00(7.67 \mathrm{E}-01)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $7.24 \mathrm{E}+00(1.82 \mathrm{E}+00)$ | $5.22 \mathrm{E}+01(5.63 \mathrm{E}+00)$ | $5.06 \mathrm{E}+01(5.77 \mathrm{E}+00)$ | $3.69 \mathrm{E}+01(1.04 \mathrm{E}+01)$ | $8.28 \mathrm{E}+01(7.46 \mathrm{E}+00)$ | $4.69 \mathrm{E}+00(1.62 \mathrm{E}+00)$ |
| F10 | $4.08 \mathrm{E}-03(1.18 \mathrm{E}-02)$ | $2.30 \mathrm{E}+02(3.34 \mathrm{E}+01)$ | $3.60 \mathrm{E}+01(4.47 \mathrm{E}+00)$ | $5.30 \mathrm{E}-01(5.14 \mathrm{E}-01)$ | $1.93 \mathrm{E}+02(2.72 \mathrm{E}+01)$ | $9.18 \mathrm{E}-03(1.59 \mathrm{E}-02)$ |
| F11 | $1.20 \mathrm{E}+03(1.91 \mathrm{E}+02)$ | $3.00 \mathrm{E}+03(2.64 \mathrm{E}+02)$ | $3.19 \mathrm{E}+03(2.34 \mathrm{E}+02)$ | $1.85 \mathrm{E}+03(4.75 \mathrm{E}+02)$ | $4.05 \mathrm{E}+03(2.61 \mathrm{E}+02)$ | $1.60 \mathrm{E}+03(4.42 \mathrm{E}+02)$ |
| F12 | $1.60 \mathrm{E}-01(2.77 \mathrm{E}-02)$ | $5.48 \mathrm{E}-01(6.02 \mathrm{E}-02)$ | $6.29 \mathrm{E}-01(8.13 \mathrm{E}-02)$ | $5.57 \mathrm{E}-02(3.79 \mathrm{E}-02)$ | $9.19 \mathrm{E}-01(1.04 \mathrm{E}-01)$ | $3.02 \mathrm{E}-01(1.23 \mathrm{E}-01)$ |
| F13 | $1.21 \mathrm{E}-01(1.63 \mathrm{E}-02)$ | $1.70 \mathrm{E}-01(2.28 \mathrm{E}-02)$ | $1.87 \mathrm{E}-01(2.67 \mathrm{E}-02)$ | $2.38 \mathrm{E}-01(4.39 \mathrm{E}-02)$ | $2.84 \mathrm{E}-01(3.12 \mathrm{E}-02)$ | $1.22 \mathrm{E}-01(1.75 \mathrm{E}-02)$ |
| F14 | $2.29 \mathrm{E}-01(2.84 \mathrm{E}-02)$ | $2.18 \mathrm{E}-01(1.96 \mathrm{E}-02)$ | $2.33 \mathrm{E}-01(2.64 \mathrm{E}-02)$ | $2.40 \mathrm{E}-01(4.15 \mathrm{E}-02)$ | $2.46 \mathrm{E}-01(2.82 \mathrm{E}-02)$ | $2.18 \mathrm{E}-01(2.38 \mathrm{E}-02)$ |
| F15 | $2.13 \mathrm{E}+00(1.99 \mathrm{E}-01)$ | $6.65 \mathrm{E}+00(6.24 \mathrm{E}-01)$ | $5.79 \mathrm{E}+00(5.45 \mathrm{E}-01)$ | $2.89 \mathrm{E}+00(8.77 \mathrm{E}-01)$ | $9.69 \mathrm{E}+00(7.66 \mathrm{E}-01)$ | $2.49 \mathrm{E}+00(2.39 \mathrm{E}-01)$ |
| F16 | $8.40 \mathrm{E}+00(4.93 \mathrm{E}-01)$ | $1.02 \mathrm{E}+01(2.91 \mathrm{E}-01)$ | $1.06 \mathrm{E}+01(4.56 \mathrm{E}-01)$ | $9.33 \mathrm{E}+00(7.70 \mathrm{E}-01)$ | $1.14 \mathrm{E}+01(2.71 \mathrm{E}-01)$ | $9.24 \mathrm{E}+00(5.55 \mathrm{E}-01)$ |
| F17 | $2.33 \mathrm{E}+02(1.25 \mathrm{E}+02)$ | $2.96 \mathrm{E}+02(1.04 \mathrm{E}+02)$ | $4.30 \mathrm{E}+02(2.39 \mathrm{E}+02)$ | $1.28 \mathrm{E}+03(1.04 \mathrm{E}+03)$ | $4.34 \mathrm{E}+02(2.19 \mathrm{E}+02)$ | $1.36 \mathrm{E}+02(7.15 \mathrm{E}+01)$ |
| F18 | $7.86 \mathrm{E}+00(3.07 \mathrm{E}+00)$ | $1.29 \mathrm{E}+01(6.26 \mathrm{E}+00)$ | $1.41 \mathrm{E}+01(7.78 \mathrm{E}+00)$ | $1.43 \mathrm{E}+01(6.91 \mathrm{E}+00)$ | $5.01 \mathrm{E}+01(1.14 \mathrm{E}+01)$ | $6.35 \mathrm{E}+00(2.56 \mathrm{E}+00)$ |
| F19 | $3.83 \mathrm{E}+00(6.27 \mathrm{E}-01)$ | $4.25 \mathrm{E}+00(5.72 \mathrm{E}-01)$ | $4.13 \mathrm{E}+00(7.12 \mathrm{E}-01)$ | $2.60 \mathrm{E}+00(4.05 \mathrm{E}-01)$ | $4.36 \mathrm{E}+00(4.26 \mathrm{E}-01)$ | $3.25 \mathrm{E}+00(5.95 \mathrm{E}-01)$ |
| F20 | $2.74 \mathrm{E}+00(1.13 \mathrm{E}+00)$ | $1.16 \mathrm{E}+01(2.04 \mathrm{E}+00)$ | $1.51 \mathrm{E}+01(4.41 \mathrm{E}+00)$ | $1.11 \mathrm{E}+01(4.67 \mathrm{E}+00)$ | $2.58 \mathrm{E}+01(5.39 \mathrm{E}+00)$ | $3.86 \mathrm{E}+00(1.29 \mathrm{E}+00)$ |
| F21 | $1.08 \mathrm{E}+02(7.81 \mathrm{E}+01)$ | $2.38 \mathrm{E}+02(1.20 \mathrm{E}+02)$ | $2.14 \mathrm{E}+02(1.34 \mathrm{E}+02)$ | $2.43 \mathrm{E}+02(1.45 \mathrm{E}+02)$ | $4.03 \mathrm{E}+02(1.09 \mathrm{E}+02)$ | $3.22 \mathrm{E}+01(4.47 \mathrm{E}+01)$ |
| F22 | $2.42 \mathrm{E}+01(3.37 \mathrm{E}+00)$ | $1.23 \mathrm{E}+02(6.12 \mathrm{E}+01)$ | $1.86 \mathrm{E}+02(6.39 \mathrm{E}+01)$ | $1.47 \mathrm{E}+02(9.58 \mathrm{E}+01)$ | $2.13 \mathrm{E}+02(5.14 \mathrm{E}+01)$ | $3.36 \mathrm{E}+01(1.71 \mathrm{E}+01)$ |
| F23 | $3.15 \mathrm{E}+02(3.59 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(4.02 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(4.02 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(3.18 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(7.53 \mathrm{E}-13)$ | $3.06 \mathrm{E}+02(3.13 \mathrm{E}+01)$ |
| F24 | $2.24 \mathrm{E}+02(1.77 \mathrm{E}+00)$ | $2.23 \mathrm{E}+02(1.02 \mathrm{E}+00)$ | $2.23 \mathrm{E}+02(1.09 \mathrm{E}+00)$ | $2.25 \mathrm{E}+02(2.42 \mathrm{E}+00)$ | $2.24 \mathrm{E}+02(5.53 \mathrm{E}-01)$ | $2.14 \mathrm{E}+02(1.16 \mathrm{E}+01)$ |
| F25 | $2.03 \mathrm{E}+02(5.09 \mathrm{E}-02)$ | $2.03 \mathrm{E}+02(1.52 \mathrm{E}-01)$ | $2.03 \mathrm{E}+02(2.93 \mathrm{E}-01)$ | $2.04 \mathrm{E}+02(9.33 \mathrm{E}-01)$ | $2.01 \mathrm{E}+02(1.98 \mathrm{E}+00)$ | $2.02 \mathrm{E}+02(6.39 \mathrm{E}-01)$ |
| F26 | $1.00 \mathrm{E}+02(1.43 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.10 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.57 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(5.65 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(3.78 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.66 \mathrm{E}-02)$ |
| F27 | $3.00 \mathrm{E}+02(1.37 \mathrm{E}-13)$ | $3.02 \mathrm{E}+02(1.40 \mathrm{E}+01)$ | $3.09 \mathrm{E}+02(2.84 \mathrm{E}+01)$ | $3.83 \mathrm{E}+02(3.67 \mathrm{E}+01)$ | $3.40 \mathrm{E}+02(4.67 \mathrm{E}+01)$ | $3.00 \mathrm{E}+02(2.67 \mathrm{E}-02)$ |
| F28 | $8.46 \mathrm{E}+02(1.33 \mathrm{E}+01)$ | $8.24 \mathrm{E}+02(1.42 \mathrm{E}+01)$ | $8.06 \mathrm{E}+02(2.42 \mathrm{E}+01)$ | $8.32 \mathrm{E}+02(2.72 \mathrm{E}+01)$ | $8.48 \mathrm{E}+02(1.43 \mathrm{E}+02)$ | $8.18 \mathrm{E}+02(9.20 \mathrm{E}+01)$ |
| F29 | $7.16 \mathrm{E}+02(2.80 \mathrm{E}+00)$ | $7.18 \mathrm{E}+02(4.83 \mathrm{E}+00)$ | $7.17 \mathrm{E}+02(3.18 \mathrm{E}+00)$ | $7.68 \mathrm{E}+02(1.60 \mathrm{E}+02)$ | $2.45 \mathrm{E}+02(1.07 \mathrm{E}+02)$ | $6.85 \mathrm{E}+02(1.27 \mathrm{E}+02)$ |
| F30 | $1.99 \mathrm{E}+03(7.82 \mathrm{E}+02)$ | $1.25 \mathrm{E}+03(4.69 \mathrm{E}+02)$ | $1.08 \mathrm{E}+03(5.04 \mathrm{E}+02)$ | $8.86 \mathrm{E}+02(3.74 \mathrm{E}+02)$ | $6.66 \mathrm{E}+02(1.63 \mathrm{E}+02)$ | $4.87 \mathrm{E}+02(1.12 \mathrm{E}+02)$ |


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| （00＋马96 ¢ $)$ z0＋岛L0． | （ $\mathrm{L} 0+368^{\circ} \mathrm{C}$ ） $70+\mathrm{H} 0 \mathrm{c}^{\circ} \mathrm{E}$ |  |  |  |  | IもH |
|  |  |  |  | （ $70+$ 岛9¢ 7 ） $70+$ 鸟L6 8 |  | 0才先 |
|  |  |  |  |  |  | 68岳 |
|  |  |  |  |  |  | 88H |
|  | （10－H07．9）00＋年60．8 |  | （10－马8\％6）00＋马68： | （10－马70\％6）00＋岛9\％L | （10－马8L：9）00＋血9999 | LEH |
| （L0＋马g¢ 9） $70+$ HE¢ ${ }^{\text {L }}$ |  |  |  | （ $20+$ H97 ${ }^{\circ}$ ） $80+$ 鸟 $90^{\circ}$ I | （L0＋H8L＊6） $70+$ H $2 I^{\circ}$ \％ | 98号 |
|  |  |  | （ $70+$ H80 \％） $80+$ 鸟02．I |  |  | 98G |
|  | （00＋马G9 ${ }^{\circ}$ ） $10+$ HE $8^{\circ} 8$ |  |  |  | （00＋G99．L） $00+$ 鸟 $68^{\circ} \mathrm{L}$ | －8， |
|  |  |  | （ $70-马 967$ ） 0 0 + H80 7 |  |  | 88H |
| （00＋H00＊0）00＋马 000 | （ $70+$ H 78.9 ） $70+$ H08．9 | （00＋直00．0）00＋马 00.0 | （00＋H00＊0）00＋马 000 | （00＋H00＊0）00＋马 00.0 | （00＋H00＊0）00＋年00．0 | 78U |
| （00＋马 $00 \%$ ） $00+$ 出 00.0 |  |  |  |  | $(00+马 400 \%) 00+马$ 年 000 | LEH |

Table A.5: Error values achieved by the proposed LSAOS-DE, EPSDE, MPEDE, UMOEAs and AMALGAM-SO for 30D

| problem | EPSDE | MPEDE | UMOEAS | AMALGAM-SO | LSAOSDE |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $6.10 \mathrm{E}+04(3.88 \mathrm{E}+05)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.62 \mathrm{E}+01(1.16 \mathrm{E}+02)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F02 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $4.74 \mathrm{E}-04(9.28 \mathrm{E}-05)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $6.45 \mathrm{E}-04(9.55 \mathrm{E}-04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $7.86 \mathrm{E}-02(5.58 \mathrm{E}-01)$ | $2.20 \mathrm{E}-04(1.35 \mathrm{E}-03)$ | $2.57 \mathrm{E}+00(1.24 \mathrm{E}+01)$ | $9.04 \mathrm{E}-04(1.45 \mathrm{E}-04)$ | $7.19 \mathrm{E}-05(3.06 \mathrm{E}-04)$ |
| F05 | $2.04 \mathrm{E}+01(4.00 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01(6.60 \mathrm{E}-02)$ | $2.02 \mathrm{E}+01(2.80 \mathrm{E}-01)$ | $2.02 \mathrm{E}+01(1.13 \mathrm{E}-01)$ | $2.03 \mathrm{E}+01(8.29 \mathrm{E}-02)$ |
| F06 | $1.87 \mathrm{E}+01(1.49 \mathrm{E}+00)$ | $2.45 \mathrm{E}-01(4.24 \mathrm{E}-01)$ | $1.86 \mathrm{E}+00(1.60 \mathrm{E}+00)$ | $5.65 \mathrm{E}-03(2.40 \mathrm{E}-03)$ | $4.49 \mathrm{E}-02(1.65 \mathrm{E}-01)$ |
| F07 | $6.76 \mathrm{E}-04(2.92 \mathrm{E}-03)$ | $1.45 \mathrm{E}-04(1.04 \mathrm{E}-03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.35 \mathrm{E}-0391.68 \mathrm{E}-04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F08 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $2.39 \mathrm{E}+00(1.38 \mathrm{E}+00)$ | $2.48 \mathrm{E}-02(2.31 \mathrm{E}-02)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $4.31 \mathrm{E}+01(7.14 \mathrm{E}+00)$ | $2.76 \mathrm{E}+01(7.60 \mathrm{E}+00)$ | $1.25 \mathrm{E}+01(4.47 \mathrm{E}+00)$ | $2.97 \mathrm{E}+00(2.82 \mathrm{E}+00)$ | $4.69 \mathrm{E}+00(1.62 \mathrm{E}+00)$ |
| F10 | $2.25 \mathrm{E}-01(1.95 \mathrm{E}-01)$ | $1.40 \mathrm{E}-01(4.57 \mathrm{E}-02)$ | $1.22 \mathrm{E}+01(2.08 \mathrm{E}+01)$ | $1.35 \mathrm{E}+01(2.40 \mathrm{E}+01)$ | $9.18 \mathrm{E}-03(1.59 \mathrm{E}-02)$ |
| F11 | $3.59 \mathrm{E}+03(4.00 \mathrm{E}+02)$ | $1.82 \mathrm{E}+03(3.84 \mathrm{E}+02)$ | $1.99 \mathrm{E}+03(8.82 \mathrm{E}+02)$ | $2.67 \mathrm{E}+02(3.32 \mathrm{E}+02)$ | $1.60 \mathrm{E}+03(4.42 \mathrm{E}+02)$ |
| F12 | $5.06 \mathrm{E}-01(8.57 \mathrm{E}-02)$ | $2.17 \mathrm{E}-01(8.68 \mathrm{E}-02)$ | $2.23 \mathrm{E}-03(2.13 \mathrm{E}-03)$ | $1.31 \mathrm{E}-01(6.95 \mathrm{E}-02)$ | $3.02 \mathrm{E}-01(1.23 \mathrm{E}-01)$ |
| F13 | $2.50 \mathrm{E}-01(3.90 \mathrm{E}-02)$ | $1.59 \mathrm{E}-01(3.85 \mathrm{E}-02)$ | $5.83 \mathrm{E}-02(2.55 \mathrm{E}-02)$ | $7.64 \mathrm{E}-02(2.54 \mathrm{E}-02)$ | $1.22 \mathrm{E}-01(1.75 \mathrm{E}-02)$ |
| F14 | $2.88 \mathrm{E}-01(4.89 \mathrm{E}-02)$ | $2.19 \mathrm{E}-01(2.29 \mathrm{E}-02)$ | $2.20 \mathrm{E}-01(4.58 \mathrm{E}-02)$ | $3.06 \mathrm{E}-01(4.18 \mathrm{E}-02)$ | $2.18 \mathrm{E}-01(2.38 \mathrm{E}-02)$ |
| F15 | $5.44 \mathrm{E}+00(7.31 \mathrm{E}-01)$ | $2.68 \mathrm{E}+00(5.96 \mathrm{E}-01)$ | $3.49 \mathrm{E}+00(1.15 \mathrm{E}+00)$ | $2.68 \mathrm{E}+00(4.62 \mathrm{E}-01)$ | $2.49 \mathrm{E}+00(2.39 \mathrm{E}-01)$ |
| F16 | $1.12 \mathrm{E}+01(3.76 \mathrm{E}-01)$ | $9.23 \mathrm{E}+00(4.38 \mathrm{E}-01)$ | $1.13 \mathrm{E}+01(5.45 \mathrm{E}-01)$ | $9.43 \mathrm{E}+00(6.99 \mathrm{E}-01)$ | $9.24 \mathrm{E}+00(5.55 \mathrm{E}-01)$ |
| F17 | $3.94 \mathrm{E}+04(3.99 \mathrm{E}+04)$ | $9.93 \mathrm{E}+01(7.09 \mathrm{E}+01)$ | $1.23 \mathrm{E}+03(3.20 \mathrm{E}+02)$ | $1.07 \mathrm{E}+03(4.49 \mathrm{E}+02)$ | $1.36 \mathrm{E}+02(7.15 \mathrm{E}+01)$ |
| F18 | $2.12 \mathrm{E}+02(2.75 \mathrm{E}+02)$ | $1.04 \mathrm{E}+01(4.06 \mathrm{E}+00)$ | $5.66 \mathrm{E}+01(2.16 \mathrm{E}+01)$ | $7.87 \mathrm{E}+01(2.61 \mathrm{E}+01)$ | $6.35 \mathrm{E}+00(2.56 \mathrm{E}+00)$ |
| F19 | $1.31 \mathrm{E}+01(1.04 \mathrm{E}+00)$ | $3.06 \mathrm{E}+00(4.34 \mathrm{E}-01)$ | $5.66 \mathrm{E}+00(7.45 \mathrm{E}-01)$ | $3.91 \mathrm{E}+00(8.67 \mathrm{E}-01)$ | $3.25 \mathrm{E}+00(5.95 \mathrm{E}-01)$ |
| F20 | $6.01 \mathrm{E}+01(1.10 \mathrm{E}+02)$ | $6.61 \mathrm{E}+00(1.96 \mathrm{E}+00)$ | $1.91 \mathrm{E}+01(9.97 \mathrm{E}+00)$ | $5.18 \mathrm{E}+01(3.76 \mathrm{E}+01)$ | $3.86 \mathrm{E}+00(1.29 \mathrm{E}+00)$ |
| F21 | $5.89 \mathrm{E}+03(6.24 \mathrm{E}+03)$ | $7.25 \mathrm{E}+01(7.79 \mathrm{E}+01)$ | $4.10 \mathrm{E}+02(1.98 \mathrm{E}+02)$ | $5.72 \mathrm{E}+02(2.68 \mathrm{E}+02)$ | $3.22 \mathrm{E}+01(4.47 \mathrm{E}+01)$ |
| F22 | $2.39 \mathrm{E}+02(1.00 \mathrm{E}+02)$ | $8.87 \mathrm{E}+01(7.04 \mathrm{E}+01)$ | $1.35 \mathrm{E}+02(7.19 \mathrm{E}+01)$ | $1.25 \mathrm{E}+02(4.55 \mathrm{E}+01)$ | $3.36 \mathrm{E}+01(1.71 \mathrm{E}+01)$ |
| F23 | $3.14 \mathrm{E}+02(8.89 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(4.02 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(3.44 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02(3.78 \mathrm{E}-04)$ | $3.06 \mathrm{E}+02(3.13 \mathrm{E}+01)$ |
| F24 | $2.28 \mathrm{E}+02(5.46 \mathrm{E}+00)$ | $2.24 \mathrm{E}+02(8.00 \mathrm{E}-01)$ | $2.25 \mathrm{E}+02(4.17 \mathrm{E}+00)$ | $2.00 \mathrm{E}+02(3.29 \mathrm{E}-02)$ | $2.14 \mathrm{E}+02(1.16 \mathrm{E}+01)$ |
| F25 | $2.00 \mathrm{E}+02(1.43 \mathrm{E}-01)$ | $2.03 \mathrm{E}+02(2.15 \mathrm{E}-01)$ | $2.04 \mathrm{E}+02(1.05 \mathrm{E}+00)$ | $2.02 \mathrm{E}+02(7.57 \mathrm{E}-01)$ | $2.02 \mathrm{E}+02(6.39 \mathrm{E}-01)$ |
| F26 | $1.00 \mathrm{E}+02(3.66 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(3.26 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(7.37 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(3.87 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.66 \mathrm{E}-02)$ |
| F27 | $8.33 \mathrm{E}+02(1.21 \mathrm{E}+02)$ | $3.63 \mathrm{E}+02(4.89 \mathrm{E}+01)$ | $3.58 \mathrm{E}+02(4.15 \mathrm{E}+01)$ | $3.00 \mathrm{E}+02(3.09 \mathrm{E}-02)$ | $3.00 \mathrm{E}+02(2.67 \mathrm{E}-02)$ |
| F28 | $3.94 \mathrm{E}+02(1.26 \mathrm{E}+01)$ | $8.19 \mathrm{E}+02(2.62 \mathrm{E}+01)$ | $8.75 \mathrm{E}+02(3.97 \mathrm{E}+01)$ | $7.96 \mathrm{E}+02(2.56 \mathrm{E}+01)$ | $8.18 \mathrm{E}+02(9.20 \mathrm{E}+01)$ |
| F29 | $2.14 \mathrm{E}+02(1.21 \mathrm{E}+00)$ | $6.73 \mathrm{E}+02(1.53 \mathrm{E}+02)$ | $7.08 \mathrm{E}+02(2.10 \mathrm{E}+02)$ | $7.11 \mathrm{E}+02(2.88 \mathrm{E}+02)$ | $6.85 \mathrm{E}+02(1.27 \mathrm{E}+02)$ |
| F30 | $5.73 \mathrm{E}+02(1.27 \mathrm{E}+02)$ | $5.20 \mathrm{E}+02(1.30 \mathrm{E}+02)$ | $1.34 \mathrm{E}+03(5.54 \mathrm{E}+02)$ | $1.53 \mathrm{E}+03(4.98 \mathrm{E}+02)$ | $4.87 \mathrm{E}+02(1.12 \mathrm{E}+02)$ |


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Table A.6: Error values achieved by the proposed LSAOS-DE, LSHADE, SHADE, JADE, CoDE and SaDE for 50 D

| problem | LSHADE | SHADE | JADE | CoDE | SaDE | LSAOSDE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $1.49 \mathrm{E}+03(1.96 \mathrm{E}+03)$ | $9.49 \mathrm{E}+03(8.76 \mathrm{E}+03)$ | $4.12 \mathrm{E}+03(4.27 \mathrm{E}+03)$ | $2.18 \mathrm{E}+05(1.10 \mathrm{E}+05)$ | $4.28 \mathrm{E}+05(1.83 \mathrm{E}+05)$ | $1.23 \mathrm{E}+03(2.50 \mathrm{E}+03)$ |
| F02 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.36 \mathrm{E}+02(2.60 \mathrm{E}+02)$ | $2.72 \mathrm{E}+03(1.56 \mathrm{E}+03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.85 \mathrm{E}+03(2.05 \mathrm{E}+03)$ | $2.85 \mathrm{E}+01(5.16 \mathrm{E}+01)$ | $5.91 \mathrm{E}-02(2.04 \mathrm{E}-01)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $6.94 \mathrm{E}+01(4.29 \mathrm{E}+01)$ | $5.49 \mathrm{E}+01(4.08 \mathrm{E}+01)$ | $3.40 \mathrm{E}+01(3.99 \mathrm{E}+01)$ | $3.16 \mathrm{E}+01(3.70 \mathrm{E}+01)$ | $1.04 \mathrm{E}+02(2.79 \mathrm{E}+01)$ | $3.93 \mathrm{E}+01(3.93 \mathrm{E}+01)$ |
| F05 | $2.03 \mathrm{E}+01(3.33 \mathrm{E}-02)$ | $2.06 \mathrm{E}+01(3.28 \mathrm{E}-02)$ | $2.06 \mathrm{E}+01(8.10 \mathrm{E}-02)$ | $2.00 \mathrm{E}+01(8.54 \mathrm{E}-02)$ | $2.08 \mathrm{E}+01(4.03 \mathrm{E}-02)$ | $2.04 \mathrm{E}+01(2.30 \mathrm{E}-03)$ |
| F06 | $2.52 \mathrm{E}-01(5.39 \mathrm{E}-01)$ | $7.52 \mathrm{E}-02(3.09 \mathrm{E}-01)$ | $9.80 \mathrm{E}+00(1.30 \mathrm{E}+01)$ | $8.36 \mathrm{E}+00(3.65 \mathrm{E}+00)$ | $3.34 \mathrm{E}+00(1.46 \mathrm{E}+00)$ | $1.20 \mathrm{E}+00(7.82 \mathrm{E}-01)$ |
| F07 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.30 \mathrm{E}-03(3.09 \mathrm{E}-03)$ | 8.22E-03(3.18E-03) | $3.09 \mathrm{E}-03(4.65 \mathrm{E}-03)$ |
| F08 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $6.12 \mathrm{E}+01(4.58 \mathrm{E}+00)$ | $1.36 \mathrm{E}+01(1.27 \mathrm{E}+00)$ | $6.44 \mathrm{E}-01(7.13 \mathrm{E}-01)$ | $5.62 \mathrm{E}+01(3.17 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $1.17 \mathrm{E}+01(2.23 \mathrm{E}+00)$ | $1.70 \mathrm{E}+02(1.22 \mathrm{E}+01)$ | $1.29 \mathrm{E}+02(9.03 \mathrm{E}+00)$ | $7.94 \mathrm{E}+01(1.83 \mathrm{E}+01)$ | $2.12 \mathrm{E}+02(9.83 \mathrm{E}+000-$ | $1.70 \mathrm{E}+01(2.96 \mathrm{E}+00)$ |
| F10 | $4.78 \mathrm{E}-02(2.27 \mathrm{E}-02)$ | $2.37 \mathrm{E}+03(2.13 \mathrm{E}+02)$ | $6.11 \mathrm{E}+02(6.48 \mathrm{E}+01)$ | $5.26 \mathrm{E}+00(2.63 \mathrm{E}+00)$ | $1.93 \mathrm{E}+03(1.92 \mathrm{E}+02)$ | $1.31 \mathrm{E}+00(1.49 \mathrm{E}+00)$ |
| F11 | $3.25 \mathrm{E}+03(2.51 \mathrm{E}+02)$ | $7.95 \mathrm{E}+03(5.73 \mathrm{E}+02)$ | $7.61 \mathrm{E}+03(3.80 \mathrm{E}+02)$ | $4.30 \mathrm{E}+03(6.50 \mathrm{E}+02)$ | $9.04 \mathrm{E}+03(3.40 \mathrm{E}+02)$ | $4.02 \mathrm{E}+03(7.88 \mathrm{E}+02)$ |
| F12 | $2.10 \mathrm{E}-01(2.43 \mathrm{E}-02)$ | 8.22E-01(8.23E-02) | 8.52E-01(8.10E-02) | $8.10 \mathrm{E}-02(4.70 \mathrm{E}-02)$ | $1.22 \mathrm{E}+00(1.26 \mathrm{E}-01)$ | $3.71 \mathrm{E}-01(2.27 \mathrm{E}-02)$ |
| F13 | $1.55 \mathrm{E}-01(1.92 \mathrm{E}-02)$ | $2.44 \mathrm{E}-01(2.41 \mathrm{E}-02)$ | $2.84 \mathrm{E}-01(3.07 \mathrm{E}-02)$ | $3.28 \mathrm{E}-01(5.85 \mathrm{E}-02)$ | $4.26 \mathrm{E}-01(3.65 \mathrm{E}-02)$ | $1.97 \mathrm{E}-01(2.04 \mathrm{E}-02)$ |
| F14 | $3.02 \mathrm{E}-01(3.14 \mathrm{E}-02)$ | $2.75 \mathrm{E}-01(2.84 \mathrm{E}-02)$ | $2.94 \mathrm{E}-01(2.41 \mathrm{E}-02)$ | $2.78 \mathrm{E}-01(3.10 \mathrm{E}-02)$ | $3.08 \mathrm{E}-01(1.95 \mathrm{E}-02)$ | $2.94 \mathrm{E}-01(1.88 \mathrm{E}-02)$ |
| F15 | $5.10 \mathrm{E}+00(4.91 \mathrm{E}-01)$ | $1.89 \mathrm{E}+01(1.25 \mathrm{E}+00)$ | $1.44 \mathrm{E}+01(8.81 \mathrm{E}-01)$ | $6.48 \mathrm{E}+00(1.42 \mathrm{E}+00)$ | $2.23 \mathrm{E}+01(1.49 \mathrm{E}+00)$ | $6.08 \mathrm{E}+00(8.36 \mathrm{E}-01)$ |
| F16 | $1.68 \mathrm{E}+01(4.36 \mathrm{E}-01)$ | $2.01 \mathrm{E}+01(8.64 \mathrm{E}-01)$ | $2.00 \mathrm{E}+01(8.17 \mathrm{E}-01)$ | $1.80 \mathrm{E}+01(1.04 \mathrm{E}+00)$ | $2.06 \mathrm{E}+01(2.58 \mathrm{E}-01)$ | $1.80 \mathrm{E}+01(9.65 \mathrm{E}-01)$ |
| F17 | $1.67 \mathrm{E}+03(4.53 \mathrm{E}+02)$ | $1.89 \mathrm{E}+03(4.66 \mathrm{E}+02)$ | $1.86 \mathrm{E}+03(4.61 \mathrm{E}+02)$ | $1.47 \mathrm{E}+04(7.39 \mathrm{E}+03)$ | $1.44 \mathrm{E}+03(3.94 \mathrm{E}+02)$ | $1.04 \mathrm{E}+03(3.56 \mathrm{E}+02)$ |
| F18 | $1.06 \mathrm{E}+02(1.71 \mathrm{E}+01)$ | $9.64 \mathrm{E}+01(2.22 \mathrm{E}+01)$ | $1.15 \mathrm{E}+02(2.07 \mathrm{E}+01)$ | $3.03 \mathrm{E}+02(3.59 \mathrm{E}+02)$ | $9.94 \mathrm{E}+01(1.42 \mathrm{E}+01)$ | $8.60 \mathrm{E}+01(1.06 \mathrm{E}+01)$ |
| F19 | $7.73 \mathrm{E}+00(1.74 \mathrm{E}+00)$ | $1.14 \mathrm{E}+01(5.74 \mathrm{E}-01)$ | $1.14 \mathrm{E}+01(7.35 \mathrm{E}-01)$ | $6.75 \mathrm{E}+00(1.56 \mathrm{E}+00)$ | $1.19 \mathrm{E}+01(3.83 \mathrm{E}+00)$ | $1.06 \mathrm{E}+01(8.51 \mathrm{E}-01)$ |
| F20 | $1.49 \mathrm{E}+01(4.93 \mathrm{E}+00)$ | $3.21 \mathrm{E}+01(1.63 \mathrm{E}+01)$ | $2.26 \mathrm{E}+01(1.30 \mathrm{E}+01)$ | $1.73 \mathrm{E}+02(1.54 \mathrm{E}+02)$ | $8.34 \mathrm{E}+01(1.68 \mathrm{E}+01)$ | $1.18 \mathrm{E}+01(3.98 \mathrm{E}+00)$ |
| F21 | $5.64 \mathrm{E}+02(1.62 \mathrm{E}+02)$ | $7.03 \mathrm{E}+02(2.28 \mathrm{E}+02)$ | $7.71 \mathrm{E}+02(2.35 \mathrm{E}+02)$ | $9.74 \mathrm{E}+03(7.69 \mathrm{E}+03)$ | $1.11 \mathrm{E}+03(3.69 \mathrm{E}+02)$ | $4.15 \mathrm{E}+02(1.20 \mathrm{E}+02)$ |
| F22 | $9.83 \mathrm{E}+01(6.64 \mathrm{E}+01)$ | $5.13 \mathrm{E}+02(1.25 \mathrm{E}+02)$ | $7.74 \mathrm{E}+02(1.34 \mathrm{E}+02)$ | $5.54 \mathrm{E}+02(1.97 \mathrm{E}+02)$ | $7.37 \mathrm{E}+02(1.29 \mathrm{E}+02)$ | $1.80 \mathrm{E}+02(8.48 \mathrm{E}+01)$ |
| F23 | $3.44 \mathrm{E}+02(3.84 \mathrm{E}-13)$ | $3.44 \mathrm{E}+02(3.03 \mathrm{E}-13)$ | $3.44 \mathrm{E}+02(2.78 \mathrm{E}-13)$ | $3.44 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.44 \mathrm{E}+02(2.21 \mathrm{E}-08)$ | $3.41 \mathrm{E}+02(2.03 \mathrm{E}+01)$ |
| F24 | $2.75 \mathrm{E}+02(6.45 \mathrm{E}-01)$ | $2.73 \mathrm{E}+02(1.39 \mathrm{E}+00)$ | $2.73 \mathrm{E}+02(1.25 \mathrm{E}+00)$ | $2.71 \mathrm{E}+02(2.34 \mathrm{E}+00)$ | $2.71 \mathrm{E}+02(1.98 \mathrm{E}+00)$ | $2.52 \mathrm{E}+02(3.13 \mathrm{E}+01)$ |
| F25 | $2.05 \mathrm{E}+02(2.99 \mathrm{E}-01)$ | $2.05 \mathrm{E}+02(3.77 \mathrm{E}-01)$ | $2.06 \mathrm{E}+02(2.18 \mathrm{E}+00)$ | $2.09 \mathrm{E}+02(5.65 \mathrm{E}+00)$ | $2.00 \mathrm{E}+02(8.68 \mathrm{E}-08)$ | $2.04 \mathrm{E}+02(2.62 \mathrm{E}+00)$ |
| F26 | $1.00 \mathrm{E}+02(1.78 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(3.42 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.96 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(8.38 \mathrm{E}-02)$ | $1.26 \mathrm{E}+02(4.39 \mathrm{E}+01)$ | $1.00 \mathrm{E}+02(1.74 \mathrm{E}-02)$ |
| F27 | $3.44 \mathrm{E}+02(2.78 \mathrm{E}+01)$ | $3.25 \mathrm{E}+02(2.75 \mathrm{E}+01)$ | $3.26 \mathrm{E}+02(3.06 \mathrm{E}+01)$ | $5.39 \mathrm{E}+02(7.20 \mathrm{E}+01)$ | $3.79 \mathrm{E}+02(4.57 \mathrm{E}+01)$ | $3.24 \mathrm{E}+02(2.35 \mathrm{E}+01)$ |
| F28 | $1.12 \mathrm{E}+03(3.58 \mathrm{E}+01)$ | $1.10 \mathrm{E}+03(2.34 \mathrm{E}+01)$ | $1.09 \mathrm{E}+03(2.73 \mathrm{E}+01)$ | $1.18 \mathrm{E}+03(5.53 \mathrm{E}+01)$ | $1.52 \mathrm{E}+03(1.47 \mathrm{E}+02)$ | $1.11 \mathrm{E}+03(1.34 \mathrm{E}+02)$ |
| F29 | $8.05 \mathrm{E}+02(3.46 \mathrm{E}+01)$ | $8.01 \mathrm{E}+02(3.09 \mathrm{E}+01)$ | $7.99 \mathrm{E}+02(4.10 \mathrm{E}+01)$ | $9.65 \mathrm{E}+02(8.89 \mathrm{E}+01)$ | $5.85 \mathrm{E}+02(9.10 \mathrm{E}+01)$ | $7.91 \mathrm{E}+02(4.87 \mathrm{E}+01)$ |
| F30 | $8.78 \mathrm{E}+03(5.23 \mathrm{E}+02)$ | $8.52 \mathrm{E}+03(3.47 \mathrm{E}+02)$ | $8.64 \mathrm{E}+03(3.59 \mathrm{E}+02)$ | $9.07 \mathrm{E}+03(4.84 \mathrm{E}+02)$ | $1.11 \mathrm{E}+04(1.09 \mathrm{E}+03)$ | $8.57 \mathrm{E}+03(4.19 \mathrm{E}+02)$ |


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| problem | EPSDE | MPEDE | UMOEAS | AMALGAM-SO | LSAOSDE |
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|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $2.19 \mathrm{E}+06(5.90 \mathrm{E}+06)$ | $5.98 \mathrm{E}+03(6.15 \mathrm{E}+03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.83 \mathrm{E}-02(1.11 \mathrm{E}-03)$ | $1.23 \mathrm{E}+03(2.50 \mathrm{E}+03)$ |
| F02 | $8.01 \mathrm{E}-09(1.65 \mathrm{E}-08)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.08 \mathrm{E}+04(1.89 \mathrm{E}+04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $2.42 \mathrm{E}-08(9.86 \mathrm{E}-08)$ | $1.89 \mathrm{E}-04(3.42 \mathrm{E}-04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $9.85 \mathrm{E}-04(6.09 \mathrm{E}-04)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $2.82 \mathrm{E}+01(2.10 \mathrm{E}+01)$ | $2.59 \mathrm{E}+01(3.35 \mathrm{E}+01)$ | $9.05 \mathrm{E}+01(2.67 \mathrm{E}+01)$ | $3.84 \mathrm{E}+01(3.13 \mathrm{E}+01)$ | $3.93 \mathrm{E}+01(3.93 \mathrm{E}+01)$ |
| F05 | $2.06 \mathrm{E}+01(3.31 \mathrm{E}-02)$ | $2.04 \mathrm{E}+01(7.67 \mathrm{E}-02)$ | $2.02 \mathrm{E}+01(3.00 \mathrm{E}-01)$ | $2.00 \mathrm{E}+01(1.56 \mathrm{E}-01)$ | $2.04 \mathrm{E}+01(2.30 \mathrm{E}-03)$ |
| F06 | $4.67 \mathrm{E}+01(3.21 \mathrm{E}+00)$ | $2.17 \mathrm{E}+00(1.36 \mathrm{E}+00)$ | $4.12 \mathrm{E}+00(2.57 \mathrm{E}+00)$ | $9.50 \mathrm{E}+00(4.79 \mathrm{E}-01)$ | $1.20 \mathrm{E}+00(7.82 \mathrm{E}-01)$ |
| F07 | $5.55 \mathrm{E}-03(6.87 \mathrm{E}-03)$ | $1.16 \mathrm{E}-03(2.97 \mathrm{E}-03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $2.44 \mathrm{E}-03(2.10 \mathrm{E}-04)$ | $3.09 \mathrm{E}-03(4.65 \mathrm{E}-03)$ |
| F08 | $7.80 \mathrm{E}-02(2.70 \mathrm{E}-01)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $5.94 \mathrm{E}+00(3.36 \mathrm{E}+00)$ | $4.26 \mathrm{E}+01(2.68 \mathrm{E}-01)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $1.46 \mathrm{E}+02(1.80 \mathrm{E}+01)$ | $5.09 \mathrm{E}+01(9.95 \mathrm{E}+00)$ | $2.28 \mathrm{E}+01(5.21 \mathrm{E}+00)$ | $9.06 \mathrm{E}+01(4.02 \mathrm{E}+00)$ | $1.70 \mathrm{E}+01(2.96 \mathrm{E}+00)$ |
| F10 | $5.89 \mathrm{E}+02(6.22 \mathrm{E}+02)$ | $3.44 \mathrm{E}+00(1.62 \mathrm{E}+00)$ | $2.07 \mathrm{E}+02(2.36 \mathrm{E}+02)$ | $1.88 \mathrm{E}+03(2.37 \mathrm{E}+01)$ | $1.31 \mathrm{E}+00(1.49 \mathrm{E}+00)$ |
| F11 | $9.03 \mathrm{E}+03(7.20 \mathrm{E}+02)$ | $4.16 \mathrm{E}+03(6.81 \mathrm{E}+02)$ | $4.05 \mathrm{E}+03(1.27 \mathrm{E}+03)$ | $4.35 \mathrm{E}+03(4.23 \mathrm{E}+02)$ | $4.02 \mathrm{E}+03(7.88 \mathrm{E}+02)$ |
| F12 | $8.62 \mathrm{E}-01(9.60 \mathrm{E}-02)$ | $2.90 \mathrm{E}-01(7.97 \mathrm{E}-02)$ | $1.27 \mathrm{E}-03(8.53 \mathrm{E}-04)$ | $3.00 \mathrm{E}-02(7.73 \mathrm{E}-02)$ | $3.71 \mathrm{E}-01(2.27 \mathrm{E}-02)$ |
| F13 | $3.69 \mathrm{E}-01(5.04 \mathrm{E}-02)$ | $2.46 \mathrm{E}-01(3.34 \mathrm{E}-02)$ | $9.58 \mathrm{E}-02(3.47 \mathrm{E}-02)$ | $2.90 \mathrm{E}-01(3.41 \mathrm{E}-02)$ | $1.97 \mathrm{E}-01(2.04 \mathrm{E}-02)$ |
| F14 | $3.46 \mathrm{E}-01(1.23 \mathrm{E}-01)$ | $2.76 \mathrm{E}-01(2.88 \mathrm{E}-02)$ | $2.85 \mathrm{E}-01(5.03 \mathrm{E}-02)$ | $5.24 \mathrm{E}-01(3.34 \mathrm{E}-02)$ | $2.94 \mathrm{E}-01(1.88 \mathrm{E}-02)$ |
| F15 | $1.80 \mathrm{E}+01(2.06 \mathrm{E}+00)$ | $5.56 \mathrm{E}+00(1.02 \mathrm{E}+00)$ | $6.13 \mathrm{E}+00(1.20 \mathrm{E}+00)$ | $6.21 \mathrm{E}+00(4.81 \mathrm{E}-01)$ | $6.08 \mathrm{E}+00(8.36 \mathrm{E}-01)$ |
| F16 | $2.07 \mathrm{E}+01(4.68 \mathrm{E}-01)$ | $1.77 \mathrm{E}+01(6.80 \mathrm{E}-01)$ | $2.02 \mathrm{E}+01(5.50 \mathrm{E}-01)$ | $2.06 \mathrm{E}+01(1.28 \mathrm{E}+00)$ | $1.80 \mathrm{E}+01(9.65 \mathrm{E}-01)$ |
| F17 | $2.05 \mathrm{E}+05(1.55 \mathrm{E}+05)$ | $1.15 \mathrm{E}+03(3.60 \mathrm{E}+02)$ | $2.50 \mathrm{E}+03(4.91 \mathrm{E}+02)$ | $2.77 \mathrm{E}+03(4.43 \mathrm{E}+02)$ | $1.04 \mathrm{E}+03(3.56 \mathrm{E}+02)$ |
| F18 | $4.02 \mathrm{E}+03(6.52 \mathrm{E}+03)$ | $9.20 \mathrm{E}+01(1.15 \mathrm{E}+01)$ | $1.31 \mathrm{E}+02(4.08 \mathrm{E}+01)$ | $2.25 \mathrm{E}+02(5.57 \mathrm{E}+01)$ | $8.60 \mathrm{E}+01(1.06 \mathrm{E}+01)$ |
| F19 | $2.47 \mathrm{E}+01(1.51 \mathrm{E}+00)$ | $8.25 \mathrm{E}+00(1.24 \mathrm{E}+00)$ | $1.09 \mathrm{E}+01(1.81 \mathrm{E}+00)$ | $2.13 \mathrm{E}+01(2.57 \mathrm{E}+00)$ | $1.06 \mathrm{E}+01(8.51 \mathrm{E}-01)$ |
| F20 | $6.36 \mathrm{E}+02(1.64 \mathrm{E}+03)$ | $2.43 \mathrm{E}+01(7.47 \mathrm{E}+00)$ | $1.28 \mathrm{E}+02(4.02 \mathrm{E}+01)$ | $3.73 \mathrm{E}+02(1.25 \mathrm{E}+02)$ | $1.18 \mathrm{E}+01(3.98 \mathrm{E}+00)$ |
| F21 | $7.43 \mathrm{E}+04(5.11 \mathrm{E}+04)$ | $4.70 \mathrm{E}+02(1.40 \mathrm{E}+02)$ | $1.50 \mathrm{E}+03(3.95 \mathrm{E}+02)$ | $1.71 \mathrm{E}+03(3.76 \mathrm{E}+02)$ | $4.15 \mathrm{E}+02(1.20 \mathrm{E}+02)$ |
| F22 | $7.98 \mathrm{E}+02(1.64 \mathrm{E}+02)$ | $4.31 \mathrm{E}+02(1.81 \mathrm{E}+02)$ | $3.67 \mathrm{E}+02(1.88 \mathrm{E}+02)$ | $8.15 \mathrm{E}+02(1.18 \mathrm{E}+02)$ | $1.80 \mathrm{E}+02(8.48 \mathrm{E}+01)$ |
| F23 | $3.37 \mathrm{E}+02(3.20 \mathrm{E}-12)$ | $3.44 \mathrm{E}+02(4.73 \mathrm{E}-13)$ | $3.44 \mathrm{E}+02(2.85 \mathrm{E}-13)$ | $3.44 \mathrm{E}+02(7.75 \mathrm{E}-04)$ | $3.41 \mathrm{E}+02(2.03 \mathrm{E}+01)$ |
| F24 | $2.72 \mathrm{E}+02(5.75 \mathrm{E}+00)$ | $2.75 \mathrm{E}+02(1.08 \mathrm{E}+00)$ | $2.73 \mathrm{E}+02(2.24 \mathrm{E}+00)$ | $2.74 \mathrm{E}+02(2.03 \mathrm{E}+00)$ | $2.52 \mathrm{E}+02(3.13 \mathrm{E}+01)$ |
| F25 | $2.01 \mathrm{E}+02(2.24 \mathrm{E}+00)$ | $2.05 \mathrm{E}+02(1.66 \mathrm{E}+00)$ | $2.08 \mathrm{E}+02(2.66 \mathrm{E}+00)$ | $2.01 \mathrm{E}+02(2.26 \mathrm{E}+00)$ | $2.04 \mathrm{E}+02(2.62 \mathrm{E}+00)$ |
| F26 | $1.00 \mathrm{E}+02(4.96 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(3.19 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.06 \mathrm{E}-01)$ | $1.54 \mathrm{E}+02(8.49 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.74 \mathrm{E}-02)$ |
| F27 | $1.57 \mathrm{E}+03(4.62 \mathrm{E}+01)$ | $3.56 \mathrm{E}+02(4.41 \mathrm{E}+01)$ | $4.55 \mathrm{E}+02(6.50 \mathrm{E}+01)$ | $5.99 \mathrm{E}+02(2.95 \mathrm{E}+01)$ | $3.24 \mathrm{E}+02(2.35 \mathrm{E}+01)$ |
| F28 | $3.87 \mathrm{E}+02(1.22 \mathrm{E}+01)$ | $1.15 \mathrm{E}+03(3.81 \mathrm{E}+01)$ | $1.29 \mathrm{E}+03(7.01 \mathrm{E}+01)$ | $1.70 \mathrm{E}+03(4.74 \mathrm{E}+01)$ | $1.11 \mathrm{E}+03(1.34 \mathrm{E}+02)$ |
| F29 | $2.25 \mathrm{E}+02(2.26 \mathrm{E}+00)$ | $7.94 \mathrm{E}+02(5.77 \mathrm{E}+01)$ | $8.13 \mathrm{E}+02(9.79 \mathrm{E}+01)$ | $7.20 \mathrm{E}+02(2.57 \mathrm{E}+02)$ | $7.91 \mathrm{E}+02(4.87 \mathrm{E}+01)$ |
| F30 | $1.08 \mathrm{E}+03(1.90 \mathrm{E}+02)$ | $8.79 \mathrm{E}+03(4.33 \mathrm{E}+02)$ | $8.99 \mathrm{E}+03(7.39 \mathrm{E}+02)$ | $1.48 \mathrm{E}+04(7.71 \mathrm{E}+02)$ | $8.57 \mathrm{E}+03(4.19 \mathrm{E}+02)$ |


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|  |  |  |  |  | 8\＆J |
| （ $00+$ H $00 \cdot 0$ ） $00+$ 式 0000 |  | （ $00+$ H00＊0）00＋具0000 | （ $00+$ H00＊0） $00+$ 号 0000 | （80－GLC．L） $60-$－GL6 9 | 78E |
|  |  |  |  | （ $20+$ HzI ${ }^{\circ}$ ） $90+$ 鳥07＊ |  |


|  | AOSDE-LS | AOSDE-SR | AOSDE-FIR | AOSDE-PR | AOSDE-PBM | AOSDE-RD | AOSDE-PAOC | LSAOS-DE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F02 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F04 | $1.65 \mathrm{E}+01(1.74 \mathrm{E}+01)$ | $1.99 \mathrm{E}+01(1.73 \mathrm{E}+01)$ | $2.01 \mathrm{E}+01(1.70 \mathrm{E}+01)$ | $1.99 \mathrm{E}+01(1.73 \mathrm{E}+01)$ | $1.65 \mathrm{E}+01(1.74 \mathrm{E}+01)$ | $1.65 \mathrm{E}+01(1.74 \mathrm{E}+01)$ | $1.99 \mathrm{E}+01(1.73 \mathrm{E}+01)$ | $1.65 \mathrm{E}+01(1.74 \mathrm{E}+01)$ |
| F05 | $1.41 \mathrm{E}+01(7.33 \mathrm{E}+00)$ | $1.67 \mathrm{E}+01(6.09 \mathrm{E}+00)$ | $1.59 \mathrm{E}+01(6.76 \mathrm{E}+00)$ | $1.65 \mathrm{E}+01(6.34 \mathrm{E}+00)$ | $1.41 \mathrm{E}+01(7.88 \mathrm{E}+00)$ | $1.41 \mathrm{E}+01(7.29 \mathrm{E}+00)$ | $1.72 \mathrm{E}+01(6.05 \mathrm{E}+00)$ | $1.38 \mathrm{E}+01(7.90 \mathrm{E}+00)$ |
| F06 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F07 | 8.21E-04(3.06E-03) | $6.04 \mathrm{E}-03(8.73 \mathrm{E}-03)$ | $5.22 \mathrm{E}-03(7.66 \mathrm{E}-03)$ | $5.22 \mathrm{E}-03(9.31 \mathrm{E}-03)$ | $3.87 \mathrm{E}-04(1.99 \mathrm{E}-03)$ | $1.45 \mathrm{E}-04(1.04 \mathrm{E}-03)$ | $5.60 \mathrm{E}-03(1.18 \mathrm{E}-02)$ | $1.01 \mathrm{E}-03(3.31 \mathrm{E}-03)$ |
| F08 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
| F09 | $1.03 \mathrm{E}+00(1.73 \mathrm{E}+00)$ | $3.47 \mathrm{E}+00(1.51 \mathrm{E}+00)$ | $3.06 \mathrm{E}+00(1.29 \mathrm{E}+00)$ | $3.79 \mathrm{E}+00(1.97 \mathrm{E}+00)$ | $1.06 \mathrm{E}+00(1.62 \mathrm{E}+00)$ | $1.13 \mathrm{E}+00(1.66 \mathrm{E}+00)$ | $2.70 \mathrm{E}+00(1.26 \mathrm{E}+00)$ | $8.42 \mathrm{E}-01(1.29 \mathrm{E}+00)$ |
| F10 | $4.90 \mathrm{E}-03(2.11 \mathrm{E}-02)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.22 \mathrm{E}-03(8.75 \mathrm{E}-03)$ | $3.67 \mathrm{E}-03(1.48 \mathrm{E}-02)$ | $1.22 \mathrm{E}-03(8.75 \mathrm{E}-03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $2.45 \mathrm{E}-03(1.22 \mathrm{E}-02)$ | $2.45 \mathrm{E}-03(1.75 \mathrm{E}-02)$ |
| 1 | $7.20 \mathrm{E}+01(5.26 \mathrm{E}+01)$ | $7.39 \mathrm{E}+01(5.23 \mathrm{E}+01)$ | $7.03 \mathrm{E}+01(6.20 \mathrm{E}+01)$ | $7.70 \mathrm{E}+01(6.67 \mathrm{E}+01)$ | $6.56 \mathrm{E}+01(4.94 \mathrm{E}+01)$ | $8.17 \mathrm{E}+01(5.84 \mathrm{E}+01)$ | $4.77 \mathrm{E}+01(5.42 \mathrm{E}+01)$ | $5.15 \mathrm{E}+01(4.88 \mathrm{E}+01)$ |
| F12 | $1.93 \mathrm{E}-01(9.88 \mathrm{E}-02)$ | $2.16 \mathrm{E}-01(9.80 \mathrm{E}-02)$ | $1.67 \mathrm{E}-01(1.04 \mathrm{E}-01)$ | $2.17 \mathrm{E}-01(9.02 \mathrm{E}-02)$ | $2.03 \mathrm{E}-01(8.86 \mathrm{E}-02)$ | $1.89 \mathrm{E}-01(9.71 \mathrm{E}-02)$ | $1.12 \mathrm{E}-01(6.83 \mathrm{E}-02)$ | $1.49 \mathrm{E}-01(9.30 \mathrm{E}-02)$ |
| F13 | $4.38 \mathrm{E}-02(1.76 \mathrm{E}-02)$ | $2.91 \mathrm{E}-02(1.21 \mathrm{E}-02)$ | $4.40 \mathrm{E}-02(1.64 \mathrm{E}-02)$ | $3.04 \mathrm{E}-02(1.18 \mathrm{E}-02)$ | $3.63 \mathrm{E}-02(1.73 \mathrm{E}-02)$ | $3.96 \mathrm{E}-02(1.84 \mathrm{E}-02)$ | $5.06 \mathrm{E}-02(1.68 \mathrm{E}-02)$ | $5.06 \mathrm{E}-02(1.34 \mathrm{E}-02)$ |
| 14 | $9.61 \mathrm{E}-02(3.44 \mathrm{E}-02)$ | 8.98E-02(3.04E-02) | $1.06 \mathrm{E}-01(3.31 \mathrm{E}-02)$ | $9.19 \mathrm{E}-02(3.29 \mathrm{E}-02)$ | $9.94 \mathrm{E}-02(3.05 \mathrm{E}-02)$ | $1.07 \mathrm{E}-01(3.63 \mathrm{E}-02)$ | $9.26 \mathrm{E}-02(3.09 \mathrm{E}-02)$ | $1.06 \mathrm{E}-01(3.07 \mathrm{E}-02)$ |
| F15 | $5.10 \mathrm{E}-01(1.99 \mathrm{E}-01)$ | $6.17 \mathrm{E}-01(1.67 \mathrm{E}-01)$ | $5.05 \mathrm{E}-01(1.75 \mathrm{E}-01)$ | $5.93 \mathrm{E}-01(2.07 \mathrm{E}-01)$ | $5.51 \mathrm{E}-01(2.04 \mathrm{E}-01)$ | $5.49 \mathrm{E}-01(1.98 \mathrm{E}-01)$ | $4.17 \mathrm{E}-01(7.25 \mathrm{E}-02)$ | $4.03 \mathrm{E}-01(6.57 \mathrm{E}-02)$ |
| F16 | $1.28 \mathrm{E}+00(4.20 \mathrm{E}-01)$ | $1.17 \mathrm{E}+00(5.36 \mathrm{E}-01)$ | $1.36 \mathrm{E}+00(4.41 \mathrm{E}-01)$ | $1.17 \mathrm{E}+00(4.94 \mathrm{E}-01)$ | $1.32 \mathrm{E}+00(3.94 \mathrm{E}-01)$ | $1.24 \mathrm{E}+00(3.91 \mathrm{E}-01)$ | $1.30 \mathrm{E}+00(3.00 \mathrm{E}-01)$ | $1.26 \mathrm{E}+00(3.42 \mathrm{E}-01)$ |
| F17 | $1.18 \mathrm{E}+00(1.63 \mathrm{E}+00)$ | $1.47 \mathrm{E}+00(1.04 \mathrm{E}+00)$ | $1.05 \mathrm{E}+00(1.63 \mathrm{E}+00)$ | $1.09 \mathrm{E}+00(9.49 \mathrm{E}-01)$ | $1.11 \mathrm{E}+00(1.09 \mathrm{E}+00)$ | $1.05 \mathrm{E}+00(9.50 \mathrm{E}-01)$ | $1.14 \mathrm{E}+00(1.23 \mathrm{E}+00)$ | $1.04 \mathrm{E}+00(1.01 \mathrm{E}+00)$ |
| F18 | $9.94 \mathrm{E}-02(1.15 \mathrm{E}-01)$ | $1.34 \mathrm{E}-01(1.68 \mathrm{E}-01)$ | $2.34 \mathrm{E}-01(3.64 \mathrm{E}-01)$ | $1.71 \mathrm{E}-01(2.41 \mathrm{E}-01)$ | $1.37 \mathrm{E}-01(2.07 \mathrm{E}-01)$ | $1.38 \mathrm{E}-01(1.88 \mathrm{E}-01)$ | $1.74 \mathrm{E}-01(1.73 \mathrm{E}-01)$ | $1.30 \mathrm{E}-01(1.43 \mathrm{E}-01)$ |
| F19 | $1.15 \mathrm{E}-01(7.12 \mathrm{E}-02)$ | $1.33 \mathrm{E}-01(1.39 \mathrm{E}-01)$ | $1.29 \mathrm{E}-01(1.53 \mathrm{E}-01)$ | $1.18 \mathrm{E}-01(6.33 \mathrm{E}-02)$ | $1.07 \mathrm{E}-01(7.57 \mathrm{E}-02)$ | $9.23 \mathrm{E}-02(6.22 \mathrm{E}-02)$ | $6.85 \mathrm{E}-02(3.84 \mathrm{E}-02)$ | $7.84 \mathrm{E}-02(5.92 \mathrm{E}-02)$ |
| F20 | $1.84 \mathrm{E}-01(1.60 \mathrm{E}-01)$ | $1.78 \mathrm{E}-01(1.47 \mathrm{E}-01)$ | $2.05 \mathrm{E}-01(1.73 \mathrm{E}-01)$ | $2.54 \mathrm{E}-01(1.80 \mathrm{E}-01)$ | $2.30 \mathrm{E}-01(1.60 \mathrm{E}-01)$ | $2.49 \mathrm{E}-01(1.89 \mathrm{E}-01)$ | $1.74 \mathrm{E}-01(1.47 \mathrm{E}-01)$ | $1.75 \mathrm{E}-01(1.67 \mathrm{E}-01)$ |
| F21 | $3.60 \mathrm{E}-01(2.72 \mathrm{E}-01)$ | $3.18 \mathrm{E}-01(1.96 \mathrm{E}-01)$ | $3.10 \mathrm{E}-01(2.78 \mathrm{E}-01)$ | $2.88 \mathrm{E}-01(2.17 \mathrm{E}-01)$ | $3.55 \mathrm{E}-01(2.90 \mathrm{E}-01)$ | $2.84 \mathrm{E}-01(2.23 \mathrm{E}-01)$ | $2.64 \mathrm{E}-01(2.45 \mathrm{E}-01)$ | $2.88 \mathrm{E}-01(2.43 \mathrm{E}-01)$ |
| F2 | $1.48 \mathrm{E}-01(5.28 \mathrm{E}-02)$ | $1.60 \mathrm{E}-01(6.16 \mathrm{E}-02)$ | $1.44 \mathrm{E}-01(5.21 \mathrm{E}-02)$ | $1.55 \mathrm{E}-01(5.27 \mathrm{E}-02)$ | $1.49 \mathrm{E}-01(5.62 \mathrm{E}-02)$ | $1.42 \mathrm{E}-01(4.37 \mathrm{E}-02)$ | $1.27 \mathrm{E}-01(5.37 \mathrm{E}-02)$ | $1.22 \mathrm{E}-01(4.57 \mathrm{E}-02)$ |
| 3 | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.23 \mathrm{E}+02(2.87 \mathrm{E}-13)$ | $3.29 \mathrm{E}+02(2.87 \mathrm{E}-13)$ |
| F24 | $1.09 \mathrm{E}+02(2.12 \mathrm{E}+00)$ | $1.10 \mathrm{E}+02(2.89 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(2.90 \mathrm{E}+00)$ | $1.10 \mathrm{E}+02(2.96 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(2.75 \mathrm{E}+00)$ | $1.09 \mathrm{E}+02(3.34 \mathrm{E}+00)$ | $1.08 \mathrm{E}+02(3.06 \mathrm{E}+00)$ | $1.08 \mathrm{E}+02(2.60 \mathrm{E}+00)$ |
| F25 | $1.14 \mathrm{E}+02(6.15 \mathrm{E}+00)$ | $1.18 \mathrm{E}+02(5.74 \mathrm{E}+00)$ | $1.12 \mathrm{E}+02(6.54 \mathrm{E}+00)$ | $1.18 \mathrm{E}+02(5.48 \mathrm{E}+00)$ | $1.16 \mathrm{E}+02(1.21 \mathrm{E}+01)$ | $1.17 \mathrm{E}+02(1.32 \mathrm{E}+01)$ | $1.11 \mathrm{E}+02(5.94 \mathrm{E}+00)$ | $1.10 \mathrm{E}+02(6.57 \mathrm{E}+00)$ |
| F | $1.00 \mathrm{E}+02(1.81 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.01 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.03 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.74 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.70 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.93 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.64 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.66 \mathrm{E}-02)$ |
| F27 | $1.56 \mathrm{E}+00(2.95 \mathrm{E}-01)$ | $7.27 \mathrm{E}+00(4.18 \mathrm{E}+01)$ | $1.44 \mathrm{E}+00(3.41 \mathrm{E}-01)$ | $7.26 \mathrm{E}+00(4.18 \mathrm{E}+01)$ | $1.48 \mathrm{E}+00(3.74 \mathrm{E}-01)$ | $1.43 \mathrm{E}+00(3.73 \mathrm{E}-01)$ | $7.31 \mathrm{E}+00(4.18 \mathrm{E}+01)$ | $1.52 \mathrm{E}+00(3.01 \mathrm{E}-01)$ |
| F | $3.65 \mathrm{E}+02(1.63 \mathrm{E}+01)$ | $3.62 \mathrm{E}+02(6.51 \mathrm{E}+00)$ | $3.64 \mathrm{E}+02(6.39 \mathrm{E}+00)$ | $3.62 \mathrm{E}+02(6.50 \mathrm{E}+00)$ | $3.66 \mathrm{E}+02(1.62 \mathrm{E}+01)$ | $3.65 \mathrm{E}+02(1.45 \mathrm{E}+01)$ | $3.62 \mathrm{E}+02(6.50 \mathrm{E}+00)$ | $3.65 \mathrm{E}+02(1.63 \mathrm{E}+01)$ |
| F29 | $2.22 \mathrm{E}+02(2.02 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(3.09 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(3.10 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(2.89 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(2.33 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(2.04 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(2.97 \mathrm{E}-01)$ | $2.22 \mathrm{E}+02(2.02 \mathrm{E}-01)$ |
| F30 | $4.62 \mathrm{E}+02(3.48 \mathrm{E}+00)$ | $4.63 \mathrm{E}+02(2.82 \mathrm{E}+00)$ | $4.63 \mathrm{E}+02(4.24 \mathrm{E}+00)$ | $4.65 \mathrm{E}+02(6.18 \mathrm{E}+00)$ | $4.64 \mathrm{E}+02(4.99 \mathrm{E}+00)$ | $4.66 \mathrm{E}+02(1.01 \mathrm{E}+01)$ | $4.62 \mathrm{E}+02(1.64 \mathrm{E}+00)$ | $4.62 \mathrm{E}+02(1.63 \mathrm{E}+00)$ |


| （00＋G00\％） $70+$ g $00^{\circ} \mathrm{I}$ |  |  |  | （tI－gIc．2） $20+$ gion I | （00＋g00．0） $\mathbf{7 0}+\mathrm{H} 00 \cdot \mathrm{I}$ | （00＋G00＊0） $70+$ g $00 \cdot \mathrm{I}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $(20+G 98)$ ） $00+$ H80 8 |  | （ $20+3 \downarrow 99) \varepsilon 0+$ g¢ 6 \％ |  |  | （ $20+$ ge $\underbrace{\circ}$ ） $80+3800^{\circ}$ | TたH |
|  |  |  |  |  |  |  |  | cセ |
|  |  |  |  |  |  |  |  |  |
|  |  |  |  | （ $20+$ g0 ${ }^{\circ} \mathrm{I}$ ） $\mathrm{I} 0+\mathrm{Az} 0^{\circ} 9$ | （ $20+$ g0 ${ }^{\circ} \mathrm{I}$ ） $10+$ ge 80.9 | （ $20+\mathrm{H} 0 \mathrm{z}^{\circ} \mathrm{I}$ ） $10+$ gø0 9 |  | ［th |
|  | $\left(z 0-\mathrm{G} 69^{\circ} \mathrm{z}\right) \mathrm{z0}+$ 可 21.7 |  |  |  |  | （80－马ゅ0．9） $\mathrm{z} 0+\mathrm{G} 2 \mathrm{I}^{\circ} \mathrm{Z}$ | （ $80-\mathrm{T} 69^{\circ} 6$ ） $\mathrm{zo} 0+\mathrm{H} 2 \mathrm{I}^{\prime} \mathrm{Z}$ |  |
|  |  |  |  |  |  | （ $\mathrm{z} 0-\mathrm{H} 90 \cdot \mathrm{E}$ ） $\mathrm{z0} 0+\mathrm{H00}$ I |  |  |
| （L0－G09 \％） 0 －Gce |  | （ $10-\mathrm{Z} \angle 2 \cdot \mathrm{Z}$ ） $\mathrm{I} 0-\mathrm{Hz6}$ ¢ | （ $10-\mathrm{Hz} 6 \mathrm{6}$ ） $\mathrm{L} 0-\mathrm{H} 89 \mathrm{E}$ |  |  |  |  | 88H |
|  | （ $\mathrm{t} 0-\mathrm{g} 9 L^{\prime} \mathrm{Z}$ ） $000+$ gLi＇I | 0－gtで「） $10-39$ |  | （ $\mathrm{L} 0-\mathrm{H9} 9 \mathrm{~T}$ ） $\mathrm{t} 0-\mathrm{g}$ 2 |  | （ $\mathrm{0} 0-\mathrm{GL} 8^{\circ} \mathrm{L}$ ） L 0 －ģ\％ | L0－gitit $\mathrm{LO-GLE}$－ |  |
| $(00+马 T L \cdot \tau) 00+g 马 8$ |  |  |  | （ $\mathrm{L} 0-\mathrm{G} 886$ ） $00+\mathrm{g}$ |  |  | $\left(00+G 766^{\circ}\right.$ ） $00+\mathrm{GL} 20 . \mathrm{I}$ |  |
| （ $\mathrm{L} 0+\mathrm{g}$ ¢ $9^{\circ} \mathrm{C}$ ） $\mathrm{L} 0+\mathrm{Z} 2 \mathrm{Z}^{\circ} \mathrm{C}$ |  | （ $\mathrm{L} 0+\mathrm{Z} 69.8) \mathrm{L} 0+\mathrm{GL} 0^{\circ} \mathrm{T}$ | （ $\mathrm{L} 0+\mathrm{Z} 7 \mathrm{I}^{\circ} \mathrm{F}$ ） $\mathrm{L} 0+\mathrm{Z} 898$ | （ $\mathrm{L} 0+\mathrm{Z} 6 \mathrm{I}^{\circ} 9$ ） $\mathrm{L} 0+\mathrm{Z} 88.9$ | （ $\left.\mathrm{L} 0+\mathrm{Z} 8 \mathrm{I}^{\circ} \mathrm{C}\right) \mathrm{L} 0+\mathrm{H} 66^{\circ} \mathrm{z}$ |  | （ $\mathrm{L} 0+\mathrm{Z} 89 . \mathrm{z}$ ） $\mathrm{I} 0+\mathrm{HL} \varepsilon^{\prime} \mathrm{E}$ |  |
| $\left(00+G L \downarrow^{\circ} \mathrm{I}\right) 00+G Z I^{\prime} \mathrm{I}$ | $(00+$ g¢ 5 \％$) 00+$ H | $(00+$ gli 7$) 00+$ g $69 \cdot$－ |  |  | $\left(00+\right.$ ge $L^{\circ}$ ） $000+702 \%$ |  | $\left(00+\right.$ gc $\varepsilon^{\prime}$ ） $00+$ gt 0 \％ |  |
|  | $(00+760 . \mathrm{L}) \mathrm{L} 0+388{ }^{\text {．}}$ | （00＋G91．9） 0 ＋${ }^{\text {che }} 9.1$ |  | $\left(00+\right.$－ $78 . \mathrm{c}$ ） $\mathrm{L} 0+\mathrm{H} 99^{\circ} \mathrm{L}$ | $\left(00+G 7 \%^{\circ} \mathrm{G}\right) \mathrm{L} 0+\mathrm{GS} L^{\prime}$ L |  |  |  |
| （00＋G00\％） $00+$＋ 0000 | （00＋G00\％） $00+700 \cdot 0$ | （00＋G00\％） $00+$＋ 00.0 | （00＋G00．0）00＋ 0 00．0 | （00＋G00．0）00＋g00．0 | $(00+$ H00．0） $00+$ g 0000 | （00＋900\％） $00+$＋ 000 | $(00+700 \cdot 0) 00+$ H00．0 | 28J |
| （00＋G00\％） $00+$＋ 0000 | （00＋G00\％） $00+700 \cdot 0$ | （00＋G00\％） $00+$ H00\％ | （00＋G00．0）00＋G00．0 | $(00+$ H00．0） $00+\mathrm{g} 00 \cdot 0$ | $(00+$ H00．0） $00+$ g 0000 | （00＋G00\％） 00 ＋ 7000 | $(00+$ H00．0） $00+$＋ 0000 |  |

Table A.9: Mean error results and standard deviation achieved by the proposed algorithm and seven other heuristic- based

|  | AOSDE-LS | AOSDE-SR | AOSDE-FIR | AOSDE-PR | AOSDE-PBM | AOSDE-RD | AOSDE-PAOC | LSAOS-DE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) | Mean(Std.) |
| F01 | E+03(3.58E- | +02(2.67E | E+0337.93E+ | E+022(1.94E+ | +03(4.97E+ | E+03(5.63E | E-08(3.88E-0 | +00(0.00E |
| F02 | $1.54 \mathrm{E}+03(2.99 \mathrm{E}+03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $1.37 \mathrm{E}+03(2.89 \mathrm{E}+03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $9.92 \mathrm{E}+02(2.69 \mathrm{E}+03)$ | $2.08 \mathrm{E}+03(3.70 \mathrm{E}+03)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}$ |
| F03 | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $7.04 \mathrm{E}-09(3.26 \mathrm{E}-08)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $2.68 \mathrm{E}-06(1.72 \mathrm{E}-05)$ | 1.01E-06(4.68E-06) | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ | $0.00 \mathrm{E}+00\left(0.00 \mathrm{E}+0{ }^{\text {a }}\right.$ |
| F04 | $4.48 \mathrm{E}+00(1.79 \mathrm{E}+01)$ | $1.35 \mathrm{E}+00(1.06 \mathrm{E}+00)$ | $1.27 \mathrm{E}+01(2.92 \mathrm{E}+01)$ | $1.45 \mathrm{E}+00(1.05 \mathrm{E}+00)$ | $1.55 \mathrm{E}+01(2.94 \mathrm{E}+01$ | $2.06 \mathrm{E}+01(3.43 \mathrm{E}+01$ | $5.74 \mathrm{E}-06(1.96 \mathrm{E}-05)$ | $7.19 \mathrm{E}-05(3.06 \mathrm{E}-04)$ |
| F05 | $2.02 \mathrm{E}+01(8.41 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01$ (7.14E-02) | $2.03 \mathrm{E}+01(6.51 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01(9.00 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01(1.05 \mathrm{E}-01)$ | $2.03 \mathrm{E}+01(8.07 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01(5.11 \mathrm{E}-02)$ | $2.03 \mathrm{E}+01(8.29 \mathrm{E}-02)$ |
| F06 | 1.19E-01(3.50E-01) | $2.47 \mathrm{E}-01(1.76 \mathrm{E}+00)$ | $6.13 \mathrm{E}-01(2.00 \mathrm{E}+00)$ | $2.79 \mathrm{E}-01(1.76 \mathrm{E}+00)$ | 1.79E-01(3.45E-01) | 3.80E-01(6.93E-01) | $8.20 \mathrm{E}-02(2.65 \mathrm{E}-01)$ | 4.49E-02(1.65E-01) |
| F07 | 1.80E-07(1.24E-06) | $00 \mathrm{E}+00(0.00$ | 2.59E-07(1.28E-06) | $00 \mathrm{E}+00(0.00 \mathrm{E}+0$ | 9.13E-08(4.61E-07) | 1.29E-07(4.34E-07) | 0E $+00(0.00 \mathrm{E}+00$ | . $00 \mathrm{E}+00$ (0.00E |
| F08 | 2.61E-07(1.14E-06) | $5.44 \mathrm{E}-10(2.73 \mathrm{E}-09)$ | 4.07E-06(2.80E-05) | 2.70E-09(1.76E-08) | 2.96E-07(1.70E-06) | 8.30E-06(4.53E-05) | $6.05 \mathrm{E}-07(2.47 \mathrm{E}-06)$ | $0.00 \mathrm{E}+00$ |
| F09 | $6.45 \mathrm{E}+00(4.67 \mathrm{E}+00)$ | $2.02 \mathrm{E}+01(6.90 \mathrm{E}+00$ ) | $1.06 \mathrm{E}+01(5.42 \mathrm{E}+00$ | $1.98 \mathrm{E}+01(5.79 \mathrm{E}+00$ | $8.80 \mathrm{E}+00(6.46 \mathrm{E}+00$ | $9.83 \mathrm{E}+00(8.18 \mathrm{E}+00)$ | $9.04 \mathrm{E}+00(4.51 \mathrm{E}+00)$ | $4.69 \mathrm{E}+00(1.62 \mathrm{E}$ |
| F10 | $9.39 \mathrm{E}-03(1.53 \mathrm{E}-02)$ | $6.17 \mathrm{E}-03(1.60 \mathrm{E}-02)$ | 32E-03(1.37E-02) | $9.39 \mathrm{E}-03(1.53 \mathrm{E}-02)$ | $6.38 \mathrm{E}-03(1.32 \mathrm{E}-02)$ | $6.29 \mathrm{E}-03(1.24 \mathrm{E}-02)$ | 4.15E-03(1.04E-02) | $9.18 \mathrm{E}-03(1.59 \mathrm{E}-02)$ |
| F11 | $1.89 \mathrm{E}+03(4.10 \mathrm{E}+02)$ | $1.96 \mathrm{E}+03(4.69 \mathrm{E}+02)$ | $1.87 \mathrm{E}+03(4.69 \mathrm{E}+02)$ | $2.03 \mathrm{E}+03(3.73 \mathrm{E}+02)$ | $1.73 \mathrm{E}+03(4.78 \mathrm{E}+02)$ | $1.85 \mathrm{E}+03(4.32 \mathrm{E}+02)$ | $1.74 \mathrm{E}+033(3.75 \mathrm{E}+02)$ | 1.60E+03(4.42E+02) |
| F12 | 2.97E-01(1.21E-01) | $3.37 \mathrm{E}-01(1.12 \mathrm{E}-01)$ | $3.24 \mathrm{E}-01(1.21 \mathrm{E}-01)$ | 3.52E-01(1.01E-01) | $3.32 \mathrm{E}-01(1.26 \mathrm{E}-01)$ | $3.01 \mathrm{E}-01(1.28 \mathrm{E}-01)$ | 2.35E-01(7.94E-02) | $3.02 \mathrm{E}-01(1.23 \mathrm{E}-01)$ |
| F13 | $1.17 \mathrm{E}-01(2.69 \mathrm{E}-02)$ | 9.48E-02(1.97E-02) | $1.23 \mathrm{E}-01(2.01 \mathrm{E}-02)$ | $1.27 \mathrm{E}-01(1.42 \mathrm{E}-02)$ | $1.09 \mathrm{E}-01(2.87 \mathrm{E}-02)$ | $1.17 \mathrm{E}-01(2.46 \mathrm{E}-02)$ | $1.28 \mathrm{E}-01(1.30 \mathrm{E}-02)$ | 1.22E-01(1.75E-02) |
| F14 | 2.22E-01(2.74E-02) | $2.29 \mathrm{E}-01(2.67 \mathrm{E}-02)$ | $2.41 \mathrm{E}-01(2.21 \mathrm{E}-02)$ | $2.31 \mathrm{E}-01(2.93 \mathrm{E}-02)$ | $2.29 \mathrm{E}-01(3.36 \mathrm{E}-02)$ | $2.31 \mathrm{E}-01(3.67 \mathrm{E}-02)$ | $2.31 \mathrm{E}-01(2.59 \mathrm{E}-02)$ | $2.18 \mathrm{E}-01(2.38 \mathrm{E}-02)$ |
| F15 | $2.75 \mathrm{E}+00(4.15 \mathrm{E}-01)$ | $3.07 \mathrm{E}+00(8.04 \mathrm{E}-01)$ | $2.75 \mathrm{E}+00(5.84 \mathrm{E}-1$ | $3.00 \mathrm{E}+00(7.87 \mathrm{E}-0$ | $2.92 \mathrm{E}+00(5.31 \mathrm{E}-01$ | $2.93 \mathrm{E}+00(6.40 \mathrm{E}-01$ | $2.50 \mathrm{E}+00(2.62 \mathrm{E}-01)$ | $2.49 \mathrm{E}+00(2.39 \mathrm{E}-01)$ |
| F16 | $9.36 \mathrm{E}+00(4.80 \mathrm{E}-01)$ | $9.48 \mathrm{E}+00(6.95 \mathrm{E}-01)$ | $9.29 \mathrm{E}+00(5.59 \mathrm{E}-01$ | $9.56 \mathrm{E}+00(7.57 \mathrm{E}-01)$ | $9.33 \mathrm{E}+00(5.21 \mathrm{E}-0$ | $9.63 \mathrm{E}+00(6.91 \mathrm{E}-01$ | $9.15 \mathrm{E}+00(4.90 \mathrm{E}-01)$ | $9.24 \mathrm{E}+00(5.55 \mathrm{E}-01)$ |
| F17 | $1.72 \mathrm{E}+02(1.18 \mathrm{E}+02)$ | 9.07E+01(6.73E+01) | $1.18 \mathrm{E}+02$ (7.33E+01 | $8.78 \mathrm{E}+01(7.57 \mathrm{E}+01)$ | $1.46 \mathrm{E}+02(1.05 \mathrm{E}+02)$ | $1.36 \mathrm{E}+02(9.98 \mathrm{E}+0)$ | $1.07 \mathrm{E}+02(6.16 \mathrm{E}+01)$ | $1.36 \mathrm{E}+02(7.15 \mathrm{E}+01)$ |
|  | $1.02 \mathrm{E}+01(5.22 \mathrm{E}+00)$ | $8.22 \mathrm{E}+00(3.23 \mathrm{E}+00)$ | $7.70 \mathrm{E}+00(3.95 \mathrm{E}+$ | $8.03 \mathrm{E}+00(2.77 \mathrm{E}+00)$ | ${ }^{8} .04 \mathrm{E}+000(3.87 \mathrm{E}+$ | $8.56 \mathrm{E}+000(4.61 \mathrm{E}+$ | $5.74 \mathrm{E}+00(1.98 \mathrm{E}+00)$ | $6.35 \mathrm{E}+000(2.56 \mathrm{E}+00)$ |
| F19 | $3.43 \mathrm{E}+000(6.05 \mathrm{E}-01)$ | $2.99 \mathrm{E}+00(4.54 \mathrm{E}-01)$ | $3.16 \mathrm{E}+00(5.05 \mathrm{E}-01$ | $3.05 \mathrm{E}+00(4.93 \mathrm{E}-01)$ | $3.18 \mathrm{E}+00(5.91 \mathrm{E}-01$ | $3.33 \mathrm{E}+00(5.96 \mathrm{E}-0$ ) | $3.25 \mathrm{E}+00(5.64 \mathrm{E}-01)$ | $3.25 \mathrm{E}+00(5.95 \mathrm{E}-01)$ |
| F20 | $4.12 \mathrm{E}+00(1.57 \mathrm{E}+00)$ | $6.28 \mathrm{E}+00(2.04 \mathrm{E}+00)$ | 5.17E+00(1.82E+00 | $5.95 \mathrm{E}+00(1.84 \mathrm{E}+00)$ | $4.62 \mathrm{E}+00(1.77 \mathrm{E}+00$ | $4.74 \mathrm{E}+00(1.89 \mathrm{E}+00$ | $4.07 \mathrm{E}+00(1.53 \mathrm{E}+00)$ | $3.86 \mathrm{E}+00(1.29 \mathrm{E}+00)$ |
|  | $4.80 \mathrm{E}+01(5.22 \mathrm{E}+01)$ | $5.57 \mathrm{E}+01(6.43 \mathrm{E}+01)$ | $4.70 \mathrm{E}+01(5.30 \mathrm{E}+01$ | $6.27 \mathrm{E}+01(6.46 \mathrm{E}+01)$ | $4.00 \mathrm{E}+01(5.06 \mathrm{E}+0$ | $3.92 \mathrm{E}+01(4.80 \mathrm{E}+0$ | $5.41 \mathrm{E}+01(5.47 \mathrm{E}+01)$ | $3.22 \mathrm{E}+01(4.47 \mathrm{E}+01)$ |
| F22 | $5.12 \mathrm{E}+01(4.79 \mathrm{E}+01)$ | $3.62 \mathrm{E}+01(3.13 \mathrm{E}+01)$ | $3.83 \mathrm{E}+01(1.09 \mathrm{E}+01)$ | $3.55 \mathrm{E}+01(2.97 \mathrm{E}+01)$ | $4.48 \mathrm{E}+01(3.59 \mathrm{E}+01)$ | $3.49 \mathrm{E}+01(2.82 \mathrm{E}+01)$ | $3.15 \mathrm{E}+01(1.77 \mathrm{E}+01)$ | $3.36 \mathrm{E}+01(1.71 \mathrm{E}+$ |
| F23 | $3.06 \mathrm{E}+02(3.13 \mathrm{E}+01)$ | $3.15 \mathrm{E}+02(4.50 \mathrm{E}-13)$ | $3.15 \mathrm{E}+02$ (9.22E-09) | $3.15 \mathrm{E}+02$ (4.64E-08) | $3.06 \mathrm{E}+02(3.13 \mathrm{E}+01)$ | $3.06 \mathrm{E}+02(3.13 \mathrm{E}+01)$ | $3.15 \mathrm{E}+02(4.02 \mathrm{E}-13)$ | $3.06 \mathrm{E}+02(3.13 \mathrm{E}+01)$ |
|  | $2.14 \mathrm{E}+02(1.16 \mathrm{E}+01)$ | $2.24 \mathrm{E}+02(9.59 \mathrm{E}-01$ | $2.24 \mathrm{E}+02(9.83 \mathrm{E}-1$ | $2.24 \mathrm{E}+02(9.45 \mathrm{E}-01)$ | $2.14 \mathrm{E}+02(1.15 \mathrm{E}+01)$ | $2.14 \mathrm{E}+02(1.16 \mathrm{E}+01)$ | $2.24 \mathrm{E}+02(8.76 \mathrm{E}-01)$ | $2.14 \mathrm{E}+02(1.16 \mathrm{E}+01)$ |
| F25 | $2.02 \mathrm{E}+02(6.44 \mathrm{E}-01)$ | $2.03 \mathrm{E}+02(5.78 \mathrm{E}-02$ ) | $2.03 \mathrm{E}+02(1.14 \mathrm{E}-01)$ | $2.03 \mathrm{E}+02(5.84 \mathrm{E}-02$ ) | $2.02 \mathrm{E}+02(5.44 \mathrm{E}-01)$ | $2.03 \mathrm{E}+02(6.40 \mathrm{E}-01)$ | $2.03 \mathrm{E}+02(8.63 \mathrm{E}-02)$ | $2.02 \mathrm{E}+02(6.39 \mathrm{E}-01)$ |
| F26 | $1.00 \mathrm{E}+02(2.16 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.03 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.81 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.80 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.58 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(2.51 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.42 \mathrm{E}-02)$ | $1.00 \mathrm{E}+02(1.66 \mathrm{E}-02)$ |
| F27 | $3.00 \mathrm{E}+02(3.06 \mathrm{E}-02)$ | $3.00 \mathrm{E}+02(2.40 \mathrm{E}-03)$ | $3.00 \mathrm{E}+02(8.73 \mathrm{E}-0$ | $3.00 \mathrm{E}+02(1.48 \mathrm{E}-03)$ | $3.00 \mathrm{E}+02(7.74 \mathrm{E}-01)$ | $3.00 \mathrm{E}+02(1.13 \mathrm{E}+00)$ | $3.00 \mathrm{E}+02(4.89 \mathrm{E}-04)$ | $3.00 \mathrm{E}+02(2.67 \mathrm{E}-02)$ |
| F28 | $8.09 \mathrm{E}+02(1.26 \mathrm{E}+02)$ | $8.10 \mathrm{E}+02(2.39 \mathrm{E}+01)$ | $8.34 \mathrm{E}+02(1.95 \mathrm{E}+01)$ | $8.14 \mathrm{E}+02(2.59 \mathrm{E}+01)$ | $8.04 \mathrm{E}+02(1.26 \mathrm{E}+02)$ | $8.06 \mathrm{E}+02(1.26 \mathrm{E}+02)$ | 8.26E+02(2.38E+01) | $8.18 \mathrm{E}+02(9.20 \mathrm{E}+01)$ |
| F29 | $5.87 \mathrm{E}+02(2.15 \mathrm{E}+02)$ | $3.08 \mathrm{E}+02(2.31 \mathrm{E}+02)$ | $5.85 \mathrm{E}+02(2.28 \mathrm{E}+02$ | $2.98 \mathrm{E}+02(2.23 \mathrm{E}+02)$ | $5.07 \mathrm{E}+02(2.50 \mathrm{E}+02)$ | $4.30 \mathrm{E}+02(2.53 \mathrm{E}+0.12)$ | 6.74E+02(1.46E+02) | $6.85 \mathrm{E}+02(1.27 \mathrm{E}+02)$ |
| F30 | $5.01 \mathrm{E}+02(1.06 \mathrm{E}+02)$ | $4.99 \mathrm{E}+02(1.21 \mathrm{E}+02$ ) | $5.05 \mathrm{E}+02(1.16 \mathrm{E}+0$ ) | $4.99 \mathrm{E}+02(1.18 \mathrm{E}+02)$ | $4.97 \mathrm{E}+02(1.05 \mathrm{E}+02)$ | $5.01 \mathrm{E}+02(1.15 \mathrm{E}+0$ ) | $5.00 \mathrm{E}+02(1.31 \mathrm{E}+02)$ | $4.87 \mathrm{E}+02(1.12 \mathrm{E}+02)$ |
| F31 | $2.92 \mathrm{E}+03(5.88 \mathrm{E}+03)$ | 2.42E+02 (3.47E+02) | $6.18 \mathrm{E}-09(2.91 \mathrm{E}-08)$ | $2.33 \mathrm{E}+02(3.46 \mathrm{E}+02)$ | $2.80 \mathrm{E}+03(6.40 \mathrm{E}+0.3)$ | 1.67E+03(4.13E+03) | $2.35 \mathrm{E}-07(2.28 \mathrm{E}-07)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+00)$ |
|  | $1.92 \mathrm{E}+02(3.77 \mathrm{E}+02)$ | $6.55 \mathrm{E}-02(3.05 \mathrm{E}-01)$ | $0.00 \mathrm{E}+00(0.00 \mathrm{E}+$ | 8.15E-02(3.13E-01) | $1.59 \mathrm{E}+02(3.34 \mathrm{E}+02)$ | $1.52 \mathrm{E}+02(4.02 \mathrm{E}+02)$ | $4.27 \mathrm{E}-08(5.05 \mathrm{E}-08)$ | $0.00 \mathrm{E}+00$ (0.00E |
| F33 | $2.02 \mathrm{E}+01(8.79 \mathrm{E}-02)$ | $2.02 \mathrm{E}+01(8.40 \mathrm{E}-02)$ | $2.02 \mathrm{E}+01$ (7.88E-02) | 2.03E+01(5.69E-02) | 2.03E+01(6.34E-02) | 2.03E+01(9.29E-02) | $2.08 \mathrm{E}+01(1.42 \mathrm{E}-01)$ | $2.02 \mathrm{E}+01(7.42 \mathrm{E}-02)$ |
| F3 | $6.62 \mathrm{E}+00(4.00 \mathrm{E}+00)$ | $2.09 \mathrm{E}+01(6.29 \mathrm{E}+00)$ | 7.82E+00(1.77E+00) | $1.99 \mathrm{E}+01(6.05 \mathrm{E}+00)$ | $1.04 \mathrm{E}+01(6.78 \mathrm{E}+00)$ | $1.03 \mathrm{E}+01(7.61 \mathrm{E}+00)$ | 7.61E+01(4.04E+01) | $4.70 \mathrm{E}+00(1.41 \mathrm{E}+00)$ |
|  | $1.83 \mathrm{E}+03(4.95 \mathrm{E}+02)$ | $1.97 \mathrm{E}+03(4.74 \mathrm{E}+02)$ | $1.80 \mathrm{E}+03(5.95 \mathrm{E}+02)$ | $2.07 \mathrm{E}+03(5.04 \mathrm{E}+02)$ | $1.85 \mathrm{E}+03(5.24 \mathrm{E}+02)$ | $1.82 \mathrm{E}+03(5.07 \mathrm{E}+02)$ | $5.73 \mathrm{E}+03(6.85 \mathrm{E}+02)$ | $1.43 \mathrm{E}+03(2.46 \mathrm{E}+02)$ |
| F36 | $1.47 \mathrm{E}+02(6.27 \mathrm{E}+01)$ | $1.05 \mathrm{E}+02(7.36 \mathrm{E}+01)$ | $1.08 \mathrm{E}+02(5.45 \mathrm{E}+01)$ | $1.01 \mathrm{E}+02(6.42 \mathrm{E}+01)$ | $1.41 \mathrm{E}+02(6.75 \mathrm{E}+01)$ | $1.26 \mathrm{E}+02(6.59 \mathrm{E}+01)$ | $6.88 \mathrm{E}+02(1.56 \mathrm{E}+02)$ | $1.33 \mathrm{E}+02(6.55 \mathrm{E}+01)$ |
| F37 | $6.46 \mathrm{E}+00(7.69 \mathrm{E}-01)$ | $5.19 \mathrm{E}+00(8.52 \mathrm{E}-01)$ | $6.40 \mathrm{E}+00(5.16 \mathrm{E}-01)$ | $5.65 \mathrm{E}+00(1.13 \mathrm{E}+00)$ | $5.40 \mathrm{E}+00(1.13 \mathrm{E}+00)$ | $5.87 \mathrm{E}+00(9.85 \mathrm{E}-01)$ | $8.03 \mathrm{E}+00(3.30 \mathrm{E}-01)$ | $6.43 \mathrm{E}+00(5.77 \mathrm{E}-01)$ |
|  | $3.23 \mathrm{E}+01(1.44 \mathrm{E}+01)$ | $2.99 \mathrm{E}+01(1.48 \mathrm{E}+01)$ | $2.85 \mathrm{E}+01(1.45 \mathrm{E}+01)$ | $3.25 \mathrm{E}+01(1.84 \mathrm{E}+01)$ | $3.12 \mathrm{E}+01(1.32 \mathrm{E}+01)$ | $3.29 \mathrm{E}+01(1.82 \mathrm{E}+01)$ | $3.69 \mathrm{E}+02(6.47 \mathrm{E}+01)$ | $2.90 \mathrm{E}+01(1.39 \mathrm{E}+01)$ |
| F39 | $1.03 \mathrm{E}+02(1.85 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(1.17 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(1.03 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(1.36 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(1.75 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(1.85 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(8.90 \mathrm{E}-02)$ | $1.02 \mathrm{E}+02(1.05 \mathrm{E}-01)$ |
| F40 | $4.02 \mathrm{E}+02(1.28 \mathrm{E}+02)$ | $3.50 \mathrm{E}+02(1.27 \mathrm{E}+02)$ | $3.74 \mathrm{E}+02(1.42 \mathrm{E}+02$ | $3.54 \mathrm{E}+02(1.24 \mathrm{E}+02)$ | $3.92 \mathrm{E}+02(1.19 \mathrm{E}+02)$ | $3.97 \mathrm{E}+02(1.32 \mathrm{E}+02)$ | $6.98 \mathrm{E}+02(1.32 \mathrm{E}+02)$ | $4.52 \mathrm{E}+02(1.23 \mathrm{E}+02)$ |
|  | $3.95 \mathrm{E}+02(2.45 \mathrm{E}+01)$ | 26E+02(1.94E+01) | $3.96 \mathrm{E}+02(1.95 \mathrm{E}+01)$ | $3.96 \mathrm{E}+02(1.95 \mathrm{E}+01)$ | $3.95 \mathrm{E}+02(2.46 \mathrm{E}+01)$ | $3.95 \mathrm{E}+02(2.47 \mathrm{E}+01)$ | $3.98 \mathrm{E}+02(1.39 \mathrm{E}+01)$ | $4.01 \mathrm{E}+02(5.96 \mathrm{E}+00)$ |
| F42 | $1.03 \mathrm{E}+02(2.80 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(2.61 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(1.87 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(2.36 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(3.77 \mathrm{E}-01)$ | $1.03 \mathrm{E}+02(3.44 \mathrm{E}-01)$ | $1.04 \mathrm{E}+02(2.84 \mathrm{E}-01)$ | . $03 \mathrm{E}+02$ (1.99E-01) |
| F43 | $2.64 \mathrm{E}-02(9.19 \mathrm{E}-04)$ | $2.60 \mathrm{E}-02(3.94 \mathrm{E}-04)$ | 2.62E-02(4.99E-04) | $2.64 \mathrm{E}-02(8.35 \mathrm{E}-04)$ | $2.65 \mathrm{E}-02(9.98 \mathrm{E}-04)$ | $2.66 \mathrm{E}-02(1.22 \mathrm{E}-03)$ | $2.61 \mathrm{E}-02(4.63 \mathrm{E}-04)$ | $2.64 \mathrm{E}-02(6.54 \mathrm{E}-04)$ |
| F44 | $3.13 \mathrm{E}+04(1.63 \mathrm{E}+02)$ | $3.14 \mathrm{E}+04(4.64 \mathrm{E}+02)$ | $3.15 \mathrm{E}+04(4.66 \mathrm{E}+02)$ | $3.14 \mathrm{E}+04(4.72 \mathrm{E}+02)$ | $3.13 \mathrm{E}+04(1.26 \mathrm{E}+02)$ | $3.13 \mathrm{E}+04(1.51 \mathrm{E}+02)$ | $3.14 \mathrm{E}+04(4.78 \mathrm{E}+02)$ | $3.16 \mathrm{E}+04(6.91 \mathrm{E}+02)$ |
| F45 | $1.00 \mathrm{E}+02(1.23 \mathrm{E}-13)$ | $1.00 \mathrm{E}+02(1.39 \mathrm{E}-13)$ | $1.00 \mathrm{E}+02(1.39 \mathrm{E}-13)$ | $1.00 \mathrm{E}+02(2.23 \mathrm{E}-08)$ | $1.00 \mathrm{E}+02(5.28 \mathrm{E}-05)$ | $1.00 \mathrm{E}+02(8.21 \mathrm{E}-07)$ | $1.00 \mathrm{E}+02(8.35 \mathrm{E}-12)$ | $1.00 \mathrm{E}+02(1.23 \mathrm{E}-13$ |


| （8L－G99．L）z0＋g00．I | （80－G08 6 ） $70+\mathrm{H} 00^{\circ} \mathrm{I}$ | （ $50-\mathrm{GzE} \cdot \mathrm{I}$ ） $\mathrm{zo} 0+\mathrm{H} 00 \cdot \mathrm{I}$ |  |  |  |  |  | CtI |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\left(80+76 \varepsilon^{\circ} \mathrm{G}\right) \dagger 0+\mathrm{g} 9 \Gamma^{\circ} 9$ | $(80+280 \mathrm{c}) 70+\mathrm{H} 96{ }^{\text {c }}$ |  |  |  | $(80+760 \mathrm{c}) \downarrow 0+\mathrm{H} 0009$ | $\left(80+\mathrm{H} 60^{\circ} \mathrm{C}\right) \mathrm{t} 0+\mathrm{gc} 0^{\circ} 9$ | $\left(80+799^{\circ}\right.$ ）$\dagger 0+7866^{\circ}$ | Dr |
|  |  |  | （ $80-367 \times 2)$ ） 0 －39\％ 8 |  |  |  | $\left(80-400^{\circ} \mathrm{C}\right) \mathrm{z} 0-\mathrm{H} 0 \pm 8$ | Eta |
| （ $\mathrm{L} 0-\mathrm{G} 08.7$ ） $\mathrm{z} 0+\mathrm{H} 20 . \mathrm{L}$ | （ $\mathrm{L}-\mathrm{G} 60^{\circ} \mathrm{t}$ ） $70+\mathrm{CH} 0^{\circ} \mathrm{L}$ |  |  |  |  |  |  | 27¢ |
|  |  |  |  |  |  | （ $\mathrm{L} 0+\mathrm{gzo}$ ） $\mathrm{z} 0+76 \varepsilon^{\circ} \mathrm{F}$ |  | Lヵ， |
| （ $\mathrm{L} 0+\mathrm{gc} 96$ ） $\mathrm{z} 0+\mathrm{gz} 0 \cdot 6$ | $\left(\mathrm{z} 0+\mathrm{g} 8 L^{\circ} \mathrm{G}\right) 80+\mathrm{g} 0 \varepsilon^{\circ} \mathrm{I}$ |  |  | $\left(\mathrm{z} 0+\mathrm{g} 0 \vdash^{\circ} \mathrm{I}\right) \mathrm{z} 0+\mathrm{g} 0 \varepsilon^{6}$ |  |  | $\left(\mathrm{z} 0+\mathrm{GI} 8^{\circ} \mathrm{I}\right) \mathrm{E} 0+\mathrm{g} 00^{\circ} \mathrm{I}$ | 0¢G |
| （ $\mathrm{L} 0-\mathrm{g} 79 \cdot \mathrm{~L}$ ） $\mathrm{zo}+$＋ |  |  |  |  |  |  |  | 68． |
|  | （ $\left.20+\mathrm{g} 9 \mathrm{z}^{\prime} \mathrm{z}\right) \mathrm{z} 0+702 \cdot 8$ |  |  | （ $20+$ gst ${ }^{\circ}$ ） $20+4888^{\circ} \mathrm{I}$ |  |  |  | 88． |
| （00＋g8 $L^{\circ}$ ） $\mathrm{L} 0+\mathrm{Z} 80^{\circ} \mathrm{\tau}$ |  | （土0＋g80 \％） $10+$ gø0 |  |  | （ $\mathrm{O}-\mathrm{G} 0 \mathrm{E}^{\circ} \mathrm{L}$ ） $\mathrm{I} 0+\mathrm{H} 00^{\circ} \mathrm{t}$ | （ $\mathrm{O} 0-\mathrm{G08} \mathrm{~L}$ ） $\mathrm{L} 0+\mathrm{G} 00^{\circ} \mathrm{T}$ |  | L8J |
| （ $20+478.7$ ） $80+$ H $20 . \mathrm{I}$ |  | （80＋g6 ${ }^{\circ} \mathrm{I}$ ） $80+\mathrm{gc} \mathrm{z}^{\circ} \mathrm{L}$ |  | $(70+49 \mathrm{C} \cdot \mathrm{E}) 80+\mathrm{H} 20 \cdot \mathrm{I}$ |  | $(z 0+$ H8 $2 \cdot 8) 80+320 \cdot \mathrm{~L}$ |  | 98． |
|  |  |  |  | （ $20+$ gs $\left.9^{\circ} 8\right) 80+389^{\circ} \mathrm{F}$ |  | （ $70+\mathrm{g} 92 \cdot 9) \varepsilon 0+962 \cdot 8$ |  | 98， |
|  |  | （ $\mathrm{L} 0+\mathrm{H} 89 \%$ ） $\mathrm{I} 0+\mathrm{H} 88^{\prime} \mathrm{z}$ | （ $\mathrm{L} 0+\mathrm{g} 90^{\circ} \mathrm{I}$ ） $\mathrm{L} 0+\mathrm{g} 80 \mathrm{E}^{\circ}$ | （ $\mathrm{t} 0+\mathrm{gl} 0^{\circ} \mathrm{L}$ ） $\mathrm{L} 0+\mathrm{gze} \mathrm{S}^{\circ} \mathrm{E}$ |  |  |  | I\＆ |
|  |  |  |  |  |  |  |  | 88． |
| （00＋马400\％） $00+$ H00．0 |  |  |  |  | （00＋ $700 \%$ ） $00+$ H00\％ | （00＋鳥00\％） $00+$＋ 00.0 |  | 28． |
|  |  |  |  |  | $\left(80+709^{\circ} \mathrm{E}\right) \mathrm{E} 0+76 \mathrm{~L}^{\prime} \mathrm{\varepsilon}$ | $\left(80+400^{\circ} \mathrm{E}\right) \varepsilon 0+76 \tau^{\prime} \mathrm{E}$ |  | L8． |
|  |  |  |  |  |  |  |  | 08． 4 |
|  |  |  | （ $\left.\mathrm{L} 0+\mathrm{g} 66^{\circ} \mathrm{C}\right) 70+\mathrm{g} 88^{\circ} \mathrm{L}$ |  | （ $\mathrm{L} 0+789 . \mathrm{c}$ ） $70+766{ }^{\circ} \mathrm{L}$ | （ $\mathrm{L} 0+\mathrm{g} \angle 2 \cdot \mathrm{~V}$ ） $70+\mathrm{Hz} 8^{\circ} \mathrm{L}$ | （ $\mathrm{L} 0+788 L^{\circ} 9$ ） $70+\mathrm{GLL} \cdot 8$ | 62． |
|  | （ $\mathrm{L} 0+\mathrm{g} 70 \cdot \mathrm{E}) \varepsilon 0+\mathrm{gz} \mathrm{I}^{-1}$ | $(80+\mathrm{gIL} \cdot \mathrm{I}) \mathrm{E}_{0}+\mathrm{g} \varepsilon \mathrm{I}^{\circ} \mathrm{I}$ |  | （ $\left.\mathrm{L} 0+\mathrm{g} 6 L^{\circ} \mathrm{E}\right) \varepsilon 0+\mathrm{g}$ ¢ $\mathrm{L}^{\circ} \mathrm{I}$ |  | （ $\mathrm{L} 0+\mathrm{g} 700^{\circ}$ ） $80+\mathrm{gz} \mathrm{I}^{\circ} \mathrm{L}$ |  | 8．${ }^{\text {d }}$ |
|  |  |  |  |  |  |  |  | LZA |
|  |  |  |  |  |  |  |  | 7． |
|  |  |  |  | （ $10-\mathrm{GL} 2 \varepsilon^{\circ} \mathrm{E}$ ） $70+$ 可 $0^{\circ} \mathrm{Z}$ |  |  |  | 964 |
|  |  |  |  |  |  |  |  | $\pm 2$ |
|  |  |  |  |  |  |  |  | 8\％」 |
|  |  |  |  |  |  | （ $\mathrm{L} 0+\mathrm{g} 9 \mathrm{I}^{\circ} \mathrm{8}$ ） $\mathrm{z} 0+768^{\circ} \mathrm{L}$ |  | 27． |
|  |  |  | （ $\left.20+389^{\circ} \mathrm{L}\right) 70+\mathrm{Gc} 9^{\circ} \mathrm{t}$ |  |  | $(\mathrm{z0}+\mathrm{H} 00 \cdot \mathrm{~L}) \mathrm{z0}+\mathrm{G} 80 \cdot \mathrm{~T}$ |  | LZ． |
| （00＋G86 ${ }^{\circ}$ ） $\mathrm{L} 0+38 \mathrm{~L}^{\cdot} \mathrm{I}$ | （ $00+\mathrm{g} 9 . \mathrm{E}$ ） $\mathrm{L} 0+\mathrm{G} 2 \mathrm{~F}^{\circ} \mathrm{I}$ | （ $\mathrm{L} 0+\mathrm{G} 68^{\circ} \mathrm{L}$ ） $\mathrm{L} 0+\mathrm{G} 62^{\circ} \mathrm{I}$ | （00＋gst．9） 0 0 ${ }^{\text {a }} 900$ \％ | （00＋GワL L ）L0＋GL゙て |  | （ $00+\mathrm{g} 2 . \mathrm{C}$ ） $\mathrm{L} 0+\mathrm{g} \angle \mathrm{Z}^{\circ} \mathrm{L}$ | $(00+G 7 \% \cdot 8) \mathrm{L} 0+\mathrm{H} 0 \mathrm{~s}^{\cdot} \mathrm{L}$ | 2． |
| （ $\mathrm{L} 0-\mathrm{HLE} \cdot 8$ ） $\mathrm{L} 0+\mathrm{H} 90 \cdot \mathrm{I}$ | （ $\mathrm{t} 0-\mathrm{GO} 0 \mathrm{~L}$ ） $\mathrm{I} 0+\mathrm{H} 20 . \mathrm{I}$ | （ $\mathrm{L} 0+\mathrm{H} 0 \mathrm{z}^{\circ} \mathrm{L}$ ） $\mathrm{L} 0+\mathrm{H} 60{ }^{\circ} \mathrm{L}$ |  | （ $\mathrm{t} 0-\mathrm{G} 89.9$ ） $\mathrm{L} 0+\mathrm{Hz} 0^{\circ} \mathrm{I}$ | （ $\mathrm{L} 0-\mathrm{HL} 6^{\circ} \mathrm{C}$ ） $\mathrm{L} 0+380{ }^{\circ} \mathrm{L}$ | （ $\mathrm{L} 0-\mathrm{H} 08.2) \mathrm{L} 0+\mathrm{GL} 0^{\circ} \mathrm{I}$ |  | 6It |
| （ $\mathrm{t} 0+\mathrm{g} 90^{\circ} \mathrm{I}$ ） $\mathrm{I} 0+\mathrm{H} 09{ }^{\circ} 8$ |  | （ $\mathrm{t} 0+\mathrm{g} 99 \cdot 8$ ） $\mathrm{T} 0+\mathrm{G} 8 \mathrm{~L}^{\prime} 8$ |  |  | （ $\mathrm{L} 0+\mathrm{G6} \mathrm{I}^{\circ} \mathrm{Z}$ ） $\mathrm{I} 0+\mathrm{H96} 9$ |  | （ $\mathrm{t} 0+76 \mathrm{I}^{\circ} \mathrm{I}$ ） $\mathrm{I} 0+\mathrm{H} 80.6$ | 8LH |
|  | $(z 0+g 90 \cdot 8) 70+788^{\circ} 8$ |  | （z0＋gz9 ${ }^{\circ}$ ） $80+\mathrm{g} 9 \mathrm{z}^{\circ} \mathrm{I}$ | $(70+780 \cdot 8) 70+960 \cdot 8$ | （ $20+$ g Li＇t） $20+$ gt9 6 |  |  | LLA |
| （ $\mathrm{t} 0-\mathrm{g} 996$ ） $\mathrm{I} 0+\mathrm{H} 08 . \mathrm{I}$ | （ $\mathrm{L} 0-\mathrm{S} 98.9$ ） $\mathrm{I} 0+\mathrm{G} 2 \mathrm{~L}^{\circ} \mathrm{I}$ | （ $\mathrm{L} 0+\mathrm{g} \mathrm{I} 8^{\circ} \mathrm{I}$ ） $\mathrm{I} 0+\mathrm{G} 62^{\circ} \mathrm{I}$ |  | （ $\mathrm{t} 0-\mathrm{g} 7 \mathrm{~L}^{\circ} \mathrm{8}$ ） $\mathrm{L} 0+\mathrm{H} 28^{\prime} \mathrm{I}$ | （ L 0 －g99 6 ） $\mathrm{I} 0+\mathrm{H} 78^{\circ} \mathrm{I}$ |  | （ $\mathrm{I} 0-\mathrm{g} 99^{-8}$ ） $\mathrm{L} 0+\mathrm{g} 88^{\prime} \mathrm{I}$ | 9LH |
| （ 0 －－998：8） $00+$ 鳥 809 |  | $\left(00+g 28^{\circ} \mathrm{C}\right) 00+\mathrm{gl} 6^{\circ} \mathrm{S}$ | $(00+960 \cdot \mathrm{~T}) 00+\mathrm{g} 6 \mathrm{c}^{\circ} \mathrm{s}$ | （ $\mathrm{T} 0-\mathrm{g} 86 \mathrm{~L}$ ） $00+\mathrm{g}$［ 9 9 |  |  | （ 0 －G7999） $00+$ GST 9 | CLIH |
|  |  | （ 10 －g96 \％） $10-396 \%$ |  |  |  |  |  | ILH |
|  |  |  | （ $\mathrm{z} 0-\mathrm{Hz}$ | （ $00-\mathrm{HL} 9 \mathrm{7}$ ） $\mathrm{I} 0-\mathrm{H} 26 . \mathrm{L}$ |  | （ $70-\mathrm{G} 29^{\circ} \mathrm{I}$ ） $\mathrm{I} 0-\mathrm{-G} 86^{\circ} \mathrm{I}$ |  | 8LS |
|  | （ $\mathrm{L} 0-\mathrm{S} 6 \mathrm{~F}^{\circ} \mathrm{T}$ ） L 0 －gct |  |  |  | （ L 0 －969 ${ }^{\text {L }}$ ） L 0 －－ 68.8 | （ $10-\mathrm{Hz} 9^{\circ} \mathrm{L}$ ） $\mathrm{L} 0-\mathrm{-g} 19 \%$ |  | 2LIA |
|  | （ $\left.20+400^{\circ} 9\right) 80+马 800^{\circ}$ |  | （ $20+4662.80+702 \pm$ | （ $20+4608) \varepsilon 0+$ ge $L^{\prime}$＇ |  | $\left(20+79 \varepsilon^{\circ}\right.$ ）$) 80+790{ }^{\circ}$ | （ $\left.20+70 z^{\circ} 8\right) \varepsilon 0+70 \varepsilon^{*} \pm$ | LLH |
|  | （ $10-\mathrm{Zc}$ \％ 2 ） $\mathrm{L} 0-\mathrm{H8} \mathrm{\%} 9$ |  |  | $\left(00+马 \angle 7^{\circ} \mathrm{L}\right) 00+G \angle \varepsilon^{\circ} \mathrm{L}$ |  |  |  | IH |
|  | （00＋Gもで¢） 0 0 0 gli | （ $\mathrm{L} 0+\mathrm{g} \mathrm{L} \mathrm{Z}^{\circ} \mathrm{Z}$ ） $\mathrm{L} 0+\mathrm{H} 66^{\circ} \mathrm{L}$ | （ $\mathrm{L} 0+\mathrm{g} 90^{\circ} \mathrm{L}$ ） $\mathrm{L} 0+\mathrm{g} 2 \mathrm{C}^{\circ} \mathrm{Z}$ |  |  |  |  | 60 |
| （00＋G00．0）00＋ 0 00\％ 0 | （ $90-\mathrm{H} 90^{\circ} \mathrm{T}$ ） $90-\mathrm{H} 8 L^{\circ} 9$ | （ $90-\mathrm{g}$ ¢ $2 \cdot 6$ ） $90-\mathrm{H} 89 \mathrm{Z}$ | （ $00-\mathrm{H} 80 \cdot \mathrm{C}$ ） 0 0－GLZ |  |  |  |  | 80J |
|  | （80－gze f） $00-\mathrm{BLz}$ \％ | $(80-\mathrm{H} 0 \varepsilon \mathrm{\varepsilon}$ ） $80-\mathrm{-g} 2 \mathrm{Z}$ ¢ | $(80-\mathrm{Hz} 9$ ）$)$ \％ 0 －ges ¢ |  |  |  | $(80-\mathrm{g} 9 \mathrm{c} \cdot \mathrm{f}) 80-\mathrm{H} 06.7$ | 0， |
|  |  | $\left(00+788^{\circ} \mathrm{t}\right) 00+760^{\circ} \mathrm{L}$ | $\left(00+G \angle 1 I^{\circ}\right.$ ） $00+G \angle 9^{\circ} \mathrm{L}$ | （L0－g00 ¢） 0 －乌̧zs | $\left(00+\right.$ g6 ${ }^{\circ}$ L） $00+$ GL 6.1 |  | （ $\mathrm{t} 0-\mathrm{G99} 9 \mathrm{~L}$ ） $00+\mathrm{H} 8 \mathrm{I}^{\circ} \mathrm{I}$ | 90－ |
|  |  |  |  |  |  |  |  | H |
| （ $\mathrm{L} 0+\mathrm{g} \varepsilon 66$ ） $\mathrm{L} 0+\mathrm{H} \varepsilon 66$ | （ $\mathrm{L} 0+\mathrm{H} 8 \mathrm{~F}^{\circ} \mathrm{E}$ ） $\mathrm{L} 0+\mathrm{T} 80 \cdot \varepsilon$ | （L0＋gz\％ 2 ） $10+$ g\％ $8^{\circ} 8$ |  | （ $\mathrm{L} 0+\mathrm{H} 0 \varepsilon \cdot \mathrm{~L}$ ） $\mathrm{L} 0+\mathrm{SI}$ ¢ 6 | （ $\mathrm{L} 0+\mathrm{g} 69 \mathrm{E}$ ） $\mathrm{L} 0+\mathrm{g} 266$ |  | （ $\mathrm{L} 0+\mathrm{gc} L^{\circ} \mathrm{E}$ ） $\mathrm{L} 0+\mathrm{gz} \mathrm{I}^{\circ} \mathrm{C}$ | 70¢ |
| （00＋ 000.0$) 00+$ H00．0 | （00＋ 0 00．0） $00+$＋ 0000 |  |  |  | （00＋G98\％） $10-9876$ | （00＋ $000 \cdot 0) 00+700 \% 0$ | （ $10-\mathrm{Hz9} 9 \mathrm{c}$ ） $\mathrm{O} 0-\mathrm{G} 90 \cdot \mathrm{~s}$ | 80ㄱ |
| （00＋H00\％） $00+\mathrm{H} 00.0$ | （ $20-\mathrm{BC} 0^{\circ} \mathrm{Z}$ ） $80-\mathrm{-g68} 8^{\circ} \mathrm{L}$ |  | $\left(80+G 29^{\circ}\right.$ ）$\varepsilon_{0} 0+768^{\circ} \mathrm{T}$ |  |  |  | $(70+7886) 70+499 \%$ | 20才 |
|  |  |  | $\left(\mathrm{c} 0+\mathrm{g} 09^{\circ} \mathrm{T}\right) \mathrm{s} 0+\mathrm{g} 0 \varepsilon^{\circ} \mathrm{L}$ |  |  | $\left(80+972 L^{\circ} \mathrm{E}\right) \mathrm{E} 0+988^{\circ} \mathrm{T}$ | $\left(\mathrm{c}_{0}+\mathrm{g} 26^{\circ} \mathrm{I}\right) \mathrm{s} 0+\mathrm{g} 00^{\circ} \mathrm{I}$ | I0 |
|  | （－P7S）पеәЈЈ | （－P7S）पеәли | （－P7S）पеәЈЈ | （ $\mathrm{P}+\mathrm{S}$ ）पегәЈ |  | （－P7S）¢гелЈ |  |  |
| ga－SOVST | DOVd－gasob | बצ－gasov | NGd－HaSOV | yd－gasov | YIA－gasov | US－3GSOV | ST－HaSOV |  |

Table A.11: Detailed results for reduction mechanism

|  | Ver1 |  | Ver2 |  | Ver3 |  | Ver4 |  | Ver5 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. |
| F01 | $2.11 \mathrm{E}-07$ | $8.39 \mathrm{E}-07$ | $1.07 \mathrm{E}-05$ | $3.21 \mathrm{E}-05$ | 7.95E-04 | $2.70 \mathrm{E}-03$ | $3.11 \mathrm{E}-06$ | $1.83 \mathrm{E}-05$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F02 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F03 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F04 | $5.40 \mathrm{E}-06$ | $3.69 \mathrm{E}-05$ | 5.72E-06 | $1.76 \mathrm{E}-05$ | $1.90 \mathrm{E}-05$ | $1.02 \mathrm{E}-04$ | $3.00 \mathrm{E}-05$ | $2.12 \mathrm{E}-04$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| 5 | $2.02 \mathrm{E}+01$ | $8.73 \mathrm{E}-02$ | $2.02 \mathrm{E}+01$ | $8.73 \mathrm{E}-02$ | $2.02 \mathrm{E}+01$ | $8.23 \mathrm{E}-02$ | $2.01 \mathrm{E}+01$ | $2.91 \mathrm{E}-02$ | $2.02 \mathrm{E}+01$ | $5.44 \mathrm{E}-02$ |
| F06 | $1.96 \mathrm{E}-02$ | 7.18E-02 | $8.04 \mathrm{E}-02$ | $2.12 \mathrm{E}-01$ | $1.26 \mathrm{E}-01$ | $3.04 \mathrm{E}-01$ | $1.59 \mathrm{E}-01$ | $3.95 \mathrm{E}-01$ | $1.80 \mathrm{E}-01$ | $1.28 \mathrm{E}+00$ |
| F07 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F08 | $0.00 \mathrm{E}+00$ | $3.71 \mathrm{E}-08$ | $6.43 \mathrm{E}-08$ | $3.22 \mathrm{E}-07$ | $1.36 \mathrm{E}-08$ | $9.48 \mathrm{E}-08$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| 9 | $1.49 \mathrm{E}+01$ | $6.31 \mathrm{E}+00$ | $1.46 \mathrm{E}+01$ | $6.12 \mathrm{E}+00$ | $1.50 \mathrm{E}+01$ | $6.93 \mathrm{E}+00$ | $1.23 \mathrm{E}+01$ | $4.93 \mathrm{E}+00$ | $1.19 \mathrm{E}+01$ | $7.15 \mathrm{E}+00$ |
| F10 | $8.16 \mathrm{E}-04$ | $4.08 \mathrm{E}-03$ | $4.08 \mathrm{E}-04$ | 2.92E-03 | $1.63 \mathrm{E}-03$ | $5.65 \mathrm{E}-03$ | $8.16 \mathrm{E}-04$ | $4.08 \mathrm{E}-03$ | $2.45 \mathrm{E}-03$ | $6.77 \mathrm{E}-03$ |
| F11 | $1.57 \mathrm{E}+03$ | $3.88 \mathrm{E}+02$ | $1.64 \mathrm{E}+03$ | $4.28 \mathrm{E}+02$ | $1.65 \mathrm{E}+03$ | $4.63 \mathrm{E}+02$ | $1.37 \mathrm{E}+03$ | $3.24 \mathrm{E}+02$ | $1.61 \mathrm{E}+03$ | $4.91 \mathrm{E}+02$ |
| F12 | $2.70 \mathrm{E}-01$ | $1.13 \mathrm{E}-01$ | $2.76 \mathrm{E}-01$ | $1.12 \mathrm{E}-01$ | $2.66 \mathrm{E}-01$ | $9.74 \mathrm{E}-02$ | $1.75 \mathrm{E}-01$ | $2.46 \mathrm{E}-02$ | $2.26 \mathrm{E}-01$ | $4.44 \mathrm{E}-02$ |
| F13 | $1.07 \mathrm{E}-01$ | $2.64 \mathrm{E}-02$ | $1.09 \mathrm{E}-01$ | $2.76 \mathrm{E}-02$ | $1.08 \mathrm{E}-01$ | $3.03 \mathrm{E}-02$ | $1.17 \mathrm{E}-01$ | $1.92 \mathrm{E}-02$ | 8.12E-02 | $2.58 \mathrm{E}-02$ |
| 4 | $2.21 \mathrm{E}-01$ | $2.75 \mathrm{E}-02$ | $2.33 \mathrm{E}-01$ | $2.59 \mathrm{E}-02$ | 2.16E-01 | $2.37 \mathrm{E}-02$ | $2.17 \mathrm{E}-01$ | $2.12 \mathrm{E}-02$ | $2.44 \mathrm{E}-01$ | $2.83 \mathrm{E}-02$ |
| F15 | $2.91 \mathrm{E}+00$ | $7.28 \mathrm{E}-01$ | $2.85 \mathrm{E}+00$ | $6.49 \mathrm{E}-01$ | $2.79 \mathrm{E}+00$ | $6.00 \mathrm{E}-01$ | $2.77 \mathrm{E}+00$ | 5.74E-01 | $2.94 \mathrm{E}+00$ | $7.56 \mathrm{E}-01$ |
| F16 | $9.02 \mathrm{E}+00$ | $5.15 \mathrm{E}-01$ | $95 \mathrm{E}+00$ | $5.92 \mathrm{E}-01$ | $9.02 \mathrm{E}+00$ | $6.36 \mathrm{E}-01$ | $8.72 \mathrm{E}+00$ | $3.69 \mathrm{E}-01$ | $16 \mathrm{E}+00$ | $8.39 \mathrm{E}-01$ |
| F17 | $1.39 \mathrm{E}+02$ | $7.97 \mathrm{E}+01$ | $1.80 \mathrm{E}+02$ | $1.04 \mathrm{E}+02$ | $2.13 \mathrm{E}+02$ | $1.10 \mathrm{E}+02$ | $1.37 \mathrm{E}+02$ | $7.41 \mathrm{E}+01$ | $1.73 \mathrm{E}+02$ | $9.88 \mathrm{E}+01$ |
| F18 | $7.86 \mathrm{E}+00$ | $3.30 \mathrm{E}+00$ | $8.88 \mathrm{E}+00$ | $4.19 \mathrm{E}+00$ | $9.87 \mathrm{E}+00$ | $4.35 \mathrm{E}+00$ | $8.33 \mathrm{E}+00$ | $3.74 \mathrm{E}+00$ | $6.94 \mathrm{E}+00$ | $2.87 \mathrm{E}+00$ |
| F19 | $3.05 \mathrm{E}+00$ | $5.61 \mathrm{E}-01$ | $3.32 \mathrm{E}+00$ | $6.37 \mathrm{E}-01$ | $3.23 \mathrm{E}+00$ | $7.27 \mathrm{E}-01$ | $3.34 \mathrm{E}+00$ | $6.17 \mathrm{E}-01$ | $2.70 \mathrm{E}+00$ | $6.18 \mathrm{E}-01$ |
| F20 | $4.50 \mathrm{E}+00$ | $1.28 \mathrm{E}+00$ | $5.28 \mathrm{E}+00$ | $1.74 \mathrm{E}+00$ | $5.23 \mathrm{E}+00$ | $1.79 \mathrm{E}+00$ | $4.86 \mathrm{E}+00$ | $1.84 \mathrm{E}+00$ | $3.64 \mathrm{E}+00$ | $1.34 \mathrm{E}+00$ |
| F21 | $5.03 \mathrm{E}+01$ | $5.97 \mathrm{E}+01$ | $6.39 \mathrm{E}+01$ | $6.45 \mathrm{E}+01$ | $9.24 \mathrm{E}+01$ | $8.30 \mathrm{E}+01$ | $6.79 \mathrm{E}+01$ | $8.01 \mathrm{E}+01$ | $6.96 \mathrm{E}+01$ | $7.06 \mathrm{E}+01$ |
| F22 | $2.77 \mathrm{E}+01$ | $1.80 \mathrm{E}+01$ | $3.71 \mathrm{E}+01$ | $2.89 \mathrm{E}+01$ | $3.61 \mathrm{E}+01$ | $3.19 \mathrm{E}+01$ | $3.57 \mathrm{E}+01$ | $3.32 \mathrm{E}+01$ | $2.83 \mathrm{E}+01$ | $1.92 \mathrm{E}+01$ |
| F23 | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.12 \mathrm{E}+02$ | $1.71 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.15 \mathrm{E}+02$ | $3.73 \mathrm{E}-13$ |
| F24 | $2.18 \mathrm{E}+02$ | $1.02 \mathrm{E}+01$ | $2.19 \mathrm{E}+02$ | $9.51 \mathrm{E}+00$ | $2.19 \mathrm{E}+02$ | $9.81 \mathrm{E}+00$ | $2.18 \mathrm{E}+02$ | $1.05 \mathrm{E}+01$ | $2.22 \mathrm{E}+02$ | $6.46 \mathrm{E}+00$ |
| F25 | $2.03 \mathrm{E}+02$ | $4.06 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.26 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.34 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.32 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.20 \mathrm{E}-02$ |
| F26 | $1.00 \mathrm{E}+02$ | 2.24E-02 | $1.00 \mathrm{E}+02$ | $2.35 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | $3.30 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | $1.58 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | $2.04 \mathrm{E}-02$ |
| F27 | $3.00 \mathrm{E}+02$ | 1.08E-01 | $3.02 \mathrm{E}+02$ | $1.41 \mathrm{E}+01$ | $3.00 \mathrm{E}+02$ | $4.86 \mathrm{E}+01$ | $3.00 \mathrm{E}+02$ | $6.33 \mathrm{E}-02$ | $3.00 \mathrm{E}+02$ | 1.59E-03 |
| F28 | $8.06 \mathrm{E}+02$ | $1.26 \mathrm{E}+02$ | $8.09 \mathrm{E}+02$ | $1.26 \mathrm{E}+02$ | $8.04 \mathrm{E}+02$ | $1.25 \mathrm{E}+02$ | $8.10 \mathrm{E}+02$ | $1.27 \mathrm{E}+02$ | $8.31 \mathrm{E}+02$ | $1.98 \mathrm{E}+01$ |
| F29 | $6.63 \mathrm{E}+02$ | $1.64 \mathrm{E}+02$ | $7.06 \mathrm{E}+02$ | $7.56 \mathrm{E}+01$ | $6.87 \mathrm{E}+02$ | $1.20 \mathrm{E}+02$ | $7.06 \mathrm{E}+02$ | $7.79 \mathrm{E}+01$ | $7.18 \mathrm{E}+02$ | $5.36 \mathrm{E}+00$ |
| F30 | $5.69 \mathrm{E}+02$ | $1.74 \mathrm{E}+02$ | $5.72 \mathrm{E}+02$ | $1.81 \mathrm{E}+02$ | $5.18 \mathrm{E}+02$ | $1.54 \mathrm{E}+02$ | $5.84 \mathrm{E}+02$ | $2.11 \mathrm{E}+02$ | $7.68 \mathrm{E}+02$ | $2.61 \mathrm{E}+02$ |


| 70＋早87． | 70＋G98．t | て0＋g72． |  | 20＋G99．L | 70＋G67：9 |  | 70＋ $790{ }^{\circ}$ | \％0＋号L0\％ | 60＋G9L｀ | $70+48 L \cdot 7$ |  | \％0＋GU $27 . \%$ |  | 08． |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ＋ $789{ }^{\circ}$ | z0＋G90\％ | z0＋G呂 $27^{\prime}$ I | ＋ 798.9 | 70＋ 790 － | 70＋車969 | 70＋鸟09 ${ }^{\text {I }}$ | 70＋ 789.9 | \％0＋ $76 \varepsilon^{\circ}$ I | 70＋号L8．9 | 70＋Gg0． | 70＋㱏 26.9 |  | 70＋G78．9 | 67， |
| L0＋GSt 8 | 20＋Ģ | L0＋G07： 6 | 70＋G81．8 |  | て0＋年もE8 | L0＋鸟67\％ | 70＋鸟20．8 |  | 70＋G97．8 | 10＋Gฑでて | 70＋H08：8 | 10＋G90\％ |  | 87， |
| 80－马 | $70+$ | \％0－ | $20+$ | 70 | \％0 | L0 | Z0 | 10 | \％0 | 10 | 70 | 10 |  | LZH |
| 70－G09．1 | z0＋守00＊I | 70－G99＊ | 70＋年00．1 | 70－H07． | 70＋H00． | 70－马明 | 70＋子00．I | 70－g0c．z |  |  | 70＋年00＊ | z0－gzs．z | 70＋H00＇L | 96， |
| L0－＇̧69\％\％ | z0＋ $780 \cdot \mathrm{z}$ | L0－＇g68．9 | z0＋ $3 \mathbf{7} 0^{\circ} \boldsymbol{z}$ | 70－G18．9 | z0＋ $780 \cdot \square$ | L0－岛9才， | 70＋ $780 \cdot \mathrm{z}$ | て0－岛も9＊8 | z0＋島80\％ $\boldsymbol{z}$ | L0－GII＇\＆ |  |  | z0＋ $780 \cdot \square$ | H |
| L0＋年tI＇I | \％0＋Ģt＇z | L0＋㐌91． | z0＋岛矿 $\boldsymbol{z}$ | L0＋鸟70．I | \％ |  |  | 00＋G8\％ 2 |  | $00+300 \cdot 8$ | 70＋Ģ̧．z | $00+$ 年99＊ |  | ， H |
| L0＋GL9． | 70＋马8L＇ | L0＋GEI＇8 | 70＋早90．8 | \＆L－Hz0＇も |  | 0＋G97．${ }^{\text {c }}$ | z0＋GLI＇8 | \＆L－G91＇t | z0＋G9t＇ | \＆L－Hz0｀ | 20＋Ggic | \＆L－H70＊ | z0＋Ggi＇8 | 86H |
| L0＋G90． | L0＋G98．8 | L0＋GIL． | L0＋H98． | L0＋年LİI | L0＋486．$\%$ | 10 | L0＋G8\％ 8 | L0＋号乐 6 | ［0＋GLC9 | L0＋ Hg 9 ¢ | L0＋GLも゙も | L0＋GL6．9 |  | 7\％Д |
| L0＋Gge ${ }^{\text {\％}}$ | L0＋ 0 09．$\%$ | L0＋ |  | L0＋ 0 089 | L0＋GIET | L0＋ $\mathrm{Hzc} \mathrm{c}^{\circ}$ | L0＋GI8．$¢$ | L0＋G0才9 | L0＋GIL 9 | L0 | L＇8 | L0＋GLた 8 | 70＋G99．1 | LZH |
| 00＋Gg\％ | 00 |  | $00+$ 鸟 98.8 | 00 | 00＋身git | 00＋Ģ\％ | $00+$ 鸟 9 ¢ | $00+$ gez | 00＋ | 00＋GI6． | $00+$ H87 ${ }^{\circ}$ | 00＋GIS | L0＋GI0 I | H |
| L0－g68 ¢ | $00+$ H07 8 | L0－G969 | $00+$ Hg ${ }^{\text {c }}$ ¢ | L0－geL c | ＋ 778 ¢ | L0－H62．9 | $00+$ H60 8 | L0－马989 |  | L0－G85．9 | $00+$ 年68 $\%$ | 0－36才｀ | $00+$ H88 $\varepsilon$ | L |
| 00＋具 21.7 | 00＋岛9L．9 | 00＋G9¢ ${ }^{\text {che }}$ | 00＋ | $00+$ H26． 6 | 00＋马888．9 |  | 00＋ $767 \cdot 8$ | 00＋Gtc ${ }^{\circ}$ | 00＋岛けI＇8 | $00+$ G29．9 | L0＋G97． | L0＋Gもて＇L | L0＋G08 ${ }^{\text {\％}}$ | 8LH |
| L0＋G89．9 | 20＋ | L0＋Ggi＇2 | ＋ | 10＋早60\％ | 70＋480． | 0＋男169 | 70＋ | L0＋ | 20＋G89 ${ }^{\text {a }}$ | $20+$ | z0＋${ }^{\text {dag }}$ \％ | \％0＋ $997 . \%$ |  | H |
| L0－H88： | $00+3$ | L0－ggc c | $00+$ 岛もて 6 | $0-\mathrm{gz} \mathrm{\%}$ ¢ | $0+$＋ 68.8 | L0 | $00+$ 身 66.8 | L0－ | 00＋早L2．8 | － | $00+$ H88 8 | 18 | $00+$ GL0 6 | H |
| L0－H7¢ 7 | $00+$ H99 ${ }^{\text {\％}}$ | L0－g68：z |  | 10－ |  |  | $00+$ He8 7 | － | 00 | 9 | $00+$ 年 $0 L^{\prime} \mathrm{Z}$ | \％88 | $00+389^{\circ} 7$ | H |
| 70－Gøて＇Z | L0－¢99「\％ |  | L0－H8L ${ }^{\text {\％}}$ | 70－乌ヵ9． | L0－＇̧91・を |  | $\checkmark$ | 70－H09\％ | L0－gIz \％ | 70－gtc 7 | L0－GIE\％ | 0－31゙¢ |  | H |
| \％0 | L0－g97． |  | L0－g7\％ | z0 | L0 |  | L0－GLZ． | 70－马̧\％ 6 | L0 |  | I | 70－马99 \％ | L0－GIC． | ELH |
| L0－g¢［ ${ }^{\text {L }}$ | L0－－ | 10－ | L0－g70 \＆ | L0－G8İL | 10－9 | L0－g9［ ${ }^{\text {L }}$ | L0－gze ${ }^{\text {a }}$ | 20－ | L0－491．$\%$ | \％0 | L0－g¢9［ | Z0－马67． | L0－yt0． | H |
| 70＋马86 ${ }^{\text {\％}}$ | 80＋G89． | 70＋ | 80＋G09－ | 20＋${ }^{\text {\％}} 00$ \％ | $80+$ G69 ${ }^{\text {L }}$ | 70＋ 789.8 | 80＋G67 ${ }^{\text {L }}$ | て0＋G60＇t | $80+$ g8t ${ }^{\circ}$ |  | $80+$ 年 $67^{\circ}$ L |  | $80+$ 年 $97^{\circ} \mathrm{L}$ | 边 |
| 20－g29 8 | \％0－g16 \％ | O0 | 80－981 6 | 80 | 80－ģ\％ | 00＋策00．0 | 00＋早00：0 | 00＋守00\％ | 00＋守00\％ 0 | 00＋年00：0 | 00＋年00：0 | 00＋㱏00\％ | 00＋${ }^{\text {H00 }} 0$ | H |
|  |  | 00＋G799 I | 00＋ 年69 $^{\text {¢ }}$ | $00+$ H98 | 00＋H67．8 | $00+$ ges | $00+$ H67： | $00+$ 田だも | $00+$ 990 6 | $00+$ H88 9 | L0＋日ZI＇I |  |  | 60H |
| 80－G69［ | 60－GLC． | 00＋ $300 \cdot 0$ |  | 80－＇ | 60－7 | 00＋号00：0 | 00＋鸟00：0 | 80－马68． | 60－马96 I | 00＋乐00：0 | 00＋年00：0 | 00＋鸟00：0 | 00＋G00．0 | H |
| 00＋${ }^{\text {200 }} 0$ | 00＋年00．0 | 00＋ $400 \cdot 0$ | 00＋走00\％ | 00＋島00．0 | 00＋年00．0 | 00＋走00．0 | 00＋走00\％ | 00＋易00：0 | 00＋早00：0 | 00＋子00：0 | 00＋ 0000 | \＆0－乌ワでも | 80－gSt L | 20H |
| 70－G98．${ }^{\text {\％}}$ | 80－＇H | 0 － | 20－ | L0－g78 ${ }^{\text {I }}$ | 70－ | L0 | 70－G88 ${ }^{\circ}$ | ＋+ H08 ${ }^{\text {\％}}$ | L0－Hz9 6 | $00+$ ge ${ }^{\text {c }}$ \％ |  | 00＋年01．8 | $00+$ H61 ${ }^{\circ} \mathrm{E}$ | 90－ |
| 70－H82．8 | 10＋G80\％ | 70－ |  | て0－9768 | L0＋G80 ${ }^{\text {\％}}$ | 70－799•8 | L0＋g70 ${ }^{\text {\％}}$ | 70－马99 6 | L0＋G70 ${ }^{\text {\％}}$ | 70－马67\％ | 10＋早L0\％ | 70－GZL．9 | L0＋ 0 L0： $\boldsymbol{z}$ | 90H |
| 70－乌t\％ 7 | 80－Чø0．9 | モ0－乌90＇¢ | $90-76 L^{\circ} \mathrm{L}$ | 90－H88． I | L0－乌7L＇\％ | 20－H81＇も | 20－H87 I | 20－H87＊ | 20－马L6 I | 20－G7\％${ }^{\text {－}}$ | 80－马01．8 | モ0－gctit | ¢0－H0\％ 6 | I0， |
| 00＋年00\％ | 00＋年00\％ | 00＋早00\％ | 00＋直00：0 | 00＋鸟00．0 | 00＋G00．0 | 00＋罭00：0 | 00＋罭00：0 | 00＋年00．0 | 00＋年00．0 | 00＋悤00．0 | 00＋年00．0 | 00＋年00\％ | 00＋ 0000 | 80¢ |
| 00＋ 0000 | 00＋ 0000 | 00＋年00．0 | 00＋早00：0 | 00＋式00．0 | 00＋年00．0 | 00＋策00：0 | 00＋策00\％ | 00＋早00\％ | 00＋早00\％ | 00＋策00：0 | 00＋${ }^{\text {H00 }} 0$ | 00＋走00：0 | 00＋ $700 \cdot 0$ | 70H |
| $80-\mathrm{H} 0 \mathrm{z}^{\circ} \mathrm{L}$ |  | 80－ģe9 \％ | 60－马86．8 | 90－G20 I | L0－马99\％ | 90－989［ |  | ¢0－g\＆8 | 90－792 | L0－H0z＇6 | L0－马8\＆\％ | $80+$ gris | $80+9 t \varepsilon^{\circ}$ | L0， |
| P7S | шеәЈ | P7S | шеәЈ | －P7S | шеәЈ | －P7S | шеәЈ | P7S | шеәЈ | －P7S | иеәЈ | P7S | Чセว， |  |
| $T 0 ¢={ }_{\text {mud }}$ d $N$ |  | $\square 9 \%={ }_{\text {zup }}$ d $N$ |  | $G 0 Z={ }_{\text {mun }}$ d $N$ |  | $\square 8 \mathrm{~L}={ }_{\text {zun }}$ d $N$ |  | $Q S \mathrm{I}={ }_{\text {mup }}{ }^{\text {d }} N$ |  | $C 0 \mathrm{I}={ }_{\text {mund }} \mathrm{N}$ |  | $G \mathrm{C}=\operatorname{mux}^{\text {m }} N$ |  |  |

[^2]Table A.13: Detailed results for CS

|  | $C S=25$ |  | $C S=50$ |  | CS $=75$ |  | $C S=100$ |  | $C S=150$ |  | $C S=200$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. |
| F01 | $2.11 \mathrm{E}-07$ | $8.39 \mathrm{E}-07$ | 2.98E-06 | $1.73 \mathrm{E}-05$ | 5.76E-07 | $1.91 \mathrm{E}-06$ | $2.87 \mathrm{E}-07$ | $8.77 \mathrm{E}-07$ | $4.62 \mathrm{E}-07$ | $1.68 \mathrm{E}-06$ | $2.00 \mathrm{E}-07$ | $4.15 \mathrm{E}-07$ |
| F02 | 00E+ | $0.00 \mathrm{E}+00$ | .00E+ | $0.00 \mathrm{E}+$ | .00E+ | 0.00E+00 | $0.00 \mathrm{E}+00$ | 0.00E+00 | 00E+00 | 0.00E+00 | $0.00 \mathrm{E}+00$ | 00 |
| F03 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F04 | 5.40E-06 | $3.69 \mathrm{E}-05$ | 4.31E-08 | $2.64 \mathrm{E}-07$ | $6.53 \mathrm{E}-04$ | $4.66 \mathrm{E}-03$ | $2.97 \mathrm{E}-08$ | $1.35 \mathrm{E}-07$ | 1.28E-07 | 4.18E-07 | $1.22 \mathrm{E}-07$ | $3.84 \mathrm{E}-0$ |
| F05 | $2.02 \mathrm{E}+01$ | 8.73E-02 | $2.02 \mathrm{E}+01$ | $9.46 \mathrm{E}-02$ | $2.02 \mathrm{E}+01$ | $8.20 \mathrm{E}-02$ | $2.02 \mathrm{E}+01$ | 8.48E-02 | $2.02 \mathrm{E}+01$ | $8.66 \mathrm{E}-02$ | $2.02 \mathrm{E}+01$ | $8.33 \mathrm{E}-02$ |
| F06 | 1.96E-02 | 7.18E-02 | $3.99 \mathrm{E}-01$ | $1.62 \mathrm{E}+00$ | 7.08E-02 | $2.65 \mathrm{E}-01$ | $2.07 \mathrm{E}-01$ | $1.34 \mathrm{E}+00$ | 4.88E-02 | $1.40 \mathrm{E}-01$ | 6.00E-02 | .79E-01 |
| F07 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+0$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | 0.00E+00 | $0.00 \mathrm{E}+00$ | 0.00E+00 | $0.00 \mathrm{E}+00$ | 0.00E+00 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F08 | $0.00 \mathrm{E}+00$ | 3.71E-08 | 08 | 07 | 09 | -08 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | 0.00 | 0.00E+00 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| F09 | $1.49 \mathrm{E}+01$ | $6.31 \mathrm{E}+00$ | $1.50 \mathrm{E}+01$ | $7.15 \mathrm{E}+00$ | $1.48 \mathrm{E}+01$ | 5.53E+00 | $1.16 \mathrm{E}+01$ | $5.66 \mathrm{E}+00$ | $7.29 \mathrm{E}+0$ | $4.35 \mathrm{E}+00$ | $1.03 \mathrm{E}+01$ | $5.65 \mathrm{E}+00$ |
| F10 | $8.16 \mathrm{E}-04$ | $4.08 \mathrm{E}-03$ | 8.16E-04 | $4.08 \mathrm{E}-03$ | $8.16 \mathrm{E}-04$ | $4.08 \mathrm{E}-03$ | $4.08 \mathrm{E}-04$ | $2.92 \mathrm{E}-03$ | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ | $1.63 \mathrm{E}-03$ | 5.65E-03 |
| F11 | $1.57 \mathrm{E}+03$ | $3.88 \mathrm{E}+02$ | $1.63 \mathrm{E}+03$ | $4.66 \mathrm{E}+02$ | $1.60 \mathrm{E}+03$ | $4.65 \mathrm{E}+02$ | $1.51 \mathrm{E}+03$ | $4.22 \mathrm{E}+02$ | $1.49 \mathrm{E}+03$ | $3.68 \mathrm{E}+02$ | $1.41 \mathrm{E}+03$ | $3.83 \mathrm{E}+02$ |
| F12 | 2.70E-01 | $1.13 \mathrm{E}-01$ | $2.69 \mathrm{E}-01$ | 1.03E-01 | $2.38 \mathrm{E}-01$ | 1.09E-01 | $2.96 \mathrm{E}-01$ | 1.13E-01 | 2.32E-01 | 1.16E-01 | $2.84 \mathrm{E}-01$ | $1.16 \mathrm{E}-01$ |
| F13 | $1.07 \mathrm{E}-01$ | $2.64 \mathrm{E}-02$ | 1.09E-01 | $2.27 \mathrm{E}-02$ | $9.97 \mathrm{E}-02$ | $2.61 \mathrm{E}-02$ | $1.08 \mathrm{E}-01$ | $2.35 \mathrm{E}-02$ | $1.21 \mathrm{E}-01$ | $2.12 \mathrm{E}-02$ | $1.18 \mathrm{E}-01$ | $1.77 \mathrm{E}-02$ |
| F14 | $2.21 \mathrm{E}-01$ | $2.75 \mathrm{E}-02$ | $2.35 \mathrm{E}-01$ | 2.45 | $2.30 \mathrm{E}-01$ | $2.55 \mathrm{E}-02$ | $2.31 \mathrm{E}-01$ | $2.23 \mathrm{E}-02$ | $2.29 \mathrm{E}-01$ | 02 | $2.23 \mathrm{E}-01$ | 02 |
| F15 | .91E+0 | $7.28 \mathrm{E}-0$ | $2.87 \mathrm{E}+00$ | 01 | $2 \mathrm{E}+0$ | -01 | $2.88 \mathrm{E}+0$ | 14E-01 | $2.83 \mathrm{E}+00$ | E-0 | $2.29 \mathrm{E}+00$ | $2.61 \mathrm{E}-01$ |
| F16 | 9.02E+0 | 5.15E-01 | $8.86 \mathrm{E}+00$ | 5.51E-01 | $9.01 \mathrm{E}+00$ | 6.13E-01 | $8.87 \mathrm{E}+00$ | $4.13 \mathrm{E}-01$ | $8.95 \mathrm{E}+00$ | $6.33 \mathrm{E}-01$ | $8.96 \mathrm{E}+00$ | 4.52E-01 |
| F17 | $1.39 \mathrm{E}+02$ | 7.97E+01 | $1.35 \mathrm{E}+02$ | $6.84 \mathrm{E}+01$ | $1.55 \mathrm{E}+02$ | 7.23E+01 | $1.39 \mathrm{E}+02$ | 9.64E+01 | $1.38 \mathrm{E}+02$ | $6.91 \mathrm{E}+01$ | $1.49 \mathrm{E}+02$ | 8.71E+01 |
| F18 | $7.86 \mathrm{E}+00$ | $3.30 \mathrm{E}+00$ | $8.24 \mathrm{E}+00$ | $3.86 \mathrm{E}+00$ | $6.53 \mathrm{E}+00$ | $2.56 \mathrm{E}+00$ | 7.77E+00 | $3.05 \mathrm{E}+00$ | $8.29 \mathrm{E}+00$ | $2.89 \mathrm{E}+00$ | $6.75 \mathrm{E}+00$ | $3.20 \mathrm{E}+00$ |
| F19 | $3.05 \mathrm{E}+00$ | $5.61 \mathrm{E}-01$ | $3.25 \mathrm{E}+00$ | 6.88E-01 | $3.23 \mathrm{E}+00$ | $4.63 \mathrm{E}-01$ | $3.25 \mathrm{E}+00$ | $6.33 \mathrm{E}-01$ | $3.09 \mathrm{E}+00$ | 5.79E-01 | $3.26 \mathrm{E}+00$ | $5.67 \mathrm{E}-01$ |
| F20 | $4.50 \mathrm{E}+00$ | $1.28 \mathrm{E}+00$ | $4.35 \mathrm{E}+00$ | $1.19 \mathrm{E}+00$ | $4.71 \mathrm{E}+00$ | $1.35 \mathrm{E}+00$ | $4.42 \mathrm{E}+00$ | 1.47E+00 | $4.46 \mathrm{E}+00$ | $1.25 \mathrm{E}+00$ | $4.61 \mathrm{E}+00$ | $1.60 \mathrm{E}+00$ |
| F21 | $5.03 \mathrm{E}+01$ | $5.97 \mathrm{E}+01$ | $4.59 \mathrm{E}+01$ | $5.69 \mathrm{E}+01$ | $4.96 \mathrm{E}+01$ | $6.05 \mathrm{E}+01$ | 5.98E+01 | $6.84 \mathrm{E}+01$ | $3.81 \mathrm{E}+01$ | 5.52E+01 | $4.16 \mathrm{E}+01$ | $6.27 \mathrm{E}+01$ |
| F22 | $2.77 \mathrm{E}+01$ | $1.80 \mathrm{E}+01$ | $2.82 \mathrm{E}+01$ | $1.89 \mathrm{E}+01$ | $2.62 \mathrm{E}+01$ | $1.73 \mathrm{E}+01$ | $2.82 \mathrm{E}+01$ | $1.81 \mathrm{E}+01$ | $3.48 \mathrm{E}+01$ | $2.81 \mathrm{E}+01$ | $2.83 \mathrm{E}+01$ | $1.73 \mathrm{E}+01$ |
| F23 | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ | $3.11 \mathrm{E}+02$ | $2.26 \mathrm{E}+01$ |
| F24 | 2.18E+02 | 1.02E+01 | $2.16 \mathrm{E}+02$ | $1.11 \mathrm{E}+01$ | 2.17E+02 | $1.10 \mathrm{E}+01$ | 2.17E+02 | 1.07E+01 | $2.17 \mathrm{E}+02$ | $1.08 \mathrm{E}+01$ | $2.17 \mathrm{E}+02$ | $1.08 \mathrm{E}+01$ |
| F25 | $2.03 \mathrm{E}+02$ | $4.06 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.21 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.22 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $5.65 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $4.46 \mathrm{E}-01$ | $2.03 \mathrm{E}+02$ | $4.42 \mathrm{E}-01$ |
| F26 | $1.00 \mathrm{E}+02$ | $2.24 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | $2.27 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | 2.58E-02 | $1.00 \mathrm{E}+02$ | $2.00 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | $2.34 \mathrm{E}-02$ | $1.00 \mathrm{E}+02$ | 1.65E-02 |
| F27 | $3.00 \mathrm{E}+02$ | $1.08 \mathrm{E}-01$ | $3.00 \mathrm{E}+02$ | $9.15 \mathrm{E}-01$ | $3.00 \mathrm{E}+02$ | $3.69 \mathrm{E}-02$ | $2.94 \mathrm{E}+02$ | $4.15 \mathrm{E}+01$ | $2.95 \mathrm{E}+02$ | 4.16E+01 | $2.95 \mathrm{E}+02$ | 4.15E+01 |
| F28 | $8.06 \mathrm{E}+02$ | $1.26 \mathrm{E}+02$ | 8.15E+02 | $9.51 \mathrm{E}+01$ | $8.15 \mathrm{E}+02$ | 9.62E+01 | $8.14 \mathrm{E}+02$ | $9.58 \mathrm{E}+01$ | $8.07 \mathrm{E}+02$ | 9.49E+01 | 8.14E+02 | $9.59 \mathrm{E}+01$ |
| F29 | $6.63 \mathrm{E}+02$ | $1.64 \mathrm{E}+02$ | $6.79 \mathrm{E}+02$ | $1.38 \mathrm{E}+02$ | $7.07 \mathrm{E}+02$ | 7.78E+01 | $6.74 \mathrm{E}+02$ | $1.51 \mathrm{E}+02$ | 6.63E+02 | $1.60 \mathrm{E}+02$ | $6.53 \mathrm{E}+02$ | $1.79 \mathrm{E}+02$ |
| F30 | $5.69 \mathrm{E}+02$ | $1.74 \mathrm{E}+02$ | 5.64E+02 | $1.77 \mathrm{E}+02$ | $5.78 \mathrm{E}+02$ | $2.09 \mathrm{E}+02$ | $5.41 \mathrm{E}+02$ | $1.65 \mathrm{E}+02$ | $5.06 \mathrm{E}+02$ | $1.39 \mathrm{E}+02$ | $4.96 \mathrm{E}+02$ | $1.45 \mathrm{E}+02$ |


|  | 70＋GEL｀ $\boldsymbol{\text { \％}}$ | 70＋马 HLI I | 70＋马78＇も |  | 70＋ | 70＋${ }^{\text {P }} 88^{\circ} \mathrm{I}$ | 70＋ H88 $^{\text {\％}}$ | L0＋BLI•8 |  |  | 70＋岛28 ${ }^{\text {\％}}$ | 08． |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $00+$ 鸟68 $\checkmark$ | 70＋㱏LI＇ 2 | 70＋GLZ ${ }^{\text {\％}}$ I | 70＋靣78．9 |  | $70+$ 鸟68．9 |  | $70+$ 岛 6.9 |  | $70+$ 鸟98．9 | 70＋G马LZ 1 | 60＋G989 | 67， |
| L0＋岛L0 6 | 20＋島7I＇8 | z0＋ $797{ }^{\text {a }}$ |  | L0＋马゙Lも゙ 6 |  | ［0＋ 360.6 | 20＋Gg＇8 | 70＋宜9\％${ }^{\circ}$ I |  | ［0＋ | 70＋${ }^{\text {\％}}$［ ${ }^{\circ} 8$ | 87H |
| L0＋年IF゙I | 70＋马720 ¢ | L0－＇H60％ | 70＋ $700{ }^{\circ} \mathrm{E}$ | 80－H9\％＇E | 70＋岛00．8 | 80－HZずも | 70＋慁00＇8 |  | 70＋它00．8 | 70－鸟L9： | 70＋ $700{ }^{\circ} \mathrm{E}$ | LZH |
| 70－G98． | 70＋囪00＊ | 70－789． | 70＋ $0^{\circ} 00^{\circ}$ L |  | 70＋它00＊ | 70－＇⿹\zh4灬9T | 70＋守00＊ | 70－＇岛ge． | 70＋它00＊ | 70－＇大99 ${ }^{\circ}$ L | 70＋舃00＊ | 97ㄱ |
| L0－可もて＇9 | z0＋靣0． $\boldsymbol{z}$ | L0－G8E $\cdot 9$ |  | L0－GDİも | 70＋马马80 $\checkmark$ | L0－98879 | $70+$ 鸟 $70 \cdot \square$ | L0－＇直67：9 | 70＋它 $\mathbf{7 0} \mathbf{\square}$ | ［0－＇直68．9 | z0＋靣0． $\boldsymbol{z}$ | 97， |
| L0＋ | \％0＋年91＇\％ | L0＋GEI |  | L0＋BEI ${ }^{\text {L }}$ | 70＋岛9T＇ 7 | L0 |  | L0＋且6 ${ }^{\circ} \mathrm{L}$ | 70＋岛8L＇ | ［0＋ |  | ，H |
|  |  | L0＋G7L＇Z | 20＋ $780 \cdot 8$ |  | 70＋鸟90．8 | ［0＋ 367.7 |  | L0＋GEL． 8 | 70＋鸟90．8 | L0＋年\＆I• | 70＋ $790 \cdot 8$ | 87\％ |
| 10＋马87\％¢ | ［0＋号97：9 | L0＋ | ［0＋ $788{ }^{\circ} \mathrm{C}$ | L0＋＇H99 ${ }^{\text {c }}$ |  | ［0＋${ }^{\text {［16 }}$［ | ［0＋ 370 ¢ | ［0＋岛L8． 7 | L0＋ $792 \cdot \mathrm{E}$ | L0＋宜LL＇I | L0＋G98． 8 | 石 |
| ［0＋马99． 9 | ［0＋马9 $0^{\circ} \mathrm{G}$ | L0＋马69．9 | ［0＋Gg9 9 | L0＋ 0 ¢0 $0^{\circ}$ | ［0＋ | L0＋Btc 9 | I0＋易9才 $\dagger$ | ［0＋ | ［0＋且L0．9 | LO＋宜LIT |  | LZH |
|  | $00+马 ¢ 88 \cdot 8$ | $00+马 9 \varepsilon^{\cdot}$ I | 00＋ 360 ¢ | 00＋鳥¢ ${ }^{\circ}$ L | 00＋直g $2 \cdot 8$ | 00＋岛LZ＇I | 00＋ 300 ¢ |  | $00+马 92 \cdot \mathcal{L}$ | 00＋号67． | $00+$ 岛98．8 | 07， |
| ［0－GL | 00＋鸟 | ［0－H6 | 00＋ | 10， | 00tut | L0－GEL 9 | $\varepsilon$ | L0－岛0才9 | $00+$ 鸟 87 ¢ $¢$ | ［0－r96．9 |  | H |
| $00+$ 鸟Lも「 | $00+$ 鸟 $88^{\circ} \mathrm{G}$ | $00+$ 可69 7 | 00＋GZ\＆ 9 | $00+$ H6才 | $00+G L L C$ | 00＋${ }^{\text {G } 69^{\circ} \mathrm{I}}$ | $00+496$ |  | 00＋㿾99．9 |  | $00+$ GSE 9 | 8LH |
| IO | $20+$ |  | $\checkmark$ | L0 | $\checkmark$ | IO | $\checkmark$ | L0＋GLL：9 | 70＋岛70T | L0＋马95 2 | 70＋${ }^{\text {¢ }} 9 \mathrm{E}^{\cdot}$ I | H |
| L0－岛L0＇ | 00＋马鸟09 6 | L0－＇H00｀ | $00+马 \square \square^{\circ} 6$ | L0－GE0＇ | $00+$ 鸟晌 6 | 10－＇gL9 ¢ | 00＋${ }^{\text {a }} 976$ | L0－ģg c | $00+$ 鸟 $7 \varepsilon^{\circ} 6$ | ［0－rge ${ }^{\circ}$ | $00+$ 岛 $7^{*} 6$ | 9IH |
| L0－ģ6． | $00+马 69^{\circ} \mathrm{E}$ | L0－＇H60 \＆ |  | L0－＇gTL ${ }^{\text {cos }}$ | $00+$ 鸟S0 \％ | L0－岛 $28^{\circ} \mathrm{Z}$ | $00+382 \cdot 7$ | L0－ģ99\％ | $00+$ GEC． 7 | 10－＇直68＇z |  | SIH |
| 70－BLも？ | L0－＇gez ${ }^{\text {d }}$ | 70－＇g08 |  | 70－G80 ${ }^{\text {c }}$ |  | 70－＇大89「7 | ［0－＇易8L＇z | 70－G7C． 7 |  | 70－＇直88＇7 | 10－鸟8I＇も | 巩 |
| 70－g92 | L0－g¢E I | 70－g7c． | L0－H67＇ |  | L0－ģz | 70－乌IS | 10－g8\％ 1 | 70－＇H89－ | L0－GLZ＇I |  | ［0－＇GEZ． | \＆LH |
| L0－g70 I | L0－号09｀ | L0－BLI I |  | L0－＇H60 I | L0－岛L6．8 | ［0－H8 | L0－岛L才® | L0－＇g7I I | L0－get 8 | ［0－＇早97． | ［0－血0才＇ 8 | ZIH |
| $70+787{ }^{\circ} \mathrm{E}$ | ¢0＋岛もでて | 20＋ | $80+370 \%$ | 20＋岁68： 7 | 80＋鸟96 | 20＋${ }^{\text {¢ }} 66^{\circ} \mathrm{E}$ |  | 70＋面02．8 | 80＋鸟高边 | 60＋男LI＇も |  | LIH |
| $00+马 787$ ¢ | 00＋马7 79.9 | $00+马 90{ }^{\circ}$ | 00＋${ }^{\text {H } 28.7}$ | L0－ģt 6 | ［0－GLE 6 | L0－＇HEt I | L0－G7C． | 70－马96． | 80－马69．6 | 70－鸟 $2 \boldsymbol{Z} \cdot$ I | 80－鸟80：9 | 0LH |
| $00+马 \underline{4} 9 \cdot{ }^{\text {c }}$ | 00＋马馬08 | $00+$ H10 ¢ | 00＋鳬汇8 | 00＋马giz | $00+$ 鸟も8．9 | 00＋号L6． | 00＋ 366 \％ |  | $00+$ 鸟 $6 . \pm$ | 00＋島79＊ | 00＋面69＊ | 60H |
|  |  | 90－马可近 |  | 90－GLLCG |  | 20－马7\％I |  | 00＋面00\％ | 00＋奋00\％ | 00＋直00\％ | 00＋面00\％ | 80H |
| 00＋哥00\％ | 00＋直00\％ | 00＋直00\％ | 00＋直00\％ | 00＋可00\％ | 00＋直00\％ | 00＋直00\％ | 00＋出00\％ | 00＋直00\％ | 00＋奋00\％ | 00＋直00\％ | 00＋直00\％ | 20H |
| 70－＇早89．E | 80－976．2 | $00+马$ Ge ${ }^{\circ}$ I | L0－®G98\％ | L0－Я97\％¢ | 70－岛比8 | L0－H6L＇I | 70－马4299 | 70－马992\％ | 70－¢ $899^{\circ} 7$ | L0－＇g99 ${ }^{\circ}$ |  | 90ㄱ |
| 70－乌̧989 | L0＋ HE0 $^{\text {c }}$ | 70－马廌LI9 | L0＋G80\％$冖$ | L0－G80 I | I0＋GE0 7 | 70－马8T：8 | L0＋BE0 7 | 70－G7¢ L | L0＋G80\％$冖$ | 70－岛80\％ | L0＋岛70． $\boldsymbol{z}$ | 90H |
| 90－rycit | 20－自巧 6 | $90-$－ 06.7 | 90－马9T｀9 | 90－＇H70 9 | 20－GもC． 6 | ¢0－马8E 9 |  |  |  |  | ¢0－H6İL | D0H |
| 00＋直00＊0 | 00＋直00\％ | 00＋直00\％ | 00＋面00\％ | 00＋直00＊0 | 00＋面00\％ | 00＋面00\％ | $00+$ 企00＊0 | 00＋面00\％ | 00＋㽛000 | 00＋直00\％ | 00＋面00\％ | 80H |
| 00＋直00\％ | 00＋直00\％ | 00＋直00\％ | 00＋直00\％ | 00＋鸟00\％ | 00＋出00\％ | 00＋直00\％ | 00＋哥00\％ | 00＋直00\％ | 00＋直00\％ | 00＋直00\％ | 00＋直00\％ | 70H |
| 60－马［LL I |  | 80－378． 7 | 60－马06．9 |  | 0L－GIL 6 | 20－马70． | 80－767 | 60－G02\％ 6 | 60－¢070\％¢ | 00＋直00\％ | 00＋面00\％ | L0H |
| ＇P7S | บセวЈ | P7S | บセวЈ | － 77 S | 廿еวЈ | ＇P7S | иъวЈ | ＇P7S | 廿еәЈ | ＇P7S | 廿еวЈ |  |
| $0 \mathrm{C}=\operatorname{urud} N$ |  | $0 \pm=$ unud $N$ |  | $0 ¢={ }_{u!u}{ }^{\text {a }}$ N |  | $0 Z={ }_{u!u}{ }_{\text {und }} N$ |  | $0 \mathrm{~L}=\mathrm{u}$ und $N$ |  | $L=$ urud $N$ |  |  |

## Appendix B

| 9L－Ģ86790＊6 | 00＋号L0809 $\mathrm{g}^{-}$ | 00＋号L0809 ${ }^{\text {c }}$ | 91－HE67906 | 00＋具L0809： $\mathrm{g}^{-}$ | 00＋早L0809： $\mathrm{g}^{-}$ | 91－H\＆6790\％6 | 00＋号L0809：${ }^{-}$ | 00＋号L0809 ${ }^{\text {c }}$ | 77.8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| L0－G6も678． | 70＋早91000 －$^{-}$ | 70＋马G9 $0000^{-}$ | 70＋ | 70＋G906［8 ${ }^{\text { }}{ }^{-}$ | 70＋马778098：${ }^{-1}$ | 70＋島L9L68． | L0＋早28IL0 9 |  | 87．8 |
| L0＋ | 70＋示LLL90 $\%$ | 70＋马g\％286 ${ }^{\text {I }}$ | L0＋H06900 9 |  |  | 70＋马289IE 7 | 70＋马80866 ${ }^{\circ}$ | 70＋马Z | LZ．8 |
| 0I－Gֻ¢¢98¢ | L0＋G99997．8 | L0＋G999978 | L0－G7L6L9 ${ }^{\text {\％}}$ | L0＋G09才t \＆$^{\circ} \mathrm{E}$ | L0＋G88．LLて＇¢ | 00＋岛L9989\％6 | L0＋G9706I＇8 | L0＋可をELLO 9 | 61．8 |
| 70－GLL6879 | L0－H7TLOC＇8－ | L0－马9\％099 $8^{-}$ | 70－H2TLE96 | L0－H68089 $\mathrm{L}^{-}$ | L0－H67999 ${ }^{\text {－}}{ }^{-}$ | 80－g7п98\％＇9 | L0－H67c9¢ ${ }^{\text {－}}$ | L0－马8モ¢z9 ${ }^{-}$ | $8 L^{\text {．}}$ |
|  | 80＋马 $002488^{\circ} 8$ |  | L0＋GE0096． 8 | 80＋号L7976．8 | 80＋马L7698 ${ }^{\circ}$ | L0＋ 0 g 28 L8 6 | 80＋马96才00＊6 | ¢0＋ $\mathrm{H} 76788^{\circ} 8$ | $21^{\text {．}}$ |
| 91－GLもてES＇も | 00＋G9LS06 ${ }^{-}{ }^{-}$ | 00＋G9TS06 ${ }^{\text {－}}$ | 9I－HITLOZ＇9 | 00＋G9TS06 ${ }^{\text {－}}$ | 00＋马9TC06 ${ }^{-}{ }^{-}$ | モ0－GILETRL L |  | 00＋其L0906 ${ }^{\text {－}}$ | 91．8 |
| EL－G99L089 | 70＋GgTLI9 6 | 70＋GgILI9＊6 | モ0－H90L¢Z I | 70＋GgILI9＊6 | 70＋GctLI9 6 | 00＋句も680¢ 7 |  | 70＋马GEILI9＊ | 91.8 |
|  |  |  | 00＋G8077I．L | 10＋G6797才 ${ }^{\circ}$－ | L0＋ Hz0zL9 $^{\text {¢ }}{ }^{-}$ |  | 10＋号 $8890 \varepsilon^{\circ}$－$^{-}$ | 10＋G00989 ${ }^{\text {－}}$ | －1． |
| L0－G7¢ 8 ¢ L \％ |  | 70－GIEE69 ${ }^{\text {¢ }}$ | 70－H9007I＇I | L0－Hで¢ 966 | L0－G007Sた 6 | L0－G6991z \％ | L0－G89¢08．8 | 70－GLecti 2 | 81.8 |
| $00+$ H00000 0 | $00+$ H00000 ${ }^{\text {L }}{ }^{-}$ | $00+$ H00000 ${ }^{\text {I }}$ | 00＋ $3000000^{\circ}$ | 00＋H00000 ${ }^{\text {－}}{ }^{-}$ | $00+$ H00000 ${ }^{\text {－}}{ }^{-}$ | 00＋${ }^{\text {¢ }} 00000000$ | 00＋ | $00+$ H00000 ${ }^{\text {－}}{ }^{-}$ | $\underline{7}$ \％ |
| 9I－GZIEEL｀I | L0－H00667＊ | L0－H00667 $\mathrm{L}^{\circ}$ | 9I－HZIEEI＇I | L0－H00667 $\mathrm{L}^{\circ}$ | L0－H00667 $\mathrm{L}^{\circ}$ | 80－G87¢90 2 | L0－边9789．L | L0－H00667＊ | 11.8 |
| 7L－G48870¢ | 80＋马̧z670 2 |  | 00＋H0LZL9．9 | 80＋GEL890\％ | 80＋ $769090 \cdot 2$ | L0＋4784LI＇¢ | 80＋直8008İ | 80＋马72067İ 2 | $0 L^{8}$ |
| \＆L－G98L87\％¢ | 20＋走0¢908．9 | 70＋马0¢908．9 | ¢0－H9E997： | 70＋马0¢908．9 | 20＋走0¢908．9 | 70－HIZTLE9 | 70＋马Lも0L8．9 | 70＋马00608．9 | $60^{\text {8 }}$ |
| LI－G0才91も．I | 70－H09788 $6^{-}$ | 70－H09789 $6^{-}$ | LI－H0ヵ9Lゅ．L | 70－H09788： $6^{-}$ | 70－H0¢ 88 $^{\circ} 6^{-}$ | LI－H0才9した | 70－H0¢789 $6^{-}$ | 70－H0¢788 ${ }^{\circ} 6^{-}$ | $80^{8}$ |
| ¢L－GtLtL9 |  |  | \＆0－HLIZ\＆G\％ |  | L0＋GZLIE才て | L0－Hgi068 L | L0＋马Z0¢ ${ }^{\text {a }}$－ 7 | L0＋直を99\％ 7 | 20.8 |
| $00+$ 鳥00000 0 | \＆0＋号L8L96 ${ }^{-}$ | \＆0＋号L8L96 $9^{-}$ | $00+$ H0000000 | 80＋号L8L96．9－ | \＆0＋号L8L96 ${ }^{-}$ | 0I－H8\＆8tec | 80＋号L8L96．9－ | \＆0＋号L8196．9－ | $90^{8}$ |
| ZL－HGLt8L\％ | 80＋ $\mathrm{H} 0 \mathrm{S971} \mathrm{C}^{\circ}$ | \＆0＋G0G97L｀ |  |  |  | 10＋马6L8LZ．9 | \＆0＋Gz\＆tLİG | \＆0＋H80chicc | 90.8 |
| 6I－G00¢LLE |  |  | 7T－H86LE9\％ | モ0＋马̧sc990 ${ }^{-}$ | モ0＋马̧99990 ¢ $^{-}$ | 90－H8\＆LZ\％＇¢ | 70＋马̧99990 $\mathrm{E}^{-}$ |  | 70．8 |
| ¢L－G86987＇I | $00+$ H09000 ${ }^{\text {L }}$ | $00+$ H09000 ${ }^{\text {－}}$ | 70－HSL069 6 | L0－HZIStI $L^{-}$ | L0－G098L9 $8^{-}$ | 70－H76867．6 | L0－H0\＆ $28 \mathrm{I}^{\prime} \%^{-}$ | L0－g97z¢L｀¢－ | 80.8 |
| ¢0－G98Itf $¢$ | L0－H08870 ${ }^{-}{ }^{-}$ | L0－马65980 ${ }^{-}$ | ¢0－HzE8Lも | L0－马L0980＊${ }^{-}$ | L0－\％9L980 $8^{-}$ | モ0－马も0¢60 9 | L0－H698L0 ${ }^{-8}$ | L0－H7L670 ${ }^{-}$ | 70.8 |
| $00+7400000^{\circ} 0$ | L0＋G700009 ${ }^{\text {［ }} \mathrm{L}^{-}$ | L0＋G00009 ${ }^{\text {［ }}$－ | 00＋ $300000{ }^{\circ}$ | L0＋H0000¢ ${ }^{\text {¢ }}$－ |  | 00＋ | L0＋G00009 ${ }^{\text {［ }}$－ | I0＋G00009 ${ }^{\text {［ }}$－ | 10.8 |
| －P7S | ә．\％еıәл V | 7 Fag | ＇p7S | ә．se．ıəл V | 7sag | ＇P7S |  | 7sag | suә¢qosd |
| \＆$\Lambda$ |  |  | Z $\Lambda$ |  |  | L $\Lambda$ |  |  |  |


Table B.2: Function values obtained by proposed MLS-MODE with different $C S$ values of $C S=25,50$ and 75 generations

| problems | $C S=\mathbf{2 5}$ |  |  | $C S=50$ |  |  | $C S=75$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. |
| g01 | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ |
| g02 | -8.036E-01 | -8.024E-01 | $3.442 \mathrm{E}-03$ | -8.036E-01 | -8.032E-01 | $2.202 \mathrm{E}-03$ | -8.036E-01 | -8.032E-01 | $2.202 \mathrm{E}-03$ |
| g03 | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $1.286 \mathrm{E}-15$ | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $1.722 \mathrm{E}-10$ | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $8.296 \mathrm{E}-15$ |
| g04 | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ |
| g05 | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ |
| g06 | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ |
| g07 | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $7.675 \mathrm{E}-15$ | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $7.606 \mathrm{E}-15$ | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $1.264 \mathrm{E}-14$ |
| g08 | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ |
| g09 | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.282 \mathrm{E}-13$ | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.442 \mathrm{E}-13$ | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.403 \mathrm{E}-13$ |
| g10 | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $3.503 \mathrm{E}-12$ | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $3.647 \mathrm{E}-12$ | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $3.107 \mathrm{E}-12$ |
| g11 | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ |
| g12 | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ |
| g13 | $5.693 \mathrm{E}-02$ | $4.891 \mathrm{E}-01$ | $2.738 \mathrm{E}-01$ | $6.750 \mathrm{E}-02$ | $5.544 \mathrm{E}-01$ | $2.486 \mathrm{E}-01$ | $5.436 \mathrm{E}-02$ | $5.923 \mathrm{E}-01$ | $2.762 \mathrm{E}-01$ |
| g14 | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.521 \mathrm{E}-14$ | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.521 \mathrm{E}-14$ | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.635 \mathrm{E}-14$ |
| g15 | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ |
| g16 | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ |
| g17 | $8.854 \mathrm{E}+03$ | $8.887 \mathrm{E}+03$ | $4.059 \mathrm{E}+01$ | $8.854 \mathrm{E}+03$ | $8.893 \mathrm{E}+03$ | $4.047 \mathrm{E}+01$ | $8.854 \mathrm{E}+03$ | $8.896 \mathrm{E}+03$ | $4.132 \mathrm{E}+01$ |
| g18 | -8.660E-01 | -8.507E-01 | $5.290 \mathrm{E}-02$ | -8.660E-01 | -8.355E-01 | $7.148 \mathrm{E}-02$ | -8.660E-01 | -8.355E-01 | $7.148 \mathrm{E}-02$ |
| g19 | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $3.365 \mathrm{E}-10$ | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | 8.824E-10 | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $5.710 \mathrm{E}-10$ |
| g21 | $1.937 \mathrm{E}+02$ | $2.067 \mathrm{E}+02$ | $3.765 \mathrm{E}+01$ | $1.937 \mathrm{E}+02$ | $2.042 \mathrm{E}+02$ | $3.627 \mathrm{E}+01$ | $1.937 \mathrm{E}+02$ | $2.021 \mathrm{E}+02$ | $2.782 \mathrm{E}+01$ |
| g23 | $-4.001 \mathrm{E}+02$ | $-4.000 \mathrm{E}+02$ | $1.329 \mathrm{E}-01$ | $-4.001 \mathrm{E}+02$ | $-3.998 \mathrm{E}+02$ | $1.217 \mathrm{E}+00$ | $-4.001 \mathrm{E}+02$ | $-4.001 \mathrm{E}+02$ | $2.426 \mathrm{E}-03$ |
| g24 | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ |


| 91－H990＊6 | 00＋ $880 \mathrm{c}^{\circ} \mathrm{g}-$ | 00＋ $880 \mathrm{c} \cdot \mathrm{g}-$ | 91－H990＊6 |  | 00＋ 780 g ¢ $\mathrm{g}^{-}$ | 91－H990 6 | 00＋ $8809 \mathrm{c}^{-}$ | 00＋ $880 \mathrm{c}^{\circ} \mathrm{q}^{-}$ | も7．8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 70－498L＊6 | 70＋马 $0000^{\circ}{ }^{-}$ |  | L0－H28E＇ | 20＋H000 ${ }^{-}$－ |  |  | 70＋ $7000{ }^{\circ}{ }^{-}$ | 70＋${ }^{\text {a }}$ L00 \％－$^{-}$ | 87．8 |
| 10＋早 299.7 | z0＋G670 ${ }^{\text {\％}}$ | 70＋GLE6． |  | z0＋过LL0 $\%$ | 70＋马L86．${ }^{\text {I }}$ | L0＋G188．I | 70＋马896．I | 70＋GL86．I | 17.8 |
| 80－HZ币た「て | L0＋马99\％＇¢ | L0＋ $7997^{\circ} \mathrm{E}$ | 60－G920 | L0＋ $7997^{\circ} \mathrm{E}$ | L0＋ $9997{ }^{\circ} \mathrm{E}$ | $60-$ HLE0＇ | L0＋ $7997^{\circ} \mathrm{E}$ | L0＋ $0997^{\circ} \mathrm{E}$ | $65^{\text {．}}$ |
| 70－H067｀ | L0－HLOC．8－ | L0－H099 $8^{-}$ | 70－H067： | L0－H209＇8－ | L0－H099 ${ }^{-}$ | 70－H067： 9 | 10－G209 ${ }^{\text {－}}{ }^{-}$ | L0－H099 ${ }^{\text {－}}$ | $85^{.8}$ |
| L0＋边标も | 80＋H968．8 | 80＋HtC8．8 |  | ¢0＋H968．8 |  | L0＋H02L＇t |  | 80＋4798．8 | 41.8 |
| 9I－Hzecit | 00＋马S06 ${ }^{\text {I }}$ | 00＋马S06．${ }^{-}$ | 91－gzecit | $00+$ 鸟906 $\mathrm{I}^{-}$ | $00+$ 鸟 $906 \mathrm{I}^{-}$ | 91－Hz\＆c＇t | $00+$ H $906 \mathrm{I}^{-}$ |  | 91.8 |
| \＆L－Hz08｀ | 70＋GLI9．6 | 70＋GLI9 6 | \＆L－gz08．9 | 70＋边LI9 6 | 70＋边 2196 | \＆L－Hz0899 | 70＋马LI9 6 | 70＋H219＊6 | ¢1． |
| モL－HL6ギて | 10＋日92L＇も－ | 10＋马92L＇も－ | モL－H829\％ |  |  | モL－H8L9\％ | L0＋G9LL＇も－ |  | ¢1．8 |
| L0－Hで0 を | L0－HZLİ9 | 70－HE\＆\％ 9 | L0－4も8ぢを | L0－BStic | 70－3768： | L0－H8Es 7 | L0－H900．9 | 70－7087．9 | $81^{\text {．}}$ |
| 00＋ $40000^{\circ}$ | 00＋ $7000 \mathrm{I}^{-}$ | $00+$＋ $000{ }^{\text {－}}{ }^{-}$ | 00＋ $7000{ }^{\circ}$ | $00+$ H000 ${ }^{-}{ }^{-}$ |  | 00＋H000＊0 | $00+$ H000 ${ }^{\text {－}}$－ | $00+$ H000 ${ }^{\text {I }}{ }^{-}$ | $\underline{18}$ |
| 9I－H\＆\＆L． | L0－H667 L | L0－H667 L |  | L0－H66\％${ }^{\text {L }}$ | L0－366\％${ }^{\text {L }}$ | 91－HE¢L．L | L0－H66\％ 2 | L0－－366\％L | LL．${ }^{\text {d }}$ |
| 7L－H98๖． | ¢0＋ 6670 － | 80＋ 6670 － | 7L－H888．8 |  | $80+$ 边 $60 \%$ L | 7－Htci | ¢0＋示670 2 | $80+$ H670 2 | $01^{\text {．}}$ |
|  | 70＋H908．9 | 70＋H908．9 | \＆L－GI8t． | 70＋ 7908.9 | 20＋ 9908.9 | \＆L－HE98．8 | 70＋ 9908.9 | 70＋ 2908.9 | $60^{\text {．}}$ |
| LI－H667． | 70－G¢8¢ ${ }^{\text {6－}}$ | 70－स889 $6^{-}$ | LI－G66才 ${ }^{\text {I }}$ | 70－G888：6－ | 70－HE89 $6^{-}$ | LI－H667．${ }^{\text {a }}$ | 70－H888＊ $6^{-}$ | 70－H888＊6－ | $80^{\text {．}}$ |
| \＆L－4978． |  |  | 仕－4698． | L0＋日LEt ${ }^{\text {\％}}$ | L0＋边LE＊$冖$ | ¢L－H0L0＇8 | L0＋鳥Et Z | L0＋鳥E\％ Z | $20^{\text {8 }}$ |
| 00＋ 70000 | 80＋${ }^{\text {¢ }}$ \％96．9－ | 80＋ 7696.9 － | 00＋G000．0 | 80＋马72969－ | $80+$＋ $7969^{-}$ | 00＋H000＊0 |  | $80+$＋ 7 \％96．9－ | $90^{\circ}$ |
| 7L－H98L｀ |  | 80＋H97İg | 7L－G98 ${ }^{\circ} \mathrm{Z}$ | 80＋ $298 \mathrm{t}^{\circ} \mathrm{C}$ | $80+$ 9971．9 | 7L－H878．${ }^{\circ}$ | 80＋ 9 972＇g |  | 90.8 |
| てI－HELL＇E | モ0＋马 $290 \varepsilon^{-}$ | モ0＋边 $290 \varepsilon^{-}$ | てI－g\＆Lic | モ0＋島290 $\varepsilon^{-}$ | ¢0＋ $\mathrm{H} 290 \mathrm{E}^{-}$ | てL－HELLC | モ0＋GL290 $\varepsilon^{-}$ | モ0＋GL290 $\varepsilon^{-}$ | ¢0． |
| ¢L－H898： | $00+$＋ $100{ }^{-1}{ }^{-}$ | 00＋边 $00{ }^{-} \mathrm{I}^{-}$ | 91－4876．8 | $00+$ HL00 ${ }^{-}$ | 00＋㱏100 ${ }^{-}$ | ¢L－3100． | $00+$ HL00 ${ }^{-}{ }^{-}$ | $00+$ HL00 ${ }^{-}{ }^{-}$ | 80.8 |
| \＆0－H08L＇飞 | L0－H870 ${ }^{-1}$ | L0－H980 $8^{-}$ | 90－H880 | L0－\％980 ${ }^{-8}$ | L0－H980 ${ }^{-1}$ |  | L0－ม780＊${ }^{-}$ | L0－4980 ${ }^{-}$ | $\underline{0.8}$ |
| 00＋ $7000{ }^{\circ} 0$ |  |  | 00＋ $\mathrm{H} 000{ }^{\circ}$ |  | L0＋H009 ${ }^{\text {－}}$ | 00＋ |  |  | L0．8 |
| ＇P7S | ueә小 | 759 g | －P7S | uean | $7{ }^{\text {fag }}$ | － P ＋ S | ueand | $7{ }^{\text {fag }}$ | suәiqoıd |
| $09 \mathrm{~L}=S \sim$ |  |  | $\mathbf{¢} \mathbf{Z I}=S$ D |  |  | $\mathbf{0 0 1}=S \sim$ |  |  |  |


Table B.4: Function values obtained by proposed MLS-MODE with different $N P^{\text {init }}$ values of $N P^{\text {init }}=50$, 75 and 100 individuals

| problems | $N P^{\text {init }}=50$ |  |  | $N P^{\text {init }}=75$ |  |  | $N P^{\text {init }}=\mathbf{1 0 0}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. |
| g01 | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ |
| g02 | -8.036E-01 | -7.957E-01 | $8.246 \mathrm{E}-03$ | -8.036E-01 | -8.009E-01 | $8.003 \mathrm{E}-03$ | -8.036E-01 | -8.032E-01 | $2.202 \mathrm{E}-03$ |
| g03 | $-1.001 \mathrm{E}+00$ | -9.812E-01 | $6.771 \mathrm{E}-02$ | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $5.027 \mathrm{E}-16$ | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $3.846 \mathrm{E}-16$ |
| g04 | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ |
| g05 | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $1.339 \mathrm{E}-12$ | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ |
| g06 | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ |
| g07 | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $3.518 \mathrm{E}-10$ | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $3.182 \mathrm{E}-14$ | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $1.533 \mathrm{E}-14$ |
| g08 | -9.583E-02 | -9.583E-02 | $1.267 \mathrm{E}-17$ | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ |
| g09 | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.890 \mathrm{E}-13$ | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.603 \mathrm{E}-13$ | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $6.240 \mathrm{E}-12$ |
| g10 | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $2.230 \mathrm{E}-05$ | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $3.581 \mathrm{E}-12$ | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $1.553 \mathrm{E}-12$ |
| g11 | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ |
| g12 | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ |
| g13 | $5.394 \mathrm{E}-02$ | $2.804 \mathrm{E}-01$ | $1.856 \mathrm{E}-01$ | $5.394 \mathrm{E}-02$ | $3.298 \mathrm{E}-01$ | $2.751 \mathrm{E}-01$ | $5.610 \mathrm{E}-02$ | $4.502 \mathrm{E}-01$ | $2.616 \mathrm{E}-01$ |
| g14 | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $4.839 \mathrm{E}-13$ | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.302 \mathrm{E}-14$ | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.431 \mathrm{E}-14$ |
| g15 | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ |
| g16 | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $7.036 \mathrm{E}-16$ | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ |
| g17 | $8.854 \mathrm{E}+03$ | $8.909 \mathrm{E}+03$ | $3.495 \mathrm{E}+01$ | $8.854 \mathrm{E}+03$ | $8.901 \mathrm{E}+03$ | $3.881 \mathrm{E}+01$ | $8.854 \mathrm{E}+03$ | $8.893 \mathrm{E}+03$ | $4.118 \mathrm{E}+01$ |
| g18 | -8.660E-01 | -7.896E-01 | $9.552 \mathrm{E}-02$ | -8.660E-01 | -8.355E-01 | $7.148 \mathrm{E}-02$ | -8.660E-01 | -8.278E-01 | $7.799 \mathrm{E}-02$ |
| g19 | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $2.234 \mathrm{E}-07$ | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $1.257 \mathrm{E}-10$ | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $4.717 \mathrm{E}-10$ |
| g21 | $1.937 \mathrm{E}+02$ | $2.147 \mathrm{E}+02$ | $4.901 \mathrm{E}+01$ | $1.937 \mathrm{E}+02$ | $2.199 \mathrm{E}+02$ | $5.347 \mathrm{E}+01$ | $1.937 \mathrm{E}+02$ | $2.046 \mathrm{E}+02$ | $2.984 \mathrm{E}+01$ |
| g23 | $-4.001 \mathrm{E}+02$ | $-4.001 \mathrm{E}+02$ | $2.110 \mathrm{E}-04$ | $-4.001 \mathrm{E}+02$ | $-4.001 \mathrm{E}+02$ | $1.033 \mathrm{E}-08$ | $-4.001 \mathrm{E}+02$ | $-4.000 \mathrm{E}+02$ | $1.486 \mathrm{E}-01$ |
| g24 | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ |


| 9L－HC90 6 | 00＋ $880 \mathrm{c} \cdot \mathrm{g}-$ |  | 91－4990 6 |  | 00＋ H 80 c ： $\mathrm{c}^{-}$ | 91－gc90 6 | 00＋ $880 \mathrm{c}^{\text {c }} \mathrm{g}^{-}$ | 00＋H809．g－ | ¢ 7.8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \＆0－gL0L．9 |  |  | 90－马¢\％8： | 70＋早L00 ${ }^{-}$ |  | L0－H8999 | $20+$＋ $666 \varepsilon^{-}$ | 70＋HL00 $\begin{array}{r}\text {－}\end{array}$ | $87^{8}$ |
| L0＋GLz9 \％ |  |  | L0＋ 0 He79 ${ }^{\text {\％}}$ | 70＋H066．${ }^{\text {I }}$ | 70＋早 $2866^{\text {．}}$ | L0＋4tø9．8 | 70＋H990 7 | 70＋GLE6．${ }^{\text {L }}$ | L7．8 |
| 20－gI 86.1 | L0＋G997．8 | L0＋ $2997^{\circ} \mathrm{E}$ | もく－马も02．L | L0＋ $9997{ }^{\text {c }}$ ¢ | L0＋G999\％¢ | 60－G9⿰も「 | L0＋G997\％ | L0＋G997．8 | $61^{\text {．}}$ |
| 91－H\＆6［＇G | L0－H099 $8^{-}$ | L0－H099 ${ }^{-8}$ | 9T－H998 | L0－H099 ${ }^{\text {8－}}$ | 10－H099＇8－ | 9I－G998． | L0－H099 ${ }^{\text {8－}}$ | L0－H099＇8－ | $85^{\text {．}}$ |
| L0＋GLE8．8 | $80+$ HL6 68 | 80＋边里888 | L0＋4988．8 | 80＋ $88688^{\circ}$ | $80+4$ ¢98．8 | L0＋ $2661^{\text {T }}$ | 80＋号668．8 | $80+4$ ¢98．8 | $41^{\circ}$ |
| 91－gzec＇t |  | $00+$ G906 ${ }^{-}$ | 91－gzec＇ | $00+$ 鸟 $906 \mathrm{I}^{-}$ | $00+$ H906 ${ }^{\text {L－}}$ | 91－gzec． | $00+$＋${ }^{\text {c }} 06 \mathrm{I}^{\text {－}} \mathrm{I}^{-}$ | $00+$ H906 ${ }^{\text {L－}}$ | 91．8 |
| \＆L－gz08｀9 | 20＋GLI9 6 | 70＋边LI96 | \＆L－gz08．9 | 乙0＋示LI9＊6 | 70＋日LL9 6 | \＆L－gz08｀ | 70＋边LI9＊6 | 70＋边LI9 6 | 91.8 |
| モL－HLZ9\％ | L0＋日92L＇も－ |  | モた－HIEもう |  | L0＋H9LL ${ }^{\text {\％}}$ | モI－gI6才 ${ }^{\text {¢ }}$ | L0＋日92L\％${ }^{-}$ | L0＋H9LL ${ }^{\text {\％}}$ | ¢1．8 |
| L0－Hz09．${ }^{\text {che }}$ | L0－H9LE¢ | 70－马768： | L0－H96I＇z | L0－－3689 ¢ | 70－H7689 | L0－Hc08． | L0－－38\＆\％＇も | 70－g768： | $8 L^{\circ}$ |
| 00＋H000．0 | $00+$＋ $0000^{-\mathrm{I}^{-}}$ | $00+$ H000 ${ }^{\text {－}}$ | 00＋ $40000^{\circ}$ | $00+$ H000 ${ }^{\text {－}}$－ | $00+\mathrm{H} 000{ }^{\text {－}}$－ | 00＋ $7000{ }^{\circ}$ | $00+$＋ $0000^{\text {－}} \mathrm{I}^{-}$ | $00+\mathrm{H} 000{ }^{\text {－}}$－ | $\underline{7}$ L． |
| 91－ge\＆c「I | L0－4667 L | L0－9667\％ | 9I－G8¢L ${ }^{\text {a }}$ | L0－3667＇L | L0－9667－ | 9I－gecti | L0－3667 ${ }^{\text {L }}$ | L0－9667－ | L1．8 |
| 80－H079－ | 80＋ 6670 － | $80+4670 \sim 2$ | 60－GL988 | 80＋ $2670 \sim 2$ | $80+8670 \sim$ | てI－G6⿰訁匚 | $80+4670$ L | $80+8670 \sim$ | $01^{\text {．}}$ |
| \＆L－ge9e\％ | 20＋ 9908.9 | 70＋ 7908.9 | \＆L－gてtic | 70＋ 7908.9 | 70＋ 7908.9 | \＆L－g\＆98． | 70＋ 2908.9 | 70＋ 7908.9 | 60.8 |
| LI－GLLC＇I | 70－HE88： $6^{-}$ | 70－H889 $6^{-}$ | LI－g91も ${ }^{\text {a }}$ | 70－9888： $6^{-}$ | 70－足889：6－ | LI－g91も I | 70－g888 $6^{-}$ | 70－HE88． $6^{-}$ | 80.8 |
| てI－H8L09 |  | L0＋出LEt $\checkmark$ | ¢L－g86L ${ }^{\text {c }}$ |  | L0＋号18t ${ }^{\text {a }}$ | もL－HL8で「 |  |  | $20^{\text {8 }}$ |
| 00＋ $4000{ }^{\circ}$ |  | $80+$ H796 $9^{-}$ | $00+4000 \cdot 0$ |  | 80＋+ \％ 96.9 － | 00＋ $7000 \cdot 0$ |  | 80＋${ }^{\text {¢ }}$ \％96 9 － | 90.8 |
| 7I－H878．\％ |  | $80+497 \mathrm{I}^{\circ} \mathrm{G}$ | 7L－g98L | $80+497 \mathrm{I}^{\circ} \mathrm{G}$ | $80+498 \mathrm{I}^{\circ} \mathrm{C}$ | 7I－G982＇z | $80+$ H97İg | $80+498 \mathrm{I}^{\circ} \mathrm{C}$ | 90.8 |
|  | ¢0＋边 $290 \cdot \mathrm{E}^{-}$ | ¥0＋G290 $8^{-}$ | 7T－g\＆Lice | ¥0＋G290 ¢－$^{-}$ | ¢0＋H290 $8^{-}$ | 6I－g\＆IL | 70＋马L290 $\varepsilon^{-}$ | ¢0＋H290 $8^{-}$ | ¢0．8 |
|  | $00+$＋ $100{ }^{-1}{ }^{-}$ | $00+$ HL00 ${ }^{-}$ | モL－g789 ${ }^{\text {c }}$ | $00+$ HL00 ${ }^{-}$ | $00+$ HL00 ${ }^{\text {L－}}$ | てL－gic9 ¢ | $00+$＋ $100 \mathrm{I}^{-}$ | $00+$ HL00 ${ }^{\text {I－}}$ | 80.8 |
| \＆0－gtLİを | L0－HCZ0 $8^{-}$ | L0－9980 ${ }^{-1}$ | 80－g707\％ | L0－3780＊${ }^{-}$ | L0－4980 ${ }^{-8}$ | 80－gIELE | L0－HLZ0＊8－ | L0－H980 ${ }^{-8}$ | 70．8 |
| $00+$ H000 0 | L0＋ 0 009 $\mathrm{I}^{-}$ | L0＋H009 ${ }^{\text {²－}}$ | $00+4000{ }^{\circ}$ | L0＋H009 ${ }^{\text {c }}$－ | L0＋H009 ${ }^{\text {I }}$－ | $00+4000 \cdot 0$ | L0＋ $000 \mathrm{~S}^{\cdot} \mathrm{I}^{-}$ | L0＋H009 ${ }^{\text {I }}$ | L0．8 |
| －P7S | иеәЈ | ${ }_{7} \mathrm{Sag}^{\text {d }}$ | －p7S | иеәЈ | 7 7ag | － P ＋S | иеәЈ | 7 799 | suәpqoid |
| $007={ }_{\text {quar }}$ d $N$ |  |  | $0 ¢ \mathrm{~L}={ }_{\text {quu }} \mathrm{d} N$ |  |  |  |  |  |  |

s［enp！a！pu！
Table B．5：Function values obtained by proposed MLS－MODE with different $N P^{\text {init }}$ values of $N P^{i n i t}=125,150$ and 200
Table B.6: Function values obtained by proposed MLS-MODE with different $N P^{\min }$ values of $N P^{\text {min }}=4,10$ and 20 individuals

| problems | $N P^{\text {min }}=\mathbf{4}$ |  |  | $N P^{\text {min }}=10$ |  |  | $N P^{\text {min }}=\mathbf{2 0}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. |
| g01 | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ | $-1.500 \mathrm{E}+01$ | $-1.500 \mathrm{E}+01$ | $0.000 \mathrm{E}+00$ |
| g02 | -8.036E-01 | -8.027E-01 | $3.046 \mathrm{E}-03$ | -8.036E-01 | -8.020E-01 | $3.759 \mathrm{E}-03$ | -8.036E-01 | -8.036E-01 | $1.906 \mathrm{E}-06$ |
| g03 | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $4.382 \mathrm{E}-08$ | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $1.390 \mathrm{E}-11$ | $-1.001 \mathrm{E}+00$ | $-1.001 \mathrm{E}+00$ | $1.639 \mathrm{E}-06$ |
| g04 | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ | $-3.067 \mathrm{E}+04$ | $-3.067 \mathrm{E}+04$ | $3.713 \mathrm{E}-12$ |
| g05 | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.870 \mathrm{E}-12$ | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ | $5.126 \mathrm{E}+03$ | $5.126 \mathrm{E}+03$ | $2.785 \mathrm{E}-12$ |
| g06 | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ | $-6.962 \mathrm{E}+03$ | $-6.962 \mathrm{E}+03$ | $0.000 \mathrm{E}+00$ |
| g07 | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $1.798 \mathrm{E}-14$ | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $3.455 \mathrm{E}-13$ | $2.431 \mathrm{E}+01$ | $2.431 \mathrm{E}+01$ | $7.216 \mathrm{E}-15$ |
| g08 | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ | -9.583E-02 | -9.583E-02 | $1.329 \mathrm{E}-17$ | -9.583E-02 | -9.583E-02 | $1.416 \mathrm{E}-17$ |
| g09 | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.458 \mathrm{E}-13$ | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.403 \mathrm{E}-13$ | $6.806 \mathrm{E}+02$ | $6.806 \mathrm{E}+02$ | $3.496 \mathrm{E}-13$ |
| g10 | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $4.829 \mathrm{E}-11$ | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $3.823 \mathrm{E}-08$ | $7.049 \mathrm{E}+03$ | $7.049 \mathrm{E}+03$ | $2.347 \mathrm{E}-08$ |
| g11 | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ | $7.499 \mathrm{E}-01$ | $7.499 \mathrm{E}-01$ | $1.133 \mathrm{E}-16$ |
| g12 | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $-1.000 \mathrm{E}+00$ | $0.000 \mathrm{E}+00$ |
| g13 | $5.394 \mathrm{E}-02$ | $4.119 \mathrm{E}-01$ | $2.382 \mathrm{E}-01$ | $5.394 \mathrm{E}-02$ | $3.972 \mathrm{E}-01$ | $2.376 \mathrm{E}-01$ | $5.394 \mathrm{E}-02$ | $4.143 \mathrm{E}-01$ | $2.672 \mathrm{E}-01$ |
| g14 | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.491 \mathrm{E}-14$ | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.284 \mathrm{E}-14$ | $-4.776 \mathrm{E}+01$ | $-4.776 \mathrm{E}+01$ | $2.461 \mathrm{E}-14$ |
| g15 | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ | $9.617 \mathrm{E}+02$ | $9.617 \mathrm{E}+02$ | $5.802 \mathrm{E}-13$ |
| g16 | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ | $-1.905 \mathrm{E}+00$ | $-1.905 \mathrm{E}+00$ | $4.532 \mathrm{E}-16$ |
| g17 | $8.854 \mathrm{E}+03$ | $8.906 \mathrm{E}+03$ | $3.638 \mathrm{E}+01$ | $8.854 \mathrm{E}+03$ | $8.911 \mathrm{E}+03$ | $3.635 \mathrm{E}+01$ | $8.854 \mathrm{E}+03$ | $8.895 \mathrm{E}+03$ | $3.965 \mathrm{E}+01$ |
| g18 | -8.660E-01 | -8.584E-01 | $3.821 \mathrm{E}-02$ | -8.660E-01 | -8.584E-01 | $3.821 \mathrm{E}-02$ | -8.660E-01 | -8.660E-01 | $1.813 \mathrm{E}-16$ |
| g19 | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $2.859 \mathrm{E}-09$ | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $3.793 \mathrm{E}-11$ | $3.266 \mathrm{E}+01$ | $3.266 \mathrm{E}+01$ | $6.880 \mathrm{E}-14$ |
| g21 | $1.937 \mathrm{E}+02$ | $1.990 \mathrm{E}+02$ | $2.620 \mathrm{E}+01$ | $1.937 \mathrm{E}+02$ | $1.937 \mathrm{E}+02$ | $1.081 \mathrm{E}-08$ | $1.937 \mathrm{E}+02$ | $2.042 \mathrm{E}+02$ | $3.627 \mathrm{E}+01$ |
| g23 | $-4.001 \mathrm{E}+02$ | $-4.001 \mathrm{E}+02$ | $4.343 \mathrm{E}-07$ | $-4.001 \mathrm{E}+02$ | $-4.001 \mathrm{E}+02$ | $2.022 \mathrm{E}-04$ | $-4.001 \mathrm{E}+02$ | $-4.001 \mathrm{E}+02$ | $9.662 \mathrm{E}-08$ |
| g24 | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ | $-5.508 \mathrm{E}+00$ | $-5.508 \mathrm{E}+00$ | $9.065 \mathrm{E}-16$ |


| 9［－4990＊6 |  | 00＋ $7809^{\circ} \mathrm{G}^{-}$ | 9［－H990＊6 |  | 00＋${ }^{\text {H }} 809^{\circ} \mathrm{G}^{-}$ | 9［－49906 | 00＋ $7809^{\circ} \mathrm{G}^{-}$ |  | 77．8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 90－7690 7 | 70＋直L00 ${ }^{-}$ | 20＋式L00 ${ }^{-}$ | 90－Hgze＇t | 70＋直L00 －$^{-}$ | 70＋旦L00 －$^{-}$ | 90－486才 ${ }^{\circ}$ | 20＋島L00 $\square^{-}$ | 20＋ | 87．8 |
| L0＋H079 ${ }^{\text {\％}}$ | 70＋具066． | 70＋BLE6 ${ }^{\text {I }}$ | L0＋我0z9 ${ }^{\text {\％}}$ | 70＋直066． I | 70＋且LE6 ${ }^{\text {I }}$ | L0＋ | 70＋年066 ${ }^{\text {I }}$ | 70＋云LE6 ${ }^{\text {I }}$ | ［7．8 |
| ¢L－HLZ9＊6 | L0＋${ }^{\text {¢ }} 9997^{\circ} \mathrm{E}$ | L0＋ $7998^{\circ} \mathrm{E}$ | モ［－Hø02． | L0＋ $7997^{\circ} \mathrm{E}$ | L0＋ $7997^{\circ} \mathrm{E}$ | 圴－号LG6 | L0＋ $7997^{\circ} \mathrm{E}$ | L0＋ $7997^{\circ} \mathrm{E}$ | $6{ }^{\text {L }}$－ |
| 70－HL78．8 | L0－岛789 $8^{-8}$ | L0－부099＊8－ | 70－GL28． 8 |  | L0－버099＊8－ |  | L0－岛789 $8^{-}$ | L0－브099 $8^{-}$ | 81．8 |
| L0＋Hø¢6．$¢$ | 80＋${ }^{\text {¢ }}$ 98888 |  | L0＋早988．$¢$ | 80＋ | 80＋可豕988 |  | 80＋出п68．8 |  | 12.8 |
| 9［－Hz\＆G＇も |  |  | 9［－Hz\＆G＇も | $00+$ 鸟906 ${ }^{-1}$ |  | 91－HzEG ${ }^{\text {¢ }}$ | $00+$ 走906 ${ }^{\text {［ }}{ }^{-}$ | $00+$ 直906 ${ }^{\text {I }}{ }^{-}$ | 91．8 |
| \＆I－HZ08＇9 | 70＋号LI9＊6 | 70＋BLI9＊6 | \＆I－HZ08＇9 |  | 70＋且LI9 6 | \＆L－G708 ${ }^{\text {c }}$ | 20＋自LI9 6 | 20＋自LI9 6 | $9 \mathrm{C}^{8}$ |
| モL－HLZc． | L0＋H9LL＇${ }^{-}$ | 10＋H9L2＇才－ | モ下－HIEt $冖$ | L0＋直9LL －$^{-}$ | L0＋ |  | L0＋H9LL ${ }^{-}$ | L0＋ | 71．8 |
| L0－7968 7 | L0－H696．$\%$ | 20－Hも6\％¢ | L0－马96［＇\％ | ［0－H689． 8 | 20－可66： 9 | ［0－H269 ${ }^{\text {I }}$ | L0－H6T\＆＇$¢$ | 20－ $7 \mathrm{y} 68 \cdot 9$ | \＆1．8 |
| 00＋ | 00＋ $3000{ }^{\text {L }}{ }^{-}$ | 00＋页000 ${ }^{\text {T－}}$ | 00＋且000＊0 | $00+$ H000 ${ }^{\text {－}}$ | $00+$ H000 ${ }^{\text {－}}$ | 00＋且000＊ | 00＋年000 ${ }^{\text {I }}$ | $00+$ 年000 ${ }^{\text {－}}$ | Z1．8 |
| 9L－HEEI＇L | L0－3667＊ | L0－H667＊ | 9T－HEEI＇I | L0－3667＊ | L0－3667＇L | 9L－GEEI＇L | L0－3667＊ | L0－3667＇L | LT． |
| 80－BL60＇$冖$ | $80+$ 鸟670 2 | $80+$ H670 2 | 60－HL98． 8 | $80+$ 年670 2 | $80+$ H670 L | 60－马0才で9 | $80+$ 示670 2 | $80+$ 年670 2 | 01．8 |
| ¢L－H89\％＇¢ | 70＋早9089 | 70＋B908 9 | ¢L－H7だ¢ ¢ | 70＋直9089 | 70＋直9089 | ¢L－直\＆0才¢ | 70＋直9089 | 70＋ 79089 | 60.8 |
| LI－HLLGI | 70－배E89 $6^{-}$ | 70－－HE89 $6^{-}$ | LI－H9LF゙T | 70－®H889 $6^{-}$ | 70－®8889 $6^{-}$ | LI－直9IだI | 70－＇HE89 $6^{-}$ | 70－＇HE89 $6^{-}$ | $80^{\text {．}}$ |
| 9T－H0才9： | L0＋HIEt 7 | L0＋HIEt 7 | ¢T－HE6L．8 | L0＋島IEt 7 | L0＋皿樶 7 | 9T－37988 | 10＋式IEt 7 | 10＋式IEt 7 | 20.8 |
| $00+$ H000＊0 |  |  | $00+$ H000＊0 | $80+$ Hz96．9－ | $80+$ Hz96 $9^{-}$ | 00＋直000＊ | 80＋ | 80＋ | 90.8 |
| 6T－G98L\％ |  | $80+$ H97I 9 | 7I－g98L $冖$ | $80+$ H97I｀ | $80+$ H97I 9 | 7L－直98L\％ | 80＋ | $80+$ H97I ¢ | 90.8 |
| ZL－HELLE | 五0＋式 $290{ }^{\circ}$－ |  | ZL－HELL＇E | 五0＋直 $2908^{-}$ | 王0＋直 $290 \varepsilon^{-}$ | てI－HELL． |  |  | 70．8 |
| EL－HZもL゙も | 00＋式L00 ${ }^{\text {－}}$ | 00＋式L00 ${ }^{\text {－}}$ | モT－H789．9 | $00+$ 早L00 ${ }^{\text {－}}$ | $00+$ 鸟L00 ${ }^{\text {－}}$ | ¢L－Hze\％ | 00＋年L00 ${ }^{\text {I }}$ | $00+$ HL00 ${ }^{\text {－}}$ | 80.8 |
|  | 10－7880 ${ }^{-}$ | 10－ $99808^{-}$ | 80－g70\％${ }^{\text {－}}$ | L0－H780＊－ | L0－r980＊－ | 90－378¢ ¢ | L0－H980＊－ | L0－H980＊－ | 70．8 |
| 00＋㱏000＊0 | L0＋H009 L $^{-}$ | L0＋H009 L $^{-}$ | $00+$ H000＊0 | L0＋直009 ${ }^{-1}$ | L0＋${ }^{\text {H0，}} 009^{\circ} \mathrm{T}^{-}$ | $00+$ 或000＊ | L0＋年009 $\mathrm{T}^{-}$ | L0＋直009 $\mathrm{T}^{-}$ | ［0．8 |
| － 7 ＋ | uеәЈ | 7sag | －${ }^{\text {＋}}$ S | иеәЈ | 7sag | ＇p7S | uеә小 | 7sag | suəəqoid |
| 0G $=$ uıud $N$ |  |  | $0 \pm=$ uıud $N$ |  |  | $08=$ uıud $N$ |  |  |  |



Table B.8: Function values obtained by MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE for g01-g07

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| g01 | D-MODE | $-1.500000 \mathrm{E}+01$ | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | Q-MODE | $-1.500000 \mathrm{E}+01$ | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | QD-MODE | $-1.500000 \mathrm{E}+01$ | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | MFDC-MODE | $-1.500000 \mathrm{E}+01$ | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-1.500000 \mathrm{E}+01$ | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
| g02 | D-MODE | -8.036185E-01 | -7.962040E-01 | $1.639750 \mathrm{E}-02$ |
|  | Q-MODE | -8.036185E-01 | -8.011601E-01 | $5.202655 \mathrm{E}-03$ |
|  | QD-MODE | -8.036188E-01 | -7.999280E-01 | $9.133567 \mathrm{E}-03$ |
|  | MFDC-MODE | -8.036191E-01 | -8.000662E-01 | $1.258981 \mathrm{E}-02$ |
|  | MLS-MODE | -8.036191E-01 | -8.036170E-01 | $4.381993 \mathrm{E}-06$ |
| g03 | D-MODE | $-1.000500 \mathrm{E}+00$ | -9.997030E-01 | 3.393859E-03 |
|  | Q-MODE | $-1.000500 \mathrm{E}+00$ | -9.857461E-01 | $5.671599 \mathrm{E}-02$ |
|  | QD-MODE | $-1.000500 \mathrm{E}+00$ | -9.991963E-01 | $6.493081 \mathrm{E}-03$ |
|  | MFDC-MODE | $-1.000500 \mathrm{E}+00$ | -9.308200E-01 | $1.242538 \mathrm{E}-01$ |
|  | MLS-MODE | $-1.000500 \mathrm{E}+00$ | $-1.000356 \mathrm{E}+00$ | 7.186536E-04 |
| g04 | D-MODE | $-3.066554 \mathrm{E}+04$ | $-3.066554 \mathrm{E}+04$ | 3.712997E-12 |
|  | Q-MODE | $-3.066554 \mathrm{E}+04$ | $-3.066554 \mathrm{E}+04$ | $3.712997 \mathrm{E}-12$ |
|  | QD-MODE | $-3.066554 \mathrm{E}+04$ | $-3.066554 \mathrm{E}+04$ | $3.712997 \mathrm{E}-12$ |
|  | MFDC-MODE | $-3.066554 \mathrm{E}+04$ | $-3.066554 \mathrm{E}+04$ | $3.712997 \mathrm{E}-12$ |
|  | MLS-MODE | $-3.066554 \mathrm{E}+04$ | $-3.066554 \mathrm{E}+04$ | $3.712997 \mathrm{E}-12$ |
| g05 | D-MODE | $5.126497 \mathrm{E}+03$ | $5.126497 \mathrm{E}+03$ | $2.784747 \mathrm{E}-12$ |
|  | Q-MODE | $5.126497 \mathrm{E}+03$ | $5.126497 \mathrm{E}+03$ | $1.947112 \mathrm{E}-12$ |
|  | QD-MODE | $5.126497 \mathrm{E}+03$ | $5.126497 \mathrm{E}+03$ | $2.911804 \mathrm{E}-12$ |
|  | MFDC-MODE | $5.126497 \mathrm{E}+03$ | $5.126497 \mathrm{E}+03$ | $2.784747 \mathrm{E}-12$ |
|  | MLS-MODE | $5.126497 \mathrm{E}+03$ | $5.126497 \mathrm{E}+03$ | $2.784747 \mathrm{E}-12$ |
| g06 | D-MODE | $-6.961814 \mathrm{E}+03$ | $-6.961814 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | Q-MODE | $-6.961814 \mathrm{E}+03$ | $-6.961814 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | QD-MODE | $-6.961814 \mathrm{E}+03$ | $-6.961814 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | MFDC-MODE | $-6.961814 \mathrm{E}+03$ | $-6.961814 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-6.961814 \mathrm{E}+03$ | $-6.961814 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
| g07 | D-MODE | $2.430621 \mathrm{E}+01$ | $2.430621 \mathrm{E}+01$ | 7.858915E-14 |
|  | Q-MODE | $2.430621 \mathrm{E}+01$ | $2.430621 \mathrm{E}+01$ | 8.236628E-15 |
|  | QD-MODE | $2.430621 \mathrm{E}+01$ | $2.430621 \mathrm{E}+01$ | 8.792518E-15 |
|  | MFDC-MODE | $2.430621 \mathrm{E}+01$ | $2.430621 \mathrm{E}+01$ | 3.434283E-10 |
|  | MLS-MODE | $2.430621 \mathrm{E}+01$ | $2.430621 \mathrm{E}+01$ | $5.279497 \mathrm{E}-15$ |

Table B.9: Function values obtained by MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE for g08-g14

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| g08 | D-MODE | -9.582504E-02 | -9.582504E-02 | $1.444446 \mathrm{E}-17$ |
|  | Q-MODE | -9.582504E-02 | -9.582504E-02 | $1.234785 \mathrm{E}-17$ |
|  | QD-MODE | -9.582504E-02 | -9.582504E-02 | $1.328697 \mathrm{E}-17$ |
|  | MFDC-MODE | -9.582504E-02 | -9.582504E-02 | $1.498972 \mathrm{E}-17$ |
|  | MLS-MODE | -9.582504E-02 | -9.582504E-02 | $1.498972 \mathrm{E}-17$ |
| g09 | D-MODE | $6.806301 \mathrm{E}+02$ | $6.806301 \mathrm{E}+02$ | $3.602575 \mathrm{E}-13$ |
|  | Q-MODE | $6.806301 \mathrm{E}+02$ | $6.806301 \mathrm{E}+02$ | 3.617493E-13 |
|  | QD-MODE | $6.806301 \mathrm{E}+02$ | $6.806301 \mathrm{E}+02$ | 3.587596E-13 |
|  | MFDC-MODE | $6.806301 \mathrm{E}+02$ | $6.806301 \mathrm{E}+02$ | 3.549870E-13 |
|  | MLS-MODE | $6.806301 \mathrm{E}+02$ | $6.806301 \mathrm{E}+02$ | 3.322626E-13 |
| g10 | D-MODE | $7.049248 \mathrm{E}+03$ | $7.049248 \mathrm{E}+03$ | $4.020508 \mathrm{E}-12$ |
|  | Q-MODE | $7.049248 \mathrm{E}+03$ | $7.049248 \mathrm{E}+03$ | $4.084296 \mathrm{E}-12$ |
|  | QD-MODE | $7.049248 \mathrm{E}+03$ | $7.049248 \mathrm{E}+03$ | $3.294958 \mathrm{E}-12$ |
|  | MFDC-MODE | $7.049248 \mathrm{E}+03$ | $7.049248 \mathrm{E}+03$ | 4.703718E-09 |
|  | MLS-MODE | $7.049248 \mathrm{E}+03$ | $7.049248 \mathrm{E}+03$ | $3.413131 \mathrm{E}-12$ |
| g11 | D-MODE | $7.499000 \mathrm{E}-01$ | $7.499000 \mathrm{E}-01$ | $1.133117 \mathrm{E}-16$ |
|  | Q-MODE | $7.499000 \mathrm{E}-01$ | $7.499000 \mathrm{E}-01$ | $1.133117 \mathrm{E}-16$ |
|  | QD-MODE | $7.499000 \mathrm{E}-01$ | $7.499000 \mathrm{E}-01$ | $1.133117 \mathrm{E}-16$ |
|  | MFDC-MODE | $7.499000 \mathrm{E}-01$ | $7.499000 \mathrm{E}-01$ | $1.133117 \mathrm{E}-16$ |
|  | MLS-MODE | $7.499000 \mathrm{E}-01$ | $7.499000 \mathrm{E}-01$ | $1.133117 \mathrm{E}-16$ |
| g12 | D-MODE | $-1.000000 \mathrm{E}+00$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Q-MODE | $-1.000000 \mathrm{E}+00$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | QD-MODE | $-1.000000 \mathrm{E}+00$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MFDC-MODE | $-1.000000 \mathrm{E}+00$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-1.000000 \mathrm{E}+00$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| g13 | D-MODE | $5.394151 \mathrm{E}-02$ | $2.455780 \mathrm{E}-01$ | $1.762731 \mathrm{E}-01$ |
|  | Q-MODE | $5.394151 \mathrm{E}-02$ | $3.438241 \mathrm{E}-01$ | $2.258916 \mathrm{E}-01$ |
|  | QD-MODE | $5.394151 \mathrm{E}-02$ | $3.493872 \mathrm{E}-01$ | $2.611549 \mathrm{E}-01$ |
|  | MFDC-MODE | $5.427658 \mathrm{E}-02$ | $6.496030 \mathrm{E}-01$ | $2.773624 \mathrm{E}-01$ |
|  | MLS-MODE | $5.394151 \mathrm{E}-02$ | $3.900748 \mathrm{E}-01$ | $2.663948 \mathrm{E}-01$ |
| g14 | D-MODE | -4.776489E+01 | $-4.776489 \mathrm{E}+01$ | $2.051160 \mathrm{E}-14$ |
|  | Q-MODE | $-4.776489 \mathrm{E}+01$ | $-4.776489 \mathrm{E}+01$ | $2.284075 \mathrm{E}-14$ |
|  | QD-MODE | $-4.776489 \mathrm{E}+01$ | $-4.776489 \mathrm{E}+01$ | 2.325151E-14 |
|  | MFDC-MODE | $-4.776489 \mathrm{E}+01$ | $-4.776489 \mathrm{E}+01$ | $2.431295 \mathrm{E}-14$ |
|  | MLS-MODE | $-4.776489 \mathrm{E}+01$ | $-4.776489 \mathrm{E}+01$ | $2.461392 \mathrm{E}-14$ |

Table B.10: Function values obtained by MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE for g15-g24

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| g15 | D-MODE | $9.617150 \mathrm{E}+02$ | $9.617150 \mathrm{E}+02$ | $5.801557 \mathrm{E}-13$ |
|  | Q-MODE | $9.617150 \mathrm{E}+02$ | $9.617150 \mathrm{E}+02$ | $5.801557 \mathrm{E}-13$ |
|  | QD-MODE | $9.617150 \mathrm{E}+02$ | $9.617150 \mathrm{E}+02$ | $5.801557 \mathrm{E}-13$ |
|  | MFDC-MODE | $9.617150 \mathrm{E}+02$ | $9.617150 \mathrm{E}+02$ | $5.801557 \mathrm{E}-13$ |
|  | MLS-MODE | $9.617150 \mathrm{E}+02$ | $9.617150 \mathrm{E}+02$ | $5.801557 \mathrm{E}-13$ |
| g16 | D-MODE | $-1.905155 \mathrm{E}+00$ | $-1.905155 \mathrm{E}+00$ | $4.532467 \mathrm{E}-16$ |
|  | Q-MODE | $-1.905155 \mathrm{E}+00$ | $-1.905155 \mathrm{E}+00$ | $4.532467 \mathrm{E}-16$ |
|  | QD-MODE | $-1.905155 \mathrm{E}+00$ | $-1.905155 \mathrm{E}+00$ | $4.532467 \mathrm{E}-16$ |
|  | MFDC-MODE | $-1.905155 \mathrm{E}+00$ | $-1.905155 \mathrm{E}+00$ | $4.532467 \mathrm{E}-16$ |
|  | MLS-MODE | $-1.905155 \mathrm{E}+00$ | $-1.905155 \mathrm{E}+00$ | $4.532467 \mathrm{E}-16$ |
| g17 | D-MODE | $8.853534 \mathrm{E}+03$ | $8.884710 \mathrm{E}+03$ | $3.857447 \mathrm{E}+01$ |
|  | Q-MODE | $8.853534 \mathrm{E}+03$ | $8.883499 \mathrm{E}+03$ | $3.746824 \mathrm{E}+01$ |
|  | QD-MODE | $8.853534 \mathrm{E}+03$ | 8.884073E+03 | $3.818070 \mathrm{E}+01$ |
|  | MFDC-MODE | $8.853534 \mathrm{E}+03$ | $8.872295 \mathrm{E}+03$ | $3.736106 \mathrm{E}+01$ |
|  | MLS-MODE | $8.853534 \mathrm{E}+03$ | $8.869420 \mathrm{E}+03$ | $3.215566 \mathrm{E}+01$ |
| g18 | D-MODE | -8.660254E-01 | -8.660254E-01 | $2.299976 \mathrm{E}-16$ |
|  | Q-MODE | -8.660254E-01 | -8.507419E-01 | $5.289768 \mathrm{E}-02$ |
|  | QD-MODE | -8.660254E-01 | -8.583836E-01 | $3.820879 \mathrm{E}-02$ |
|  | MFDC-MODE | -8.660254E-01 | -8.583836E-01 | $3.820879 \mathrm{E}-02$ |
|  | MLS-MODE | -8.660254E-01 | -8.660254E-01 | 8.869285E-15 |
| g19 | D-MODE | $3.265559 \mathrm{E}+01$ | $3.265559 \mathrm{E}+01$ | $1.241793 \mathrm{E}-09$ |
|  | Q-MODE | $3.265559 \mathrm{E}+01$ | $3.265559 \mathrm{E}+01$ | $1.677505 \mathrm{E}-13$ |
|  | QD-MODE | $3.265559 \mathrm{E}+01$ | $3.265559 \mathrm{E}+01$ | $9.409662 \mathrm{E}-14$ |
|  | MFDC-MODE | $3.265559 \mathrm{E}+01$ | $3.265559 \mathrm{E}+01$ | $5.226907 \mathrm{E}-07$ |
|  | MLS-MODE | $3.265559 \mathrm{E}+01$ | $3.265559 \mathrm{E}+01$ | $1.555369 \mathrm{E}-14$ |
| g21 | D-MODE | $1.937245 \mathrm{E}+02$ | $2.042028 \mathrm{E}+02$ | $3.626626 \mathrm{E}+01$ |
|  | Q-MODE | $1.937245 \mathrm{E}+02$ | $2.042028 \mathrm{E}+02$ | $3.626626 \mathrm{E}+01$ |
|  | QD-MODE | $1.937245 \mathrm{E}+02$ | $1.989636 \mathrm{E}+02$ | $2.619567 \mathrm{E}+01$ |
|  | MFDC-MODE | $1.937245 \mathrm{E}+02$ | $2.106096 \mathrm{E}+02$ | $4.085840 \mathrm{E}+01$ |
|  | MLS-MODE | $1.937245 \mathrm{E}+02$ | $2.019837 \mathrm{E}+02$ | $2.968475 \mathrm{E}+01$ |
| g23 | D-MODE | -4.000551E+02 | $-3.998953 \mathrm{E}+02$ | $6.334253 \mathrm{E}-01$ |
|  | Q-MODE | $-4.000551 \mathrm{E}+02$ | $-3.977503 \mathrm{E}+02$ | $4.609776 \mathrm{E}+00$ |
|  | QD-MODE | $-4.000551 \mathrm{E}+02$ | $-4.000551 \mathrm{E}+02$ | $1.209669 \mathrm{E}-05$ |
|  | MFDC-MODE | $-4.000551 \mathrm{E}+02$ | $-3.997105 \mathrm{E}+02$ | $1.048797 \mathrm{E}+00$ |
|  | MLS-MODE | $-4.000551 \mathrm{E}+02$ | $-4.000545 \mathrm{E}+02$ | $3.007736 \mathrm{E}-03$ |
| g24 | D-MODE | $-5.508013 \mathrm{E}+00$ | $-5.508013 \mathrm{E}+00$ | $9.064933 \mathrm{E}-16$ |
|  | Q-MODE | $-5.508013 \mathrm{E}+00$ | $-5.508013 \mathrm{E}+00$ | $9.064933 \mathrm{E}-16$ |
|  | QD-MODE | $-5.508013 \mathrm{E}+00$ | $-5.508013 \mathrm{E}+00$ | $9.064933 \mathrm{E}-16$ |
|  | MFDC-MODE | $-5.508013 \mathrm{E}+00$ | $-5.508013 \mathrm{E}+00$ | $9.064933 \mathrm{E}-16$ |
|  | MLS-MODE | $-5.508013 \mathrm{E}+00$ | $-5.508013 \mathrm{E}+00$ | $9.064933 \mathrm{E}-16$ |

Table B.11: Function values obtained by MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE for r01-r06

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r01 | D-MODE | $1.544418 \mathrm{E}+04$ | $1.544418 \mathrm{E}+04$ | $2.251581 \mathrm{E}-06$ |
|  | Q-MODE | $1.544418 \mathrm{E}+04$ | $1.544436 \mathrm{E}+04$ | $8.793190 \mathrm{E}-01$ |
|  | QD-MODE | $1.544418 \mathrm{E}+04$ | $1.544454 \mathrm{E}+04$ | $1.217362 \mathrm{E}+00$ |
|  | MFDC-MODE | $1.544418 \mathrm{E}+04$ | $1.544418 \mathrm{E}+04$ | $1.893493 \mathrm{E}-07$ |
|  | MLS-MODE | $1.544418 \mathrm{E}+04$ | $1.544418 \mathrm{E}+04$ | 6.184698E-07 |
| r02 | D-MODE | $1.806264 \mathrm{E}+04$ | $1.812390 \mathrm{E}+04$ | $4.266121 \mathrm{E}+01$ |
|  | Q-MODE | $1.807523 \mathrm{E}+04$ | $1.812145 \mathrm{E}+04$ | $3.789364 \mathrm{E}+01$ |
|  | QD-MODE | $1.807839 \mathrm{E}+04$ | $1.811303 \mathrm{E}+04$ | $3.735577 \mathrm{E}+01$ |
|  | MFDC-MODE | $1.802537 \mathrm{E}+04$ | $1.808985 \mathrm{E}+04$ | $2.508071 \mathrm{E}+01$ |
|  | MLS-MODE | $1.805091 \mathrm{E}+04$ | $1.810492 \mathrm{E}+04$ | $3.711234 \mathrm{E}+01$ |
| r03 | D-MODE | $3.276626 \mathrm{E}+04$ | $3.288048 \mathrm{E}+04$ | $5.457285 \mathrm{E}+01$ |
|  | Q-MODE | $3.275845 \mathrm{E}+04$ | $3.284286 \mathrm{E}+04$ | $5.231876 \mathrm{E}+01$ |
|  | QD-MODE | $3.279047 \mathrm{E}+04$ | $3.286095 \mathrm{E}+04$ | $4.968852 \mathrm{E}+01$ |
|  | MFDC-MODE | $3.284191 \mathrm{E}+04$ | $3.289203 \mathrm{E}+04$ | $3.018005 \mathrm{E}+01$ |
|  | MLS-MODE | $3.279775 \mathrm{E}+04$ | $3.289093 \mathrm{E}+04$ | $4.777296 \mathrm{E}+01$ |
| r04 | D-MODE | $1.256059 \mathrm{E}+05$ | $1.272531 \mathrm{E}+05$ | $9.608122 \mathrm{E}+02$ |
|  | Q-MODE | $1.253963 \mathrm{E}+05$ | $1.267771 \mathrm{E}+05$ | $9.331146 \mathrm{E}+02$ |
|  | QD-MODE | $1.252848 \mathrm{E}+05$ | $1.267037 \mathrm{E}+05$ | $6.302580 \mathrm{E}+02$ |
|  | MFDC-MODE | $1.250032 \mathrm{E}+05$ | $1.258866 \mathrm{E}+05$ | $5.946653 \mathrm{E}+02$ |
|  | MLS-MODE | $1.228168 \mathrm{E}+05$ | $1.244875 \mathrm{E}+05$ | $7.285228 \mathrm{E}+02$ |
| r05 | D-MODE | $1.818684 \mathrm{E}+06$ | $1.866965 \mathrm{E}+06$ | $2.302252 \mathrm{E}+04$ |
|  | Q-MODE | $1.812447 \mathrm{E}+06$ | $1.844349 \mathrm{E}+06$ | $1.947029 \mathrm{E}+04$ |
|  | QD-MODE | $1.850348 \mathrm{E}+06$ | $1.870118 \mathrm{E}+06$ | $1.005462 \mathrm{E}+04$ |
|  | MFDC-MODE | $1.822830 \mathrm{E}+06$ | $1.843878 \mathrm{E}+06$ | $1.177728 \mathrm{E}+04$ |
|  | MLS-MODE | $1.676914 \mathrm{E}+06$ | $1.781277 \mathrm{E}+06$ | $4.984852 \mathrm{E}+04$ |
| r06 | D-MODE | $5.012135 \mathrm{E}+04$ | $5.133615 \mathrm{E}+04$ | $5.742851 \mathrm{E}+02$ |
|  | Q-MODE | $4.841733 \mathrm{E}+04$ | $4.999552 \mathrm{E}+04$ | $9.386280 \mathrm{E}+02$ |
|  | QD-MODE | $5.076869 \mathrm{E}+04$ | $5.177887 \mathrm{E}+04$ | $4.442427 \mathrm{E}+02$ |
|  | MFDC-MODE | $4.958437 \mathrm{E}+04$ | $5.034825 \mathrm{E}+04$ | $4.598598 \mathrm{E}+02$ |
|  | MLS-MODE | $4.870594 \mathrm{E}+04$ | $5.064304 \mathrm{E}+04$ | $1.270508 \mathrm{E}+03$ |

Table B.12: Function values obtained by MLS-MODE, Q-MODE, D-MODE, QD-MODE and MFDC-MODE for r07-r10

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r07 | D-MODE | $1.064496 \mathrm{E}+06$ | $1.070949 \mathrm{E}+06$ | $2.620949 \mathrm{E}+03$ |
|  | Q-MODE | $1.056977 \mathrm{E}+06$ | $1.061533 \mathrm{E}+06$ | $2.508282 \mathrm{E}+03$ |
|  | QD-MODE | $1.065570 \mathrm{E}+06$ | $1.070672 \mathrm{E}+06$ | $2.948745 \mathrm{E}+03$ |
|  | MFDC-MODE | $1.058648 \mathrm{E}+06$ | $1.068715 \mathrm{E}+06$ | $3.571217 \mathrm{E}+03$ |
|  | MLS-MODE | $1.054462 \mathrm{E}+06$ | $1.068496 \mathrm{E}+06$ | $4.924136 \mathrm{E}+03$ |
|  | D-MODE | $9.157478 \mathrm{E}+05$ | $9.163686 \mathrm{E}+05$ | $5.202005 \mathrm{E}+02$ |
|  | Q-MODE | $9.157221 \mathrm{E}+05$ | $9.162300 \mathrm{E}+05$ | $3.913204 \mathrm{E}+02$ |
|  | QD-MODE | $9.157536 \mathrm{E}+05$ | $9.161650 \mathrm{E}+05$ | $3.142032 \mathrm{E}+02$ |
|  | MFDC-MODE | $9.157581 \mathrm{E}+05$ | $9.161236 \mathrm{E}+05$ | $2.928442 \mathrm{E}+02$ |
|  | MLS-MODE | $9.157841 \mathrm{E}+05$ | $9.161801 \mathrm{E}+05$ | $2.622739 \mathrm{E}+02$ |
| r09 | D-MODE | $9.173792 \mathrm{E}+05$ | $9.204819 \mathrm{E}+05$ | $1.336856 \mathrm{E}+03$ |
|  | Q-MODE | $9.178093 \mathrm{E}+05$ | $9.204829 \mathrm{E}+05$ | $1.385599 \mathrm{E}+03$ |
|  | QD-MODE | $9.174963 \mathrm{E}+05$ | $9.200026 \mathrm{E}+05$ | $1.403220 \mathrm{E}+03$ |
|  | MFDC-MODE | $9.184978 \mathrm{E}+05$ | $9.209209 \mathrm{E}+05$ | $8.304877 \mathrm{E}+02$ |
|  | MLS-MODE | $9.197099 \mathrm{E}+05$ | $9.242760 \mathrm{E}+05$ | $1.612274 \mathrm{E}+03$ |
|  | D-MODE | $9.304478 \mathrm{E}+05$ | $9.369086 \mathrm{E}+05$ | $3.531980 \mathrm{E}+03$ |
|  | Q-MODE | $9.291824 \mathrm{E}+05$ | $9.338445 \mathrm{E}+05$ | $3.424019 \mathrm{E}+03$ |
|  | QD-MODE | $9.305926 \mathrm{E}+05$ | $9.359744 \mathrm{E}+05$ | $3.601523 \mathrm{E}+03$ |
|  | MFDC-MODE | $9.301181 \mathrm{E}+05$ | $9.339471 \mathrm{E}+05$ | $2.817914 \mathrm{E}+03$ |
|  | MLS-MODE | $9.268975 \mathrm{E}+05$ | $9.348549 \mathrm{E}+05$ | $4.451490 \mathrm{E}+03$ |

Table B.13: Function values obtained by MLS-MODE, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE for CEC2006 for g01-g04

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g01 | MLS-MODE | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | AH-DEa | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
| g02 | MLS-MODE | -8.036191E-01 | $4.509747 \mathrm{E}-16$ |
|  | EHCT_DE | -7.936387E-01 | $1.120000 \mathrm{E}-02$ |
|  | AIS-ZHY | -8.021930E-01 | $5.190000 \mathrm{E}-10$ |
|  | ISMOADE-CMA | -7.92440E-01 | $2.80000 \mathrm{E}-02$ |
|  | SAMO-DE | -7.987000E-01 | $8.801 \mathrm{E}-03$ |
|  | ECHT-EP2 | -7.998220E-01 | $1.260000 \mathrm{E}-02$ |
|  | $\epsilon \mathrm{DEg}$ | -8.036191E-01 | $1.750000 \mathrm{E}-08$ |
|  | AH-DEa | -8.007000E-01 | $3.912 \mathrm{E}-03$ |
|  | SAMO-GA | -7.960000E-01 | $5.803 \mathrm{E}-03$ |
|  | APF-GA | -8.035000E-01 | $1.000 \mathrm{E}-04$ |
|  | rank-iMDDE | -8.02012E-01 | $1.11335 \mathrm{E}-02$ |
| g03 | MLS-MODE | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.0005000 \mathrm{E}+00$ | $1.7700000 \mathrm{E}-11$ |
|  | ISMOADE-CMA | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.0005000 \mathrm{E}+00$ | $2.9600000 \mathrm{E}-31$ |
|  | AH-DEa | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $-1.0005000 \mathrm{E}+00$ | $2.9600000 \mathrm{E}-31$ |
| g04 | MLS-MODE | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-3.06655390 \mathrm{E}+04$ | $3.69000000 \mathrm{E}-13$ |
|  | ISMOADE-CMA | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-3.06655386 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | AH-DEa | $-3.06655387 \mathrm{E}+04$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-3.06655387 \mathrm{E}+04$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $-3.067000 \mathrm{E}+04$ | $1.000000 \mathrm{E}-04$ |
|  | rank-iMDDE | $-3.06655387 \mathrm{E}+04$ | $7.31261000 \mathrm{E}-12$ |

Table B.14: Function values obtained by MLS-MODE, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE for CEC2006 for g05-g08

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g05 | MLS-MODE | $5.1264970 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $5.126498 \mathrm{E}+03$ | $1.700000 \mathrm{E}-02$ |
|  | ISMOADE-CMA | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $5.126000 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $5.128000 \mathrm{E}+03$ | $1.117000 \mathrm{E}+00$ |
|  | APF-GA | $5.128000 \mathrm{E}+03$ | $1.432000 \mathrm{E}+00$ |
|  | rank-iMDDE | $5.12650 \mathrm{E}+03$ | $7.31261 \mathrm{E}-12$ |
| g06 | MLS-MODE | $-6.9618140 \mathrm{E}+03$ | $0.0000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-6.96181400 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-6.96181385 \mathrm{E}+03$ | $1.90000000 \mathrm{E}-12$ |
|  | ISMOADE-CMA | $-6.96181388 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-6.96181388 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-6.96181400 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-6.96181388 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | AH-DEa | $-6.9618140 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-6.9618140 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $-6.9618140 \mathrm{E}+03$ | $4.600000 \mathrm{E}-12$ |
|  | rank-iMDDE | $-6.96181 \mathrm{E}+03$ | $1.37111 \mathrm{E}-11$ |
| g07 | MLS-MODE | $2.4306210 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $2.430620 \mathrm{E}+01$ | $1.140000 \mathrm{E}-10$ |
|  | AIS-ZHY | $2.435570 \mathrm{E}+01$ | $8.200000 \mathrm{E}-03$ |
|  | ISMOADE-CMA | $2.4306210 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $2.430960 \mathrm{E}+01$ | $1.590000 \mathrm{E}-03$ |
|  | ECHT-EP2 | $2.430630 \mathrm{E}+01$ | $3.190000 \mathrm{E}-05$ |
|  | $\epsilon \mathrm{DEg}$ | $2.430620 \mathrm{E}+01$ | $2.180000 \mathrm{E}-15$ |
|  | AH-DEa | $2.431000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $2.441000 \mathrm{E}+01$ | $4.591000 \mathrm{E}-02$ |
|  | APF-GA | $2.431000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $2.43062 \mathrm{E}+01$ | $7.74285 \mathrm{E}-07$ |
| g08 | MLS-MODE | -9.5825040E-02 | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | -9.582504E-02 | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | -9.582500E-02 | $2.610000 \mathrm{E}-08$ |
|  | $\epsilon \mathrm{DEg}$ | -9.582500E-02 | $1.230000 \mathrm{E}-32$ |
|  | AH-DEa | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | -9.58250E-02 | $8.36862 \mathrm{E}-17$ |

Table B.15: Function values obtained by MLS-MODE, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE for CEC2006 for g09-g12

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g09 | MLS-MODE | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $6.806500 \mathrm{E}+02$ | $1.200000 \mathrm{E}-08$ |
|  | ISMOADE-CMA | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $6.8063010 \mathrm{E}+02$ | $1.160000 \mathrm{E}-05$ |
|  | ECHT-EP2 | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $6.8063010 \mathrm{E}+02$ | $1.457000 \mathrm{E}-03$ |
|  | APF-GA | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $6.80630 \mathrm{E}+02$ | $2.285190 \mathrm{E}-13$ |
| g10 | MLS-MODE | $7.0492480 \mathrm{E}+03$ | $6.0989160 \mathrm{E}-10$ |
|  | EHCT_DE | $7.049248 \mathrm{E}+03$ | $4.180000 \mathrm{E}-07$ |
|  | AIS-ZHY | $7.049570 \mathrm{E}+03$ | $4.500000 \mathrm{E}-04$ |
|  | ISMOADE-CMA | $7.049248 \mathrm{E}+03$ | $5.420000 \mathrm{E}-06$ |
|  | SAMO-DE | $7.059813 \mathrm{E}+03$ | $7.860000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $7.049249 \mathrm{E}+03$ | $6.600000 \mathrm{E}-04$ |
|  | $\epsilon \mathrm{DEg}$ | $7.049248 \mathrm{E}+03$ | $4.240000 \mathrm{E}-13$ |
|  | AH-DEa | $7.0492480 \mathrm{E}+03$ | $1.688000 \mathrm{E}-09$ |
|  | SAMO-GA | $7.144000 \mathrm{E}+03$ | $6.786000 \mathrm{E}+01$ |
|  | APF-GA | $7.078000 \mathrm{E}+03$ | $5.124000 \mathrm{E}+01$ |
|  | rank-iMDDE | $7.04925 \mathrm{E}+03$ | $1.50134 \mathrm{E}-05$ |
| g11 | MLS-MODE | $7.4990000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $7.499000 \mathrm{E}-01$ | $1.400000 \mathrm{E}-08$ |
|  | ISMOADE-CMA | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $7.49900 \mathrm{E}-01$ | $1.78531 \mathrm{E}-15$ |
| g12 | MLS-MODE | $-1.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $-1.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ |

Table B.16: Function values obtained by MLS-MODE, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE for CEC2006 for g13-g16

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g13 | MLS-MODE | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $5.39415 \mathrm{E}-02$ | $7.800000 \mathrm{E}-10$ |
|  | ISMOADE-CMA | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $5.39415 \mathrm{E}-02$ | $1.750000 \mathrm{E}-08$ |
|  | ECHT-EP2 | $5.39415 \mathrm{E}-02$ | $1.000000 \mathrm{E}-12$ |
|  | $\epsilon \mathrm{DEg}$ | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $5.403000 \mathrm{E}-02$ | $5.941000 \mathrm{E}-05$ |
|  | APF-GA | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $5.39415 \mathrm{E}-02$ | $3.03523 \mathrm{E}-07$ |
| g14 | MLS-MODE | $-4.7764890 \mathrm{E}+01$ | $2.6066690 \mathrm{E}-14$ |
|  | EHCT_DE | $-4.776489 \mathrm{E}+01$ | $3.260000 \mathrm{E}-13$ |
|  | AIS-ZHY | $-4.776488 \mathrm{E}+01$ | $1.000000 \mathrm{E}-12$ |
|  | ISMOADE-CMA | $-4.776489 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-4.768115 \mathrm{E}+01$ | $4.040000 \mathrm{E}-02$ |
|  | ECHT-EP2 | $-4.776480 \mathrm{E}+01$ | $2.720000 \mathrm{E}-05$ |
|  | $\epsilon \mathrm{DEg}$ | $-4.776489 \mathrm{E}+01$ | $1.390000 \mathrm{E}-15$ |
|  | AH-DEa | $-4.776000 \mathrm{E}+01$ | $3.894000 \mathrm{E}-05$ |
|  | SAMO-GA | $-4.776489 \mathrm{E}+01$ | $3.159000 \mathrm{E}-01$ |
|  | APF-GA | $-4.776000 \mathrm{E}+01$ | $1.000000 \mathrm{E}-04$ |
|  | rank-iMDDE | $-4.77649 \mathrm{E}+01$ | $2.23259 \mathrm{E}-05$ |
| g15 | MLS-MODE | $9.6171500 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $9.617150 \mathrm{E}+02$ | $2.010000 \mathrm{E}-13$ |
|  | $\epsilon \mathrm{DEg}$ | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $9.617150 \mathrm{E}+02$ | $5.524000 \mathrm{E}-05$ |
|  | APF-GA | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $9.61715 \mathrm{E}+02$ | $7.99817 \mathrm{E}-13$ |
| g16 | MLS-MODE | $-1.9051550 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.905155 \mathrm{E}+00$ | $1.120000 \mathrm{E}-10$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.905155 \mathrm{E}+00$ | $1.580000 \mathrm{E}-30$ |
|  | AH-DEa | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.905155 \mathrm{E}+00$ | $6.952000 \mathrm{E}-07$ |
|  | APF-GA | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $-1.905155 \mathrm{E}+00$ | $1.562140 \mathrm{E}-15$ |

Table B.17: Function values obtained by MLS-MODE, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE for CEC2006 for g17-g21

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g17 | MLS-MODE | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $8.853540 \mathrm{E}+03$ | $1.900000 \mathrm{E}-09$ |
|  | ISMOADE-CMA | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $8.853540 \mathrm{E}+03$ | $1.150000 \mathrm{E}-05$ |
|  | ECHT-EP2 | $8.853540 \mathrm{E}+03$ | $2.130000 \mathrm{E}-08$ |
|  | $\epsilon \mathrm{DEg}$ | $8.853540 \mathrm{E}+03$ | $1.210000 \mathrm{E}-27$ |
|  | AH-DEa | $8.858000 \mathrm{E}+03$ | $1.847000 \mathrm{E}+01$ |
|  | SAMO-GA | $8.854000 \mathrm{E}+03$ | $1.740000 \mathrm{E}-01$ |
|  | APF-GA | $8.888000 \mathrm{E}+03$ | $2.903000 \mathrm{E}+01$ |
|  | rank-iMDDE | $8.85354 \mathrm{E}+03$ | $1.31206 \mathrm{E}+00$ |
| g18 | MLS-MODE | -8.6602540E-01 | $5.1068250 \mathrm{E}-15$ |
|  | EHCT_DE | -8.660240E-01 | $5.150000 \mathrm{E}-06$ |
|  | AIS-ZHY | -8.660250E-01 | $1.300000 \mathrm{E}-15$ |
|  | ISMOADE-CMA | -8.660250E-01 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | -8.660240E-01 | $7.040000 \mathrm{E}-07$ |
|  | ECHT-EP2 | -8.660250E-01 | $1.000000 \mathrm{E}-09$ |
|  | $\epsilon \mathrm{DEg}$ | -8.660250E-01 | $2.180000 \mathrm{E}-17$ |
|  | AH-DEa | -8.6602540E-01 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | -8.655000E-01 | $4.080000 \mathrm{E}-04$ |
|  | APF-GA | -8.659000E-01 | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | -8.66025E-01 | $8.62135 \mathrm{E}-08$ |
| g19 | MLS-MODE | $3.2655590 \mathrm{E}+01$ | $1.7525120 \mathrm{E}-14$ |
|  | EHCT_DE | $3.265654 \mathrm{E}+01$ | $7.760000 \mathrm{E}-04$ |
|  | AIS-ZHY | $3.265559 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $3.265559 \mathrm{E}+01$ | $6.460000 \mathrm{E}-07$ |
|  | SAMO-DE | $3.275734 \mathrm{E}+01$ | $6.150000 \mathrm{E}-02$ |
|  | ECHT-EP2 | $3.266230 \mathrm{E}+01$ | $3.400000 \mathrm{E}-03$ |
|  | $\epsilon \mathrm{DEg}$ | $3.265560 \mathrm{E}+01$ | $1.260000 \mathrm{E}-05$ |
|  | AH-DEa | $3.457000 \mathrm{E}+01$ | $2.524000 \mathrm{E}+00$ |
|  | SAMO-GA | $3.643000 \mathrm{E}+01$ | $1.037000 \mathrm{E}+00$ |
|  | APF-GA | $3.266000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $3.26556 \mathrm{E}+01$ | $1.70016 \mathrm{E}-03$ |
| g21 | MLS-MODE | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $1.967245 \mathrm{E}+02$ | $1.100000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $1.937714 \mathrm{E}+02$ | $1.960000 \mathrm{E}-02$ |
|  | ECHT-EP2 | $1.937438 \mathrm{E}+02$ | $1.650000 \mathrm{E}-02$ |
|  | $\epsilon \mathrm{DEg}$ | $1.937245 \mathrm{E}+02$ | $3.340000 \mathrm{E}-14$ |
|  | AH-DEa | $1.939000 \mathrm{E}+02$ | $6.977000 \mathrm{E}-01$ |
|  | SAMO-GA | $2.461000 \mathrm{E}+02$ | $1.492000 \mathrm{E}+01$ |
|  | APF-GA | $1.995000 \mathrm{E}+02$ | $3.866000 \mathrm{E}+00$ |
|  | rank-iMDDE | $1.93725 \mathrm{E}+02$ | $1.68174 \mathrm{E}-10$ |

Table B.18: Function values obtained by MLS-MODE, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon$ DEg, AH-DEa, SAMO-GA, APF-GA and rank-iMDDE for CEC2006 for g23-g24

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g23 | MLS-MODE | $-4.0005120 \mathrm{E}+02$ | $1.9083780 \mathrm{E}-02$ |
|  | EHCT_DE | $-4.000546 \mathrm{E}+02$ | $2.180000 \mathrm{E}-03$ |
|  | AIS-ZHY | $-3.998743 \mathrm{E}+02$ | $2.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-3.956240 \mathrm{E}+02$ | $7.790000 \mathrm{E}+00$ |
|  | SAMO-DE | $-3.608177 \mathrm{E}+02$ | $1.960000 \mathrm{E}+01$ |
|  | ECHT-EP2 | $-3.732178 \mathrm{E}+02$ | $3.370000 \mathrm{E}+01$ |
|  | $\epsilon$ DEg | $-4.000551 \mathrm{E}+02$ | $1.110000 \mathrm{E}-14$ |
|  | AH-DEa | $-3.444000 \mathrm{E}+02$ | $7.782000 \mathrm{E}+01$ |
|  | SAMO-GA | $-1.948000 \mathrm{E}+02$ | $5.328000 \mathrm{E}+01$ |
|  | APF-GA | $-3.948000 \mathrm{E}+02$ | $3.866000 \mathrm{E}+00$ |
|  | rank-iMDDE | $-3.78181 \mathrm{E}+02$ | $8.20199 \mathrm{E}-05$ |
|  | MLS-MODE | $-5.5080130 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| g24 | ECHT-EP2 | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon$ DEg | $-5.508013 \mathrm{E}+00$ | $2.520000 \mathrm{E}-29$ |
|  | AH-DEa | $-5.508000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-5.508000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | APF-GA | $-5.508000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | rank-iMDDE | $-5.50801 \mathrm{E}+00$ | $1.78531 \mathrm{E}-15$ |


| 00＋G000076 L | 10＋马000889\％ | もて－¢00T089 \％ | 00＋G00000000 | 00＋${ }^{\text {cou00000 }} 0$ | 00＋年000000＊0 | สG－yONY |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 20－H000も¢T8 | 20－g000c¢\％ | 6I－H000I8F＇9 |  | 0I－－HE9906I ${ }^{\text {T }}$ |  | VD－ONVS |  |
|  |  |  | 00＋G00tgLL． | L0－H00z099\％ | ¢L－G008tくも゙て | OSdTD－o， |  |
| － | － |  | 2I＋H029600 ${ }^{\text {I }}$ |  |  | गgvə |  |
| 9L－GとLtもtを9 | 9t－G606809 ${ }^{\text { }}$ | 00＋H000000＊ 0 | ¢z－g¢ $9680^{\circ} \mathrm{I}$ | 97－HLZL989 ${ }^{\text {² }}$ | 00＋ $2000000^{\circ}$ | xeuqの－®の | ¢0 ${ }^{\circ}$ |
| L0－H69tLt0 8 | L0＋H98LE88\％ | L0＋GLIEL98\％ | 00＋H00000000 | 00＋H000000 0 | $00+$ \％000000 0 | $\stackrel{8}{\text { ²，}}{ }^{\text {² }}$ |  |
| Lz－H0009tI＇I | て7－H000978．${ }^{\text {\％}}$ | モて－－4009669．も | ヶ\％－g0tcot9 I | 86－H0008Lİも | 00＋ 0 000000 0 | gaonvs |  |
| 96－马8Ltcer＇L | 96－G02L788：9 | 00＋马000000＊0 | 00＋G000000 0 | $00+$ H00000000 | $00+$ H000000 0 | хrшыялея示 |  |
| g\％－gtclulitit | 9て－gで18006． | 00＋H0000000＊ 0 | $00+$ H0000000 0 | 00＋示0000000 0 | 00＋ $70000000 \cdot 0$ | HGON－STN |  |
| 70－H000098： | 00＋G00902 ${ }^{\text {² }}{ }^{\text {－}}$ | 00＋ $700209 Z^{\prime} \mathrm{Z}^{-}$ | ¢0－G00000\％¢ | 80＋G000LLて $\mathrm{Z}^{-}$ | 00＋H00LLL ${ }^{\text {\％}} 7^{-}$ | ¢G－¢ONYV－LHDษ |  |
| 80－H008Lticg | 00＋ $8888797^{\circ} 7^{-}$ |  | 80－g008L97＇z | 00＋ 6 60972\％ $7^{-}$ | 00＋HL6tLLZ $7^{-}$ | Vn－owvs |  |
| L0－H002966 ${ }^{\text {L }}$ | 00＋ $7006707^{\prime} \%^{-}$ | 00＋ $0006087^{-} \%^{-}$ | 70－g009L97． | 00＋H009997\％ －$^{-}$ | 00＋H00LLLZ $7^{-}$ | OSdToº |  |
| し0－H06モ6で6 | 00＋G0LI999\％ | 10－G0279¢\％ I－$^{-}$ | 00＋－7069889 ${ }^{\text {a }}$ | L0－H0¢68tで ${ }^{-}$ | 00＋H0gtget $7^{-}$ | गGV |  |
| ¢0－年6T9L29＊ | 00＋ $88 L$ LGLZ $\square^{-}$ |  | L0－G27206［ ${ }^{\text {－}}$ |  |  | хешяの－ษФ | $80^{\circ}$ |
|  |  |  | 70－G6LL688＇ 7 |  |  | $\stackrel{8}{\text { ® }}$ ¢ ${ }^{\text { }}$ |  |
| ¢0－H000902＇\％ |  |  | ¢0－GLabmit |  | 00＋H60LLLZ ${ }^{\text {－}}$ | gaonvs |  |
| 80－Дもてた0¢T＇8 | 00＋ $997992 z^{\prime} \%^{-}$ |  | 70－H27L688：8 | 00＋${ }^{\text {a }} 99886 \mathrm{~L}^{\prime} \mathrm{Z}^{-}$ |  |  |  |
| 70－H89しゃて98＊8 |  |  | 70－H6876L61．${ }^{\text {－}}$ | 00＋方を\＆L\＆6Lでで | 00＋示6L69c\＆\％\％－ | GGON－STN |  |
| 70－40000tc z | 10－g007668 L－ | L0－G00908］ $8^{-}$ | ¢0－¢00000才＇I | 00＋G00002才 L－ | 10－g000¢Lt＇ $\mathrm{L}^{-}$ |  |  |
| ¢0－H076Lさでし | L0－4667cil ${ }^{-8}$ | L0－HEL8LIZ $8-$ | ¢0－G89942E I | L0－H0¢z02F゙ $\mathrm{L}^{\text {－}}$ | 10－H860\＆Lt ${ }^{\text {－}}$ | VĐ－ONVS |  |
| 70－G00z¢z0 c | 10－G0086st $\mathrm{L}^{\text {－}}$ | 10－G008890 $8^{-}$ | 70－G008784． | 10－g008988 L－ | 10－g00telti ${ }^{\text {－}}$ | OSdTD－o |  |
| 70－H068928＇も | 10－H0¢¢¢08 L－ | L0－G0¢9791－8－ | 70－g08L689\％ | 10－H0Lcz9T ${ }^{-}$ | 10－G0TLZLF゙ ${ }^{\text {－}}$ | गgvə |  |
| 80－H80L917\％ | 10－G6789¢t＇8－ | L0－g¢\％88Iで8－ | ¢0－GL88799\％ | 10－g866897＇${ }^{-}$ | 10－gtotela＇${ }^{\text {－}}$ | xeuga－ษの | $10^{3}$ |
| モ0－H\＆68¢01． | 10－H289807 $8^{-}$ | L0－G9978LZ $8^{-}$ | ¢0－G698698＇ | 10－Hi0clati ${ }^{\text {－}}$ | 10－gtoteli ${ }^{\text {－}}$ | $\stackrel{8}{8} \mathrm{H}^{\text { }}$ |  |
| 80－H000992＇も | L0－gtL9ett $8^{-}$ | 10－H8¢885\％ $8^{-}$ | ¢0－G889098． |  | 10－gtotela ${ }^{\text {－}}$ | gGONVS |  |
| 80－4969tciz | 10－g2z9cer ${ }^{-8}$ | 10－G\＆゙ャ81で8－ | 80－GL88z99\％ | 10－ge66897＊ －$^{\text {－}}$ |  |  |  |
| モ0－¢0299668．¢ | L0－乌ャて908Lで8－ | 10－4¢¢ャ88Lで8－ | ¢L－H008てもLでも | L0－G980t8L才 $\mathrm{L}^{-}$ | L0－G98018L7 $\mathrm{L}^{-}$ | HGON－STN |  |
| P7S | แセวл | ${ }^{\text {7Sag }}$ | P7S | แеวЈ | $7^{75} \mathrm{~g}$ g | ${ }^{8}{ }^{\text {I }} \mathrm{T}$ | шәто．л |
|  | đ0¢ |  |  | đ0I |  |  |  |


Table B．19：Function values obtained by MLS－MODE，DEbavDBmax ，SAMODE，DE－DBmax，SAMO－DE，eABC，Co－CLPSO，
Table B.20: Function values obtained by MLS-MODE, DEbavDBmax , SAMODE, DE-DBmax, SAMO-DE, eABC, Co-CLPSO,
SAMO-GA, $\epsilon \mathrm{DEg}$, and ECHT-ARMOR-DE for CEC2010 for c04-c06

|  |  | 10D |  |  | 30D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| problem | Alg. | Best | Mean | Std. | Best | Mean | Std. |
| c04 | MLS-MODE | -1.0000000E-05 | -1.0000000E-05 | $0.0000000 \mathrm{E}+00$ | -3.3333333E-06 | -3.3333333E-06 | 1.1749496E-15 |
|  | DEbavDBmax | -1.000000E-05 | -1.000000E-05 | $0.000000 \mathrm{E}+00$ | -3.332962E-06 | -3.330868E-06 | $2.772148 \mathrm{E}-09$ |
|  | SAMODE | -1.000000E-05 | -1.000000E-05 | $1.446083 \mathrm{E}-11$ | -3.248000E-06 | -2.411300E-06 | $4.492340 \mathrm{E}-07$ |
|  | $\epsilon \mathrm{DEg}$ | -9.992345E-06 | -9.918452E-06 | $1.546730 \mathrm{E}-07$ | $4.698111 \mathrm{E}-03$ | 8.162973E-03 | $3.067785 \mathrm{E}-03$ |
|  | DE-DBmax | -1.000000E-05 | -1.000000E-05 | $0.000000 \mathrm{E}+00$ | -3.333311E-06 | -3.331620E-06 | $1.710576 \mathrm{E}-09$ |
|  | eABC |  |  |  |  |  |  |
|  | Co-CLPSO | -1.000000E-05 | -9.338500E-06 | $1.074800 \mathrm{E}-06$ | -2.930000E-06 | $1.126900 \mathrm{E}-01$ | $5.633500 \mathrm{E}-01$ |
|  | SAMO-GA | -1.000000E-05 | -9.934308E-06 | $5.118391 \mathrm{E}-08$ | -2.644300E-06 | $1.470915 \mathrm{E}-03$ | $7.359431 \mathrm{E}-03$ |
|  | ECHT-ARMOR-DE | -1.000000E-05 | -1.000000E-05 | $0.000000 \mathrm{E}+00$ | -3.332600E-06 | $8.371300 \mathrm{E}-02$ | $2.890000 \mathrm{E}-01$ |
| c05 | MLS-MODE | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ | 3.4809343E-13 | -4.8361062E+02 | $-4.8361062 \mathrm{E}+02$ | 1.2749496E-14 |
|  | DEbavDBmax | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $4.948079 \mathrm{E}-06$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $7.160225 \mathrm{E}-09$ |
|  | SAMODE | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $4.144280 \mathrm{E}-06$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $5.389910 \mathrm{E}-06$ |
|  | $\epsilon \mathrm{DEg}$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $3.890350 \mathrm{E}-13$ | $-4.531307 \mathrm{E}+02$ | $-4.495460 \mathrm{E}+02$ | $2.899105 \mathrm{E}+00$ |
|  | DE-DBmax | $-4.836106 \mathrm{E}+02$ | $-4.835891 \mathrm{E}+02$ | $3.316223 \mathrm{E}-02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $3.598556 \mathrm{E}-08$ |
|  | eABC | $4.659550 \mathrm{E}+01$ | $3.652470 \mathrm{E}+02$ | $1.172050 \mathrm{E}+02$ | $1.463110 \mathrm{E}+02$ | $3.718920 \mathrm{E}+02$ | $7.888540 \mathrm{E}+01$ |
|  | Co-CLPSO | $-4.836100 \mathrm{E}+02$ | $-4.836000 \mathrm{E}+02$ | $1.957700 \mathrm{E}-02$ | $-4.836000 \mathrm{E}+02$ | $-3.124900 \mathrm{E}+02$ | $8.833200 \mathrm{E}+01$ |
|  | SAMO-GA | $-4.836106 \mathrm{E}+02$ | $-4.016976 \mathrm{E}+02$ | $1.112600 \mathrm{E}+02$ | $-4.784754 \mathrm{E}+02$ | $-4.716434 \mathrm{E}+02$ | $3.783287 \mathrm{E}+00$ |
|  | ECHT-ARMOR-DE | $-4.836100 \mathrm{E}+02$ | $-4.836100 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ | $-4.812200 \mathrm{E}+02$ | $-4.333500 \mathrm{E}+02$ | $1.460000 \mathrm{E}+02$ |
| c06 | MLS-MODE | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ | 4.2790171E-13 | $-5.3063786 \mathrm{E}+02$ | $-5.3026981 \mathrm{E}+02$ | $5.9692277 \mathrm{E}-01$ |
|  | DEbavDBmax | $-5.755047 \mathrm{E}+02$ | $-5.755047 \mathrm{E}+02$ | 7.677759E-07 | $-5.306379 \mathrm{E}+02$ | $-5.305663 \mathrm{E}+02$ | $2.346488 \mathrm{E}-01$ |
|  | SAMODE | $-5.786624 \mathrm{E}+02$ | $-5.786562 \mathrm{E}+02$ | $9.352190 \mathrm{E}-03$ | $-5.306368 \mathrm{E}+02$ | $-5.306155 \mathrm{E}+02$ | $1.288050 \mathrm{E}-02$ |
|  | $\epsilon \mathrm{DEgg}$ | $-5.786581 \mathrm{E}+02$ | $-5.786528 \mathrm{E}+02$ | $3.627169 \mathrm{E}-03$ | $-5.285750 \mathrm{E}+02$ | $-5.279068 \mathrm{E}+02$ | $4.748378 \mathrm{E}-01$ |
|  | DE-DBmax | $-5.755047 \mathrm{E}+02$ | $-5.755047 \mathrm{E}+02$ | $3.512664 \mathrm{E}-05$ | $-5.306379 \mathrm{E}+02$ | $-5.306316 \mathrm{E}+02$ | $1.817352 \mathrm{E}-02$ |
|  | eABC | $2.384680 \mathrm{E}+02$ | $4.381680 \mathrm{E}+02$ | $8.595360 \mathrm{E}+01$ | $3.259620 \mathrm{E}+02$ | $4.738410 \mathrm{E}+02$ | $6.302590 \mathrm{E}+01$ |
|  | Co-CLPSO | $-5.786600 \mathrm{E}+02$ | $-5.786600 \mathrm{E}+02$ | $5.728900 \mathrm{E}-04$ | $-2.860100 \mathrm{E}+02$ | $-2.447000 \mathrm{E}+02$ | $3.948100 \mathrm{E}+01$ |
|  | SAMO-GA | $-5.786619 \mathrm{E}+02$ | $-5.777351 \mathrm{E}+02$ | $3.260495 \mathrm{E}+00$ | $-5.249595 \mathrm{E}+02$ | $-5.208121 \mathrm{E}+02$ | $3.169611 \mathrm{E}+00$ |
|  | ECHT-ARMOR-DE | $-5.786600 \mathrm{E}+02$ | $-5.786600 \mathrm{E}+02$ | $4.000000 \mathrm{E}-13$ | $-5.246500 \mathrm{E}+02$ | $-4.893100 \mathrm{E}+02$ | $1.320000 \mathrm{E}+02$ |

$4.2790171 \mathrm{E}-13 \quad-5.3063786 \mathrm{E}+02 \quad-5.3026981 \mathrm{E}+02 \quad 5.9692277 \mathrm{E}-01$ $7.677759 \mathrm{E}-07 \quad-5.306379 \mathrm{E}+02 \quad-5.305663 \mathrm{E}+02 \quad 2.346488 \mathrm{E}-01$

 $3.948100 \mathrm{E}+01$

 $-2.447000 \mathrm{E}+02$
 $9.352190 \mathrm{E}-03-5.306368 \mathrm{E}+02$ $3.627169 \mathrm{E}-03 \quad-5.285750 \mathrm{E}+02$ $3.512664 \mathrm{E}-05 \quad-5.306379 \mathrm{E}+02$ $3.259620 \mathrm{E}+02$

 20+G00997で $\mathrm{g}^{-}$

| L0＋G0000t\＆ 6 | 00＋G000LL9＊ | 00＋ $3000000^{\circ}$ | 10－H000008＊ | L0－H00¢c92 ${ }^{\text {I }}$ | 00＋${ }^{2} 0000000^{\circ}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| もて－H0L992L．9 | もて－4098769 | 86－406298\％＇8 | ¢б－马00z869 ¢ | 87－H002879 \％ | 9z－̧00¢も¢9\％8 | VM－ONVS |  |
| 80＋G0060St ${ }^{\text {\％}}$ | 80＋H007787 ${ }^{\text {I }}$ | 70＋H009696．${ }^{\text {I }}$ | 0L＋H008896 6 | 0I＋G008866 ${ }^{\text {I }}$ | 9I－H00tGSLE | OSdTDº |  |
|  |  | 2I＋H0tLEL9 ${ }^{\text {a }}$ | 2I＋G0¢80L8．${ }^{\text {I }}$ | 2I＋H0t\＆650\％ |  | गgvə |  |
|  | 97－g88stLl＇t | 00＋G000000＊0 | ¢\％－H098t99 ${ }^{\text {L }}$ |  | 00＋ $70000000^{\circ}$ |  | $60^{\circ}$ |
|  | L0＋G0才LZLO | 9L－H9990LL＇z | 00＋G000000＇0 | 00＋H00000000 | 00＋G00000000 | $\stackrel{8}{8} \mathrm{Ha}^{\text { }}$ |  |
| 10＋G669zet． | 00＋GL996L0＇9 | 07－H0LI98［＇I |  | 00＋ $\mathrm{HzS} 2680^{\circ} \mathrm{G}$ | 00＋ | faonvs |  |
| 97－398LtLも゙も | 97－4967て0¢\％ | 00＋H000000．0 | ¢\％－－468¢688． |  | 00＋ | xrugdлeqga |  |
| もて－G86669LI＇I | 9\％－HzLLLses ${ }^{\text {c }}$ | 00＋H0000000 0 | 00＋H0000000＊0 | 00＋H0000000 0 | 00＋H0000000＊ | HGON－STW |  |
| L0＋H000002＇币 | L0＋G00L0L0 ${ }^{\text {\％}}$ | 00＋H000000＊0 | 00＋ $70000000^{\circ} \mathrm{C}$ | 00＋H00z9z¢ 2 | 00＋ $70000000^{\circ}$ | Яब－ฯONYV－LНОЭ |  |
| モて－H02992L．9 | モて－G098も $69^{\circ} \mathrm{L}$ | 87－H06L98\％¢ | ¢7－H00z¢69 ¢ | ¢7－H0028t9 \％ |  | VM－ONVS |  |
| 70＋G00698I＇I | L0＋G002LSL゙も | も゙－H00才ILE＇t | 00＋G00g97t ${ }^{\text {L }}$ | ［0－G009 $280 \cdot 9$ | 0I－H00をたt9 6 | OSdTDº |  |
| L0＋G0L28t［＇L | 70＋G096L09．L | て0－H0¢t009－ | 70＋G0¢09¢8＊ 6 | 70＋G068L0T＇も | L0－G097028 \％ | गяvə |  |
| 9\％－3687981＇I | 97－G¢isc97：8 | 87－49768t9 ${ }^{\text {² }}$ |  | L0＋HE969t0 ${ }^{\text {－}}$ | ¢7－4L97886． | хъшяの－яФ | $80^{\circ}$ |
| 㕵－HLLIgset | モt－gャ9もt\＆8．2 | モt－He698t9\％ |  | 00＋H8zGLZL． 9 | 00＋ $70000000^{\circ}$ | $\stackrel{8}{8} \mathrm{Ha}^{\text { }}$ |  |
| 60－H00¢¢L¢＇z | 60－G0¢6\％¢0 ${ }^{\text {I }}$ | して－H0I89で・9 |  | 9\％－马0600zs \％ | 00＋ H00000000 $^{\circ}$ | gaONvs |  |
| 97－3LZLLI6＊$\ddagger$ | 97－9678002＇も | 9\％－H0ILZI0＇ | 00＋ $8878969^{\circ} \mathrm{E}$ | 00＋HzL89LZ 6 | 00＋ $70000000^{\circ}$ | хешяのлеяэФ |  |
| L2－96L88808．8 | LZ－H068L6LE： | 00＋H0000000＊0 | 00＋号git66¢ヶ． | 00＋HLZ8788．${ }^{\circ}$ | 00＋H0000000＊ 0 | GGON－STN |  |
| ¢\％－G00000\％＇\％ | ¢6－G0068L0＇ | 00＋H000000＊0 | 00＋马2000000＊ 0 | 00＋H000000＊0 | 00＋ $70000000^{\circ}$ |  |  |
|  | 87－H00898\％¢ | 87－H00898\％\％ | \％\％－H00L807． | ¢7－H009998． | 00＋ $70000000^{\circ}$ | Vn－ONVS |  |
| 00＋G006978 ${ }^{\text {I }}$ | 00＋G0089II ${ }^{\text {a }}$ | LI－H00t98 ${ }^{\text {c \％}}$ | 00＋G00gLz9 ${ }^{\text {－}}$ | L0－G00zel6 ${ }^{\text {L }}$ | 60－H00LILO ${ }^{\text {a }}$ | OSdTD－o |  |
| 70＋马087890 7 | 70＋G006788： | L0－H0ももT92． | L0＋G0¢LL6T ${ }^{\text {c }}$ | L0＋G0才609T 2 | 80－G0897た0＇I | गGV |  |
| 00＋ $997880{ }^{\text {c }}$－ | L0－4667681 ${ }^{\circ}$ | 00＋ H0000000＊$^{\circ}$ | 8\％－H0Lctzz\％ | 8\％－998809\％＇I | 00＋ | xruga－ga | $20^{\circ}$ |
| ¢L－G0¢tecz |  | 9t－gzitletis | 00＋年000000＊0 | 00＋H000000＊0 | 00＋ $70000000^{\circ}$ | 84 ${ }^{\text {¢ }}$ |  |
| EL－H0モ0879＇¢ | ¢L－H06L782＇L |  | ఒ7－－4008088．8 | ¢\％－H0g $2792: 2$ | 00＋G000000＇0 | gaonvs |  |
|  | L0－g0c9769．L | 00＋H000000＊0 | 87－H0L9tzz＇z | 87－998809\％＇1 | 00＋ $70000000^{\circ}$ |  |  |
|  | L6－49cccoso e | 00＋H0000000 0 | 00＋直0000000＊0 | 00＋H0000000＊ | 00＋H0000000＊0 | HaON－STL |  |


Table B.22: Function values obtained by MLS-MODE, DEbavDBmax, SAMODE, DE-DBmax, SAMO-DE, eABC, Co-CLPSO, SAMO-GA, $\epsilon$ DEg, and ECHT-ARMOR-DE for CEC2010 for c010-c12

|  |  | 10D |  |  | 30D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| problem | Alg. | Best | Mean | Std. | Best | Mean | Std. |
| c10 | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $2.9614474 \mathrm{E}-27$ | $9.6411285 \mathrm{E}-27$ |
|  | DEbavDBmax | $0.000000 \mathrm{E}+00$ | $1.333516 \mathrm{E}-26$ | $3.338908 \mathrm{E}-26$ | $1.506488 \mathrm{E}-26$ | $4.412282 \mathrm{E}-20$ | $1.211799 \mathrm{E}-19$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $4.467656 \mathrm{E}-01$ | $1.546298 \mathrm{E}+00$ | $9.769000 \mathrm{E}-21$ | $1.960780 \mathrm{E}+01$ | $2.123749 \mathrm{E}+01$ |
|  | $\epsilon \mathrm{DEg}$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $3.252002 \mathrm{E}+01$ | $3.326175 \mathrm{E}+01$ | $4.545577 \mathrm{E}-01$ |
|  | DE-DBmax | $0.000000 \mathrm{E}+00$ | $2.165980 \mathrm{E}-24$ | $1.081388 \mathrm{E}-23$ | $1.370196 \mathrm{E}-25$ | $1.540962 \mathrm{E}-19$ | $2.992547 \mathrm{E}-19$ |
|  | eABC | $4.493580 \mathrm{E}+09$ | $1.746200 \mathrm{E}+12$ | $2.583000 \mathrm{E}+12$ | $9.358200 \mathrm{E}+11$ | $1.498640 \mathrm{E}+13$ | $9.773360 \mathrm{E}+12$ |
|  | Co-CLPSO | $2.396700 \mathrm{E}-15$ | $4.974300 \mathrm{E}+10$ | $2.487100 \mathrm{E}+11$ | $3.196700 \mathrm{E}+01$ | $1.395100 \mathrm{E}+09$ | $5.843800 \mathrm{E}+09$ |
|  | SAMO-GA | $1.124000 \mathrm{E}-19$ | $1.732124 \mathrm{E}+02$ | $2.636938 \mathrm{E}+02$ | $4.164404 \mathrm{E}+01$ | $6.031654 \mathrm{E}+03$ | $7.177385 \mathrm{E}+03$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $6.020900 \mathrm{E}-13$ | $6.553600 \mathrm{E}+01$ | $1.070000 \mathrm{E}+02$ |
| c11 | MLS-MODE | -1.5227132E-03 | -1.5227132E-03 | 6.3511486E-18 | -3.9234392E-04 | -3.9234367E-04 | $2.0125659 \mathrm{E}-10$ |
|  | DEbavDBmax | -1.522713E-03 | -1.522713E-03 | $1.461597 \mathrm{E}-14$ | -3.923439E-04 | -3.923436E-04 | $3.984682 \mathrm{E}-10$ |
|  | SAMODE | -1.522710E-03 | -1.522710E-03 | $3.667610 \mathrm{E}-09$ | -3.923000E-04 | -3.869000E-04 | $6.149660 \mathrm{E}-06$ |
|  | $\epsilon \mathrm{DEg}$ | -1.522710E-03 | -1.522710E-03 | $6.341035 \mathrm{E}-11$ | -3.268462E-04 | -2.863882E-04 | $2.707605 \mathrm{E}-05$ |
|  | DE-DBmax | -1.522713E-03 | -1.522713E-03 | $6.880150 \mathrm{E}-16$ | $-3.923439 \mathrm{E}-04$ | $1.895262 \mathrm{E}-03$ | $6.322610 \mathrm{E}-03$ |
|  | eABC |  |  |  |  |  |  |
|  | Co-CLPSO | - | - | - | - | - | - |
|  | SAMO-GA | -6.205000E-04 | -5.262000E-04 | $4.904300 \mathrm{E}-05$ | -1.360000E-04 | -1.260000E-04 | $4.887000 \mathrm{E}-06$ |
|  | ECHT-ARMOR-DE | -1.522700E-03 | - | $4.400000 \mathrm{E}-02$ | -3.923400E-04 | - | $5.280000 \mathrm{E}-03$ |
| c12 | MLS-MODE | -1.1602762E+02 | $-1.6819684 \mathrm{E}+01$ | $3.7509007 \mathrm{E}+01$ | -1.9926346E-01 | -1.9926346E-01 | $5.0128642 \mathrm{E}-09$ |
|  | DEbavDBmax | -2.202514E-01 | -2.202502E-01 | $6.620404 \mathrm{E}-07$ | -1.992635E-01 | -1.992635E-01 | $1.630986 \mathrm{E}-09$ |
|  | SAMODE | $-5.700899 \mathrm{E}+02$ | $-1.166134 \mathrm{E}+02$ | $1.830005 \mathrm{E}+02$ | -1.992598E-01 | -1.992573E-01 | $1.321890 \mathrm{E}-06$ |
|  | $\epsilon \mathrm{DEg}$ | $-5.700899 \mathrm{E}+02$ | $-3.367349 \mathrm{E}+02$ | $1.782166 \mathrm{E}+02$ | -1.991453E-01 | - | $2.889253 \mathrm{E}+02$ |
|  | DE-DBmax | -2.202509E-01 | -2.202483E-01 | $2.733060 \mathrm{E}-06$ | -1.992635E-01 | -1.992635E-01 | $1.401959 \mathrm{E}-09$ |
|  | eABC | $-5.700360 \mathrm{E}+02$ | $-1.800890 \mathrm{E}+02$ | $2.757580 \mathrm{E}+02$ | $-8.826380 \mathrm{E}+02$ | - | - |
|  | Co-CLPSO | $-1.263900 \mathrm{E}+01$ | $-2.336900 \mathrm{E}+00$ | $2.432900 \mathrm{E}+01$ | -1.992600E-01 | -1.991100E-01 | $1.184000 \mathrm{E}-04$ |
|  | SAMO-GA | $-5.697441 \mathrm{E}+02$ | -5.588351E+01 | $1.351800 \mathrm{E}+02$ | -8.535971E+01 | $-3.493162 \mathrm{E}+00$ | $1.705561 \mathrm{E}+01$ |
|  | ECHT-ARMOR-DE | -1.992500E-01 | -1.992500E-01 | $1.600000 \mathrm{E}-13$ | -1.992600E-01 | -1.607600E-01 | $1.930000 \mathrm{E}-01$ |


| 60＋H000002＇L | 80＋G009TET＇E | モ0－H009LLİ「 | 00＋G000009 ${ }^{\text {I }}$ | 00＋G7009才78＇z | 00＋G000000＊0 | ษG－чONY－LHOE |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | L0－H00モt88：8 |  | z0＋ 7009 gtas 8 | 07－－3000gz8\％ | v＠－ONVS |  |
| L0＋H0069LI 6 |  | 2L－300667L ${ }^{\text {c }}$ | 00＋G002tte\％ | $00+$ H009886 \％ | 2L－H006970 ¢ | OSdT0－o |  |
| ¢L＋G0¢LOtt＇¢ | ¢L＋G0¢L98L ¢ | 2I＋G0tIL88． |  | 8L＋H092999\％ | 60＋年0LL9Iz＇t | गGvə |  |
| 07－Hz78999 9 |  |  | 乙て－gzecoct 8 |  | Lz－ד980009 \％ | xъuga－ga | $\mathrm{g}^{\text {L }}$ |
|  | L0＋G92809］＇z | L0＋G9tE09I＇$\%$ | L0－G9¢LEL8 8 | L0－H086862＇I | $00+$ H00000000 | ${ }^{\circ} \mathrm{HG}^{\text { }}$ |  |
| 00＋G0290tc＇t | 00＋G0L88LI＇z | $8 \mathrm{~L}-\mathrm{H007て78} \mathrm{C}$ | ¢0－Gg8elti $冖$ | モ0－H008¢G0\％ | $00+$ H000000＇0 | GGONVS |  |
| 77－马269896．${ }^{\text {\％}}$ |  | $97-$－五97970 ${ }^{\text {c }}$ |  | 9\％－且2て¢896\％ | $00+$ H000000 0 | хвияฮлеяаФ |  |
| L7－989288LI＇L |  | 00＋H0000000＊0 | 87－过69才ぁ¢0－8 | 67－26886801．9 | 00＋H0000000．0 | HGOw－stu |  |
| ¢0＋H00002才＇$冖$ | 70＋H0098［999 | L8－H006089．L | 00＋G7000000 0 | $00+$ H000000 0 | 00＋ $70000000^{\circ}$ | Яは－чONYV－LHO甘 |  |
|  |  | 00＋G\＆もたSti＇t | $80+$ gristuz＇I | 70＋G7897288\％ | 7\％－4000928 ${ }^{\text {I }}$ | VM－ONVS |  |
| L0－H0998L0 \％ | て0－H0z币z¢ 9 | 60－H0才¢8878 | 00＋G008800＇I | L0－H00¢685＇8 | 2T－G00008L＇ | OSdTo－o |  |
| モ0＋G0909L6 ${ }^{\text {I }}$ | 80＋G06LLI6 6 | L0－H0I6も¢ ${ }^{\text {c／8 }}$ | LI＋G080998＇z |  | モ0－G0zcttre | गgvə |  |
|  | L0－G667685 ${ }^{\text {¢ }}$ | LZ－9tcgites： | L7－H068697＇¢ | LZ－3LI9868． | $00+$ H000000 0 | xruga－яの | ¢1 ${ }^{\text {T }}$ |
| EL－G607809 G | 81－H207680\％ | モL－HE98gioc | 00＋G0000000 0 | 00＋年000000 0 | $00+$ H0000000 0 | 옥ํ ${ }^{\circ}$ |  |
|  |  |  | น7－g87698\％$\%$ | L\％－408¢907． | $00+$ H00000000 | faonvs |  |
| 97－H0987908 | 96－H289010＇I | 00＋G000000\％ | L\％－GLZ68L2＇も | Lz－49L8808． | $00+$ H0000000 0 |  |  |
| Lて－96292097\％ | LZ－gelit 880 ¢ | 00＋H0000000＊ 0 | 00＋ $70000000 \cdot 0$ | 00＋H0000000＊ 0 | 00＋H0000000＊0 | HGON－STN |  |
| 00＋H000026．${ }^{\text {I }}$ | 10＋ $0009 币 9 \pm 9^{-}$ |  | $00+$ H000000 ${ }^{\text {¢ }}$ |  |  | ษの－ฯONYV－LНО太 |  |
| 00＋鸟LL0988＇ |  | L0＋H8\＆L $2899^{-}$ | L0－G0¢G899． | L0＋ $88992889^{-}$ | 10＋Д8087\％ $8^{\circ} 9^{-}$ | VĐ－ONVS |  |
| 00＋H0092ll＇L | L0＋ $000 \pm$ ¢ $209^{-}$ |  | 00＋G080才¢！$\%$ |  |  | OSdTD ${ }^{\text {－o }}$ |  |
| 00＋G0¢Lz88＊ | I0＋G06998才 $9^{-}$ | L0＋ 0 0L89 $L^{\circ} 9^{-}$ | 00＋G002z09＇z |  | 10＋鳥068778 $9^{-}$ | गgvə |  |
| 00＋hizetaza |  | L0＋Hetcgle $9^{-}$ |  | 10＋HeLecs ${ }^{\circ} 9^{-}$ |  | xruga－яの | ¢L ${ }^{\text {d }}$ |
| L0－Gc00eses |  | 10＋马8Lもで9 $9^{-}$ | 90－G0969z0 ${ }^{\text {I }}$ | 10＋ 9 9867ヶ\％${ }^{\circ} 9^{-}$ | 10＋ 2 L\＆67\％ $8^{\circ} 9^{-}$ | $\stackrel{\text { ² }}{\text { Ha }}$ |  |
|  | L0＋ $282 \mathrm{~L} 618{ }^{\circ} 9^{-}$ | 10＋ 00767 ¢ $8^{\circ} 9^{-}$ | L0－GLL887c ${ }^{\text {a }}$ | 10＋ 2 L\＆67ヶ7 ${ }^{\circ} 9^{-}$ |  | gaonvs |  |
| 00＋G068990 $0^{\text {c }}$ | 10＋ $06908109^{-}$ | 10＋\＃¢Lze8 ${ }^{\circ} 9^{-}$ | 00＋G08LもLで， |  |  |  |  |
|  |  |  | 80－H2699788：8 |  | L0＋ $289867 \pm 89^{-}$ | HGON－STN |  |


Table B.24: Function values obtained by MLS-MODE, DEbavDBmax , SAMODE, DE-DBmax, SAMO-DE, eABC, Co-CLPSO, SAMO-GA,$\epsilon$ DEg, and ECHT-ARMOR-DE for CEC2010 for c16-c18

|  |  | 10D |  |  | 30D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| problem | Alg. | Best | Mean | Std. | Best | Mean | Std. |
| c16 | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | DEbavDBmax | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $6.469600 \mathrm{E}-03$ | $1.087042 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ | $4.160700 \mathrm{E}-03$ | $7.677900 \mathrm{E}-03$ |
|  | $\epsilon \mathrm{DEg}$ | $0.000000 \mathrm{E}+00$ | $3.702054 \mathrm{E}-01$ | $3.710479 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $2.168404 \mathrm{E}-21$ | $1.062297 \mathrm{E}-20$ |
|  | DE-DBmax | $0.000000 \mathrm{E}+00$ | $1.332800 \mathrm{E}-01$ | $3.301736 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | eABC | $0.000000 \mathrm{E}+00$ | $8.347410 \mathrm{E}-02$ | $9.106390 \mathrm{E}-02$ | $6.252940 \mathrm{E}-02$ | $8.207220 \mathrm{E}-01$ | $2.569880 \mathrm{E}-01$ |
|  | Co-CLPSO | $0.000000 \mathrm{E}+00$ | $5.986100 \mathrm{E}-03$ | $1.331500 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ | $5.240300 \mathrm{E}-16$ | $4.672200 \mathrm{E}-16$ |
|  | SAMO-GA | $0.000000 \mathrm{E}+00$ | $1.403400 \mathrm{E}-03$ | $4.880000 \mathrm{E}-03$ | $0.000000 \mathrm{E}+00$ | $3.737000 \mathrm{E}-03$ | $6.284000 \mathrm{E}-03$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $2.847800 \mathrm{E}-02$ | $5.000000 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c17 | MLS-MODE | $3.3716223 \mathrm{E}-27$ | $4.4542095 \mathrm{E}-24$ | $1.1601496 \mathrm{E}-23$ | $3.3560550 \mathrm{E}-22$ | $2.3915346 \mathrm{E}-14$ | 1.1228612E-13 |
|  | DEbavDBmax | $1.346610 \mathrm{E}-29$ | $7.053446 \mathrm{E}-19$ | $1.079196 \mathrm{E}-18$ | $1.061228 \mathrm{E}-18$ | $1.811932 \mathrm{E}-12$ | $5.281940 \mathrm{E}-12$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $1.265501 \mathrm{E}-23$ | $3.217991 \mathrm{E}-23$ | $0.000000 \mathrm{E}+00$ | $1.022630 \mathrm{E}-10$ | $1.455150 \mathrm{E}-10$ |
|  | $\epsilon \mathrm{DEg}$ | $1.463180 \mathrm{E}-17$ | $1.249561 \mathrm{E}-01$ | $1.937197 \mathrm{E}-01$ | $2.165719 \mathrm{E}-01$ | $6.326487 \mathrm{E}+00$ | $4.986691 \mathrm{E}+00$ |
|  | DE-DBmax | $3.098066 \mathrm{E}-28$ | $1.154546 \mathrm{E}-05$ | $4.146688 \mathrm{E}-05$ | $7.114167 \mathrm{E}-20$ | $6.849019 \mathrm{E}-12$ | $1.639527 \mathrm{E}-11$ |
|  | eABC | $2.533850 \mathrm{E}-02$ | $3.242900 \mathrm{E}+00$ | $6.831360 \mathrm{E}+00$ | $3.267520 \mathrm{E}+00$ | $2.680100 \mathrm{E}+01$ | $1.634550 \mathrm{E}+01$ |
|  | Co-CLPSO | $7.667700 \mathrm{E}-17$ | $3.798600 \mathrm{E}-01$ | $4.528400 \mathrm{E}-01$ | $1.578700 \mathrm{E}-01$ | $1.391900 \mathrm{E}+00$ | $4.262100 \mathrm{E}+00$ |
|  | SAMO-GA | $0.000000 \mathrm{E}+00$ | $1.270700 \mathrm{E}-02$ | $1.331029 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ | $1.343600 \mathrm{E}-02$ | $1.616200 \mathrm{E}-02$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $3.697800 \mathrm{E}-33$ | $3.100000 \mathrm{E}-33$ | $3.356400 \mathrm{E}-16$ | $4.033600 \mathrm{E}-01$ | $3.510000 \mathrm{E}-01$ |
| c18 | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $3.2170734 \mathrm{E}-31$ | 4.1468535E-31 | 1.4791142E-31 | 8.9491903E-05 | $1.1722656 \mathrm{E}-04$ |
|  | DEbavDBmax | $4.239528 \mathrm{E}-25$ | $3.885478 \mathrm{E}-24$ | $4.336668 \mathrm{E}-24$ | $1.030097 \mathrm{E}-18$ | $2.829429 \mathrm{E}-01$ | $1.356367 \mathrm{E}+00$ |
|  | SAMODE | $2.236640 \mathrm{E}-15$ | $1.617890 \mathrm{E}-14$ | $3.820340 \mathrm{E}-14$ | $1.375370 \mathrm{E}-14$ | $4.738410 \mathrm{E}-14$ | $6.573500 \mathrm{E}-14$ |
|  | $\epsilon \mathrm{DEg}$ | $3.731440 \mathrm{E}-20$ | $9.678765 \mathrm{E}-19$ | $1.811234 \mathrm{E}-18$ | $1.226054 \mathrm{E}+00$ | $8.754569 \mathrm{E}+01$ | $1.664753 \mathrm{E}+02$ |
|  | DE-DBmax | $8.320589 \mathrm{E}-25$ | $5.257827 \mathrm{E}-24$ | $9.154472 \mathrm{E}-24$ | $1.631766 \mathrm{E}-17$ | $2.901024 \mathrm{E}-04$ | $9.250217 \mathrm{E}-04$ |
|  | eABC | $3.098470 \mathrm{E}-03$ | $3.470230 \mathrm{E}+02$ | $3.710760 \mathrm{E}+02$ | $1.960850 \mathrm{E}-01$ | $2.933360 \mathrm{E}+02$ | $3.528430 \mathrm{E}+02$ |
|  | Co-CLPSO | $7.780400 \mathrm{E}-21$ | $2.319200 \mathrm{E}-01$ | $9.955900 \mathrm{E}-01$ | $6.004700 \mathrm{E}-02$ | $1.087700 \mathrm{E}+01$ | $3.716100 \mathrm{E}+01$ |
|  | SAMO-GA | $4.359000 \mathrm{E}-17$ | $1.053095 \mathrm{E}-02$ | $1.540100 \mathrm{E}-02$ | $2.818290 \mathrm{E}-01$ | $7.535728 \mathrm{E}+00$ | $1.051703 \mathrm{E}+01$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |

Table B.25: Function values obtained by MLS-MODE, ADE , EPSDE, SAMODE, DE-Acr, CDELS and CDASA for CEC2011 for r01-r05

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r01 | MLS-MODE | $1.5444180 \mathrm{E}+04$ | $1.5444180 \mathrm{E}+04$ | $6.1846980 \mathrm{E}-07$ |
|  | ADE | $1.5445380 \mathrm{E}+04$ | $1.5482070 \mathrm{E}+04$ | $3.0473660 \mathrm{E}+01$ |
|  | EPSDE | $1.5400000 \mathrm{E}+04$ | $1.5500000 \mathrm{E}+04$ | $1.5500000 \mathrm{E}+01$ |
|  | SAMODE | $1.5444190 \mathrm{E}+04$ | $1.5444230 \mathrm{E}+04$ | $3.7333110 \mathrm{E}-02$ |
|  | DE-Acr | $1.5445000 \mathrm{E}+04$ | $1.5446000 \mathrm{E}+04$ | $8.4385000 \mathrm{E}-01$ |
|  | CDELS | $1.5446550 \mathrm{E}+04$ | $1.5446999 \mathrm{E}+04$ | $1.5449634 \mathrm{E}+04$ |
|  | CDASA | $1.5461000 \mathrm{E}+04$ | $1.5511000 \mathrm{E}+04$ | $4.2337000 \mathrm{E}+01$ |
| r02 | MLS-MODE | $1.8050910 \mathrm{E}+04$ | $1.8104920 \mathrm{E}+04$ | $3.7112340 \mathrm{E}+01$ |
|  | ADE | $1.8224720 \mathrm{E}+04$ | $1.8550260 \mathrm{E}+04$ | $1.4151470 \mathrm{E}+02$ |
|  | EPSDE | $1.8100000 \mathrm{E}+04$ | $1.8100000 \mathrm{E}+04$ | $4.3900000 \mathrm{E}+01$ |
|  | SAMODE | $1.8046840 \mathrm{E}+04$ | $1.8185590 \mathrm{E}+04$ | $1.0714080 \mathrm{E}+02$ |
|  | DE-Acr | $1.8028000 \mathrm{E}+04$ | $1.8096000 \mathrm{E}+04$ | $3.9913000 \mathrm{E}+01$ |
|  | CDELS | $1.9007720 \mathrm{E}+04$ | $1.9120010 \mathrm{E}+04$ | $1.9185830 \mathrm{E}+04$ |
|  | CDASA | $1.8942000 \mathrm{E}+04$ | $1.9323000 \mathrm{E}+04$ | $2.1267000 \mathrm{E}+02$ |
| r03 | MLS-MODE | $3.2797750 \mathrm{E}+04$ | $3.2890930 \mathrm{E}+04$ | $4.7772960 \mathrm{E}+01$ |
|  | ADE | $3.2744200 \mathrm{E}+04$ | $3.2859400 \mathrm{E}+04$ | $6.8413650 \mathrm{E}+01$ |
|  | EPSDE | $3.2600000 \mathrm{E}+04$ | $3.2700000 \mathrm{E}+04$ | $3.5900000 \mathrm{E}+01$ |
|  | SAMODE | $3.2721950 \mathrm{E}+04$ | $3.2737580 \mathrm{E}+04$ | $7.7779080 \mathrm{E}+00$ |
|  | DE-Acr | $3.2730000 \mathrm{E}+04$ | $3.2790000 \mathrm{E}+04$ | $3.0447000 \mathrm{E}+01$ |
|  | CDELS | $3.2928030 \mathrm{E}+04$ | $3.2958290 \mathrm{E}+04$ | $3.3031150 \mathrm{E}+04$ |
|  | CDASA | $3.2966000 \mathrm{E}+04$ | $3.3181000 \mathrm{E}+04$ | $1.0457000 \mathrm{E}+02$ |
| r04 | MLS-MODE | $1.2281680 \mathrm{E}+05$ | $1.2448750 \mathrm{E}+05$ | $7.2852280 \mathrm{E}+02$ |
|  | ADE | $1.2406900 \mathrm{E}+05$ | $1.2553230 \mathrm{E}+05$ | $8.3625570 \mathrm{E}+02$ |
|  | EPSDE | $1.2800000 \mathrm{E}+05$ | $1.3100000 \mathrm{E}+05$ | $2.4700000 \mathrm{E}+03$ |
|  | SAMODE | $1.2278753 \mathrm{E}+05$ | $1.2409967 \mathrm{E}+05$ | $8.0725815 \mathrm{E}+02$ |
|  | DE-Acr | $1.2313000 \mathrm{E}+05$ | $1.2389000 \mathrm{E}+05$ | $4.5430000 \mathrm{E}+02$ |
|  | CDELS | $1.3590694 \mathrm{E}+05$ | $1.3771068 \mathrm{E}+05$ | $1.4118462 \mathrm{E}+05$ |
|  | CDASA | $1.3242000 \mathrm{E}+05$ | $1.4666000 \mathrm{E}+05$ | $6.3435000 \mathrm{E}+03$ |
| r05 | MLS-MODE | $1.6769140 \mathrm{E}+06$ | $1.7812770 \mathrm{E}+06$ | $4.9848520 \mathrm{E}+04$ |
|  | ADE | $1.8906710 \mathrm{E}+06$ | $1.9250980 \mathrm{E}+06$ | $2.3429040 \mathrm{E}+04$ |
|  | EPSDE | $1.9100000 \mathrm{E}+06$ | $1.9200000 \mathrm{E}+06$ | $1.1800000 \mathrm{E}+04$ |
|  | SAMODE | $1.8891308 \mathrm{E}+06$ | $1.9876716 \mathrm{E}+06$ | $1.2556507 \mathrm{E}+05$ |
|  | DE-Acr | $1.7124000 \mathrm{E}+06$ | $1.8386000 \mathrm{E}+06$ | $4.5074000 \mathrm{E}+04$ |
|  | CDELS | $1.9209047 \mathrm{E}+06$ | $1.9464404 \mathrm{E}+06$ | $1.9573575 \mathrm{E}+06$ |
|  | CDASA | $1.8828000 \mathrm{E}+06$ | $2.0375000 \mathrm{E}+06$ | $2.4110000 \mathrm{E}+05$ |

Table B.26: Function values obtained by MLS-MODE, ADE , EPSDE, SAMODE, DE-Acr, CDELS and CDASA for CEC2011 for r06-r10

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r06 | MLS-MODE | $4.8705940 \mathrm{E}+04$ | $5.0643040 \mathrm{E}+04$ | $1.2705080 \mathrm{E}+03$ |
|  | ADE | $5.0170600 \mathrm{E}+04$ | $5.4181520 \mathrm{E}+04$ | $4.8669640 \mathrm{E}+03$ |
|  | EPSDE | $5.1100000 \mathrm{E}+04$ | $5.2200000 \mathrm{E}+04$ | $7.2400000 \mathrm{E}+02$ |
|  | SAMODE | $5.0981400 \mathrm{E}+04$ | $5.3278380 \mathrm{E}+04$ | $2.0317090 \mathrm{E}+03$ |
|  | DE-Acr | $4.4847000 \mathrm{E}+04$ | $4.6321000 \mathrm{E}+04$ | $1.3962000 \mathrm{E}+03$ |
|  | CDELS | $6.8146400 \mathrm{E}+04$ | $7.3806300 \mathrm{E}+04$ | $8.0638850 \mathrm{E}+04$ |
|  | CDASA | $5.1210000 \mathrm{E}+04$ | $5.2017000 \mathrm{E}+04$ | $3.9028000 \mathrm{E}+02$ |
| r07 | MLS-MODE | $1.0544620 \mathrm{E}+06$ | $1.0684960 \mathrm{E}+06$ | $4.9241360 \mathrm{E}+03$ |
|  | ADE | $1.0785260 \mathrm{E}+06$ | $1.0866840 \mathrm{E}+06$ | $4.4556550 \mathrm{E}+03$ |
|  | EPSDE | $1.0600000 \mathrm{E}+06$ | $1.0700000 \mathrm{E}+06$ | $2.1300000 \mathrm{E}+03$ |
|  | SAMODE | $1.0675010 \mathrm{E}+06$ | $1.0707990 \mathrm{E}+06$ | $1.2727460 \mathrm{E}+03$ |
|  | DE-Acr | $1.0354000 \mathrm{E}+06$ | $1.0490000 \mathrm{E}+06$ | $2.9044000 \mathrm{E}+05$ |
|  | CDELS | $2.4228390 \mathrm{E}+06$ | $2.4461757 \mathrm{E}+06$ | $2.5662654 \mathrm{E}+06$ |
|  | CDASA | $1.2683000 \mathrm{E}+06$ | $1.2717000 \mathrm{E}+06$ | $1.8724000 \mathrm{E}+03$ |
| r08 | MLS-MODE | $9.1578410 \mathrm{E}+05$ | $9.1618010 \mathrm{E}+05$ | $2.6227390 \mathrm{E}+02$ |
|  | ADE | $9.2482150 \mathrm{E}+05$ | $9.3060260 \mathrm{E}+05$ | $3.5027700 \mathrm{E}+03$ |
|  | EPSDE | $9.3900000 \mathrm{E}+05$ | $9.4300000 \mathrm{E}+05$ | $2.6300000 \mathrm{E}+03$ |
|  | SAMODE | $9.2435370 \mathrm{E}+05$ | $9.2580000 \mathrm{E}+05$ | $6.7159130 \mathrm{E}+02$ |
|  | DE-Acr | $9.2280000 \mathrm{E}+05$ | $9.2393000 \mathrm{E}+05$ | $7.4822000 \mathrm{E}+02$ |
|  | CDELS | $9.8301754 \mathrm{E}+05$ | $1.0188345 \mathrm{E}+06$ | $1.2755968 \mathrm{E}+06$ |
|  | CDASA | $9.4142000 \mathrm{E}+05$ | $9.4569000 \mathrm{E}+05$ | $3.6946000 \mathrm{E}+03$ |
| r09 | MLS-MODE | $9.1970990 \mathrm{E}+05$ | $9.2427600 \mathrm{E}+05$ | $1.6122740 \mathrm{E}+03$ |
|  | ADE | $9.2832270 \mathrm{E}+05$ | $9.9296430 \mathrm{E}+05$ | $1.9642450 \mathrm{E}+05$ |
|  | EPSDE | $9.4000000 \mathrm{E}+05$ | $9.9000000 \mathrm{E}+05$ | $4.1400000 \mathrm{E}+04$ |
|  | SAMODE | $9.2432330 \mathrm{E}+05$ | $9.2602220 \mathrm{E}+05$ | $7.2979820 \mathrm{E}+02$ |
|  | DE-Acr | $9.2717000 \mathrm{E}+05$ | $9.3001000 \mathrm{E}+05$ | $1.6287000 \mathrm{E}+03$ |
|  | CDELS | $1.4593034 \mathrm{E}+06$ | $1.5374957 \mathrm{E}+06$ | $1.8722742 \mathrm{E}+06$ |
|  | CDASA | $1.1044000 \mathrm{E}+06$ | $1.4012000 \mathrm{E}+06$ | $1.7944000 \mathrm{E}+05$ |
| r10 | MLS-MODE | $9.2689750 \mathrm{E}+05$ | $9.3485490 \mathrm{E}+05$ | $4.4514900 \mathrm{E}+03$ |
|  | ADE | $9.2714540 \mathrm{E}+05$ | $9.3052880 \mathrm{E}+05$ | $3.0638130 \mathrm{E}+03$ |
|  | EPSDE | $9.3900000 \mathrm{E}+05$ | $9.4300000 \mathrm{E}+05$ | $2.6300000 \mathrm{E}+03$ |
|  | SAMODE | $9.2437627 \mathrm{E}+05$ | $9.2584595 \mathrm{E}+05$ | 7.6154770E+02 |
|  | DE-Acr | $9.2303000 \mathrm{E}+05$ | $9.2382000 \mathrm{E}+05$ | $5.1463000 \mathrm{E}+02$ |
|  | CDELS | $1.0026198 \mathrm{E}+06$ | $1.0295312 \mathrm{E}+06$ | $1.2755968 \mathrm{E}+06$ |
|  | CDASA | $9.3967000 \mathrm{E}+05$ | $9.4887000 \mathrm{E}+05$ | $1.8056000 \mathrm{E}+04$ |

## Appendix C

Table C.1: Function values obtained by MJADE, MCoDE and MOXDE with and without R2S for CEC2006 and CEC2011

| P | Criteria | MJADE-R2S | MJADE | MCoDE-R2S | MCoDE | MOXDE-R2S | MOXDE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| g01 | best | -1.5000E+01 | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ |
|  | Average | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.4554 \mathrm{E}+01$ | $-1.4898 \mathrm{E}+01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.0000 \mathrm{E}-10$ | $8.8037 \mathrm{E}-01$ | $5.0938 \mathrm{E}-01$ |
| g02 | best | -8.0362E-01 | -8.0253E-01 | -8.0361E-01 | -7.9982E-01 | -8.0362E-01 | -8.0362E-01 |
|  | Average | -8.0358E-01 | -8.0072E-01 | -8.0228E-01 | -7.9335E-01 | -7.9649E-01 | -7.9682E-01 |
|  | St.d | $7.6037 \mathrm{E}-05$ | $9.3017 \mathrm{E}-04$ | $3.6465 \mathrm{E}-03$ | $3.4972 \mathrm{E}-03$ | $1.0332 \mathrm{E}-02$ | $8.5005 \mathrm{E}-03$ |
| g03 | best | $-1.0005 \mathrm{E}+00$ | -8.5371E-01 | $-1.0005 \mathrm{E}+00$ | -5.4855E-01 | $-1.0005 \mathrm{E}+00$ | -8.4378E-01 |
|  | Average | $-1.0005 \mathrm{E}+00$ | -7.2806E-01 | $-1.0004 \mathrm{E}+00$ | -2.3569E-01 | $-1.0005 \mathrm{E}+00$ | -6.6064E-01 |
|  | St.d | $0.0000 \mathrm{E}+00$ | $8.2835 \mathrm{E}-02$ | $6.5150 \mathrm{E}-04$ | $1.2422 \mathrm{E}-01$ | $0.0000 \mathrm{E}+00$ | $1.0773 \mathrm{E}-01$ |
| g04 | best | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ |
|  | Average | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $4.0000 \mathrm{E}-12$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g05 | best | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1384 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ |
|  | Average | $5.1265 \mathrm{E}+03$ | $5.1859 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.2228 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1614 \mathrm{E}+03$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $5.4893 \mathrm{E}+01$ | $7.4000 \mathrm{E}-09$ | $8.4883 \mathrm{E}+01$ | $0.0000 \mathrm{E}+00$ | $6.3668 \mathrm{E}+01$ |
| g06 | best | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ |
|  | Average | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g07 | best | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4307 \mathrm{E}+01$ | $2.4312 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ |
|  | Average | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4308 \mathrm{E}+01$ | $2.4315 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $4.0714 \mathrm{E}-04$ | $2.3077 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g08 | best | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 |
|  | Average | $-9.5830 \mathrm{E}-02$ | $-9.5825 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g09 | best | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ |
|  | Average | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $6.0000 \mathrm{E}-10$ | $2.8200 \mathrm{E}-08$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g10 | best | $7.0492 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ | $7.0502 \mathrm{E}+03$ | $7.0535 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ |
|  | Average | $7.0492 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ | $7.0510 \mathrm{E}+03$ | $7.0579 \mathrm{E}+03$ | $7.0506 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ |
|  | St.d | $1.0000 \mathrm{E}-10$ | $2.0000 \mathrm{E}-12$ | $3.8705 \mathrm{E}-01$ | $2.2982 \mathrm{E}+00$ | $6.9515 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g11 | best | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ |
|  | Average | $7.4990 \mathrm{E}-01$ | $7.4991 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.5234 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.5067 \mathrm{E}-01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $2.8035 \mathrm{E}-05$ | $0.0000 \mathrm{E}+00$ | $9.7174 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $2.8554 \mathrm{E}-03$ |
| g12 | best | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ |
|  | Average | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g13 | best | $5.3942 \mathrm{E}-02$ | $8.2929 \mathrm{E}-01$ | $5.3942 \mathrm{E}-02$ | $6.1239 \mathrm{E}-01$ | $5.3942 \mathrm{E}-02$ | $5.6604 \mathrm{E}-01$ |
|  | Average | $5.3940 \mathrm{E}-02$ | $9.6981 \mathrm{E}-01$ | $5.3940 \mathrm{E}-02$ | $1.0862 \mathrm{E}+00$ | $5.3940 \mathrm{E}-02$ | $8.7747 \mathrm{E}-01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $4.2789 \mathrm{E}-02$ | $1.7400 \mathrm{E}-08$ | $6.2340 \mathrm{E}-01$ | $0.0000 \mathrm{E}+00$ | $1.4934 \mathrm{E}-01$ |
| g14 | best | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7763 \mathrm{E}+01$ | $-4.7764 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ |
|  | Average | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7758 \mathrm{E}+01$ | $-4.7763 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $4.1054 \mathrm{E}-03$ | 8.5333E-04 | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g15 | best | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ |
|  | Average | $9.6172 \mathrm{E}+02$ | $9.6215 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6230 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6201 \mathrm{E}+02$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $7.3211 \mathrm{E}-01$ | $0.0000 \mathrm{E}+00$ | $7.5150 \mathrm{E}-01$ | $0.0000 \mathrm{E}+00$ | $7.0245 \mathrm{E}-01$ |
| g16 | best | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ |
|  | Average | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g17 | best | $8.8535 \mathrm{E}+03$ | $8.8561 \mathrm{E}+03$ | $8.8535 \mathrm{E}+03$ | $8.8786 \mathrm{E}+03$ | $8.8535 \mathrm{E}+03$ | $8.8605 \mathrm{E}+03$ |
|  | Average | $8.8565 \mathrm{E}+03$ | $8.9243 \mathrm{E}+03$ | $8.8556 \mathrm{E}+03$ | $8.9457 \mathrm{E}+03$ | $8.8565 \mathrm{E}+03$ | $8.9256 \mathrm{E}+03$ |
|  | St.d | $1.4812 \mathrm{E}+01$ | $2.9491 \mathrm{E}+01$ | $2.2013 \mathrm{E}+00$ | $2.3899 \mathrm{E}+01$ | $1.4812 \mathrm{E}+01$ | $2.3980 \mathrm{E}+01$ |
| g18 | best | -8.6603E-01 | -8.6603E-01 | -8.6589E-01 | -8.6386E-01 | -8.6603E-01 | -8.6603E-01 |
|  | Average | -8.3546E-01 | -8.5838E-01 | -8.6564E-01 | -8.6160E-01 | -8.2017E-01 | -8.6603E-01 |
|  | St.d | $7.1482 \mathrm{E}-02$ | $3.8209 \mathrm{E}-02$ | $1.7955 \mathrm{E}-04$ | $1.5537 \mathrm{E}-03$ | 8.3274E-02 | $0.0000 \mathrm{E}+00$ |
| g19 | best | $3.2656 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ | $3.2684 \mathrm{E}+01$ | $3.2951 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ |
|  | Average | $3.2656 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ | $3.2717 \mathrm{E}+01$ | $3.3045 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.4406 \mathrm{E}-02$ | $7.7338 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g21 | best | $1.9372 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ | $1.9381 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ |
|  | Average | $2.3040 \mathrm{E}+02$ | $2.3040 \mathrm{E}+02$ | $2.5060 \mathrm{E}+02$ | $4.1038 \mathrm{E}+02$ | $2.5076 \mathrm{E}+02$ | $2.5243 \mathrm{E}+02$ |
|  | St.d | $6.0021 \mathrm{E}+01$ | $6.0022 \mathrm{E}+01$ | $5.8583 \mathrm{E}+01$ | $2.7323 \mathrm{E}+02$ | $6.4214 \mathrm{E}+01$ | $6.2981 \mathrm{E}+01$ |


| g23 | best | $-4.0006 \mathrm{E}+02$ | $-4.0006 \mathrm{E}+02$ | $-3.8573 \mathrm{E}+02$ | $-2.2555 \mathrm{E}+02$ | $-4.0006 \mathrm{E}+02$ | $-4.0006 \mathrm{E}+02$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Average | $-4.0006 \mathrm{E}+02$ | $-3.9741 \mathrm{E}+02$ | $-3.5557 \mathrm{E}+02$ | $-1.5979 \mathrm{E}+01$ | $-3.8805 \mathrm{E}+02$ | $-3.9936 \mathrm{E}+02$ |
|  | St.d | $6.0000 \mathrm{E}-10$ | $4.2920 \mathrm{E}+00$ | $2.0513 \mathrm{E}+01$ | $1.2491 \mathrm{E}+02$ | $6.0002 \mathrm{E}+01$ | $2.0494 \mathrm{E}+00$ |
| g24 | best | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ |
|  | Average | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| r01 | best | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5447 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ |
|  | Average | $1.5444 \mathrm{E}+04$ | $1.5449 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5454 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5451 \mathrm{E}+04$ |
|  | St.d | $1.0855 \mathrm{E}-06$ | $8.9928 \mathrm{E}+00$ | $1.1299 \mathrm{E}-02$ | $5.8502 \mathrm{E}+00$ | $6.2430 \mathrm{E}-07$ | $1.1709 \mathrm{E}+01$ |
| r02 | best | $1.8028 \mathrm{E}+04$ | $1.8075 \mathrm{E}+04$ | $1.8265 \mathrm{E}+04$ | $1.8477 \mathrm{E}+04$ | $1.8035 \mathrm{E}+04$ | $1.8019 \mathrm{E}+04$ |
|  | Average | $1.8120 \mathrm{E}+04$ | $1.8146 \mathrm{E}+04$ | $1.8474 \mathrm{E}+04$ | $1.8629 \mathrm{E}+04$ | $1.8118 \mathrm{E}+04$ | $1.8113 \mathrm{E}+04$ |
|  | St.d | $5.0666 \mathrm{E}+01$ | $4.4871 \mathrm{E}+01$ | $9.1791 \mathrm{E}+01$ | $6.3145 \mathrm{E}+01$ | $5.2259 \mathrm{E}+01$ | $4.8783 \mathrm{E}+01$ |
| r03 | best | $3.2692 \mathrm{E}+04$ | $3.2994 \mathrm{E}+04$ | $3.2761 \mathrm{E}+04$ | $3.3032 \mathrm{E}+04$ | $3.2692 \mathrm{E}+04$ | $3.2982 \mathrm{E}+04$ |
|  | Average | $3.2694 \mathrm{E}+04$ | $3.3056 \mathrm{E}+04$ | $3.2816 \mathrm{E}+04$ | $3.3151 \mathrm{E}+04$ | $3.2696 \mathrm{E}+04$ | $3.3089 \mathrm{E}+04$ |
|  | St.d | $9.5705 \mathrm{E}+00$ | $4.6986 \mathrm{E}+01$ | $3.4841 \mathrm{E}+01$ | $7.0589 \mathrm{E}+01$ | $1.3250 \mathrm{E}+01$ | $4.5181 \mathrm{E}+01$ |
| r04 | best | $1.2145 \mathrm{E}+05$ | $1.2543 \mathrm{E}+05$ | $1.2375 \mathrm{E}+05$ | $1.3098 \mathrm{E}+05$ | $1.2145 \mathrm{E}+05$ | $1.3662 \mathrm{E}+05$ |
|  | Average | $1.2157 \mathrm{E}+05$ | $1.2789 \mathrm{E}+05$ | $1.2407 \mathrm{E}+05$ | $1.3325 \mathrm{E}+05$ | $1.2157 \mathrm{E}+05$ | $1.4391 \mathrm{E}+05$ |
|  | St.d | $8.5076 \mathrm{E}+01$ | $9.5821 \mathrm{E}+02$ | $2.1117 \mathrm{E}+02$ | $1.2851 \mathrm{E}+03$ | $8.5076 \mathrm{E}+01$ | $4.0558 \mathrm{E}+03$ |
| r05 | best | $1.6649 \mathrm{E}+06$ | $1.8692 \mathrm{E}+06$ | $1.7537 \mathrm{E}+06$ | $1.9291 \mathrm{E}+06$ | $1.6649 \mathrm{E}+06$ | $1.9014 \mathrm{E}+06$ |
|  | Average | $1.6685 \mathrm{E}+06$ | $1.9044 \mathrm{E}+06$ | $1.7703 \mathrm{E}+06$ | $1.9459 \mathrm{E}+06$ | $1.6685 \mathrm{E}+06$ | $1.9444 \mathrm{E}+06$ |
|  | St.d | $3.4583 \mathrm{E}+03$ | $2.5853 \mathrm{E}+04$ | $6.2869 \mathrm{E}+03$ | $8.4284 \mathrm{E}+03$ | $3.4583 \mathrm{E}+03$ | $2.1101 \mathrm{E}+04$ |
| r06 | best | $4.5730 \mathrm{E}+04$ | $5.0962 \mathrm{E}+04$ | $4.9265 \mathrm{E}+04$ | $5.1100 \mathrm{E}+04$ | $4.5730 \mathrm{E}+04$ | $5.1042 \mathrm{E}+04$ |
|  | Average | $4.6586 \mathrm{E}+04$ | $5.2136 \mathrm{E}+04$ | $5.0198 \mathrm{E}+04$ | $5.1919 \mathrm{E}+04$ | $4.6586 \mathrm{E}+04$ | $5.2014 \mathrm{E}+04$ |
|  | St.d | $5.5149 \mathrm{E}+02$ | $5.7874 \mathrm{E}+02$ | $5.6253 \mathrm{E}+02$ | $4.2422 \mathrm{E}+02$ | $5.5149 \mathrm{E}+02$ | $4.8711 \mathrm{E}+02$ |
| r07 | best | $9.2271 \mathrm{E}+05$ | $1.0724 \mathrm{E}+06$ | $9.6681 \mathrm{E}+05$ | $1.0711 \mathrm{E}+06$ | $9.2271 \mathrm{E}+05$ | $1.0714 \mathrm{E}+06$ |
|  | Average | $9.4068 \mathrm{E}+05$ | $1.0749 \mathrm{E}+06$ | $9.7703 \mathrm{E}+05$ | $1.0733 \mathrm{E}+06$ | $1.0751 \mathrm{E}+06$ | $1.0751 \mathrm{E}+06$ |
|  | St.d | $8.0356 \mathrm{E}+03$ | $1.5285 \mathrm{E}+03$ | $5.3698 \mathrm{E}+03$ | $1.4421 \mathrm{E}+03$ | $8.0356 \mathrm{E}+03$ | $2.0023 \mathrm{E}+03$ |
| r08 | best | $9.1692 \mathrm{E}+05$ | $9.1569 \mathrm{E}+05$ | $9.1779 \mathrm{E}+05$ | $9.1811 \mathrm{E}+05$ | $9.1692 \mathrm{E}+05$ | $9.1567 \mathrm{E}+05$ |
|  | Average | $9.1733 \mathrm{E}+05$ | $9.1600 \mathrm{E}+05$ | $9.1862 \mathrm{E}+05$ | $9.1868 \mathrm{E}+05$ | $9.1733 \mathrm{E}+05$ | $9.1602 \mathrm{E}+05$ |
|  | St.d | $3.8198 \mathrm{E}+02$ | $2.8022 \mathrm{E}+02$ | $3.5551 \mathrm{E}+02$ | $2.9870 \mathrm{E}+02$ | $3.8198 \mathrm{E}+02$ | $2.5123 \mathrm{E}+02$ |
| r09 | best | $9.1749 \mathrm{E}+05$ | $9.1993 \mathrm{E}+05$ | $9.2211 \mathrm{E}+05$ | $9.2994 \mathrm{E}+05$ | $9.1749 \mathrm{E}+05$ | $9.2222 \mathrm{E}+05$ |
|  | Average | $9.1837 \mathrm{E}+05$ | $9.2095 \mathrm{E}+05$ | $9.2433 \mathrm{E}+05$ | $9.3437 \mathrm{E}+05$ | $9.1837 \mathrm{E}+05$ | $9.2841 \mathrm{E}+05$ |
|  | St.d | $5.2993 \mathrm{E}+02$ | $5.8315 \mathrm{E}+02$ | $1.0444 \mathrm{E}+03$ | $2.1156 \mathrm{E}+03$ | $5.2993 \mathrm{E}+02$ | $8.3284 \mathrm{E}+03$ |
| r10 | best | $9.2737 \mathrm{E}+05$ | $9.3680 \mathrm{E}+05$ | $9.3245 \mathrm{E}+05$ | $9.3977 \mathrm{E}+05$ | $9.2737 \mathrm{E}+05$ | $9.3870 \mathrm{E}+05$ |
|  | Average | $9.2926 \mathrm{E}+05$ | $9.4338 \mathrm{E}+05$ | $9.3444 \mathrm{E}+05$ | $9.4356 \mathrm{E}+05$ | $9.2926 \mathrm{E}+05$ | $9.4472 \mathrm{E}+05$ |
|  | St.d | $9.6017 \mathrm{E}+02$ | $3.4985 \mathrm{E}+03$ | $1.1954 \mathrm{E}+03$ | $2.3003 \mathrm{E}+03$ | $9.6017 \mathrm{E}+02$ | $3.3143 \mathrm{E}+03$ |

Table C.2: Function values obtained by FRORI, SaDE and GAMPC with and without R2S for CEC2006 and CEC2011

| P | Criteria | FRORI-R2S | FRORI | SaDE-R2S | SaDE | GAMPC-R2S | GAMPC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| g01 | best | -1.5000E+01 | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ |
|  | Average | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ | $-1.5000 \mathrm{E}+01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $9.1400 \mathrm{E}-08$ | $6.1700 \mathrm{E}-08$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g02 | best | -8.0362E-01 | -8.0355E-01 | -8.0333E-01 | -8.0308E-01 | -8.0362E-01 | -8.0362E-01 |
|  | Average | -8.0282E-01 | -8.0292E-01 | -8.0095E-01 | -7.9402E-01 | -7.9206E-01 | $-7.8907 \mathrm{E}-01$ |
|  | St.d | $2.7803 \mathrm{E}-03$ | $2.3488 \mathrm{E}-03$ | $3.0965 \mathrm{E}-03$ | $3.6435 \mathrm{E}-03$ | $1.3263 \mathrm{E}-02$ | $1.5853 \mathrm{E}-02$ |
| g03 | best | $-1.0005 \mathrm{E}+00$ | -9.8901E-01 | $-1.0005 \mathrm{E}+00$ | -6.6102E-01 | $-1.0005 \mathrm{E}+00$ | $-1.0005 \mathrm{E}+00$ |
|  | Average | $-1.0005 \mathrm{E}+00$ | -9.6684E-01 | $-1.0005 \mathrm{E}+00$ | -5.2465E-01 | $-1.0005 \mathrm{E}+00$ | -4.4515E-01 |
|  | St.d | $0.0000 \mathrm{E}+00$ | $1.0652 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ | $9.7210 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ | $2.1450 \mathrm{E}-01$ |
| g04 | Best | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ |
|  | Average | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0665 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ | $-3.0666 \mathrm{E}+04$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $8.7176 \mathrm{E}-02$ | $1.3280 \mathrm{E}-07$ | $4.0000 \mathrm{E}-12$ | $4.0000 \mathrm{E}-12$ |
| g05 | Best | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1266 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ |
|  | Average | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.1536 \mathrm{E}+03$ | $5.1265 \mathrm{E}+03$ | $5.2742 \mathrm{E}+03$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $3.0343 \mathrm{E}+01$ | $3.0000 \mathrm{E}-12$ | $1.8027 \mathrm{E}+02$ |
| g06 | Best | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-7.5933 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ |
|  | Average | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ | $-6.9871 \mathrm{E}+03$ | $-6.9618 \mathrm{E}+03$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.2630 \mathrm{E}+02$ | $0.0000 \mathrm{E}+00$ |
| g07 | Best | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ |
|  | Average | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ | $2.4306 \mathrm{E}+01$ |
|  | St.D | $2.0000 \mathrm{E}-10$ | $2.1069 \mathrm{E}-05$ | $1.6700 \mathrm{E}-07$ | $1.3695 \mathrm{E}-06$ | $9.6280 \mathrm{E}-09$ | $4.4000 \mathrm{E}-11$ |
| g08 | Best | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 | -9.5825E-02 |
|  | Average | $-9.5830 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ | $-9.5830 \mathrm{E}-02$ | $-9.5825 \mathrm{E}-02$ | $-9.5825 \mathrm{E}-02$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g09 | Best | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ |
|  | Average | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ | $6.8063 \mathrm{E}+02$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $7.5932 \mathrm{E}-05$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g10 | Best | $7.0492 \mathrm{E}+03$ | $7.0493 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ | $7.0493 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ |
|  | Average | $7.0492 \mathrm{E}+03$ | $7.0493 \mathrm{E}+03$ | $7.0493 \mathrm{E}+03$ | $7.0493 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ | $7.0492 \mathrm{E}+03$ |
|  | St.D | $7.0060 \mathrm{E}-07$ | $7.4005 \mathrm{E}-03$ | $1.7907 \mathrm{E}-02$ | $3.3504 \mathrm{E}-02$ | $3.3802 \mathrm{E}-07$ | $3.0000 \mathrm{E}-12$ |
| g11 | Best | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ |
|  | Average | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | $7.5103 \mathrm{E}-01$ | $7.4990 \mathrm{E}-01$ | 8.0388E-01 |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $5.1181 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $6.5354 \mathrm{E}-02$ |
| g12 | Best | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ |
|  | Average | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ | $-1.0000 \mathrm{E}+00$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| g13 | Best | $5.3942 \mathrm{E}-02$ | $5.3942 \mathrm{E}-02$ | $5.3942 \mathrm{E}-02$ | $8.0826 \mathrm{E}-01$ | $5.3942 \mathrm{E}-02$ | $5.3942 \mathrm{E}-02$ |
|  | Average | $5.3940 \mathrm{E}-02$ | $5.3950 \mathrm{E}-02$ | $5.3940 \mathrm{E}-02$ | $9.7581 \mathrm{E}-01$ | $5.3942 \mathrm{E}-02$ | $3.5032 \mathrm{E}-01$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $2.9450 \mathrm{E}-05$ | $0.0000 \mathrm{E}+00$ | $4.6030 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ | $2.1094 \mathrm{E}-01$ |
| g14 | Best | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ |
|  | Average | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ | $-4.7765 \mathrm{E}+01$ |
|  | St.D | $1.4600 \mathrm{E}-08$ | $4.9300 \mathrm{E}-07$ | $1.7000 \mathrm{E}-09$ | $0.0000 \mathrm{E}+00$ | $1.0554 \mathrm{E}-08$ | $1.2000 \mathrm{E}-11$ |
| g15 | Best | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ |
|  | Average | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6216 \mathrm{E}+02$ | $9.6172 \mathrm{E}+02$ | $9.6261 \mathrm{E}+02$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $6.7043 \mathrm{E}-01$ | $1.0000 \mathrm{E}-12$ | $1.0765 \mathrm{E}+00$ |
| g16 | Best | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ |
|  | Average | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ | $-1.9052 \mathrm{E}+00$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $5.0000 \mathrm{E}-09$ | $0.0000 \mathrm{E}+00$ |
| g17 | Best | $8.8535 \mathrm{E}+03$ | $8.8568 \mathrm{E}+03$ | $8.8535 \mathrm{E}+03$ | $8.9395 \mathrm{E}+03$ | $8.8535 \mathrm{E}+03$ | $8.8535 \mathrm{E}+03$ |
|  | Average | $8.8535 \mathrm{E}+03$ | $8.8632 \mathrm{E}+03$ | $8.8605 \mathrm{E}+03$ | $8.9465 \mathrm{E}+03$ | $8.8535 \mathrm{E}+03$ | $8.9013 \mathrm{E}+03$ |
|  | St.D | $1.9800 \mathrm{E}-08$ | $1.7868 \mathrm{E}+01$ | $2.3900 \mathrm{E}+01$ | $4.1999 \mathrm{E}+00$ | $2.0000 \mathrm{E}-12$ | $3.5988 \mathrm{E}+01$ |
| g18 | Best | -8.6602E-01 | -8.6579E-01 | -8.6603E-01 | -8.6603E-01 | -8.6603E-01 | -8.6603E-01 |
|  | Average | -8.6602E-01 | -8.6527E-01 | -8.2017E-01 | -8.5073E-01 | -8.5159E-01 | -8.6603E-01 |
|  | St.D | $3.8497 \mathrm{E}-06$ | $4.3520 \mathrm{E}-04$ | $8.3274 \mathrm{E}-02$ | $5.2895 \mathrm{E}-02$ | $6.3787 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ |
| g19 | Best | $3.2656 \mathrm{E}+01$ | $3.2662 \mathrm{E}+01$ | $3.2702 \mathrm{E}+01$ | $3.2667 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ |
|  | Average | $3.2656 \mathrm{E}+01$ | $3.2667 \mathrm{E}+01$ | $3.3055 \mathrm{E}+01$ | $3.2705 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ | $3.2656 \mathrm{E}+01$ |
|  | St.D | $1.2707 \mathrm{E}-06$ | $3.2269 \mathrm{E}-03$ | $3.1541 \mathrm{E}-01$ | $4.0410 \mathrm{E}-02$ | $1.0498 \mathrm{E}-06$ | $9.3340 \mathrm{E}-07$ |
| g21 | Best | $1.9372 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ | $1.9373 \mathrm{E}+02$ | $1.9377 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ | $1.9372 \mathrm{E}+02$ |
|  | Average | $1.9896 \mathrm{E}+02$ | $2.0104 \mathrm{E}+02$ | $2.2945 \mathrm{E}+02$ | $2.4011 \mathrm{E}+02$ | $2.3040 \mathrm{E}+02$ | $2.5659 \mathrm{E}+02$ |
|  | St.D | $2.6196 \mathrm{E}+01$ | $2.6013 \mathrm{E}+01$ | $2.9040 \mathrm{E}+01$ | $2.4323 \mathrm{E}+01$ | $6.0022 \mathrm{E}+01$ | $6.6786 \mathrm{E}+01$ |


| g23 | Best | $-4.0005 \mathrm{E}+02$ | $-3.8046 \mathrm{E}+02$ | -4.0004E+02 | $-3.9967 \mathrm{E}+02$ | $-4.0006 \mathrm{E}+02$ | $-4.0006 \mathrm{E}+02$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Average | $-3.9961 \mathrm{E}+02$ | $-3.5983 \mathrm{E}+02$ | $-2.6421 \mathrm{E}+02$ | $-3.7861 \mathrm{E}+02$ | $-3.7605 \mathrm{E}+02$ | $-3.8805 \mathrm{E}+02$ |
|  | St.D | $2.1845 \mathrm{E}+00$ | $1.4478 \mathrm{E}+01$ | $1.4262 \mathrm{E}+02$ | $1.3756 \mathrm{E}+01$ | $8.3075 \mathrm{E}+01$ | $6.0002 \mathrm{E}+01$ |
| g24 | Best | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ |
|  | Average | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ | $-5.5080 \mathrm{E}+00$ |
|  | St.D | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
| r01 | Best | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ |
|  | Average | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5445 \mathrm{E}+04$ | $1.5444 \mathrm{E}+04$ | $1.5454 \mathrm{E}+04$ |
|  | St.D | $1.2969 \mathrm{E}-05$ | $1.5014 \mathrm{E}+05$ | $5.2395 \mathrm{E}-06$ | $9.8578 \mathrm{E}-01$ | $4.8713 \mathrm{E}-06$ | $1.2148 \mathrm{E}+01$ |
| r02 | Best | $1.8538 \mathrm{E}+04$ | $1.8677 \mathrm{E}+04$ | $1.8075 \mathrm{E}+04$ | $1.8075 \mathrm{E}+04$ | $1.8058 \mathrm{E}+04$ | $1.8045 \mathrm{E}+04$ |
|  | Average | $1.8632 \mathrm{E}+04$ | $1.8597 \mathrm{E}+04$ | $1.8106 \mathrm{E}+04$ | $1.8111 \mathrm{E}+04$ | $1.8191 \mathrm{E}+04$ | $1.8158 \mathrm{E}+04$ |
|  | St.D | $4.6636 \mathrm{E}+01$ | $1.5010 \mathrm{E}+05$ | $3.0565 \mathrm{E}+01$ | $4.1176 \mathrm{E}+01$ | $1.2538 \mathrm{E}+02$ | $6.3008 \mathrm{E}+01$ |
| r03 | Best | $3.2695 \mathrm{E}+04$ | $3.3136 \mathrm{E}+04$ | $3.2693 \mathrm{E}+04$ | $3.2998 \mathrm{E}+04$ | $3.2692 \mathrm{E}+04$ | $3.2875 \mathrm{E}+04$ |
|  | Average | $3.2697 \mathrm{E}+04$ | $3.2962 \mathrm{E}+04$ | $3.2736 \mathrm{E}+04$ | $3.3089 \mathrm{E}+04$ | $3.2695 \mathrm{E}+04$ | $3.3033 \mathrm{E}+04$ |
|  | St.D | $1.7909 \mathrm{E}+00$ | $1.5011 \mathrm{E}+05$ | $6.9628 \mathrm{E}+01$ | $2.6260 \mathrm{E}+01$ | $9.6839 \mathrm{E}+00$ | $7.8394 \mathrm{E}+01$ |
| r04 | Best | $1.2282 \mathrm{E}+05$ | $1.3883 \mathrm{E}+05$ | $1.2182 \mathrm{E}+05$ | $1.2780 \mathrm{E}+05$ | $1.2158 \mathrm{E}+05$ | $1.3831 \mathrm{E}+05$ |
|  | Average | $1.2357 \mathrm{E}+05$ | $1.2872 \mathrm{E}+05$ | $1.2218 \mathrm{E}+05$ | $1.3010 \mathrm{E}+05$ | $1.2277 \mathrm{E}+05$ | $1.4757 \mathrm{E}+05$ |
|  | St.D | $5.1464 \mathrm{E}+02$ | $1.5015 \mathrm{E}+05$ | $2.4371 \mathrm{E}+02$ | $1.8145 \mathrm{E}+03$ | $1.8188 \mathrm{E}+03$ | $5.6931 \mathrm{E}+03$ |
| r05 | Best | $1.3304 \mathrm{E}+06$ | $1.8548 \mathrm{E}+06$ | $1.6878 \mathrm{E}+06$ | $1.8936 \mathrm{E}+06$ | $1.7378 \mathrm{E}+06$ | $1.9246 \mathrm{E}+06$ |
|  | Average | $1.3442 \mathrm{E}+06$ | $1.7615 \mathrm{E}+06$ | $1.6949 \mathrm{E}+06$ | $1.9074 \mathrm{E}+06$ | $1.7949 \mathrm{E}+06$ | $1.9470 \mathrm{E}+06$ |
|  | St.D | $1.0115 \mathrm{E}+04$ | $1.5015 \mathrm{E}+05$ | $5.1015 \mathrm{E}+03$ | $9.3519 \mathrm{E}+03$ | $3.4442 \mathrm{E}+04$ | $1.1278 \mathrm{E}+04$ |
| r06 | Best | $4.5242 \mathrm{E}+04$ | $4.8891 \mathrm{E}+04$ | $4.5516 \mathrm{E}+04$ | $5.1343 \mathrm{E}+04$ | $4.8082 \mathrm{E}+04$ | $5.1001 \mathrm{E}+04$ |
|  | Average | $4.6649 \mathrm{E}+04$ | $4.7759 \mathrm{E}+04$ | $4.6488 \mathrm{E}+04$ | $5.2176 \mathrm{E}+04$ | $4.9279 \mathrm{E}+04$ | $5.2543 \mathrm{E}+04$ |
|  | St.D | $7.1377 \mathrm{E}+02$ | $1.5015 \mathrm{E}+05$ | $4.2946 \mathrm{E}+02$ | $4.9450 \mathrm{E}+02$ | $5.4345 \mathrm{E}+02$ | $5.9771 \mathrm{E}+02$ |
| r07 | Best | $7.0105 \mathrm{E}+05$ | $9.5458 \mathrm{E}+05$ | $1.0377 \mathrm{E}+06$ | $1.0702 \mathrm{E}+06$ | $1.0659 \mathrm{E}+06$ | $1.0728 \mathrm{E}+06$ |
|  | Average | $7.1769 \mathrm{E}+05$ | $9.3263 \mathrm{E}+05$ | $1.0431 \mathrm{E}+06$ | $1.0731 \mathrm{E}+06$ | $1.0713 \mathrm{E}+06$ | $1.0753 \mathrm{E}+06$ |
|  | St.D | $8.9975 \mathrm{E}+03$ | $2.0020 \mathrm{E}+05$ | $2.3511 \mathrm{E}+03$ | $1.6103 \mathrm{E}+03$ | $2.2509 \mathrm{E}+03$ | $1.5009 \mathrm{E}+03$ |
| r08 | Best | $9.1639 \mathrm{E}+05$ | $9.1755 \mathrm{E}+05$ | $9.1662 \mathrm{E}+05$ | $9.1601 \mathrm{E}+05$ | $9.1598 \mathrm{E}+05$ | $9.1583 \mathrm{E}+05$ |
|  | Average | $9.1670 \mathrm{E}+05$ | $9.1712 \mathrm{E}+05$ | $9.1690 \mathrm{E}+05$ | $9.1630 \mathrm{E}+05$ | $9.1682 \mathrm{E}+05$ | $9.1619 \mathrm{E}+05$ |
|  | St.D | $2.2248 \mathrm{E}+02$ | $1.5003 \mathrm{E}+05$ | $2.3659 \mathrm{E}+02$ | $1.3147 \mathrm{E}+02$ | $4.1547 \mathrm{E}+02$ | $2.3447 \mathrm{E}+02$ |
| r09 | Best | $9.1766 \mathrm{E}+05$ | $9.2294 \mathrm{E}+05$ | $9.1848 \mathrm{E}+05$ | $9.2181 \mathrm{E}+05$ | $9.1707 \mathrm{E}+05$ | $9.1852 \mathrm{E}+05$ |
|  | Average | $9.1917 \mathrm{E}+05$ | $9.2168 \mathrm{E}+05$ | $9.1940 \mathrm{E}+05$ | $9.2332 \mathrm{E}+05$ | $9.2311 \mathrm{E}+05$ | $9.2713 \mathrm{E}+05$ |
|  | St.D | $8.7250 \mathrm{E}+02$ | $1.5008 \mathrm{E}+05$ | $5.3074 \mathrm{E}+02$ | $6.1649 \mathrm{E}+02$ | $5.0612 \mathrm{E}+03$ | $6.8705 \mathrm{E}+03$ |
| r10 | best | $9.2522 \mathrm{E}+05$ | $9.2833 \mathrm{E}+05$ | $9.2592 \mathrm{E}+05$ | $9.3861 \mathrm{E}+05$ | $9.2818 \mathrm{E}+05$ | $9.3808 \mathrm{E}+05$ |
|  | Average | $9.2685 \mathrm{E}+05$ | $9.2722 \mathrm{E}+05$ | $9.2660 \mathrm{E}+05$ | $9.4174 \mathrm{E}+05$ | $9.3226 \mathrm{E}+05$ | $9.4608 \mathrm{E}+05$ |
|  | St.d | $9.8155 \mathrm{E}+02$ | $2.0020 \mathrm{E}+05$ | $5.5665 \mathrm{E}+02$ | $1.6099 \mathrm{E}+03$ | $2.3048 \mathrm{E}+03$ | $4.3681 \mathrm{E}+03$ |

Table C.3: Function values obtained by MJADE, MCoDE and MOXDE with and without R2S for CEC2010 for 10D

| Problem | Criteria | MJADE-R2S | MJADE | MCoDE-R2S | MCoDE | MOXDE-R2S | MOXDE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | best | -7.4731E-01 | -7.4731E-01 | -7.4730E-01 | -7.4710E-01 | -8.2188E-01 | -7.4731E-01 |
|  | Average | -7.4529E-01 | -7.4731E-01 | -7.4540E-01 | -7.4658E-01 | -8.0572E-01 | -7.4586E-01 |
|  | St.d | $5.2900 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $5.3771 \mathrm{E}-03$ | $5.7556 \mathrm{E}-04$ | $1.2450 \mathrm{E}-02$ | $3.0000 \mathrm{E}-03$ |
| c02 | best | $-2.2777 \mathrm{E}+00$ | -6.7604E-01 | -5.6383E-01 | $2.8896 \mathrm{E}-01$ | $-2.2609 \mathrm{E}+00$ | $9.0190 \mathrm{E}-01$ |
|  | Average | $-2.0103 \mathrm{E}+00$ | $2.9705 \mathrm{E}+00$ | $1.3785 \mathrm{E}+00$ | $3.5073 \mathrm{E}+00$ | $-2.2423 \mathrm{E}+00$ | $3.3490 \mathrm{E}+00$ |
|  | St.d | $4.0944 \mathrm{E}-01$ | $1.4316 \mathrm{E}+00$ | $1.3243 \mathrm{E}+00$ | $1.1931 \mathrm{E}+00$ | $1.2930 \mathrm{E}-02$ | $1.1986 \mathrm{E}+00$ |
| c03 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.5268 \mathrm{E}-04$ | $1.6998 \mathrm{E}+08$ | $2.8673 \mathrm{E}+01$ | $7.6128 \mathrm{E}+02$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $7.1360 \mathrm{E}-01$ | $9.1783 \mathrm{E}+13$ | $7.3609 \mathrm{E}+01$ | $1.2796 \mathrm{E}+14$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.4573 \mathrm{E}+00$ | $1.9906 \mathrm{E}+14$ | $4.5431 \mathrm{E}+01$ | $2.5638 \mathrm{E}+14$ |
| c04 | best | $-1.0000 \mathrm{E}-05$ | $-1.0000 \mathrm{E}-05$ | $5.5452 \mathrm{E}-04$ | $2.2302 \mathrm{E}-02$ | $1.6791 \mathrm{E}-01$ | $2.4890 \mathrm{E}-04$ |
|  | Average | $9.9009 \mathrm{E}+00$ | $6.6700 \mathrm{E}-02$ | $1.0933 \mathrm{E}-03$ | $7.5533 \mathrm{E}-02$ | $1.3119 \mathrm{E}+00$ | $5.2282 \mathrm{E}-04$ |
|  | St.d | $1.6262 \mathrm{E}+01$ | $2.3520 \mathrm{E}-01$ | $2.8754 \mathrm{E}-04$ | $4.9194 \mathrm{E}-02$ | $1.8201 \mathrm{E}+00$ | $1.7000 \mathrm{E}-04$ |
| c05 | best | $-2.6391 \mathrm{E}+02$ | $1.4904 \mathrm{E}+02$ | $1.3972 \mathrm{E}+02$ | $5.4644 \mathrm{E}+01$ | $1.4623 \mathrm{E}+02$ | $2.3473 \mathrm{E}+02$ |
|  | Average | $3.6320 \mathrm{E}+01$ | $3.7530 \mathrm{E}+02$ | $3.2406 \mathrm{E}+02$ | $4.4302 \mathrm{E}+02$ | $3.4648 \mathrm{E}+02$ | $4.4720 \mathrm{E}+02$ |
|  | St.d | $1.4938 \mathrm{E}+02$ | $1.1848 \mathrm{E}+02$ | $1.1175 \mathrm{E}+02$ | $1.1419 \mathrm{E}+02$ | $8.7585 \mathrm{E}+01$ | $8.7287 \mathrm{E}+01$ |
| c06 | best | $-5.8089 \mathrm{E}+02$ | $7.9357 \mathrm{E}+01$ | $-1.6323 \mathrm{E}+01$ | $5.2111 \mathrm{E}+01$ | $2.3282 \mathrm{E}+01$ | $1.8963 \mathrm{E}+02$ |
|  | Average | $-7.0538 \mathrm{E}+01$ | $3.4958 \mathrm{E}+02$ | $3.2729 \mathrm{E}+02$ | $4.5242 \mathrm{E}+02$ | $3.6310 \mathrm{E}+02$ | $4.6521 \mathrm{E}+02$ |
|  | St.d | $1.9221 \mathrm{E}+02$ | $1.1561 \mathrm{E}+02$ | $1.5422 \mathrm{E}+02$ | $1.3325 \mathrm{E}+02$ | $1.1472 \mathrm{E}+02$ | $1.2585 \mathrm{E}+02$ |
| c07 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $4.5772 \mathrm{E}-01$ | $1.8932 \mathrm{E}+00$ | $2.7981 \mathrm{E}-07$ | $6.2171 \mathrm{E}-08$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.1778 \mathrm{E}+00$ | $4.2065 \mathrm{E}+00$ | $1.5437 \mathrm{E}+07$ | $1.5147 \mathrm{E}-06$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $6.5928 \mathrm{E}-01$ | $1.2638 \mathrm{E}+00$ | $4.2689 \mathrm{E}+07$ | $0.0000 \mathrm{E}+00$ |
| c08 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $5.1869 \mathrm{E}+00$ | $5.1425 \mathrm{E}+01$ | $3.3706 \mathrm{E}-01$ | $8.7724 \mathrm{E}-04$ |
|  | Average | $9.6105 \mathrm{E}+00$ | $8.8980 \mathrm{E}+00$ | $1.6222 \mathrm{E}+05$ | $1.6966 \mathrm{E}+02$ | $1.2329 \mathrm{E}+03$ | $8.3539 \mathrm{E}+00$ |
|  | St.d | $3.0696 \mathrm{E}+00$ | $4.1981 \mathrm{E}+00$ | $8.1098 \mathrm{E}+05$ | $7.4939 \mathrm{E}+01$ | $3.0737 \mathrm{E}+03$ | $4.1679 \mathrm{E}+00$ |
| c09 | best | $0.0000 \mathrm{E}+00$ | $1.2392 \mathrm{E}+12$ | $2.0543 \mathrm{E}+11$ | $2.7624 \mathrm{E}+12$ | $3.6393 \mathrm{E}+10$ | $4.2051 \mathrm{E}+12$ |
|  | Average | $3.7515 \mathrm{E}+11$ | $7.6337 \mathrm{E}+12$ | $5.1062 \mathrm{E}+12$ | $1.1508 \mathrm{E}+13$ | $2.1969 \mathrm{E}+12$ | $1.3033 \mathrm{E}+13$ |
|  | St.d | $9.4435 \mathrm{E}+11$ | $4.8842 \mathrm{E}+12$ | $5.1497 \mathrm{E}+12$ | $6.1047 \mathrm{E}+12$ | $2.9369 \mathrm{E}+12$ | $7.3894 \mathrm{E}+12$ |
| c10 | best | $0.0000 \mathrm{E}+00$ | $9.1809 \mathrm{E}+11$ | $7.9872 \mathrm{E}+11$ | $1.3036 \mathrm{E}+12$ | $1.7457 \mathrm{E}+11$ | $2.9996 \mathrm{E}+12$ |
|  | Average | $4.4535 \mathrm{E}+10$ | $8.8018 \mathrm{E}+12$ | $3.2566 \mathrm{E}+12$ | $1.0492 \mathrm{E}+13$ | $3.4309 \mathrm{E}+12$ | $9.9174 \mathrm{E}+12$ |
|  | St.d | $1.3280 \mathrm{E}+11$ | $5.4561 \mathrm{E}+12$ | $2.0610 \mathrm{E}+12$ | $6.3057 \mathrm{E}+12$ | $4.6492 \mathrm{E}+12$ | $4.3962 \mathrm{E}+12$ |
| c11 | best | -3.7220E-01 | -1.5227E-03 | $-4.2034 \mathrm{E}+00$ | -1.9172E-01 | -1.7421E-03 | -1.5126E-03 |
|  | Average | $1.4000 \mathrm{E}-01$ | $-1.5200 \mathrm{E}-03$ | -1.1449E-01 | $-7.8724 \mathrm{E}-02$ | $1.4168 \mathrm{E}-02$ | -1.4898E-03 |
|  | St.d | $4.8259 \mathrm{E}-01$ | $0.0000 \mathrm{E}+00$ | $8.8884 \mathrm{E}-01$ | $6.0429 \mathrm{E}-02$ | $1.0500 \mathrm{E}-02$ | $2.0000 \mathrm{E}-05$ |
| c12 | best | $-1.5441 \mathrm{E}+03$ | $-3.0378 \mathrm{E}+02$ | $-5.7007 \mathrm{E}+02$ | $-3.0223 \mathrm{E}+02$ | $-6.7960 \mathrm{E}+02$ | $-8.2850 \mathrm{E}+01$ |
|  | Average | $-6.6746 \mathrm{E}+02$ | $-1.2343 \mathrm{E}+01$ | $-1.3407 \mathrm{E}+02$ | $-1.1663 \mathrm{E}+01$ | $-3.6917 \mathrm{E}+01$ | $-5.1274 \mathrm{E}+00$ |
|  | St.d | $3.8228 \mathrm{E}+02$ | $6.0717 \mathrm{E}+01$ | $1.9344 \mathrm{E}+02$ | $6.0724 \mathrm{E}+01$ | $1.3870 \mathrm{E}+02$ | $1.8555 \mathrm{E}+01$ |
| c13 | best | $-6.8429 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-6.8428 \mathrm{E}+01$ | $-6.7542 \mathrm{E}+01$ | $-6.5033 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ |
|  | Average | $-6.8315 \mathrm{E}+01$ | $-6.8270 \mathrm{E}+01$ | -6.8405E+01 | $-6.5202 \mathrm{E}+01$ | $-6.1279 \mathrm{E}+01$ | $-6.6470 \mathrm{E}+01$ |
|  | St.d | $5.7018 \mathrm{E}-01$ | $1.3735 \mathrm{E}-01$ | $2.7052 \mathrm{E}-02$ | $9.6944 \mathrm{E}-01$ | $2.3874 \mathrm{E}+00$ | $3.3536 \mathrm{E}+00$ |
| c14 | best | $0.0000 \mathrm{E}+00$ | $9.8250 \mathrm{E}+08$ | $3.1282 \mathrm{E}+08$ | $6.7373 \mathrm{E}+11$ | $1.2366 \mathrm{E}+01$ | $7.8486 \mathrm{E}+11$ |
|  | Average | $1.7335 \mathrm{E}+08$ | $7.9387 \mathrm{E}+10$ | $3.1014 \mathrm{E}+11$ | $5.0417 \mathrm{E}+12$ | $2.6880 \mathrm{E}+06$ | $5.4895 \mathrm{E}+12$ |
|  | St.d | $8.4496 \mathrm{E}+08$ | $1.1947 \mathrm{E}+11$ | $9.0084 \mathrm{E}+11$ | $3.9508 \mathrm{E}+12$ | $1.0460 \mathrm{E}+07$ | $3.4284 \mathrm{E}+12$ |
| c15 | best | $4.8105 \mathrm{E}+11$ | $2.5942 \mathrm{E}+12$ | $2.0333 \mathrm{E}+13$ | $1.0261 \mathrm{E}+13$ | $4.0810 \mathrm{E}+13$ | $1.1071 \mathrm{E}+13$ |
|  | Average | $4.4552 \mathrm{E}+13$ | $3.5452 \mathrm{E}+13$ | $9.4355 \mathrm{E}+13$ | $6.2344 \mathrm{E}+13$ | $9.4942 \mathrm{E}+13$ | $6.6123 \mathrm{E}+13$ |
|  | St.d | $5.1189 \mathrm{E}+13$ | $1.8185 \mathrm{E}+13$ | $5.4568 \mathrm{E}+13$ | $3.3763 \mathrm{E}+13$ | $4.4549 \mathrm{E}+13$ | $4.1323 \mathrm{E}+13$ |
| c16 | best | $0.0000 \mathrm{E}+00$ | $8.7866 \mathrm{E}-01$ | $2.8031 \mathrm{E}-02$ | $9.8017 \mathrm{E}-01$ | $0.0000 \mathrm{E}+00$ | $9.9867 \mathrm{E}-01$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $9.9428 \mathrm{E}-01$ | $6.2085 \mathrm{E}-01$ | $1.0657 \mathrm{E}+00$ | $2.7415 \mathrm{E}-02$ | $1.0502 \mathrm{E}+00$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $3.2130 \mathrm{E}-02$ | $3.2090 \mathrm{E}-01$ | $3.0494 \mathrm{E}-02$ | $9.6750 \mathrm{E}-02$ | $2.8970 \mathrm{E}-02$ |
| c17 | best | $0.0000 \mathrm{E}+00$ | $5.6812 \mathrm{E}+01$ | $6.3408 \mathrm{E}-02$ | $2.2103 \mathrm{E}+02$ | $2.2131 \mathrm{E}-01$ | $2.0317 \mathrm{E}+02$ |
|  | Average | $1.5608 \mathrm{E}-01$ | $2.3986 \mathrm{E}+02$ | $2.2442 \mathrm{E}+01$ | $6.7148 \mathrm{E}+02$ | $4.0382 \mathrm{E}+01$ | $5.7688 \mathrm{E}+02$ |
|  | St.d | $3.7892 \mathrm{E}-01$ | $1.4535 \mathrm{E}+02$ | $5.3793 \mathrm{E}+01$ | $3.2379 \mathrm{E}+02$ | $7.0749 \mathrm{E}+01$ | $2.4107 \mathrm{E}+02$ |
| c18 | best | $0.0000 \mathrm{E}+00$ | $3.3132 \mathrm{E}+03$ | $9.6192 \mathrm{E}+02$ | $4.5765 \mathrm{E}+03$ | $7.1509 \mathrm{E}+01$ | $5.2067 \mathrm{E}+03$ |
|  | Average | $5.4925 \mathrm{E}+02$ | $1.0507 \mathrm{E}+04$ | $4.7928 \mathrm{E}+03$ | $1.4863 \mathrm{E}+04$ | $6.0808 \mathrm{E}+03$ | $1.3756 \mathrm{E}+04$ |
|  | St.d | $1.2888 \mathrm{E}+03$ | $4.8276 \mathrm{E}+03$ | $2.1971 \mathrm{E}+03$ | $7.2381 \mathrm{E}+03$ | $5.4365 \mathrm{E}+03$ | $6.1163 \mathrm{E}+03$ |

Table C.4: Function values obtained by FRORI, SaDE and GAMPC with and without R2S for CEC2010 for 10D

| Problem | Criteria | FRORI-R2S | FRORI | SaDE-R2S | SaDE | GAMPC-R2S | GAMPC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | best | -7.4731E-01 | -7.4731E-01 | -7.4731E-01 | -7.4731E-01 | -7.4731E-01 | -7.4731E-01 |
|  | Average | -7.4064E-01 | -7.4677E-01 | -7.4731E-01 | -7.4721E-01 | -7.2513E-01 | -7.2513E-01 |
|  | St.d | $4.2500 \mathrm{E}-03$ | $1.8700 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $1.7000 \mathrm{E}-04$ | $2.4539 \mathrm{E}-02$ | $2.4539 \mathrm{E}-02$ |
| c02 | best | $-2.2777 \mathrm{E}+00$ | $-2.1564 \mathrm{E}+00$ | $-4.7524 \mathrm{E}-01$ | $-2.2419 \mathrm{E}+00$ | $-2.2777 \mathrm{E}+00$ | -7.9110E-02 |
|  | Average | $-2.0556 \mathrm{E}+00$ | $-1.9329 \mathrm{E}+00$ | $3.0074 \mathrm{E}+00$ | $-1.9582 \mathrm{E}+00$ | $-1.8726 \mathrm{E}+00$ | $2.8027 \mathrm{E}+00$ |
|  | St.d | $1.4048 \mathrm{E}-01$ | $5.3027 \mathrm{E}-01$ | $1.1222 \mathrm{E}+00$ | $3.9838 \mathrm{E}-01$ | $1.3383 \mathrm{E}+00$ | $1.3912 \mathrm{E}+00$ |
| c03 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.6193 \mathrm{E}+12$ | $2.5182 \mathrm{E}+01$ | $3.5502 \mathrm{E}-01$ | $1.1897 \mathrm{E}+14$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.4424 \mathrm{E}+12$ | $1.3839 \mathrm{E}+01$ | $1.7751 \mathrm{E}+00$ | $2.1466 \mathrm{E}+14$ |
| c04 | best | -1.0000E-05 | $-1.0000 \mathrm{E}-05$ | -9.9999E-06 | -9.4983E-06 | -1.0000E-05 | $-1.0000 \mathrm{E}-05$ |
|  | Average | -1.0000E-05 | $-1.0000 \mathrm{E}-05$ | $2.7134 \mathrm{E}-02$ | $1.2432 \mathrm{E}+00$ | -1.0000E-05 | $9.3835 \mathrm{E}-02$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.3568 \mathrm{E}-01$ | $2.8164 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.6450 \mathrm{E}-01$ |
| c05 | best | $-4.8361 \mathrm{E}+02$ | $-4.8361 \mathrm{E}+02$ | $2.1842 \mathrm{E}+02$ | $-2.4591 \mathrm{E}+02$ | $4.0151 \mathrm{E}+01$ | $3.8301 \mathrm{E}+01$ |
|  | Average | $-4.8361 \mathrm{E}+02$ | $-4.8361 \mathrm{E}+02$ | $3.9346 \mathrm{E}+02$ | $-1.2556 \mathrm{E}+02$ | $3.6165 \mathrm{E}+02$ | $3.6592 \mathrm{E}+02$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $1.0000 \mathrm{E}-05$ | $9.2251 \mathrm{E}+01$ | $1.6456 \mathrm{E}+02$ | $1.6840 \mathrm{E}+02$ | $1.5055 \mathrm{E}+02$ |
| c06 | best | $-5.7866 \mathrm{E}+02$ | $-5.7866 \mathrm{E}+02$ | $1.0678 \mathrm{E}+02$ | $-4.9368 \mathrm{E}+02$ | $-5.7866 \mathrm{E}+02$ | $1.3171 \mathrm{E}+02$ |
|  | Average | $-5.7729 \mathrm{E}+02$ | $-5.7866 \mathrm{E}+02$ | $3.9100 \mathrm{E}+02$ | $-3.5756 \mathrm{E}+02$ | $3.0143 \mathrm{E}+02$ | $3.9697 \mathrm{E}+02$ |
|  | St.d | $4.0979 \mathrm{E}-01$ | $8.4000 \mathrm{E}-04$ | $1.2231 \mathrm{E}+02$ | $7.8839 \mathrm{E}+01$ | $3.2138 \mathrm{E}+02$ | $1.3605 \mathrm{E}+02$ |
| c07 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.6052 \mathrm{E}-01$ | $1.6789 \mathrm{E}-01$ | $4.7839 \mathrm{E}-01$ | $4.7839 \mathrm{E}-01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $5.4954 \mathrm{E}-01$ | $6.0840 \mathrm{E}-01$ | $1.3222 \mathrm{E}+00$ | $1.3222 \mathrm{E}+00$ |
| c08 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $8.3832 \mathrm{E}+00$ | $8.2271 \mathrm{E}+00$ | $3.5013 \mathrm{E}+00$ | $2.2048 \mathrm{E}+01$ | $8.9702 \mathrm{E}+00$ | $8.9702 \mathrm{E}+00$ |
|  | St.d | $4.0584 \mathrm{E}+00$ | $4.7210 \mathrm{E}+00$ | $5.2092 \mathrm{E}+00$ | $5.7192 \mathrm{E}+01$ | $7.9635 \mathrm{E}+00$ | $7.9635 \mathrm{E}+00$ |
| c09 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.5333 \mathrm{E}+11$ | $1.9653 \mathrm{E}-08$ | $0.0000 \mathrm{E}+00$ | $1.3770 \mathrm{E}+12$ |
|  | Average | $1.7633 \mathrm{E}-01$ | $2.7320 \mathrm{E}+01$ | $7.8619 \mathrm{E}+12$ | $9.5034 \mathrm{E}+01$ | $2.6208 \mathrm{E}+12$ | $9.1879 \mathrm{E}+12$ |
|  | St.d | 8.8163E-01 | $3.7799 \mathrm{E}+01$ | $4.7386 \mathrm{E}+12$ | $1.0057 \mathrm{E}+02$ | $3.9740 \mathrm{E}+12$ | $6.6750 \mathrm{E}+12$ |
| c10 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $3.8698 \mathrm{E}+11$ | $2.7110 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.5984 \mathrm{E}+12$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $4.0057 \mathrm{E}+01$ | $6.3719 \mathrm{E}+12$ | $8.1224 \mathrm{E}+01$ | $3.5303 \mathrm{E}+12$ | $1.0222 \mathrm{E}+13$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $8.3452 \mathrm{E}+00$ | $4.6609 \mathrm{E}+12$ | $6.7192 \mathrm{E}+01$ | $4.5032 \mathrm{E}+12$ | $4.3672 \mathrm{E}+12$ |
| c11 | best | -1.5227E-03 | -2.9449E-01 | -2.6912E-02 | -3.3588E-01 | -8.7342E-02 | -8.7342E-02 |
|  | Average | -7.0000E-05 | -1.3240E-02 | $3.9768 \mathrm{E}-03$ | $1.4292 \mathrm{E}-01$ | $4.3885 \mathrm{E}-01$ | -4.9555E-03 |
|  | St.d | $7.2600 \mathrm{E}-03$ | $5.8590 \mathrm{E}-02$ | $1.3150 \mathrm{E}-02$ | $6.8907 \mathrm{E}-01$ | $2.2557 \mathrm{E}+00$ | $1.7164 \mathrm{E}-02$ |
| c12 | best | $-8.8704 \mathrm{E}+02$ | $-5.7009 \mathrm{E}+02$ | $-1.0639 \mathrm{E}+01$ | $-8.8704 \mathrm{E}+02$ | $-8.8704 \mathrm{E}+02$ | $-4.2313 \mathrm{E}+02$ |
|  | Average | $-8.8220 \mathrm{E}+02$ | $-3.5131 \mathrm{E}+02$ | $1.2667 \mathrm{E}-01$ | $-7.0456 \mathrm{E}+02$ | $-7.3613 \mathrm{E}+02$ | $-6.0586 \mathrm{E}+01$ |
|  | St.d | $1.4285 \mathrm{E}+01$ | $2.3993 \mathrm{E}+02$ | $3.4706 \mathrm{E}+00$ | $2.8457 \mathrm{E}+02$ | $3.0879 \mathrm{E}+02$ | $1.4010 \mathrm{E}+02$ |
| c13 | best | $-6.8429 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-6.8417 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ |
|  | Average | $-6.7343 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-6.7815 \mathrm{E}+01$ | $-6.8376 \mathrm{E}+01$ | -6.3711E+01 | $-6.3711 \mathrm{E}+01$ |
|  | St.d | $5.3836 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.2020 \mathrm{E}-01$ | $1.2322 \mathrm{E}-01$ | $2.0241 \mathrm{E}+00$ | $2.0241 \mathrm{E}+00$ |
| c14 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.2106 \mathrm{E}+11$ | $2.4574 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $5.7268 \mathrm{E}+11$ | $6.0659 \mathrm{E}-01$ | $2.4363 \mathrm{E}+09$ | $2.4363 \mathrm{E}+09$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $3.7262 \mathrm{E}+11$ | $6.4674 \mathrm{E}-01$ | $1.2181 \mathrm{E}+10$ | $1.2181 \mathrm{E}+10$ |
| c15 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.5195 \mathrm{E}+12$ | $0.0000 \mathrm{E}+00$ | $5.3223 \mathrm{E}+12$ | $5.3223 \mathrm{E}+12$ |
|  | Average | $3.0951 \mathrm{E}+00$ | $3.0855 \mathrm{E}+00$ | $1.8005 \mathrm{E}+13$ | $1.0615 \mathrm{E}+00$ | $3.3224 \mathrm{E}+13$ | $3.3224 \mathrm{E}+13$ |
|  | St.d | $1.3527 \mathrm{E}+00$ | $1.3744 \mathrm{E}+00$ | $1.4528 \mathrm{E}+13$ | $1.7442 \mathrm{E}+00$ | $1.7034 \mathrm{E}+13$ | $1.7034 \mathrm{E}+13$ |
| c16 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.0088 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.1348 \mathrm{E}-02$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $1.7380 \mathrm{E}-02$ | $1.0342 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.5478 \mathrm{E}-01$ | $6.5004 \mathrm{E}-01$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $4.3340 \mathrm{E}-02$ | $1.3250 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ | $1.7613 \mathrm{E}-01$ | $4.0442 \mathrm{E}-01$ |
| c17 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $7.2933 \mathrm{E}+01$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.8531 \mathrm{E}+01$ |
|  | Average | $2.4100 \mathrm{E}-03$ | $1.1365 \mathrm{E}-01$ | $3.4038 \mathrm{E}+02$ | $1.6567 \mathrm{E}-01$ | $4.1944 \mathrm{E}-01$ | $4.9083 \mathrm{E}+02$ |
|  | St.d | $8.2000 \mathrm{E}-03$ | $2.6848 \mathrm{E}-01$ | $1.9447 \mathrm{E}+02$ | $3.1660 \mathrm{E}-01$ | $9.9827 \mathrm{E}-01$ | $2.9329 \mathrm{E}+02$ |
| c18 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.5014 \mathrm{E}+03$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.0741 \mathrm{E}+03$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $9.2596 \mathrm{E}+03$ | $1.7442 \mathrm{E}+00$ | $4.8374 \mathrm{E}+03$ | $1.1310 \mathrm{E}+04$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $4.7018 \mathrm{E}+03$ | $3.6312 \mathrm{E}+00$ | $7.0530 \mathrm{E}+03$ | $5.1203 \mathrm{E}+03$ |

Table C.5: Function values obtained by MJADE, MCoDE and MOXDE with and without R2S for CEC2010 for 30D

| Problem | Criteria | MJADE-R2S | MJADE | MCoDE-R2S | MCoDE | MOXDE-R2S | MOXDE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | best | -8.2188E-01 | -8.2028E-01 | -8.2188E-01 | -8.1188E-01 | -8.2188E-01 | -8.2186E-01 |
|  | Average | -8.1884E-01 | -8.1851E-01 | -8.1903E-01 | -8.0269E-01 | -8.0572E-01 | -8.1594E-01 |
|  | St.d | $3.3000 \mathrm{E}-03$ | $1.0600 \mathrm{E}-03$ | $2.7004 \mathrm{E}-03$ | $5.0923 \mathrm{E}-03$ | $1.2450 \mathrm{E}-02$ | $7.7000 \mathrm{E}-03$ |
| c02 | best | $-2.2807 \mathrm{E}+00$ | $1.9259 \mathrm{E}+00$ | $-1.8655 \mathrm{E}+00$ | $2.9092 \mathrm{E}+00$ | $-2.2609 \mathrm{E}+00$ | $2.3162 \mathrm{E}+00$ |
|  | Average | $-2.2702 \mathrm{E}+00$ | $3.0030 \mathrm{E}+00$ | $-1.2785 \mathrm{E}+00$ | $3.9574 \mathrm{E}+00$ | $-2.2423 \mathrm{E}+00$ | $4.4347 \mathrm{E}+00$ |
|  | St.d | $8.4000 \mathrm{E}-03$ | $5.0236 \mathrm{E}-01$ | $3.0969 \mathrm{E}-01$ | $4.2029 \mathrm{E}-01$ | $1.2930 \mathrm{E}-02$ | $8.3621 \mathrm{E}-01$ |
| c03 | best | $0.0000 \mathrm{E}+00$ | $1.5951 \mathrm{E}+11$ | $3.0113 \mathrm{E}+01$ | $3.9044 \mathrm{E}+09$ | $2.8673 \mathrm{E}+01$ | $1.0685 \mathrm{E}+11$ |
|  | Average | $1.0000 \mathrm{E}-04$ | $1.3018 \mathrm{E}+13$ | $1.1853 \mathrm{E}+02$ | $2.0792 \mathrm{E}+13$ | $7.3609 \mathrm{E}+01$ | $1.0177 \mathrm{E}+15$ |
|  | St.d | $4.9000 \mathrm{E}-04$ | $1.3674 \mathrm{E}+13$ | $4.0758 \mathrm{E}+01$ | $4.2487 \mathrm{E}+13$ | $4.5431 \mathrm{E}+01$ | $9.6758 \mathrm{E}+14$ |
| c04 | best | $-1.6641 \mathrm{E}+00$ | -3.3333E-06 | $4.2779 \mathrm{E}-02$ | $1.7617 \mathrm{E}-02$ | $1.6791 \mathrm{E}-01$ | $1.9145 \mathrm{E}-02$ |
|  | Average | $8.9271 \mathrm{E}+00$ | $1.8334 \mathrm{E}+00$ | $1.3748 \mathrm{E}+00$ | $1.4696 \mathrm{E}-01$ | $1.3119 \mathrm{E}+00$ | $4.2161 \mathrm{E}-01$ |
|  | St.d | $1.0413 \mathrm{E}+01$ | $6.0058 \mathrm{E}+00$ | $2.1426 \mathrm{E}+00$ | $1.2475 \mathrm{E}-01$ | $1.8201 \mathrm{E}+00$ | $2.8696 \mathrm{E}-01$ |
| c05 | best | $-1.7385 \mathrm{E}+02$ | $3.7216 \mathrm{E}+02$ | $2.5062 \mathrm{E}+02$ | $4.7150 \mathrm{E}+02$ | $1.4623 \mathrm{E}+02$ | $3.3424 \mathrm{E}+02$ |
|  | Average | $1.9452 \mathrm{E}+02$ | $5.1420 \mathrm{E}+02$ | $4.2385 \mathrm{E}+02$ | $5.3463 \mathrm{E}+02$ | $3.4648 \mathrm{E}+02$ | $5.2850 \mathrm{E}+02$ |
|  | St.d | $1.5427 \mathrm{E}+02$ | $4.9667 \mathrm{E}+01$ | $7.0301 \mathrm{E}+01$ | $3.0407 \mathrm{E}+01$ | $8.7585 \mathrm{E}+01$ | $5.6977 \mathrm{E}+01$ |
| c06 | best | $-1.9382 \mathrm{E}+02$ | $4.0309 \mathrm{E}+02$ | $3.5733 \mathrm{E}+02$ | $5.1301 \mathrm{E}+02$ | $2.3282 \mathrm{E}+01$ | $3.5902 \mathrm{E}+02$ |
|  | Average | $1.1422 \mathrm{E}+02$ | $5.2287 \mathrm{E}+02$ | $4.8261 \mathrm{E}+02$ | $5.6380 \mathrm{E}+02$ | $3.6310 \mathrm{E}+02$ | $5.5232 \mathrm{E}+02$ |
|  | St.d | $1.9705 \mathrm{E}+02$ | $6.0737 \mathrm{E}+01$ | $6.1308 \mathrm{E}+01$ | $2.5159 \mathrm{E}+01$ | $1.1472 \mathrm{E}+02$ | $5.2312 \mathrm{E}+01$ |
| c07 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.9633 \mathrm{E}+01$ | $2.4942 \mathrm{E}+01$ | $2.7981 \mathrm{E}-07$ | $6.1750 \mathrm{E}+00$ |
|  | Average | $4.7839 \mathrm{E}-01$ | $4.7839 \mathrm{E}-01$ | $2.0373 \mathrm{E}+07$ | $3.1394 \mathrm{E}+01$ | $1.5437 \mathrm{E}+07$ | $1.6185 \mathrm{E}+01$ |
|  | St.d | $1.3222 \mathrm{E}+00$ | $1.3222 \mathrm{E}+00$ | $7.0728 \mathrm{E}+07$ | $1.3626 \mathrm{E}+01$ | $4.2689 \mathrm{E}+07$ | $1.9577 \mathrm{E}+01$ |
| c08 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.4770 \mathrm{E}+01$ | $8.6880 \mathrm{E}+03$ | $3.3706 \mathrm{E}-01$ | $1.8225 \mathrm{E}+01$ |
|  | Average | $2.2044 \mathrm{E}+02$ | $5.9815 \mathrm{E}+01$ | $1.9627 \mathrm{E}+07$ | $2.7205 \mathrm{E}+04$ | $1.2329 \mathrm{E}+03$ | $1.2475 \mathrm{E}+02$ |
|  | St.d | $4.2871 \mathrm{E}+02$ | $1.7672 \mathrm{E}+02$ | $7.7824 \mathrm{E}+07$ | $1.2878 \mathrm{E}+04$ | $3.0737 \mathrm{E}+03$ | $3.1195 \mathrm{E}+02$ |
| c09 | best | $0.0000 \mathrm{E}+00$ | $9.8877 \mathrm{E}+12$ | $1.5969 \mathrm{E}+12$ | $1.3067 \mathrm{E}+13$ | $3.6393 \mathrm{E}+10$ | $1.6787 \mathrm{E}+13$ |
|  | Average | $7.9184 \mathrm{E}+11$ | $2.8973 \mathrm{E}+13$ | $6.1463 \mathrm{E}+12$ | $4.1919 \mathrm{E}+13$ | $2.1969 \mathrm{E}+12$ | $4.0761 \mathrm{E}+13$ |
|  | St.d | $1.9356 \mathrm{E}+12$ | $1.2011 \mathrm{E}+13$ | $4.5959 \mathrm{E}+12$ | $1.4552 \mathrm{E}+13$ | $2.9369 \mathrm{E}+12$ | $1.3102 \mathrm{E}+13$ |
| c10 | best | $3.1309 \mathrm{E}+01$ | $1.1382 \mathrm{E}+13$ | $2.7680 \mathrm{E}+12$ | $2.2768 \mathrm{E}+13$ | $1.7457 \mathrm{E}+11$ | $1.4301 \mathrm{E}+13$ |
|  | Average | $2.1642 \mathrm{E}+12$ | $2.4775 \mathrm{E}+13$ | $9.0669 \mathrm{E}+12$ | $4.0089 \mathrm{E}+13$ | $3.4309 \mathrm{E}+12$ | $3.8270 \mathrm{E}+13$ |
|  | St.d | $5.3144 \mathrm{E}+12$ | $8.3408 \mathrm{E}+12$ | $6.3115 \mathrm{E}+12$ | $1.2379 \mathrm{E}+13$ | $4.6492 \mathrm{E}+12$ | $1.1574 \mathrm{E}+13$ |
| c11 | best | -3.0787E-04 | -3.9234E-04 | -2.6345E-02 | -3.9646E-02 | -1.7421E-03 | -2.0838E-03 |
|  | Average | $4.1150 \mathrm{E}-02$ | $1.1300 \mathrm{E}-03$ | $4.8227 \mathrm{E}-02$ | -1.7251E-02 | $1.4168 \mathrm{E}-02$ | $3.1271 \mathrm{E}-02$ |
|  | St.d | $2.0760 \mathrm{E}-02$ | $5.2800 \mathrm{E}-03$ | $7.8317 \mathrm{E}-02$ | $1.2085 \mathrm{E}-02$ | $1.0500 \mathrm{E}-02$ | $1.4190 \mathrm{E}-02$ |
| c12 | best | $-3.3682 \mathrm{E}+03$ | -1.9926E-01 | $-9.0392 \mathrm{E}+02$ | $-1.0660 \mathrm{E}+02$ | $-6.7960 \mathrm{E}+02$ | -1.9925E-01 |
|  | Average | $-1.7505 \mathrm{E}+03$ | -1.9926E-01 | $-5.1517 \mathrm{E}+01$ | $-1.0725 \mathrm{E}+00$ | $-3.6917 \mathrm{E}+01$ | $5.8771 \mathrm{E}+00$ |
|  | St.d | $1.1057 \mathrm{E}+03$ | $0.0000 \mathrm{E}+00$ | $2.0168 \mathrm{E}+02$ | $2.4652 \mathrm{E}+01$ | $1.3870 \mathrm{E}+02$ | $2.4607 \mathrm{E}+01$ |
| c13 | best | $-6.8429 \mathrm{E}+01$ | $-6.6541 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-5.7684 \mathrm{E}+01$ | $-6.5033 \mathrm{E}+01$ | $-6.5611 \mathrm{E}+01$ |
|  | Average | $-6.5867 \mathrm{E}+01$ | $-6.5341 \mathrm{E}+01$ | $-6.8390 \mathrm{E}+01$ | $-5.4370 \mathrm{E}+01$ | $-6.1279 \mathrm{E}+01$ | $-6.3387 \mathrm{E}+01$ |
|  | St.d | $1.6725 \mathrm{E}+00$ | $8.5065 \mathrm{E}-01$ | $1.5502 \mathrm{E}-01$ | $1.2987 \mathrm{E}+00$ | $2.3874 \mathrm{E}+00$ | $1.2132 \mathrm{E}+00$ |
| c14 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.6332 \mathrm{E}+07$ | $1.2532 \mathrm{E}+13$ | $1.2366 \mathrm{E}+01$ | $7.8839 \mathrm{E}+12$ |
|  | Average | $9.8075 \mathrm{E}+05$ | $1.0958 \mathrm{E}+09$ | $8.5911 \mathrm{E}+09$ | $3.5324 \mathrm{E}+13$ | $2.6880 \mathrm{E}+06$ | $2.5483 \mathrm{E}+13$ |
|  | St.d | $3.4831 \mathrm{E}+06$ | $2.1367 \mathrm{E}+09$ | $1.6304 \mathrm{E}+10$ | $1.1312 \mathrm{E}+13$ | $1.0460 \mathrm{E}+07$ | $1.0502 \mathrm{E}+13$ |
| c15 | best | $2.1603 \mathrm{E}+01$ | $3.5006 \mathrm{E}+13$ | $2.1630 \mathrm{E}+13$ | $9.0749 \mathrm{E}+13$ | $4.0810 \mathrm{E}+13$ | $1.2240 \mathrm{E}+14$ |
|  | Average | $9.8781 \mathrm{E}+13$ | $1.0381 \mathrm{E}+14$ | $1.6530 \mathrm{E}+14$ | $2.3371 \mathrm{E}+14$ | $9.4942 \mathrm{E}+13$ | $2.2995 \mathrm{E}+14$ |
|  | St.d | $5.7336 \mathrm{E}+13$ | $4.3934 \mathrm{E}+13$ | $1.1241 \mathrm{E}+14$ | $6.7049 \mathrm{E}+13$ | $4.4549 \mathrm{E}+13$ | $5.2312 \mathrm{E}+13$ |
| c16 | best | $0.0000 \mathrm{E}+00$ | $1.0456 \mathrm{E}+00$ | $7.8000 \mathrm{E}-11$ | $1.1091 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.0799 \mathrm{E}+00$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $1.0734 \mathrm{E}+00$ | $4.3310 \mathrm{E}-09$ | $1.1790 \mathrm{E}+00$ | $2.7415 \mathrm{E}-02$ | $1.1292 \mathrm{E}+00$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $1.5060 \mathrm{E}-02$ | $1.9608 \mathrm{E}-08$ | $3.4530 \mathrm{E}-02$ | $9.6750 \mathrm{E}-02$ | $3.2360 \mathrm{E}-02$ |
| c17 | best | $0.0000 \mathrm{E}+00$ | $3.7835 \mathrm{E}+02$ | $1.2189 \mathrm{E}-02$ | $1.1301 \mathrm{E}+03$ | $2.2131 \mathrm{E}-01$ | $1.1314 \mathrm{E}+03$ |
|  | Average | $2.5243 \mathrm{E}-01$ | $7.3509 \mathrm{E}+02$ | $7.5812 \mathrm{E}+00$ | $1.9347 \mathrm{E}+03$ | $4.0382 \mathrm{E}+01$ | $1.7881 \mathrm{E}+03$ |
|  | St.d | $2.9517 \mathrm{E}-01$ | $2.3478 \mathrm{E}+02$ | $1.5809 \mathrm{E}+01$ | $5.1045 \mathrm{E}+02$ | $7.0749 \mathrm{E}+01$ | $3.3231 \mathrm{E}+02$ |
| c18 | best | $0.0000 \mathrm{E}+00$ | $6.7264 \mathrm{E}+03$ | $3.6159 \mathrm{E}+03$ | $2.4254 \mathrm{E}+04$ | $7.1509 \mathrm{E}+01$ | $1.9401 \mathrm{E}+04$ |
|  | Average | $2.4315 \mathrm{E}+03$ | $1.8047 \mathrm{E}+04$ | $1.2626 \mathrm{E}+04$ | $3.4018 \mathrm{E}+04$ | $6.0808 \mathrm{E}+03$ | $3.4594 \mathrm{E}+04$ |
|  | St.d | $4.7555 \mathrm{E}+03$ | $6.1590 \mathrm{E}+03$ | $6.1116 \mathrm{E}+03$ | $4.9550 \mathrm{E}+03$ | $5.4365 \mathrm{E}+03$ | $8.9789 \mathrm{E}+03$ |

Table C.6: Function values obtained by FRORI, SaDE and GAMPC with and without R2S for CEC2010 for 30D

| Problem | Criteria | FRORI-R2S | FRORI | SaDE-R2S | SaDE | GAMPC-R2S | GAMPC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | best | -8.2188E-01 | -8.2186E-01 | -8.2096E-01 | -8.1804E-01 | -8.2188E-01 | -8.2188E-01 |
|  | Average | -8.2010E-01 | -8.1954E-01 | -8.1755E-01 | -8.1793E-01 | -7.9294E-01 | -7.9193E-01 |
|  | St.d | $2.3400 \mathrm{E}-03$ | $2.7900 \mathrm{E}-03$ | $2.1400 \mathrm{E}-03$ | $4.0000 \mathrm{E}-05$ | $1.9906 \mathrm{E}-02$ | $1.9412 \mathrm{E}-02$ |
| c02 | best | $-2.0971 \mathrm{E}+00$ | $-2.0540 \mathrm{E}+00$ | $-2.2077 \mathrm{E}+00$ | $3.3416 \mathrm{E}+00$ | $-2.2726 \mathrm{E}+00$ | $3.4082 \mathrm{E}+00$ |
|  | Average | $-2.0265 \mathrm{E}+00$ | $-2.0015 \mathrm{E}+00$ | $-2.1019 \mathrm{E}+00$ | $3.9279 \mathrm{E}+00$ | $-2.2519 \mathrm{E}+00$ | $4.3779 \mathrm{E}+00$ |
|  | St.d | $4.0050 \mathrm{E}-02$ | $4.1710 \mathrm{E}-02$ | $4.1590 \mathrm{E}-02$ | $3.5800 \mathrm{E}-01$ | $3.9014 \mathrm{E}-02$ | $5.2499 \mathrm{E}-01$ |
| c03 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $3.7275 \mathrm{E}+01$ | $2.6711 \mathrm{E}+12$ | $0.0000 \mathrm{E}+00$ | $2.2513 \mathrm{E}+07$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $2.7527 \mathrm{E}+01$ | $5.3481 \mathrm{E}+01$ | $1.3364 \mathrm{E}+13$ | $1.7001 \mathrm{E}+00$ | $4.9244 \mathrm{E}+13$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $5.7347 \mathrm{E}+00$ | $9.9579 \mathrm{E}+00$ | $7.4735 \mathrm{E}+12$ | $8.5007 \mathrm{E}+00$ | $6.8614 \mathrm{E}+13$ |
| c04 | best | $-3.0155 \mathrm{E}-06$ | $-3.3333 \mathrm{E}-06$ | $6.9984 \mathrm{E}+00$ | $1.9672 \mathrm{E}-01$ | $2.3802 \mathrm{E}-03$ | $2.4993 \mathrm{E}-03$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $3.5903 \mathrm{E}+01$ | $1.5468 \mathrm{E}+00$ | $6.1171 \mathrm{E}-01$ | $6.8649 \mathrm{E}+00$ |
|  | St.d | $1.0000 \mathrm{E}-05$ | $0.0000 \mathrm{E}+00$ | $1.7274 \mathrm{E}+01$ | $2.2462 \mathrm{E}+00$ | $6.7104 \mathrm{E}-01$ | $1.2668 \mathrm{E}+01$ |
| c05 | best | $-4.8361 \mathrm{E}+02$ | $-4.8305 \mathrm{E}+02$ | $-2.0451 \mathrm{E}+02$ | $3.4584 \mathrm{E}+02$ | $4.5441 \mathrm{E}+02$ | $3.8579 \mathrm{E}+02$ |
|  | Average | $-4.8361 \mathrm{E}+02$ | $-4.8216 \mathrm{E}+02$ | $-1.4604 \mathrm{E}+02$ | $4.6744 \mathrm{E}+02$ | $5.2808 \mathrm{E}+02$ | $5.0918 \mathrm{E}+02$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $1.0092 \mathrm{E}+00$ | $1.3875 \mathrm{E}+02$ | $6.2522 \mathrm{E}+01$ | $3.7056 \mathrm{E}+01$ | $5.6067 \mathrm{E}+01$ |
| c06 | best | $-5.3064 \mathrm{E}+02$ | $-5.2962 \mathrm{E}+02$ | $-1.9106 \mathrm{E}+02$ | $4.2758 \mathrm{E}+02$ | $4.5949 \mathrm{E}+02$ | $3.8411 \mathrm{E}+02$ |
|  | Average | $-5.3064 \mathrm{E}+02$ | $-5.2849 \mathrm{E}+02$ | $-1.0098 \mathrm{E}+02$ | $5.3579 \mathrm{E}+02$ | $5.5631 \mathrm{E}+02$ | $5.5213 \mathrm{E}+02$ |
|  | St.d | $2.0700 \mathrm{E}-03$ | $1.0250 \mathrm{E}+00$ | $3.3722 \mathrm{E}+01$ | $4.8312 \mathrm{E}+01$ | $4.0248 \mathrm{E}+01$ | $4.9792 \mathrm{E}+01$ |
| c07 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $8.1494 \mathrm{E}+00$ | $6.2755 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $1.1092 \mathrm{E}+07$ | $0.0000 \mathrm{E}+00$ | $3.1043 \mathrm{E}+01$ | $2.4564 \mathrm{E}+01$ | $4.7839 \mathrm{E}-01$ | $4.7839 \mathrm{E}-01$ |
|  | St.d | $3.8390 \mathrm{E}+07$ | $0.0000 \mathrm{E}+00$ | $2.2553 \mathrm{E}+01$ | $1.8751 \mathrm{E}+01$ | $1.3222 \mathrm{E}+00$ | $1.3222 \mathrm{E}+00$ |
| c08 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.6065 \mathrm{E}+01$ | $5.5460 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $1.1759 \mathrm{E}+01$ | $3.9280 \mathrm{E}+00$ | $2.6311 \mathrm{E}+02$ | $1.7532 \mathrm{E}+02$ | $3.5933 \mathrm{E}+02$ | $3.5599 \mathrm{E}+02$ |
|  | St.d | $2.7838 \mathrm{E}+01$ | $1.9640 \mathrm{E}+01$ | $7.7430 \mathrm{E}+02$ | $3.8144 \mathrm{E}+02$ | $7.5827 \mathrm{E}+02$ | $7.5970 \mathrm{E}+02$ |
| c09 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $6.9057 \mathrm{E}+01$ | $5.2901 \mathrm{E}+12$ | $0.0000 \mathrm{E}+00$ | $1.7162 \mathrm{E}+13$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $2.0311 \mathrm{E}+02$ | $1.0789 \mathrm{E}+06$ | $2.3023 \mathrm{E}+13$ | $1.6482 \mathrm{E}+13$ | $3.6549 \mathrm{E}+13$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $8.3727 \mathrm{E}+02$ | $2.5796 \mathrm{E}+06$ | $1.1961 \mathrm{E}+13$ | $1.5558 \mathrm{E}+13$ | $1.1175 \mathrm{E}+13$ |
| c10 | best | $6.5470 \mathrm{E}+00$ | $3.1310 \mathrm{E}+01$ | $7.1281 \mathrm{E}+01$ | $1.8188 \mathrm{E}+12$ | $0.0000 \mathrm{E}+00$ | $1.5179 \mathrm{E}+13$ |
|  | Average | $6.5470 \mathrm{E}+00$ | $3.1321 \mathrm{E}+01$ | $2.1117 \mathrm{E}+06$ | $2.3065 \mathrm{E}+13$ | $1.4739 \mathrm{E}+13$ | $3.5793 \mathrm{E}+13$ |
|  | St.d | $1.0000 \mathrm{E}-05$ | $1.4550 \mathrm{E}-02$ | $4.5796 \mathrm{E}+06$ | $1.1001 \mathrm{E}+13$ | $1.6596 \mathrm{E}+13$ | $1.0174 \mathrm{E}+13$ |
| c11 | best | -1.6721E-02 | -3.9234E-04 | $-1.6287 \mathrm{E}+00$ | $-4.5147 \mathrm{E}-02$ | -3.9216E-04 | -3.9234E-04 |
|  | Average | $1.9930 \mathrm{E}-02$ | -3.9000E-04 | -1.8936E-01 | $1.0804 \mathrm{E}-02$ | $1.9630 \mathrm{E}-03$ | $4.9454 \mathrm{E}-03$ |
|  | St.d | $1.3470 \mathrm{E}-02$ | $0.0000 \mathrm{E}+00$ | $7.0524 \mathrm{E}-01$ | $4.1880 \mathrm{E}-02$ | $6.3287 \mathrm{E}-03$ | $8.7359 \mathrm{E}-03$ |
| c12 | best | $-1.5280 \mathrm{E}+02$ | $-1.2131 \mathrm{E}+02$ | $-9.1848 \mathrm{E}+02$ | $-2.2038 \mathrm{E}+02$ | $-5.7192 \mathrm{E}+02$ | -1.9926E-01 |
|  | Average | $-1.0120 \mathrm{E}+01$ | $-5.0438 \mathrm{E}+00$ | $-4.4742 \mathrm{E}+02$ | $-1.5673 \mathrm{E}+00$ | $-3.7261 \mathrm{E}+01$ | -1.9926E-01 |
|  | St.d | $3.0764 \mathrm{E}+01$ | $2.4223 \mathrm{E}+01$ | $4.1750 \mathrm{E}+02$ | $4.8439 \mathrm{E}+01$ | $1.6099 \mathrm{E}+02$ | $1.1688 \mathrm{E}-07$ |
| c13 | best | $-6.8428 \mathrm{E}+01$ | $-6.8428 \mathrm{E}+01$ | $-6.8429 \mathrm{E}+01$ | $-6.8186 \mathrm{E}+01$ | -6.4908E+01 | $-6.4908 \mathrm{E}+01$ |
|  | Average | -6.6472E+01 | $-6.8389 \mathrm{E}+01$ | -6.8291E+01 | $-6.7756 \mathrm{E}+01$ | $-6.2380 \mathrm{E}+01$ | $-6.2380 \mathrm{E}+01$ |
|  | St.d | $8.5631 \mathrm{E}+00$ | $1.0834 \mathrm{E}-01$ | $6.7939 \mathrm{E}-01$ | $1.9539 \mathrm{E}-01$ | $1.5458 \mathrm{E}+00$ | $1.5458 \mathrm{E}+00$ |
| c14 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.1754 \mathrm{E}+00$ | $1.8942 \mathrm{E}+01$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ |
|  | Average | $1.5946 \mathrm{E}-01$ | $1.5946 \mathrm{E}-01$ | $3.1266 \mathrm{E}+01$ | $2.1450 \mathrm{E}+03$ | $1.9795 \mathrm{E}+05$ | $1.9795 \mathrm{E}+05$ |
|  | St.d | 7.9732E-01 | $7.9732 \mathrm{E}-01$ | $2.6813 \mathrm{E}+01$ | $1.0215 \mathrm{E}+04$ | $7.7267 \mathrm{E}+05$ | $7.7267 \mathrm{E}+05$ |
| c15 | best | $2.1603 \mathrm{E}+01$ | $2.1603 \mathrm{E}+01$ | $4.4942 \mathrm{E}+00$ | $2.9457 \mathrm{E}+13$ | $7.3110 \mathrm{E}+13$ | $7.3110 \mathrm{E}+13$ |
|  | Average | $2.1604 \mathrm{E}+01$ | $2.1604 \mathrm{E}+01$ | $4.2988 \mathrm{E}+01$ | $6.5947 \mathrm{E}+13$ | $1.4010 \mathrm{E}+14$ | $1.4010 \mathrm{E}+14$ |
|  | St.d | $9.0000 \mathrm{E}-05$ | $9.0000 \mathrm{E}-05$ | $3.0610 \mathrm{E}+01$ | $2.4612 \mathrm{E}+13$ | $3.3911 \mathrm{E}+13$ | $3.3911 \mathrm{E}+13$ |
| c16 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.0927 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $1.0838 \mathrm{E}+00$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $5.3000 \mathrm{E}-04$ | $6.0200 \mathrm{E}-10$ | $1.1309 \mathrm{E}+00$ | $4.4158 \mathrm{E}-02$ | $1.1410 \mathrm{E}+00$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $2.6300 \mathrm{E}-03$ | $0.0000 \mathrm{E}+00$ | $2.5650 \mathrm{E}-02$ | $1.8440 \mathrm{E}-01$ | $2.8925 \mathrm{E}-02$ |
| c17 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $6.9643 \mathrm{E}-03$ | $5.3205 \mathrm{E}+02$ | $1.8351 \mathrm{E}+00$ | $9.6259 \mathrm{E}+02$ |
|  | Average | $6.9998 \mathrm{E}-01$ | $1.1333 \mathrm{E}-01$ | $5.8986 \mathrm{E}-01$ | $1.3146 \mathrm{E}+03$ | $4.2820 \mathrm{E}+02$ | $1.8612 \mathrm{E}+03$ |
|  | St.d | $1.6847 \mathrm{E}+00$ | $2.7722 \mathrm{E}-01$ | $9.4236 \mathrm{E}-01$ | $5.3577 \mathrm{E}+02$ | $5.1177 \mathrm{E}+02$ | $4.7196 \mathrm{E}+02$ |
| c18 | best | $0.0000 \mathrm{E}+00$ | $0.0000 \mathrm{E}+00$ | $2.5852 \mathrm{E}-01$ | $1.3728 \mathrm{E}+04$ | $2.2600 \mathrm{E}-10$ | $1.9605 \mathrm{E}+04$ |
|  | Average | $0.0000 \mathrm{E}+00$ | $6.4572 \mathrm{E}-01$ | $3.2206 \mathrm{E}+01$ | $2.0953 \mathrm{E}+04$ | $1.6110 \mathrm{E}+04$ | $2.7162 \mathrm{E}+04$ |
|  | St.d | $0.0000 \mathrm{E}+00$ | $1.9996 \mathrm{E}+00$ | $3.8816 \mathrm{E}+01$ | $4.9146 \mathrm{E}+03$ | $1.1335 \mathrm{E}+04$ | $4.8482 \mathrm{E}+03$ |

Table C.7: Function values obtained by proposed algorithm with different $C S$ values of $C S=1,25,50,75$ and 100 generations

|  | $\mathrm{CS}=1$ |  | $\mathrm{CS}=25$ |  | $\mathrm{CS}=50$ |  | $\mathrm{CS}=75$ |  | $\mathrm{CS}=100$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. | Mean | Std. |
| g01 | $-1.476563 \mathrm{E}+01$ | $4.784160 \mathrm{E}-01$ | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
| g02 | -8.034874E-01 | $4.503080 \mathrm{E}-04$ | -8.03584E-01 | $7.46577 \mathrm{E}-05$ | -8.03584E-01 | $7.46577 \mathrm{E}-05$ | -8.03579E-01 | $7.57183 \mathrm{E}-05$ | -8.03579E-01 | $7.57183 \mathrm{E}-05$ |
| g03 | $-1.000500 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $-1.00050 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.00050 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.00050 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.00050 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ |
| g04 | $-3.066554 \mathrm{E}+04$ | $4.000000 \mathrm{E}-12$ | $-3.06655 \mathrm{E}+04$ | $4.00000 \mathrm{E}-12$ | $-3.06655 \mathrm{E}+04$ | $4.00000 \mathrm{E}-12$ | $-3.06655 \mathrm{E}+04$ | $4.00000 \mathrm{E}-12$ | $-3.06655 \mathrm{E}+04$ | $4.00000 \mathrm{E}-12$ |
| g05 | $5.151055 \mathrm{E}+03$ | $2.221757 \mathrm{E}+01$ | $5.12650 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ | $5.12650 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ | $5.12650 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ | $5.12650 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ |
| g06 | $-6.961814 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ | $-6.96181 \mathrm{E}+03$ | $0.00000 \mathrm{E}+00$ | $-6.96181 \mathrm{E}+03$ | $0.00000 \mathrm{E}+00$ | $-6.96181 \mathrm{E}+03$ | $0.00000 \mathrm{E}+00$ | $-6.96181 \mathrm{E}+03$ | $0.00000 \mathrm{E}+00$ |
| g07 | $2.464802 \mathrm{E}+01$ | $1.709034 \mathrm{E}+00$ | $2.43062 \mathrm{E}+01$ | $6.49500 \mathrm{E}-09$ | $2.43062 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $2.43062 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $2.43062 \mathrm{E}+01$ | $6.00000 \mathrm{E}-12$ |
| g08 | $-9.582504 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ | -9.58250E-02 | $0.00000 \mathrm{E}+00$ | $-9.58250 \mathrm{E}-02$ | $0.00000 \mathrm{E}+00$ | -9.58250E-02 | $0.00000 \mathrm{E}+00$ | $-9.58250 \mathrm{E}-02$ | $0.00000 \mathrm{E}+00$ |
| g09 | $6.806301 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ | $6.80630 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $6.80630 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $6.80630 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $6.80630 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ |
| g10 | $7.049248 \mathrm{E}+03$ | $1.330000 \mathrm{E}-10$ | $7.04925 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ | $7.04925 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ | $7.04925 \mathrm{E}+03$ | $4.00000 \mathrm{E}-12$ | $7.04925 \mathrm{E}+03$ | $3.00000 \mathrm{E}-12$ |
| g11 | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $7.49900 \mathrm{E}-01$ | $0.00000 \mathrm{E}+00$ | $7.49900 \mathrm{E}-01$ | $0.00000 \mathrm{E}+00$ | $7.49900 \mathrm{E}-01$ | $0.00000 \mathrm{E}+00$ | $7.49900 \mathrm{E}-01$ | $0.00000 \mathrm{E}+00$ |
| g12 | -9.996006E-01 | $3.056963 \mathrm{E}-04$ | $-1.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ |
| g13 | $5.394151 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ | $5.39415 \mathrm{E}-02$ | $0.00000 \mathrm{E}+00$ | $5.39415 \mathrm{E}-02$ | $0.00000 \mathrm{E}+00$ | $5.39415 \mathrm{E}-02$ | $0.00000 \mathrm{E}+00$ | $5.39415 \mathrm{E}-02$ | $0.00000 \mathrm{E}+00$ |
| g14 | $-4.776489 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ | $-4.77649 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $-4.77649 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $-4.77649 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ | $-4.77649 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
| g15 | $9.617150 \mathrm{E}+02$ | $1.000000 \mathrm{E}-12$ | $9.61715 \mathrm{E}+02$ | $1.00000 \mathrm{E}-12$ | $9.61715 \mathrm{E}+02$ | $1.00000 \mathrm{E}-12$ | $9.61715 \mathrm{E}+02$ | $1.00000 \mathrm{E}-12$ | $9.61715 \mathrm{E}+02$ | $1.00000 \mathrm{E}-12$ |
| g16 | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $-1.90516 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.90516 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.90516 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-1.90516 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ |
| g17 | $8.860013 \mathrm{E}+03$ | $2.251566 \mathrm{E}+01$ | $8.86001 \mathrm{E}+03$ | $2.25157 \mathrm{E}+01$ | $8.86001 \mathrm{E}+03$ | $2.25157 \mathrm{E}+01$ | $8.86001 \mathrm{E}+03$ | $2.25157 \mathrm{E}+01$ | $8.86001 \mathrm{E}+03$ | $2.25157 \mathrm{E}+01$ |
| g18 | -7.325384E-01 | $1.425095 \mathrm{E}-01$ | -7.97706E-01 | $1.01180 \mathrm{E}-01$ | $-7.49903 \mathrm{E}-01$ | $1.71863 \mathrm{E}-01$ | $-7.83775 \mathrm{E}-01$ | $1.21678 \mathrm{E}-01$ | $-7.60720 \mathrm{E}-01$ | $1.57780 \mathrm{E}-01$ |
| g19 | $3.265559 \mathrm{E}+01$ | $5.890000 \mathrm{E}-10$ | $3.26556 \mathrm{E}+01$ | $7.00000 \mathrm{E}-11$ | $3.26556 \mathrm{E}+01$ | $9.60000 \mathrm{E}-11$ | $3.26556 \mathrm{E}+01$ | $9.60000 \mathrm{E}-11$ | $3.26556 \mathrm{E}+01$ | $9.90000 \mathrm{E}-11$ |
| g21 | $2.303989 \mathrm{E}+02$ | $6.002149 \mathrm{E}+01$ | $2.30399 \mathrm{E}+02$ | $6.00215 \mathrm{E}+01$ | $2.30399 \mathrm{E}+02$ | $6.00215 \mathrm{E}+01$ | $2.30399 \mathrm{E}+02$ | $6.00215 \mathrm{E}+01$ | $2.30399 \mathrm{E}+02$ | $6.00215 \mathrm{E}+01$ |
| g23 | $-4.000551 \mathrm{E}+02$ | $3.060520 \mathrm{E}-07$ | $-4.00055 \mathrm{E}+02$ | $1.27000 \mathrm{E}-10$ | $-4.00055 \mathrm{E}+02$ | $1.27000 \mathrm{E}-10$ | $-4.00055 \mathrm{E}+02$ | $1.27000 \mathrm{E}-10$ | $-4.00055 \mathrm{E}+02$ | $1.27000 \mathrm{E}-10$ |
| g24 | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $-5.50801 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-5.50801 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-5.50801 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $-5.50801 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ |


|  |  | 00＋ $70000000^{\circ}$ | 00＋HEL0809 $\mathrm{S}^{-}$ | 0 | － | 0 | － | $7^{\text {a }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| L0－G007089\％ | 70＋ 669 T966 $\varepsilon^{-}$ | 80－H007zたe． | 70＋马LScou0－ | 0I－G00002て＇ |  | 00＋Hz867906 | $70+$ 7696996 $8^{-}$ | $87^{8 .}$ |
| L0＋H88LZ00．9 | z0＋ 9986808.7 | L0＋GL8LZ00．9 | 20＋g98680¢ |  | 70＋H68680¢ 7 | L0＋HI¢6696．${ }_{\text {c }}$ |  | L $\square^{\text {8 }}$ |
| ع0－H88L879 2 | 10＋ 0 ¢ $60997 \cdot 8$ | LL－H00000才＇${ }^{\text {L }}$ | ＋ 66959968 | 02 | \％ | ¢G08 | $97^{\circ} \mathrm{E}$ | $61^{8}$ |
| 10－Hz8L0ze\％ | L0－499L9¢9\％ $\mathrm{g}^{-}$ | 10－H869zた0 | 18079 $\mathrm{L}^{-}$ | L0－セt08LL0． | L0－G690LL6 L－ |  | L0－G96L66L：${ }^{-}$ | $\mathrm{L}^{\text {8 }}$ |
| L0＋H7986\＆才，$冖$ | 80＋HEt¢098．8 |  | － 9967998 | ＋g99stsz | ＋get00988 | L0＋H0¢807T＇8 | L97L98 | $\mathrm{I}^{8}$ |
| ¢0－H969089 ${ }^{\text {I }}$ | $\mathrm{G}^{\text {a }} \mathrm{I}^{-}$ | H00000000 |  | H000000＊0 | ＋马gctco6 ${ }^{-1}$ | H000000 | Ggico6 | $\mathrm{I}^{8}$ |
|  | 70＋H0SLLI96 | ZI－H000000＇I | 70＋GOSLLI96 | 00000 | ct | 000000 ${ }^{\text {I }}$ | 70＋G0¢LLI96 | $\mathrm{I}^{8}$ |
| 80－－ヵt $26808^{\text {－}}$ | L0 | 00＋H000000＇0 | L0＋马68792Lも－ | 00＋H000000＊0 | $\square^{-}$ | 0000 0 | L0＋G68t9 ${ }^{\circ}$ | $\mathrm{L}^{8}$ |
| ¢0－G\＆6I889．c | 20 | 00＋H00000000 | c | 00＋H000000＇0 | 70－HLctinec | 00＋ | 20－GISIt689 | $\mathrm{L}^{\text {8 }}$ |
| 00＋ $70000000^{\circ}$ | 00 | $00+40000000^{\circ}$ | $00+$ H000000 ${ }^{\text {－}}$－ | $00+$ H200000000 | $000{ }^{\text {－}}$－ | 0000 | $00+$ H000000 ${ }^{\text {－}}$－ | $\mathrm{L}^{8}$ |
| $00+$ H000000 0 | L0－H00066キ 2 | 00＋H000000．0 | L0－H00066才＇L | $00+70000000^{\circ}$ | L0－H000667 $\mathrm{L}^{\text {L }}$ | 0 | L0－H000667 L $^{\text {L }}$ | 1.8 |
| 00 |  | $0 \mathrm{~L}-$ | ＋ | $00000 \cdot 8$ | 80＋H8もて6も0 2 | L－G000000＊$\ddagger$ |  | $\mathrm{I}^{\circ}$ |
| 20－H0L06zL． | 70＋GLIt908．9 | 00＋H000000＇0 | 70＋自10¢908．9 | 00＋H000000．0 | 70＋马L0¢908．9 | 20－－ALZL600＇L | 70＋ | $60^{\circ}$ |
| 00＋H00000000 | 70－马70¢789：6－ | 00＋H00000000 | F0¢z88： 6 | 00＋ $2000000^{\circ} 0$ | 70－gt0¢ $288^{\circ} 6^{-}$ | 00＋H000000 0 | 0－马゙¢09z89 $6^{-}$ | $80^{\circ}$ |
|  | L0＋Gt96IEt＇\％ | 2L－H0000006 |  | 60－G000967＊9 | 10＋马LZ90¢も $冖$ | 70－G¢¢¢7\％\％＇I | 80 | 208 |
| ［＇8 | ¢0 | 00 | ع0＋島亡18L96．9－ | 00＋ 00000000 |  | 00＋G0000000 | 0＋車ti8196．9 | $90^{8}$ |
| L0－H0Lz09z： |  | L－G000000＇8 | $0+$ H $26797 \mathrm{I}^{\circ} \mathrm{C}$ | L－H000000＇\＆ | 80＋H26797I．9 | ZI－H000000＇\＆ | 80＋H26797I ${ }^{\circ}$ | $0^{8}$ |
| 80－H99I6もでI | F0＋ | －H000000＊ | キ0＋ | H000000 ${ }^{\text {t }}$ | ¢－ | 00000 T | $0^{-}$ | $50^{\circ}$ |
| L0－H0才LLZ6． | $00+\mathrm{H} 00 \mathrm{~g} 000 \mathrm{I}^{-}$ | 00＋H0000000 | OG000 ${ }^{\text {－}}$ | 00＋ $2000000^{\circ} 0$ | 00＋G00¢000 ${ }^{\text {－}}{ }^{-}$ | 00＋H0000000 | 00＋ $700 \mathrm{~g} 000{ }^{-} \mathrm{L}^{-}$ | ¢0 |
| 90－H26I8tた | L0－Az¢8980 ${ }^{-}$ | ¢0－Hetce6t | L0－Hセt8980 ${ }^{-}$ | ¢0－H892997\％ | L0－Я988980 ${ }^{-}$ | ¢0－TLL8988．8 | 0－马LI9980 ${ }^{\circ}$ | $70^{8}$ |
| G9L8\％\％I＇L | L0＋H087667 | ZL－H000000＇L | ＋ 7000000 | H00000 | L0＋H00000 | H000000 0 | ＋ H 000009 | L0 ${ }^{\text {8 }}$ |
| ＋S | иеә | P7S | บеәJ | P7S | игәJ | P7S | теәЈ |  |
|  |  | $\mathrm{XVNS}_{\text {昌过L }} 0$ |  |  |  |  |  |  |



## Appendix D

Table D.1: Function values obtained by Var1, Var2 and Var3

| Problem |  | Var1 | Var2 | Var3 |
| :---: | :---: | :---: | :---: | :---: |
| c01 | Best | -7.4731036E-01 | -7.4731036E-01 | -7.4731036E-01 |
|  | Mean | -7.4731036E-01 | $-7.4731036 \mathrm{E}-01$ | -7.4731036E-01 |
|  | Std. | $1.7044364 \mathrm{E}-14$ | $4.2951518 \mathrm{E}-09$ | $4.2126954 \mathrm{E}-15$ |
| c02 | Best | $-2.2757892 \mathrm{E}+00$ | $-2.2776142 \mathrm{E}+00$ | $-2.2629924 \mathrm{E}+00$ |
|  | Mean | $-2.1826480 \mathrm{E}+00$ | $-2.1892114 \mathrm{E}+00$ | $-2.1994706 \mathrm{E}+00$ |
|  | Std. | 1.3343611E-01 | $1.9214218 \mathrm{E}-01$ | $2.0108304 \mathrm{E}-02$ |
| c03 | Best | $1.2534573 \mathrm{E}-22$ | $1.0609288 \mathrm{E}-16$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $4.6152872 \mathrm{E}+00$ | $5.3253314 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $4.5256615 \mathrm{E}+00$ | $4.4377762 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
| c04 | Best | -1.0000000E-05 | -9.9999296E-06 | -1.0000000E-05 |
|  | Mean | -6.2396532E-06 | -9.0760634E-06 | -1.0000000E-05 |
|  | Std. | $1.3565220 \mathrm{E}-05$ | $4.6012250 \mathrm{E}-06$ | $0.0000000 \mathrm{E}+00$ |
| c05 | Best | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ |
|  | Mean | $-4.8359738 \mathrm{E}+02$ | $-4.8358682 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ |
|  | Std. | $2.3975582 \mathrm{E}-02$ | $5.2893881 \mathrm{E}-02$ | $3.5059842 \mathrm{E}-13$ |
| c06 | Best | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ |
|  | Mean | $-5.7863219 \mathrm{E}+02$ | $-5.7865931 \mathrm{E}+02$ | $-5.7860234 \mathrm{E}+02$ |
|  | Std. | $5.9729751 \mathrm{E}-02$ | $7.3512507 \mathrm{E}-03$ | $2.7507558 \mathrm{E}-01$ |
| c07 | Best | $1.2889326 \mathrm{E}-17$ | $1.5558047 \mathrm{E}-14$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $6.9695739 \mathrm{E}-15$ | $8.6994386 \mathrm{E}-11$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $8.5946129 \mathrm{E}-15$ | $1.3308933 \mathrm{E}-10$ | $0.0000000 \mathrm{E}+00$ |
| c08 | Best | $3.0898267 \mathrm{E}-20$ | $7.6778018 \mathrm{E}-19$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $5.6973213 \mathrm{E}+00$ | $6.0197595 \mathrm{E}+00$ | $8.1968334 \mathrm{E}+00$ |
|  | Std. | $4.8352056 \mathrm{E}+00$ | $4.9760659 \mathrm{E}+00$ | $4.5961673 \mathrm{E}+00$ |
| c09 | Best | $5.7677413 \mathrm{E}-18$ | $3.1402380 \mathrm{E}-15$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $1.1967838 \mathrm{E}-11$ | $6.1989162 \mathrm{E}-01$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $5.9498535 \mathrm{E}-11$ | $1.5951491 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
| c10 | Best | 4.7716082E-20 | $4.6085354 \mathrm{E}-18$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $2.8633987 \mathrm{E}-02$ | $1.3192800 \mathrm{E}+01$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $1.4316979 \mathrm{E}-01$ | $3.6585559 \mathrm{E}+01$ | $0.0000000 \mathrm{E}+00$ |
| c11 | Best | -1.5227132E-03 | -1.5227132E-03 | -1.5227132E-03 |
|  | Mean | -1.5227132E-03 | -1.5227124E-03 | -1.5227132E-03 |
|  | Std. | $1.2424959 \mathrm{E}-12$ | $1.6725789 \mathrm{E}-09$ | $1.4407112 \mathrm{E}-17$ |
| c12 | Best | $-5.6838283 \mathrm{E}+02$ | $-5.6838283 \mathrm{E}+02$ | $-3.0548877 \mathrm{E}+02$ |
|  | Mean | $-6.6966693 \mathrm{E}+01$ | $-8.4840376 \mathrm{E}+01$ | -3.4183177E+01 |
|  | Std. | $1.3607554 \mathrm{E}+02$ | $1.3376205 \mathrm{E}+02$ | $8.7249340 \mathrm{E}+01$ |
| c13 | Best | $-6.8429365 \mathrm{E}+01$ | $-6.8429365 \mathrm{E}+01$ | $-6.8429365 \mathrm{E}+01$ |
|  | Mean | $-6.8335459 \mathrm{E}+01$ | $-6.8306542 \mathrm{E}+01$ | $-6.8429295 \mathrm{E}+01$ |
|  | Std. | $2.3571787 \mathrm{E}-01$ | $1.5732544 \mathrm{E}-01$ | $3.0535111 \mathrm{E}-04$ |
| c14 | Best | $8.4138513 \mathrm{E}-14$ | $1.6716963 \mathrm{E}-11$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $8.2686246 \mathrm{E}-08$ | $1.5951589 \mathrm{E}-04$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $3.5864485 \mathrm{E}-07$ | 5.7217915E-04 | $0.0000000 \mathrm{E}+00$ |


| $c 15$ | Best | $2.9163009 \mathrm{E}-16$ | $2.2031668 \mathrm{E}-11$ | $0.0000000 \mathrm{E}+00$ |
| :---: | :---: | :---: | :---: | :---: |
|  | Mean | $1.1761112 \mathrm{E}+00$ | $1.6491965 \mathrm{E}+00$ | $2.1738482 \mathrm{E}-27$ |
|  | Std. | $1.7483424 \mathrm{E}+00$ | $1.9056737 \mathrm{E}+00$ | $9.9021887 \mathrm{E}-27$ |
| c 16 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $0.0000000 \mathrm{E}+00$ | $8.6597396 \mathrm{E}-16$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $0.0000000 \mathrm{E}+00$ | $4.2610007 \mathrm{E}-15$ | $0.0000000 \mathrm{E}+00$ |
| c 17 | Best | $1.5819620 \mathrm{E}-19$ | $1.3491504 \mathrm{E}-17$ | $9.8774013 \mathrm{E}-29$ |
|  | Mean | $6.0354440 \mathrm{E}-13$ | $4.3876936 \mathrm{E}-02$ | $2.5313067 \mathrm{E}-22$ |
|  | Std. | $2.6064242 \mathrm{E}-12$ | $2.1938468 \mathrm{E}-01$ | $1.0078392 \mathrm{E}-21$ |
| c 18 | Best | $4.8440270 \mathrm{E}-21$ | $2.6472429 \mathrm{E}-18$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $1.5302277 \mathrm{E}-18$ | $3.9576223 \mathrm{E}-15$ | $7.3364064 \mathrm{E}-31$ |
|  | Std. | $4.3928235 \mathrm{E}-18$ | $6.2515289 \mathrm{E}-15$ | $1.8450015 \mathrm{E}-30$ |

Table D.2: Function values obtained by the proposed MEA-LS-R2S with different $C S$ values of $C S=25,50,75$ and 100 generations

| Problem | criteria | CS=25 | CS=50 | CS=75 | $\mathrm{CS}=100$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | Best | -7.4731036E-01 | -7.4731036E-01 | -7.4731036E-01 | -7.4731036E-0 |
|  | Mean | -7.4731036E-01 | -7.4731036E-01 | -7.4731036E-01 | -7.4731036E-01 |
|  | Std. | $2.6814434 \mathrm{E}-16$ | 5.8095631E-15 | 4.1943074E-15 | $2.8214377 \mathrm{E}-16$ |
| c02 | Best | $-2.2366334 \mathrm{E}+00$ | $-2.2396573 \mathrm{E}+00$ | $-2.2285037 \mathrm{E}+00$ | $-2.2332659 \mathrm{E}+00$ |
|  | Mean | $-2.2059516 \mathrm{E}+00$ | $-2.1996897 \mathrm{E}+00$ | $-2.2035334 \mathrm{E}+00$ | $-2.1997141 \mathrm{E}+00$ |
|  | Std. | $1.6278231 \mathrm{E}-02$ | $1.9563403 \mathrm{E}-02$ | $1.2078798 \mathrm{E}-02$ | $1.9346828 \mathrm{E}-02$ |
| c03 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $6.4785044 \mathrm{E}-27$ | $8.0133122 \mathrm{E}-26$ |
|  | Std. | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $2.2422708 \mathrm{E}-26$ | $2.2460370 \mathrm{E}-25$ |
| c04 | Best | -1.0000000E-05 | -1.0000000E-05 | -1.0000000E-05 | -1.0000000E-05 |
|  | Mean | -1.0000000E-05 | -1.0000000E-05 | -1.0000000E-05 | -1.0000000E-05 |
|  | Std. | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
| c05 | Best | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ |
|  | Mean | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ | $-4.8361062 \mathrm{E}+02$ |
|  | Std. | $3.4809343 \mathrm{E}-13$ | $1.5653457 \mathrm{E}-13$ | $2.7433453 \mathrm{E}-13$ | $9.0756183 \mathrm{E}-13$ |
| c06 | Best | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ |
|  | Mean | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ | $-5.7866237 \mathrm{E}+02$ | $-5.7866158 \mathrm{E}+02$ |
|  | Std. | $3.6545205 \mathrm{E}-13$ | $3.6692269 \mathrm{E}-13$ | $5.5533722 \mathrm{E}-12$ | $2.8471911 \mathrm{E}-03$ |
| c07 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $0.0000000 \mathrm{E}+00$ | $1.0529321 \mathrm{E}-28$ | $2.9970601 \mathrm{E}-28$ | $1.2638084 \mathrm{E}-27$ |
|  | Std. | $0.0000000 \mathrm{E}+00$ | $3.1964204 \mathrm{E}-28$ | $6.6008625 \mathrm{E}-28$ | $4.9586700 \mathrm{E}-27$ |
| c08 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $9.1761442 \mathrm{E}+00$ | $9.7437742 \mathrm{E}+00$ | $1.0051467 \mathrm{E}+01$ | $1.0474381 \mathrm{E}+01$ |
|  | Std. | $4.0880393 \mathrm{E}+00$ | $3.2426056 \mathrm{E}+00$ | $3.0260314 \mathrm{E}+00$ | $2.1845406 \mathrm{E}+00$ |
| c09 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $0.0000000 \mathrm{E}+00$ | $6.1089389 \mathrm{E}-29$ | $3.0342746 \mathrm{E}-28$ | $3.4735123 \mathrm{E}-28$ |
|  | Std. | $0.0000000 \mathrm{E}+00$ | $3.0544694 \mathrm{E}-28$ | $1.2792927 \mathrm{E}-27$ | $8.7394677 \mathrm{E}-28$ |
| c10 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $5.0487098 \mathrm{E}-29$ | $4.0945036 \mathrm{E}-28$ | 7.4619931E-28 | $1.3202376 \mathrm{E}-26$ |
|  | Std. | $2.5243549 \mathrm{E}-28$ | $1.7908399 \mathrm{E}-27$ | $2.2503728 \mathrm{E}-27$ | $3.4953462 \mathrm{E}-26$ |
| c11 | Best | -1.5227132E-03 | -1.5227132E-03 | -1.5227132E-03 | -1.5227132E-03 |
|  | Mean | -1.5227132E-03 | -1.5227132E-03 | -1.5227132E-03 | -1.5227132E-03 |
|  | Std. | $6.6938692 \mathrm{E}-18$ | $7.1153736 \mathrm{E}-18$ | $5.4665369 \mathrm{E}-18$ | $1.1295233 \mathrm{E}-17$ |
| c12 | Best | $-1.1602762 \mathrm{E}+02$ | -1.1602762E+02 | $-1.1432711 \mathrm{E}+02$ | $-1.2667138 \mathrm{E}+01$ |
|  | Mean | $-1.6388441 \mathrm{E}+01$ | $-5.7620655 \mathrm{E}+00$ | $-5.2630758 \mathrm{E}+00$ | $-1.1966772 \mathrm{E}+00$ |
|  | Std. | $3.7445613 \mathrm{E}+01$ | $2.3196732 \mathrm{E}+01$ | $2.2857855 \mathrm{E}+01$ | $3.4522031 \mathrm{E}+00$ |
| c13 | Best | $-6.8429365 \mathrm{E}+01$ | $-6.8429365 \mathrm{E}+01$ | $-6.8429365 \mathrm{E}+01$ | $-6.8429120 \mathrm{E}+01$ |
|  | Mean | $-6.8414095 \mathrm{E}+01$ | $-6.8410227 \mathrm{E}+01$ | $-6.8408192 \mathrm{E}+01$ | $-6.8414287 \mathrm{E}+01$ |
|  | Std. | $1.5047902 \mathrm{E}-02$ | $1.8960127 \mathrm{E}-02$ | $2.0436101 \mathrm{E}-02$ | $1.4365403 \mathrm{E}-02$ |
| c14 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $2.2361998 \mathrm{E}-27$ | $5.6397496 \mathrm{E}-26$ | $5.4851329 \mathrm{E}-26$ | $8.3210487 \mathrm{E}-25$ |
|  | Std. | $2.7739946 \mathrm{E}-27$ | $2.4420816 \mathrm{E}-25$ | $1.5510197 \mathrm{E}-25$ | $2.9497895 \mathrm{E}-24$ |


| c15 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean | $2.0895348 \mathrm{E}-27$ | $1.7989779 \mathrm{E}-01$ | $1.2831548 \mathrm{E}-26$ | $3.2386337 \mathrm{E}-26$ |
|  | Std. | $7.1983746 \mathrm{E}-27$ | $8.9948895 \mathrm{E}-01$ | $3.1477882 \mathrm{E}-26$ | $6.0381004 \mathrm{E}-26$ |
| c 16 | Best | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Mean | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | Std. | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
| c 17 | Best | $2.6987375 \mathrm{E}-25$ | $2.5582616 \mathrm{E}-25$ | $1.6000546 \mathrm{E}-26$ | $1.4602517 \mathrm{E}-25$ |
|  | Mean | $9.4055111 \mathrm{E}-24$ | $1.2492963 \mathrm{E}-22$ | $1.6181065 \mathrm{E}-23$ | $3.6501219 \mathrm{E}-23$ |
|  | Std. | $1.1756918 \mathrm{E}-23$ | $4.8168630 \mathrm{E}-22$ | $3.1710419 \mathrm{E}-23$ | $1.1656528 \mathrm{E}-22$ |
| c 18 | Best | $2.3111159 \mathrm{E}-31$ | $2.9582284 \mathrm{E}-31$ | $7.1490520 \mathrm{E}-31$ | $2.9582284 \mathrm{E}-31$ |
|  | Mean | $4.4031997 \mathrm{E}-30$ | $4.7048157 \mathrm{E}-30$ | $1.9274337 \mathrm{E}-29$ | $1.2036711 \mathrm{E}-28$ |
|  | Std. | $7.2563135 \mathrm{E}-30$ | $5.7723172 \mathrm{E}-30$ | $2.7678567 \mathrm{E}-29$ | $2.1132285 \mathrm{E}-28$ |


|  | L7－HELLELL＇8 |  |  | 0¢－＇H007\＆0才® | LE－G9LIILE：て | $85^{\circ}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ¢โ－H079¢88｀ 6 | ¢T－且边 $689^{\circ} \mathrm{Z}$ | 9［－H6LZ897＊ | ¢7－＇H7699LI＇I | もて－HILGG07＊6 | ¢7－H88L869＊ | LI？ |
| $00+$ 䂞000000＊0 | 00＋年000000＊0 | $00+$ 島000000＊0 | $00+$ 鸟000000＊0 | $00+$ 式000000＊0 | $00+$ 鸟000000＊0 | 9 ${ }^{\circ}$ |
|  | 91－直LDL8L6 ${ }^{\text {L }}$ | LI－798LI89． | L7－HGLE861＇L | Lて－马GEG6807 | 00＋䳐000000＊0 | ¢LJ |
|  | GT－G89もI89．8 | LI－直L9010才゙も | Lて－鸟G668LL＇て | Lて－直00798\％「 | 00＋年000000＊0 | 枵 |
| ［0－＇H28才6LE＇才 | L0＋直L967LL ${ }^{\text {9－}}$ | L0＋㱏L6IE68 ${ }^{-}$ | 70－H06Lた09．L | 10＋号0LもLも8＊9－ | 10＋直LE67才7＊9－ | \＆${ }^{\circ}$ |
| ［0＋${ }^{\text {H69679 }}{ }^{\circ} \mathrm{C}$ |  |  | L0＋㱏L99t7L． | ［0＋岛切8889 ${ }^{\circ}$－$^{-}$ |  | Z ${ }^{\circ}$ |
| GT－G7EDGGGI | \＆0－G¢LL769 $\mathrm{L}^{-}$ | 80－＇HELLZ7¢ ${ }^{\text {－}}$ | 8L－G698869＊9 | 80－GELLZ\％9 ${ }^{\text {－}}{ }^{-}$ | 80－＇̧ELL769．${ }^{-}$ | ILO |
| 91－388L8Lも | LT－直LT9006 6 | 8L－ד̧L90LE＇も | 87－H9¢Et79 7 | 67－H0LL870ㄷ | 00＋㖪0000000 | $0{ }^{\circ}$ |
| LI－島L062\＆6 ${ }^{\text {L }}$ |  | 8L－马̧\＆\＆9E\＆8＇I | $00+$ 年000000＊0 | $00+$ 田000000＊0 | 00＋㖪000000＊0 | $60^{\circ}$ |
| 00＋鸟も9999\％$\overbrace{}^{\circ}$ | 00＋忽9L088L＇6 |  | 00＋号6808807 |  | 00＋㖪000000＊0 | $80^{\circ}$ |
| LI－＇H6869LI＇I | 81－GL8L006．9 | 6T－马̧40786［＇¢ | $00+$ 奀000000＊ | $00+$ 國000000＊0 | 00＋年000000＊0 | $20^{\circ}$ |
| 20－島06\＆ET＇Z | 70＋自76998 ${ }^{\circ} \mathrm{C}-$ |  | \＆L－GLZ¢币， $9^{\circ} \mathrm{E}$ |  | 70＋年769982．9－ | $90^{\circ}$ |
| 10－乌7896079 | 70＋ $7629788^{\circ}$－$^{-}$ | 70＋鳥90L988 ${ }^{-}$ | \＆ | 70＋鳥90L988 ${ }^{-}$ | 70＋ | 40 |
| ［L－H0L6709 ${ }^{\text {［ }}$ |  | 90－ت马866666 $6^{-}$ | $00+$ 奀000000＊0 | 90－乌̧000000 ${ }^{-}$ | 90－거000000 ${ }^{-}$ | $70^{\circ}$ |
|  |  | 8L－GLELDG0才 | $00+$ 奀000000＊0 | $00+$＇马000000＊0 | $00+$ 年000000＊0 | $80^{\circ}$ |
| 70－岛LEEた00\％ |  | 00＋岛78TG07 $\square^{-}$ |  |  | 00＋ | $70^{\circ}$ |
| 9L－＇⿹勹口 6 L7899 ¢ |  | L0－Gも0LELも゙ ${ }^{-}$ |  |  | L0－乌も0LELも゙ ${ }^{-}$ | L0 |
| ＇p7S | บセวЈ | 7Səg | ＇p7S | บ๕วЈ | ұSəg | Шә［q0．Jd |
| 7 $\Lambda$ |  |  | ［ $\Lambda$ |  |  |  |

[^3]Table D.4: Function values obtained by the proposed MEA-LS-R2S with different $N P^{i n i t}$ values of $N P^{i n i t}=50,75,100$ and 125 individuals

| Problem | criteria | $N P^{\text {init }}=50$ | $N P^{\text {init }}=75$ | $N P^{\text {init }}=100$ | $N P^{\text {init }}=125$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | Best | -7.473104E-01 | -7.473104E-01 | -7.473104E-01 | -7.473104E-01 |
|  | Mean | -7.447855E-01 | -7.470402E-01 | -7.470402E-01 | -7.470402E-01 |
|  | Std. | $6.110261 \mathrm{E}-03$ | $1.350628 \mathrm{E}-03$ | $1.350628 \mathrm{E}-03$ | $1.350628 \mathrm{E}-03$ |
| c02 | Best | $-2.277710 \mathrm{E}+00$ | $-2.277710 \mathrm{E}+00$ | $-2.269389 \mathrm{E}+00$ | $-2.241026 \mathrm{E}+00$ |
|  | Mean | $-2.276648 \mathrm{E}+00$ | $-2.263310 \mathrm{E}+00$ | $-2.234157 \mathrm{E}+00$ | $-2.220710 \mathrm{E}+00$ |
|  | Std. | $5.287305 \mathrm{E}-03$ | $1.587400 \mathrm{E}-02$ | $1.474365 \mathrm{E}-02$ | $1.700886 \mathrm{E}-02$ |
| c03 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c04 | Best | $-1.000000 \mathrm{E}-05$ | -1.000000E-05 | -1.000000E-05 | $-1.000000 \mathrm{E}-05$ |
|  | Mean | $-1.000000 \mathrm{E}-05$ | -1.000000E-05 | -1.000000E-05 | -1.000000E-05 |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c05 | Best | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ |
|  | Mean | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ |
|  | Std. | $3.480934 \mathrm{E}-13$ | $3.480934 \mathrm{E}-13$ | $3.480934 \mathrm{E}-13$ | $3.480934 \mathrm{E}-13$ |
| c06 | Best | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ |
|  | Mean | $-5.780678 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ |
|  | Std. | $7.432283 \mathrm{E}-01$ | $3.979039 \mathrm{E}-13$ | $4.085878 \mathrm{E}-13$ | $3.756256 \mathrm{E}-13$ |
| c07 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $1.594632 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $7.973158 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c08 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $1.411399 \mathrm{E}+01$ | $8.731391 \mathrm{E}+00$ | $8.152591 \mathrm{E}+00$ | $1.048913 \mathrm{E}+01$ |
|  | Std. | $2.418676 \mathrm{E}+01$ | $5.690794 \mathrm{E}+00$ | $4.570200 \mathrm{E}+00$ | $2.186477 \mathrm{E}+00$ |
| c09 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $1.763559 \mathrm{E}-01$ | $2.653057 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | 8.817793E-01 | $1.326529 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c10 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c11 | Best | -1.522713E-03 | $-1.522713 \mathrm{E}-03$ | -1.522713E-03 | -1.522713E-03 |
|  | Mean | -1.522713E-03 | -1.522713E-03 | -1.522713E-03 | -1.522713E-03 |
|  | Std. | $4.517559 \mathrm{E}-15$ | $5.800059 \mathrm{E}-18$ | $6.045339 \mathrm{E}-18$ | $6.394495 \mathrm{E}-18$ |
| c12 | Best | -1.992458E-01 | $-4.231332 \mathrm{E}+02$ | $-3.054888 \mathrm{E}+02$ | $-3.037844 \mathrm{E}+02$ |
|  | Mean | -1.992458E-01 | $-2.362370 \mathrm{E}+01$ | $-8.058275 \mathrm{E}+01$ | $-5.674957 \mathrm{E}+01$ |
|  | Std. | $5.405345 \mathrm{E}-10$ | $9.037024 \mathrm{E}+01$ | $1.217887 \mathrm{E}+02$ | $1.019679 \mathrm{E}+02$ |
| c13 | Best | $-6.842937 \mathrm{E}+01$ | $-6.842937 \mathrm{E}+01$ | $-6.842937 \mathrm{E}+01$ | -6.842937E+01 |
|  | Mean | $-6.842908 \mathrm{E}+01$ | $-6.842904 \mathrm{E}+01$ | $-6.842273 \mathrm{E}+01$ | $-6.842140 \mathrm{E}+01$ |
|  | Std. | $1.107314 \mathrm{E}-03$ | $1.009323 \mathrm{E}-03$ | $2.312649 \mathrm{E}-02$ | $9.359518 \mathrm{E}-03$ |
| c14 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $1.594632 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $7.973158 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |


| $c 15$ | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean | $5.396934 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $1.491634 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c 16 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $8.196758 \mathrm{E}-30$ |
|  | Mean | $7.395571 \mathrm{E}-34$ | $1.232595 \mathrm{E}-33$ | $2.173460 \mathrm{E}-29$ | $1.208299 \mathrm{E}-25$ |
|  | Std. | $2.044028 \mathrm{E}-33$ | $2.516024 \mathrm{E}-33$ | $6.693253 \mathrm{E}-29$ | $3.292050 \mathrm{E}-25$ |
| $c 18$ | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $2.822643 \mathrm{E}-32$ | $2.428212 \mathrm{E}-32$ | $1.503766 \mathrm{E}-32$ | $1.836567 \mathrm{E}-32$ |
|  | Std. | $2.829381 \mathrm{E}-32$ | $3.187913 \mathrm{E}-32$ | $2.637809 \mathrm{E}-32$ | $2.779723 \mathrm{E}-32$ |

Table D.5: Function values obtained by the proposed MEA-LS-R2S with different $N P^{\text {min }}$ values of $N P^{\text {min }}=4,10,30$ and 40 individuals

| Problem | criteria | $N P^{\text {min }}=4$ | $N P^{\text {min }}=10$ | $N P^{\text {min }}=30$ | $N P^{\text {min }}=40$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| c01 | Best | -7.473104E-01 | -7.473104E-01 | -7.473104E-01 | -7.473104E-01 |
|  | Mean | -7.473104E-01 | -7.470402E-01 | -7.473104E-01 | -7.470402E-01 |
|  | Std. | $2.533726 \mathrm{E}-16$ | $1.350628 \mathrm{E}-03$ | $2.254874 \mathrm{E}-16$ | $1.350628 \mathrm{E}-03$ |
| c02 | Best | $-2.277710 \mathrm{E}+00$ | $-2.277710 \mathrm{E}+00$ | $-2.277710 \mathrm{E}+00$ | $-2.269389 \mathrm{E}+00$ |
|  | Mean | $-2.271055 \mathrm{E}+00$ | $-2.262074 \mathrm{E}+00$ | $-2.252877 \mathrm{E}+00$ | $-2.234157 \mathrm{E}+00$ |
|  | Std. | $1.121433 \mathrm{E}-02$ | $1.667956 \mathrm{E}-02$ | $1.889332 \mathrm{E}-02$ | $1.474365 \mathrm{E}-02$ |
| c03 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c04 | Best | $-1.000000 \mathrm{E}-05$ | -1.000000E-05 | -1.000000E-05 | -1.000000E-05 |
|  | Mean | $-1.000000 \mathrm{E}-05$ | -1.000000E-05 | -1.000000E-05 | $-1.000000 \mathrm{E}-05$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c05 | Best | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ |
|  | Mean | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ | $-4.836106 \mathrm{E}+02$ |
|  | Std. | $3.480934 \mathrm{E}-13$ | $3.480934 \mathrm{E}-13$ | $3.480934 \mathrm{E}-13$ | $3.480934 \mathrm{E}-13$ |
| c06 | Best | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ |
|  | Mean | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ | $-5.786624 \mathrm{E}+02$ |
|  | Std. | $6.345408 \mathrm{E}-12$ | $5.921000 \mathrm{E}-13$ | $4.372388 \mathrm{E}-13$ | $4.085878 \mathrm{E}-13$ |
| c07 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c08 | Best | $0.000000 \mathrm{E}+00$ | $3.986579 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $9.613806 \mathrm{E}+00$ | $1.066334 \mathrm{E}+01$ | $9.758722 \mathrm{E}+00$ | $8.152591 \mathrm{E}+00$ |
|  | Std. | $3.624085 \mathrm{E}+00$ | $1.390992 \mathrm{E}+00$ | $3.279714 \mathrm{E}+00$ | $4.570200 \mathrm{E}+00$ |
| c09 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $2.089906 \mathrm{E}-01$ | $6.877943 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $1.044953 \mathrm{E}+00$ | $3.438971 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c10 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c11 | Best | -1.522713E-03 | -1.522713E-03 | -1.522713E-03 | $-1.522713 \mathrm{E}-03$ |
|  | Mean | -1.522713E-03 | -1.522713E-03 | -1.522713E-03 | -1.522713E-03 |
|  | Std. | $5.696431 \mathrm{E}-17$ | $3.507778 \mathrm{E}-17$ | $7.601796 \mathrm{E}-18$ | $6.045339 \mathrm{E}-18$ |
| c12 | Best | $-3.054888 \mathrm{E}+02$ | $-3.054888 \mathrm{E}+02$ | $-3.054888 \mathrm{E}+02$ | $-3.054888 \mathrm{E}+02$ |
|  | Mean | $-8.508055 \mathrm{E}+01$ | $-7.938110 \mathrm{E}+01$ | $-7.538300 \mathrm{E}+01$ | $-8.058275 \mathrm{E}+01$ |
|  | Std. | $1.209995 \mathrm{E}+02$ | $1.222434 \mathrm{E}+02$ | $1.228049 \mathrm{E}+02$ | $1.217887 \mathrm{E}+02$ |
| c13 | Best | $-6.842937 \mathrm{E}+01$ | -6.842937E+01 | $-6.842937 \mathrm{E}+01$ | -6.842937E+01 |
|  | Mean | $-6.842912 \mathrm{E}+01$ | $-6.842920 \mathrm{E}+01$ | $-6.842740 \mathrm{E}+01$ | -6.842273E+01 |
|  | Std. | $5.096311 \mathrm{E}-04$ | $3.786048 \mathrm{E}-04$ | $5.845673 \mathrm{E}-03$ | $2.312649 \mathrm{E}-02$ |
| c14 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |


| $c 15$ | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Mean | $1.798978 \mathrm{E}-01$ | $1.798978 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $8.994890 \mathrm{E}-01$ | $8.994890 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| c 16 | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Std. | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Best | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $3.451266 \mathrm{E}-33$ | $2.711709 \mathrm{E}-33$ | $1.380507 \mathrm{E}-32$ | $2.173460 \mathrm{E}-29$ |
|  | Std. | $3.122304 \mathrm{E}-33$ | $3.122304 \mathrm{E}-33$ | $5.626789 \mathrm{E}-32$ | $6.693253 \mathrm{E}-29$ |
| c 18 | Best | $0.00000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | Mean | $8.443277 \mathrm{E}-33$ | $1.639352 \mathrm{E}-32$ | $1.756448 \mathrm{E}-32$ | $1.503766 \mathrm{E}-32$ |
|  | Std. | $1.840915 \mathrm{E}-32$ | $2.725448 \mathrm{E}-32$ | $2.681957 \mathrm{E}-32$ | $2.637809 \mathrm{E}-32$ |

Table D.6: Function values obtained by MEA-LS-R2S, MLS-MODE, MJADE-R2S, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon \mathrm{DEg}$, AH-DEa and SAMO-GA for CEC2006 for g01-g04

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g01 | MEA-LS-R2S | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-1.5000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | MLS-MODE | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.50000 \mathrm{E}+01$ | $0.00000 \mathrm{E}+00$ |
|  | AH-DEa | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.500000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
| g02 | MEA-LS-R2S | -8.036191E-01 | $4.163894 \mathrm{E}-07$ |
|  | MJADE-R2S | $8.0358 \mathrm{E}-01$ | $7.6037 \mathrm{E}-05$ |
|  | MLS-MODE | -8.036191E-01 | 4.509747E-16 |
|  | EHCT_DE | -7.936387E-01 | $1.120000 \mathrm{E}-02$ |
|  | AIS-ZHY | -8.021930E-01 | $5.190000 \mathrm{E}-10$ |
|  | ISMOADE-CMA | -7.92440E-01 | $2.80000 \mathrm{E}-02$ |
|  | SAMO-DE | -7.987000E-01 | $8.801 \mathrm{E}-03$ |
|  | ECHT-EP2 | -7.998220E-01 | $1.260000 \mathrm{E}-02$ |
|  | $\epsilon \mathrm{DEg}$ | -8.036191E-01 | $1.750000 \mathrm{E}-08$ |
|  | AH-DEa | -8.007000E-01 | $3.912 \mathrm{E}-03$ |
|  | SAMO-GA | -7.960000E-01 | $5.803 \mathrm{E}-03$ |
| g03 | MEA-LS-R2S | $-1.0005001 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-1.000500 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT DE | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.0005000 \mathrm{E}+00$ | $1.7700000 \mathrm{E}-11$ |
|  | ISMOADE-CMA | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.0005000 \mathrm{E}+00$ | $2.9600000 \mathrm{E}-31$ |
|  | AH-DEa | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.0005000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| g04 | MEA-LS-R2S | $-3.0665539 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $3.06665539 \mathrm{E}+04$ | $0.0000000 \mathrm{E}+00$ |
|  | MLS-MODE | -3.06655390E+04 | $0.00000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-3.06655390 \mathrm{E}+04$ | $3.69000000 \mathrm{E}-13$ |
|  | ISMOADE-CMA | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-3.06655386 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | -3.06655390E+04 | $0.00000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-3.06655390 \mathrm{E}+04$ | $0.00000000 \mathrm{E}+00$ |
|  | AH-DEa | $-3.06655387 \mathrm{E}+04$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-3.06655387 \mathrm{E}+04$ | $0.000000 \mathrm{E}+00$ |

Table D.7: Function values obtained by MEA-LS-R2S, MLS-MODE, MJADE-R2S, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon \mathrm{DEg}$, AH-DEa and SAMO-GA for CEC2006 for g05-g08

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g05 | MEA-LS-R2S | $5.126497 \mathrm{E}+03$ | $0.0000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $5.126497 \mathrm{E}+03$ | $0.0000000 \mathrm{E}+00$ |
|  | MLS-MODE | $5.1264970 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $5.126498 \mathrm{E}+03$ | $1.700000 \mathrm{E}-02$ |
|  | ISMOADE-CMA | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $5.126497 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $5.126000 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $5.128000 \mathrm{E}+03$ | $1.117000 \mathrm{E}+00$ |
| g06 | MEA-LS-R2S | $-6.961814 \mathrm{E}+03$ | $0.0000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-6.961814 \mathrm{E}+03$ | $0.0000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-6.9618140 \mathrm{E}+03$ | $0.0000000 \mathrm{E}+00$ |
|  | EHCT DE | $-6.96181400 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-6.96181385 \mathrm{E}+03$ | $1.90000000 \mathrm{E}-12$ |
|  | ISMOADE-CMA | $-6.96181388 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-6.96181388 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-6.96181400 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-6.96181388 \mathrm{E}+03$ | $0.00000000 \mathrm{E}+00$ |
|  | AH-DEa | $-6.9618140 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-6.9618140 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
| g07 | MEA-LS-R2S | $2.430621 \mathrm{E}+01$ | $0.0000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $2.430621 \mathrm{E}+01$ | $0.0000000 \mathrm{E}+00$ |
|  | MLS-MODE | $2.4306210 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $2.430620 \mathrm{E}+01$ | $1.140000 \mathrm{E}-10$ |
|  | AIS-ZHY | $2.435570 \mathrm{E}+01$ | $8.200000 \mathrm{E}-03$ |
|  | ISMOADE-CMA | $2.4306210 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $2.430960 \mathrm{E}+01$ | $1.590000 \mathrm{E}-03$ |
|  | ECHT-EP2 | $2.430630 \mathrm{E}+01$ | $3.190000 \mathrm{E}-05$ |
|  | $\epsilon \mathrm{DEg}$ | $2.430620 \mathrm{E}+01$ | $2.180000 \mathrm{E}-15$ |
|  | AH-DEa | $2.431000 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $2.441000 \mathrm{E}+01$ | $4.591000 \mathrm{E}-02$ |
| g08 | MEA-LS-R2S | -9.582504E-02 | $0.0000000 \mathrm{E}+00$ |
|  | MJADE-R2S | -9.5825040E-02 | $0.0000000 \mathrm{E}+00$ |
|  | MLS-MODE | -9.5825040E-02 | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | -9.582504E-02 | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | -9.582500E-02 | $2.610000 \mathrm{E}-08$ |
|  | $\epsilon \mathrm{DEg}$ | -9.582500E-02 | $1.230000 \mathrm{E}-32$ |
|  | AH-DEa | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | -9.582500E-02 | $0.000000 \mathrm{E}+00$ |

Table D.8: Function values obtained by MEA-LS-R2S, MLS-MODE, MJADE-R2S, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon \mathrm{DEg}$, AH-DEa and SAMO-GA for CEC2006 for g09-g12

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g09 | MEA-LS-R2S | $6.806301 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $6.806301 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $6.806500 \mathrm{E}+02$ | $1.200000 \mathrm{E}-08$ |
|  | ISMOADE-CMA | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $6.8063010 \mathrm{E}+02$ | $1.160000 \mathrm{E}-05$ |
|  | ECHT-EP2 | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $6.8063010 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $6.8063010 \mathrm{E}+02$ | $1.457000 \mathrm{E}-03$ |
| g10 | MEA-LS-R2S | $7.0492480 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $7.0492480 \mathrm{E}+03$ | $1.0000 \mathrm{E}-10$ |
|  | MLS-MODE | $7.0492480 \mathrm{E}+03$ | $6.0989160 \mathrm{E}-10$ |
|  | EHCT_DE | $7.049248 \mathrm{E}+03$ | $4.180000 \mathrm{E}-07$ |
|  | AIS-ZHY | $7.049570 \mathrm{E}+03$ | $4.500000 \mathrm{E}-04$ |
|  | ISMOADE-CMA | $7.049248 \mathrm{E}+03$ | $5.420000 \mathrm{E}-06$ |
|  | SAMO-DE | $7.059813 \mathrm{E}+03$ | $7.860000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $7.049249 \mathrm{E}+03$ | $6.600000 \mathrm{E}-04$ |
|  | $\epsilon \mathrm{DEg}$ | $7.049248 \mathrm{E}+03$ | $4.240000 \mathrm{E}-13$ |
|  | AH-DEa | $7.0492480 \mathrm{E}+03$ | $1.688000 \mathrm{E}-09$ |
|  | SAMO-GA | $7.144000 \mathrm{E}+03$ | $6.786000 \mathrm{E}+01$ |
| g11 | MEA-LS-R2S | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $7.4990000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $7.4990000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $7.499000 \mathrm{E}-01$ | $1.400000 \mathrm{E}-08$ |
|  | ISMOADE-CMA | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $7.499000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ |
| g12 | MEA-LS-R2S | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-1.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-1.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |

Table D.9: Function values obtained by MEA-LS-R2S, MLS-MODE, MJADE-R2S, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon \mathrm{DEg}$, AH-DEa and SAMO-GA for CEC2006 for g13-g16

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g13 | MEA-LS-R2S | $5.394150 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $5.394150 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $5.39415 \mathrm{E}-02$ | $7.800000 \mathrm{E}-10$ |
|  | ISMOADE-CMA | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $5.39415 \mathrm{E}-02$ | $1.750000 \mathrm{E}-08$ |
|  | ECHT-EP2 | $5.39415 \mathrm{E}-02$ | $1.000000 \mathrm{E}-12$ |
|  | $\epsilon \mathrm{DEg}$ | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $5.39415 \mathrm{E}-02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $5.403000 \mathrm{E}-02$ | $5.941000 \mathrm{E}-05$ |
| g14 | MEA-LS-R2S | $-4.7764890 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-4.7764890 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-4.7764890 \mathrm{E}+01$ | $2.6066690 \mathrm{E}-14$ |
|  | EHCT_DE | $-4.776489 \mathrm{E}+01$ | $3.260000 \mathrm{E}-13$ |
|  | AIS-ZHY | $-4.776488 \mathrm{E}+01$ | $1.000000 \mathrm{E}-12$ |
|  | ISMOADE-CMA | $-4.776489 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-4.768115 \mathrm{E}+01$ | $4.040000 \mathrm{E}-02$ |
|  | ECHT-EP2 | $-4.776480 \mathrm{E}+01$ | $2.720000 \mathrm{E}-05$ |
|  | $\epsilon \mathrm{DEg}$ | $-4.776489 \mathrm{E}+01$ | $1.390000 \mathrm{E}-15$ |
|  | AH-DEa | $-4.776000 \mathrm{E}+01$ | $3.894000 \mathrm{E}-05$ |
|  | SAMO-GA | $-4.776489 \mathrm{E}+01$ | $3.159000 \mathrm{E}-01$ |
| g15 | MEA-LS-R2S | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $9.6171500 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $9.617150 \mathrm{E}+02$ | $2.010000 \mathrm{E}-13$ |
|  | $\epsilon \mathrm{DEg}$ | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AH-DEa | $9.617150 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $9.617150 \mathrm{E}+02$ | $5.524000 \mathrm{E}-05$ |
| g16 | MEA-LS-R2S | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-1.9051550 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-1.905155 \mathrm{E}+00$ | $1.120000 \mathrm{E}-10$ |
|  | $\epsilon \mathrm{DEg}$ | $-1.905155 \mathrm{E}+00$ | $1.580000 \mathrm{E}-30$ |
|  | AH-DEa | $-1.905155 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-1.905155 \mathrm{E}+00$ | $6.952000 \mathrm{E}-07$ |

Table D.10: Function values obtained by MEA-LS-R2S, MLS-MODE, MJADE-R2S, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon \mathrm{DEg}$, AH-DEa and SAMO-GA for CEC2006 for g17-g21

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g17 | MEA-LS-R2S | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $8.8565 \mathrm{E}+03$ | $1.4812 \mathrm{E}+01$ |
|  | MLS-MODE | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $8.853540 \mathrm{E}+03$ | $1.900000 \mathrm{E}-09$ |
|  | ISMOADE-CMA | $8.853540 \mathrm{E}+03$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $8.853540 \mathrm{E}+03$ | $1.150000 \mathrm{E}-05$ |
|  | ECHT-EP2 | $8.853540 \mathrm{E}+03$ | $2.130000 \mathrm{E}-08$ |
|  | $\epsilon \mathrm{DEg}$ | $8.853540 \mathrm{E}+03$ | $1.210000 \mathrm{E}-27$ |
|  | AH-DEa | $8.858000 \mathrm{E}+03$ | $1.847000 \mathrm{E}+01$ |
|  | SAMO-GA | $8.854000 \mathrm{E}+03$ | $1.740000 \mathrm{E}-01$ |
| g18 | MEA-LS-R2S | -8.660254E-01 | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | -8.3546E-01 | $7.1482 \mathrm{E}-02$ |
|  | MLS-MODE | -8.6602540E-01 | $5.1068250 \mathrm{E}-15$ |
|  | EHCT_DE | -8.660240E-01 | $5.150000 \mathrm{E}-06$ |
|  | AIS-ZHY | -8.660250E-01 | $1.300000 \mathrm{E}-15$ |
|  | ISMOADE-CMA | -8.660250E-01 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | -8.660240E-01 | $7.040000 \mathrm{E}-07$ |
|  | ECHT-EP2 | -8.660250E-01 | $1.000000 \mathrm{E}-09$ |
|  | $\epsilon \mathrm{DEg}$ | -8.660250E-01 | $2.180000 \mathrm{E}-17$ |
|  | AH-DEa | -8.6602540E-01 | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | -8.655000E-01 | $4.080000 \mathrm{E}-04$ |
| g19 | MEA-LS-R2S | $3.265559 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $3.265559 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $3.2655590 \mathrm{E}+01$ | $1.7525120 \mathrm{E}-14$ |
|  | EHCT_DE | $3.265654 \mathrm{E}+01$ | $7.760000 \mathrm{E}-04$ |
|  | AIS-ZHY | $3.265559 \mathrm{E}+01$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $3.265559 \mathrm{E}+01$ | $6.460000 \mathrm{E}-07$ |
|  | SAMO-DE | $3.275734 \mathrm{E}+01$ | $6.150000 \mathrm{E}-02$ |
|  | ECHT-EP2 | $3.266230 \mathrm{E}+01$ | $3.400000 \mathrm{E}-03$ |
|  | $\epsilon \mathrm{DEg}$ | $3.265560 \mathrm{E}+01$ | $1.260000 \mathrm{E}-05$ |
|  | AH-DEa | $3.457000 \mathrm{E}+01$ | $2.524000 \mathrm{E}+00$ |
|  | SAMO-GA | $3.643000 \mathrm{E}+01$ | $1.037000 \mathrm{E}+00$ |
| g21 | MEA-LS-R2S | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $2.3040 \mathrm{E}+02$ | $6.0021 \mathrm{E}+01$ |
|  | MLS-MODE | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $1.967245 \mathrm{E}+02$ | $1.100000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $1.937245 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $1.937714 \mathrm{E}+02$ | $1.960000 \mathrm{E}-02$ |
|  | ECHT-EP2 | $1.937438 \mathrm{E}+02$ | $1.650000 \mathrm{E}-02$ |
|  | $\epsilon \mathrm{DEg}$ | $1.937245 \mathrm{E}+02$ | $3.340000 \mathrm{E}-14$ |
|  | AH-DEa | $1.939000 \mathrm{E}+02$ | $6.977000 \mathrm{E}-01$ |
|  | SAMO-GA | $2.461000 \mathrm{E}+02$ | $1.492000 \mathrm{E}+01$ |

Table D.11: Function values obtained by MEA-LS-R2S, MLS-MODE, MJADE-R2S, EHCT-DE, AIS-ZHY, ISMOADE-CMA, SAMO-DE, ECHT-EP2, $\epsilon \mathrm{DEg}$, AH-DEa and SAMO-GA for CEC2006 for g23-g24

| problem | Alg. | Mean | Std. |
| :---: | :---: | :---: | :---: |
| g23 | MEA-LS-R2S | $-4.000551 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-4.000520 \mathrm{E}+02$ | $3.180000 \mathrm{E}-04$ |
|  | MLS-MODE | $-4.0005120 \mathrm{E}+02$ | $1.9083780 \mathrm{E}-02$ |
|  | EHCT_DE | $-4.000546 \mathrm{E}+02$ | $2.180000 \mathrm{E}-03$ |
|  | AIS-ZHY | $-3.998743 \mathrm{E}+02$ | $2.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-3.956240 \mathrm{E}+02$ | $7.790000 \mathrm{E}+00$ |
|  | SAMO-DE | $-3.608177 \mathrm{E}+02$ | $1.960000 \mathrm{E}+01$ |
|  | ECHT-EP2 | $-3.732178 \mathrm{E}+02$ | $3.370000 \mathrm{E}+01$ |
|  | $\epsilon$ DEg | $-4.000551 \mathrm{E}+02$ | $1.110000 \mathrm{E}-14$ |
|  | AH-DEa | $-3.444000 \mathrm{E}+02$ | $7.782000 \mathrm{E}+01$ |
|  | SAMO-GA | $-1.948000 \mathrm{E}+02$ | $5.328000 \mathrm{E}+01$ |
| g24 | MEA-LS-R2S | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $-5.5080130 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | MLS-MODE | $-5.5080130 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | EHCT_DE | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | AIS-ZHY | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ISMOADE-CMA | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-DE | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | ECHT-EP2 | $-5.508013 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | $\epsilon$ DEg | $-5.508013 \mathrm{E}+00$ | $2.520000 \mathrm{E}-29$ |
|  | AH-DEa | $-5.508000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
|  | SAMO-GA | $-5.508000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |

Table D.12: Function values obtained by MEA-LS-R2S, MJADE-R2S, MLS-MODE, DEbavDBmax, SAMODE, DE-DBmax, SAMO-DE, eABC, Co-CLPSO, SAMO-GA, $\epsilon$ DEg, and ECHT-ARMOR-DE for CEC2010 for c01-c03

|  |  | 10D |  |  | 30D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| problem | Alg. | Best | Mean | Std. | Best | Mean | Std. |
| c01 | MEA-LS-R2S | -7.4731036E-01 | -7.4731036E-01 | $2.5337258 \mathrm{E}-16$ | -8.2188433E-01 | -8.2149710E-01 | 9.6427287E-04 |
|  | MJADE-R2S | -7.4731000E-01 | -7.4529000E-01 | $5.2900000 \mathrm{E}-03$ | -8.2188000E-01 | -8.1884000E-01 | $3.3000000 \mathrm{E}-03$ |
|  | MLS-MODE | -7.4731036E-01 | -7.4731036E-01 | $4.2142800 \mathrm{E}-15$ | -8.2188435E-01 | -8.2180624E-01 | 3.8996670E-04 |
|  | DEbavDBmax | -7.473104E-01 | -7.463993E-01 | $2.552887 \mathrm{E}-03$ | -8.218843E-01 | -8.135627E-01 | $7.854595 \mathrm{E}-03$ |
|  | SAMODE | -7.473104E-01 | -7.470402E-01 | $1.350638 \mathrm{E}-03$ | -8.218838E-01 | -8.143674E-01 | $4.766000 \mathrm{E}-03$ |
|  | $\epsilon$ DEag | -7.473104E-01 | -7.467701E-01 | $1.869859 \mathrm{E}-03$ | -8.218255E-01 | -8.208687E-01 | $7.103893 \mathrm{E}-04$ |
|  | DE-DBmax | -7.473104E-01 | -7.463993E-01 | $2.552887 \mathrm{E}-03$ | -8.218843E-01 | -8.146829E-01 | $7.216108 \mathrm{E}-03$ |
|  | eABC | -7.472710E-01 | -7.162570E-01 | $2.689780 \mathrm{E}-02$ | -8.162650E-01 | -7.305540E-01 | $4.875890 \mathrm{E}-02$ |
|  | Co-CLPSO | -7.473100E-01 | -7.335800E-01 | $1.784800 \mathrm{E}-02$ | -8.068800E-01 | -7.159800E-01 | $5.025200 \mathrm{E}-02$ |
|  | SAMO-GA | -7.473093E-01 | -7.470230E-01 | $1.347658 \mathrm{E}-03$ | -8.217813E-01 | -8.115299E-01 | $7.247940 \mathrm{E}-03$ |
|  | ECHT-ARMOR-DE | -7.473000E-01 | $-7.470000 \mathrm{E}+00$ | $1.400000 \mathrm{E}-03$ | -8.180600E-01 | -7.899200E-01 | $2.510000 \mathrm{E}-02$ |
| c02 | MEA-LS-R2S | $-2.2777100 \mathrm{E}+00$ | $-2.2710550 \mathrm{E}+00$ | $1.1214327 \mathrm{E}-02$ | $-2.2210704 \mathrm{E}+00$ | $-1.9697560 \mathrm{E}+00$ | $1.1252965 \mathrm{E}-01$ |
|  | MJADE-R2S | $-2.2777000 \mathrm{E}+00$ | $-2.0103000 \mathrm{E}+00$ | $4.0944000 \mathrm{E}-01$ | $-2.2807000 \mathrm{E}+00$ | $-2.2702000 \mathrm{E}+00$ | $8.4000000 \mathrm{E}-03$ |
|  | MLS-MODE | $-2.2355979 \mathrm{E}+00$ | $-2.2123734 \mathrm{E}+00$ | $1.1919289 \mathrm{E}-02$ | $-2.1390923 \mathrm{E}+00$ | $-2.0099045 \mathrm{E}+00$ | 8.8624158E-02 |
|  | DEbavDBmax | $-2.277710 \mathrm{E}+00$ | $-2.198366 \mathrm{E}+00$ | $8.389727 \mathrm{E}-02$ | $-2.280973 \mathrm{E}+00$ | $-2.276646 \mathrm{E}+00$ | $3.150424 \mathrm{E}-03$ |
|  | SAMODE | $-2.277709 \mathrm{E}+00$ | $-2.276842 \mathrm{E}+00$ | $1.154957 \mathrm{E}-03$ | $-2.280962 \mathrm{E}+00$ | $-2.276111 \mathrm{E}+00$ | $3.706000 \mathrm{E}-03$ |
|  | $\epsilon$ DEag | $-2.277702 \mathrm{E}+00$ | $-2.269502 \mathrm{E}+00$ | $2.389779 \mathrm{E}-02$ | $-2.169248 \mathrm{E}+00$ | $-2.151424 \mathrm{E}+00$ | 1.197582E-02 |
|  | DE-DBmax | $-2.277711 \mathrm{E}+00$ | $-2.182633 \mathrm{E}+00$ | $1.190727 \mathrm{E}-01$ | $-2.280973 \mathrm{E}+00$ | $-2.275178 \mathrm{E}+00$ | $4.677619 \mathrm{E}-03$ |
|  | eABC | $-2.155150 \mathrm{E}+00$ | -1.248950E-01 | $1.583590 \mathrm{E}+00$ | -1.236470E-01 | $2.556470 \mathrm{E}+00$ | $9.429490 \mathrm{E}-01$ |
|  | Co-CLPSO | $-2.277700 \mathrm{E}+00$ | $-2.266600 \mathrm{E}+00$ | $1.461600 \mathrm{E}-02$ | $-2.280900 \mathrm{E}+00$ | $-2.202900 \mathrm{E}+00$ | $1.926700 \mathrm{E}-01$ |
|  | SAMO-GA | $-2.277497 \mathrm{E}+00$ | $-2.272609 \mathrm{E}+00$ | $2.267800 \mathrm{E}-03$ | $-2.265137 \mathrm{E}+00$ | $-2.252288 \mathrm{E}+00$ | $5.747300 \mathrm{E}-03$ |
|  | ECHT-ARMOR-DE | $-2.277700 \mathrm{E}+00$ | $-2.277000 \mathrm{E}+03$ | $3.300000 \mathrm{E}-03$ | $-2.260700 \mathrm{E}+00$ | $-2.170600 \mathrm{E}+00$ | $7.360000 \mathrm{E}-02$ |
| c03 | MEA-LS-R2S | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ |
|  | MJADE-R2S | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $1.0000000 \mathrm{E}-04$ | $4.9000000 \mathrm{E}-04$ |
|  | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $1.9003142 \mathrm{E}-25$ | 4.4111754E-25 |
|  | DEbavDBmax | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $6.382170 \mathrm{E}-25$ | $7.133478 \mathrm{E}-25$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $4.173000 \mathrm{E}-23$ | $1.640510 \mathrm{E}-22$ | $4.599600 \mathrm{E}-24$ | $4.826000 \mathrm{E}-22$ | $1.146000 \mathrm{E}-21$ |
|  | $\epsilon$ DEag | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $2.867347 \mathrm{E}+01$ | $2.883785 \mathrm{E}+01$ | $8.047159 \mathrm{E}-01$ |
|  | DE-DBmax | $0.000000 \mathrm{E}+00$ | $2.686721 \mathrm{E}-26$ | $1.023925 \mathrm{E}-25$ | $0.000000 \mathrm{E}+00$ | $1.508909 \mathrm{E}-16$ | $6.314477 \mathrm{E}-16$ |
|  | eABC | $8.788210 \mathrm{E}+11$ | - | $1.009670 \mathrm{E}+12$ | - | - | - |
|  | Co-CLPSO | $2.474800 \mathrm{E}-13$ | $3.550200 \mathrm{E}-01$ | $1.775100 \mathrm{E}+00$ | - | - | - |
|  | SAMO-GA | $6.492724 \mathrm{E}-22$ | $1.190663 \mathrm{E}-10$ | $2.074947 \mathrm{E}-10$ | $5.481000 \mathrm{E}-19$ | $2.255000 \mathrm{E}-07$ | $8.154000 \mathrm{E}-07$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $2.580100 \mathrm{E}-24$ | $2.638000 \mathrm{E}+01$ | $7.940000 \mathrm{E}+00$ |


| 70＋㱏000078． |  | 70＋马岛00¢97\％¢－ | \＆L－＇H000000T |  |  | H9－ฯONYV－LHOG |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00＋疋LL969İ¢ | \％0＋鸟LZL807．9－ | 70＋马马96967\％¢－ | 00＋ 9 G67097＊ |  |  | Vn－ONVS |  |
|  |  |  |  | 70＋号009984．9－ |  | OSdTD－o |  |
| 10＋号06970 \％ 9 | 70＋G0L788L $\frac{1}{}$ | 70＋具07969\％＇¢ | ［0＋G098969 ${ }^{\circ}$ | 70＋年089188＇ธ | 70＋ $3089788^{\circ}$ \％ | गGVə |  |
| 70－Э7celis I |  | 70＋G6LE90¢ $9^{-}$ | ¢0－Ht997L¢ $¢$ | Z0＋GLTOGGL．9－ | 70＋GLTOGGL．9－ | xruga－马9 |  |
| L0－G8LE87L ${ }^{\text {¢ }}$ |  |  | ¢0－马69LLz9 ¢ |  |  | ．${ }^{\text {rega }}{ }^{\text {a }}$ | $90^{\circ}$ |
|  | 70＋ | 70＋ | 80－G06LZSE 6 |  | 70＋鸟76998L $\mathrm{G}^{-}$ | GGONVS |  |
| 10－马88797¢ ${ }^{\text {\％}}$ |  | 70＋G62¢90¢ $9^{-}$ | L0－G6SLLLA 2 | 70＋BLITOGS $L^{\circ} \mathrm{G}-$ | 60＋BLTOGS $L^{\circ} \mathrm{G}^{-}$ | хгшяФлеq＇仡 |  |
| ［0－马LLZ7696＊9 | 70＋囱L869708．9－ | 70＋㿾98L8908．9－ | 8t－GILI06L\％＇t | 70＋鸟LE7998 ${ }^{\circ} \mathrm{G}$－ | 70＋号LE79984．9－ | HGON－STIN |  |
| 70＋G0009026 I | 70＋具0007\％7T「I | 70＋年0007886 ${ }^{\text {L－}}$ | 70＋芷000L776． | L0＋ | 70＋号LE69984．9－ | S74－GTVCN |  |
| L0－ĢL8LL60＊8 |  | 70＋罭026L908．9－ | てL－H6L0才¢ ¢ ¢ 9 | 70＋鸟L67998 ${ }^{\circ} \mathrm{G}$－ | 70＋早LE6998 ${ }^{\circ} \mathrm{g}^{-}$ | SzY－ST－VGN |  |
| 70＋直00009才 ${ }^{\text {I }}$ |  | 70＋号007\％［8＊${ }^{-}$ | 00＋号000000＊0 |  |  |  |  |
| 00＋岛L87882 ¢ |  |  | 70＋鸟0097IL•I |  |  | VD－ONVS |  |
| ［0＋马007¢E8．8 |  |  | 70－马00LLS6． |  |  | OSdTDº |  |
|  | 70＋具0768LL．¢ | て0＋马0LLE9才 ${ }^{\text {L }}$ |  |  | L0＋H0cc6s9 ${ }^{\text {¢ }}$ | ग¢Və |  |
| 80－Э999869 ¢ |  |  | 70－马¢7\％9LE ¢ | 70＋㱏L68988 ${ }^{\text {－}}$ | 70＋G90L9E8 $\tau^{-}$ | xeuga－马G |  |
|  |  | 70＋号L0¢LE¢ ${ }^{\text {¢ }}$ | ¢L－G09¢068＊ |  |  | ．${ }^{\text {rega }}{ }^{\text {a }}$ | $90^{\circ}$ |
| 90－Э0L6688 ${ }^{-9}$ |  |  | 90－马086TもL＇も | 70＋＇马902988 ${ }^{\circ}{ }^{-}$ | 70＋马鸟90L9¢8 ${ }^{\circ}{ }^{-}$ | GGONVS |  |
| 60－马̧7\％09İ2 | 70＋岛90L988＊${ }^{-}$ |  | 90－马620876 ${ }^{\text {¢ }}$ |  | 70＋ 790 L9 $988^{\circ}{ }^{-}$ |  |  |
| もT－G96も6もLて＇ |  | 70＋直790L988 －$^{-}$ | ¢L－马̧Et¢6087＇¢ | 70＋马ㄱ90L988 $\overbrace{}^{-}$ | 70＋直790L9E8 $\nabla^{-}$ | GGON－STN |  |
| 70＋马40008E67 ${ }^{\text {L }}$ | 10＋鸟0000789＊ |  | 70＋鸟8867 ${ }^{\circ}$ L | L0＋${ }^{\text {H07E9 }}$ ¢ | 70＋岛L689 $7^{-}$ | SZE－GGVfN |  |
|  |  | 70＋ | ¢L－HEtE6087＊ | 70＋鸟790L988 ${ }^{\text {－}}$ | 70＋岛790L9E8 ${ }^{\text {－}}$ | SZC－ST－VGN |  |
| L0－＇马000068 ${ }^{\text {\％}}$ | 70－马00¢LLE＊ 8 | 90－Э0097\＆¢ ¢－ | 00＋号000000＊0 | ¢0－T000000 ${ }^{-}$－ | $\mathrm{C}^{-}$－ $7000000^{\circ} \mathrm{L}^{-}$ | H9－¢ONUV－LHOH |  |
| 80－马LEt698． 2 | 80－马9L60L才 |  | 80－马L6E8LI｀9 | 90－G808EE6 $6^{-}$ | S0－G000000 ${ }^{-1-}$ | Vn－ONVS |  |
| L0－H00cece 9 | L0－G00697L＇I | 90 － $7000086 \square^{-}$ | 90－7008t $20 \cdot$ I | 90－ㅍ009888 $6^{-}$ | ¢0－H000000 L－$^{-}$ | OSdTD ${ }^{\text {－o }}$ |  |
| － | － | － | － | － | － | DGV |  |
| 60－马9290TLT | 90－7079IE\＆¢－ | 90－3LIEEEE E－ | 00＋号000000＊0 | ¢0－T000000 ${ }^{-}$－ | ¢0－T000000 ${ }^{-}{ }^{-}$ | xruga－马9 |  |
| 80－马98LL90＊¢ | ¢0－马8L6z9［＊8 | ¢0－马LIL869＊${ }^{\text {¢ }}$ | L0－G0\＆L9も¢ ${ }^{\text {L }}$ | 90－ษzct8L6．6－ | 90－马̧も¢ $666^{-}$ | ．${ }^{\text {rega }}{ }^{\text {a }}$ | $\pm 0^{\circ}$ |
| 20－Э0も¢767． | 90－G00¢Lİでで | 90－马0008才7＇$¢^{-}$ | L－－马8809あも I | $9^{0}$－G000000 ${ }^{-}$－ | ¢0－G000000 ${ }^{\text {－}}$ | ษGONVS |  |
| 60－Э87LZLL＇\％ | 90－马89808¢ ¢－ | 90－马79678¢ ¢－ | 00＋鸟000000＊0 | S0－G000000 ${ }^{\text {L－}}$ | ¢0－G000000 ${ }^{-}$－ | xeugdseq马 |  |
| ¢L－G9676才LI＇I |  | 90－马\＆\＆¢¢¢¢¢ ¢－ | 00＋年0000000＊0 | $\mathrm{C}^{-}$－H0000000 $\mathrm{I}^{-}$ |  | GGON－STN |  |
| L0＋G000¢Lt0 ${ }^{\text {I }}$ | 00＋马鸟000LL76．8 | 80－h000L七99［－ | ［0＋ 20007979 $^{\text {I }}$ | 00＋直0006006．6 | $\mathrm{C}^{-}$－ $70000000 \mathrm{I}^{-}$ | Sz4－HIVfin |  |
| 9I－HGEGLDLE：8 | 90－马\＆\＆E\＆E\＆E ¢ ${ }^{-}$ |  | 00＋ | $90-$－H0000000 ${ }^{\text {［ }}$ | $90-7.70000000^{\text {－}}{ }^{-}$ | SzY－ST－V近 |  |
| ＇P7S | UеәJN | $7{ }^{\text {fag }}$ | －P7S | บеәЈN | ${ }^{7} \mathrm{~s} 2 \mathrm{~g}$ | ${ }^{\circ} \mathrm{I} \mathrm{IV}$ | шәтqоıд |
|  | T0\＆ |  |  | C0I |  |  |  |

Table D．13：Function values obtained by MEA－LS－R2S，MJADE－R2S，MLS－MODE，DEbavDBmax，SAMODE，DE－DBmax，
SAMO－DE，eABC，Co－CLPSO，SAMO－GA，$\epsilon$ DEg，and ECHT－ARMOR－DE for CEC2010 for c04－c06
Table D.14: Function values obtained by MEA-LS-R2S, MJADE-R2S, MLS-MODE, DEbavDBmax, SAMODE, DE-DBmax, SAMO-DE, eABC, Co-CLPSO, SAMO-GA, $\epsilon$ DEg, and ECHT-ARMOR-DE for CEC2010 for c07-c09

|  |  | 10D |  |  | 30D |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| problem | Alg. | Best | Mean | Std. | Best | Mean | Std. |
| c07 | MEA-LS-R2S | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $7.5841876 \mathrm{E}-28$ | $2.8794751 \mathrm{E}-27$ |
|  | MJADE-R2S | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $4.7839000 \mathrm{E}-01$ | $1.3222000 \mathrm{E}+00$ |
|  | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $3.0805556 \mathrm{E}-27$ | $5.4724404 \mathrm{E}-27$ |
|  | DEbavDBmax | $0.000000 \mathrm{E}+00$ | $1.250285 \mathrm{E}-28$ | $2.274570 \mathrm{E}-28$ | $0.000000 \mathrm{E}+00$ | $1.594650 \mathrm{E}-01$ | $7.973248 \mathrm{E}-01$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $7.762750 \mathrm{E}-23$ | $3.880800 \mathrm{E}-22$ | $9.495250 \mathrm{E}-23$ | $1.782790 \mathrm{E}-13$ | $3.628040 \mathrm{E}-13$ |
|  | $\epsilon$ DEag | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $1.147112 \mathrm{E}-15$ | $2.603632 \mathrm{E}-15$ | $1.233430 \mathrm{E}-15$ |
|  | DE-DBmax | $0.000000 \mathrm{E}+00$ | $1.250285 \mathrm{E}-28$ | $2.274570 \mathrm{E}-28$ | $0.000000 \mathrm{E}+00$ | $3.189299 \mathrm{E}-01$ | $1.103846 \mathrm{E}+00$ |
|  | eABC | $1.044680 \mathrm{E}-03$ | $7.160940 \mathrm{E}+01$ | $5.191130 \mathrm{E}+01$ | $1.761440 \mathrm{E}-01$ | $1.332900 \mathrm{E}+02$ | $2.058280 \mathrm{E}+02$ |
|  | Co-CLPSO | $1.071100 \mathrm{E}-09$ | $7.973200 \mathrm{E}-01$ | $1.627500 \mathrm{E}+00$ | $3.786100 \mathrm{E}-11$ | $1.116300 \mathrm{E}+00$ | $1.826900 \mathrm{E}+00$ |
|  | SAMO-GA | $0.000000 \mathrm{E}+00$ | $7.856600 \mathrm{E}-23$ | $1.208100 \mathrm{E}-22$ | $3.236800 \mathrm{E}-28$ | $3.236800 \mathrm{E}-28$ | $4.576600 \mathrm{E}-44$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $1.078900 \mathrm{E}-25$ | $2.200000 \mathrm{E}-25$ |
| c08 | MEA-LS-R2S | $0.0000000 \mathrm{E}+00$ | $9.6138057 \mathrm{E}+00$ | $3.6240853 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $2.4028595 \mathrm{E}-27$ | $4.9698960 \mathrm{E}-27$ |
|  | MJADE-R2S | $0.0000000 \mathrm{E}+00$ | $9.6105000 \mathrm{E}+00$ | $3.0696000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $2.2044000 \mathrm{E}+02$ | $4.2871000 \mathrm{E}+02$ |
|  | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $8.7384827 \mathrm{E}+00$ | $4.4599415 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $4.3791390 \mathrm{E}-27$ | 8.8083879E-27 |
|  | DEbavDBmax | $0.000000 \mathrm{E}+00$ | $9.216872 \mathrm{E}+00$ | $3.595848 \mathrm{E}+00$ | $1.012710 \mathrm{E}-26$ | $4.200829 \mathrm{E}-26$ | $4.917721 \mathrm{E}-26$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $2.520090 \mathrm{E}-25$ | $1.260047 \mathrm{E}-24$ | $6.425810 \mathrm{E}-21$ | $1.032930 \mathrm{E}-09$ | $2.373300 \mathrm{E}-09$ |
|  | $\epsilon$ DEag | $0.000000 \mathrm{E}+00$ | $6.727528 \mathrm{E}+00$ | $5.560648 \mathrm{E}+00$ | $2.518693 \mathrm{E}-14$ | $7.831464 \mathrm{E}-14$ | $4.855177 \mathrm{E}-14$ |
|  | DE-DBmax | $1.938261 \mathrm{E}-23$ | $1.045963 \mathrm{E}+01$ | $2.182499 \mathrm{E}+00$ | $4.643926 \mathrm{E}-28$ | $8.265845 \mathrm{E}-26$ | $1.185239 \mathrm{E}-25$ |
|  | eABC | $2.870260 \mathrm{E}-01$ | $4.107890 \mathrm{E}+02$ | $9.356030 \mathrm{E}+02$ | $1.600450 \mathrm{E}-02$ | $1.501960 \mathrm{E}+02$ | $7.148770 \mathrm{E}+01$ |
|  | Co-CLPSO | $9.644200 \mathrm{E}-10$ | $6.087600 \mathrm{E}-01$ | $1.425500 \mathrm{E}+00$ | $4.311400 \mathrm{E}-14$ | $4.751700 \mathrm{E}+01$ | $1.125900 \mathrm{E}+02$ |
|  | SAMO-GA | $3.654300 \mathrm{E}-25$ | $3.648700 \mathrm{E}-23$ | $5.693200 \mathrm{E}-23$ | $3.236790 \mathrm{E}-28$ | $1.594860 \mathrm{E}-24$ | $6.776570 \mathrm{E}-24$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $7.526200 \mathrm{E}+00$ | $5.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $2.010100 \mathrm{E}+01$ | $4.700000 \mathrm{E}+01$ |
| c09 | MEA-LS-R2S | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $4.2135334 \mathrm{E}-27$ | $1.4681996 \mathrm{E}-26$ |
|  | MJADE-R2S | $0.0000000 \mathrm{E}+00$ | $3.7515000 \mathrm{E}+11$ | $9.4435000 \mathrm{E}+11$ | $0.0000000 \mathrm{E}+00$ | $7.9184000 \mathrm{E}+11$ | $1.9356000 \mathrm{E}+12$ |
|  | MLS-MODE | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $0.0000000 \mathrm{E}+00$ | $2.5357772 \mathrm{E}-25$ | $1.1769998 \mathrm{E}-24$ |
|  | DEbavDBmax | $0.000000 \mathrm{E}+00$ | $4.538184 \mathrm{E}-26$ | $1.839539 \mathrm{E}-25$ | $0.000000 \mathrm{E}+00$ | $4.302495 \mathrm{E}-26$ | $4.474786 \mathrm{E}-26$ |
|  | SAMODE | $0.000000 \mathrm{E}+00$ | $5.089752 \mathrm{E}+00$ | $2.410828 \mathrm{E}+01$ | $1.186170 \mathrm{E}-20$ | $6.079667 \mathrm{E}+00$ | $1.432599 \mathrm{E}+01$ |
|  | $\epsilon$ DEag | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $2.770665 \mathrm{E}-16$ | $1.072140 \mathrm{E}+01$ | $2.821923 \mathrm{E}+01$ |
|  | DE-DBmax | $0.000000 \mathrm{E}+00$ | $4.248994 \mathrm{E}-26$ | $1.564360 \mathrm{E}-25$ | $0.000000 \mathrm{E}+00$ | $4.771583 \mathrm{E}-26$ | $4.869925 \mathrm{E}-26$ |
|  | eABC | $2.289850 \mathrm{E}+10$ | $2.019340 \mathrm{E}+12$ | $1.810830 \mathrm{E}+12$ | $2.613740 \mathrm{E}+12$ | $1.607560 \mathrm{E}+13$ | $9.287410 \mathrm{E}+12$ |
|  | Co-CLPSO | $3.755100 \mathrm{E}-16$ | $1.993800 \mathrm{E}+10$ | $9.968800 \mathrm{E}+10$ | $1.969500 \mathrm{E}+02$ | $1.482200 \mathrm{E}+08$ | $2.450900 \mathrm{E}+08$ |
|  | SAMO-GA | $3.654300 \mathrm{E}-25$ | $3.648700 \mathrm{E}-23$ | $5.693200 \mathrm{E}-23$ | $3.236790 \mathrm{E}-28$ | $1.594860 \mathrm{E}-24$ | $6.776570 \mathrm{E}-24$ |
|  | ECHT-ARMOR-DE | $0.000000 \mathrm{E}+00$ | $1.763300 \mathrm{E}-01$ | $8.800000 \mathrm{E}-01$ | $0.000000 \mathrm{E}+00$ | $4.611000 \mathrm{E}+00$ | $2.310000 \mathrm{E}+01$ |


| L0－＇g000086 ${ }^{\text {I }}$ |  | L0－＇9009766 ${ }^{\text {－}}{ }^{-}$ |  | L0－马009766 ${ }^{\text {－}}$－ | L0－马009766 ${ }^{\text {－}}$－ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| L0＋年L99902． | $00+$ 年79TE67 ${ }^{-}$ | L0＋具L26989．8－ | 70＋年008［98． |  | 20＋号LItL69 $9^{-}$ | Vn－ONVS |  |
| も0－G00078L｀L | T0－马00LL66 ${ }^{-}$ | L0－马009766 $\mathrm{I}^{-}$ |  | 00＋年00698¢ $\square^{-}$ | L0＋${ }^{\text {H006897 }} \mathrm{T}^{-}$ | OSdTD－o， |  |
| － | － | 70＋鸟08\＆978 $8^{-}$ | 70＋鸟089LSL｀ |  | 70＋G098002 $\mathrm{G}^{-}$ | गGVə |  |
| 60－马696L0才， | L0－GGE9766 ${ }^{-}{ }^{-}$ | L0－乌̧c9766 ${ }^{-}$ | 90－H0908¢L $冖$ | 10－Э¢88も\％0\％$\square^{-}$ |  | xeugd－эФ |  |
|  | － |  | 70＋年99I782． | 70＋示67¢L9 ${ }^{\circ}$ ¢ $^{-}$ | 20＋ 3668002 － －$^{-}$ |  | Z15 |
| 90－＇H068LZ\＆＇${ }^{\text {－}}$ | T0－G\＆LSz66 ${ }^{-}$ | 10－马869766 ${ }^{-}$ | 70＋鸟900088 ${ }^{\text {I }}$ |  | 70＋马66800 ${ }^{\circ} \mathrm{G}$－ | 马GONVS |  |
| 60－马9860¢9＊ | 10－马̧¢9766 L－$^{-}$ | ［0－乌̧c9766 L－$^{-}$ | 20－马可0も079 9 | 10－Э709\％07 $\%^{-}$ |  | хешялея： |  |
| 60－ษ7ワ987โ0＊9 | 10－马97\＆9766 －$^{-}$ |  |  | L0＋男896189 ${ }^{\text {［－}}$ | 70＋鸟79L7091＊${ }^{-}$ | HGON－STN |  |
|  | 10－马0009092 ${ }^{-}$ |  | 70＋马0008778．8 | L0－G00cz\＆z＇${ }^{-}$ | 70＋马 $66800 L^{\circ} \mathrm{G}^{-}$ | Sz¢－HCVfin |  |
|  | ［0－G97\＆9766 －$^{-}$ | L0－乌9才\＆9766 L－$^{-}$ | 70＋ $88766607^{\text { }}$［ | L0＋ |  | SZ4－ST－VGN |  |
| ¢0－H000087＇9 | － |  |  | － | ¢0－G00L7Z¢ ${ }^{\text {T－}}$ | 马Ф－${ }^{\text {－}}$ |  |
| 90－G70002887 |  |  | ¢0－G00¢706．${ }^{\text {¢ }}$ | ¢0－ $7000797 \cdot{ }^{-}$ | モ0－T000¢07．9－ | VN－ONVS |  |
| － | － | － | － | － | － | OSdTDºp |  |
| － | － | － | － | － | － | गяVə |  |
| 80－G0L9778＊9 | 80－马797¢68 ${ }^{\text {I }}$ |  | 9L－G0¢L088．9 | 80－G¢TLZ7¢ ${ }^{\text {－}}$ | 80－G¢TLZ7¢ ${ }^{\text {－}}$ | xeugd－T |  |
| 90－马909L0L｀$冖$ | モ0－马788\＆98 $\square^{-}$ |  | LL－马980Lte 9 | ¢0－G0TLZZ¢ ${ }^{-} \mathrm{T}^{-}$ | ¢0－G0TLZZ¢ ${ }^{\text {－}}$ | 䧃速 | ［LJ |
| 90－G0996才［＇9 |  |  | 60－G0L9L99 ¢ | 80－H0TLZZ¢ ${ }^{-}{ }^{-}$ | 80－H0TLZZ¢ ${ }^{-}$－ | GGONVS |  |
| 0L－H789786．¢ | モ0－马9\＆も¢ $6^{\circ}$ ¢－$^{-}$ | モ0－Э6\＆7¢ ${ }^{-} 6^{-}$ | 机－马L69L97＇ | 80－GETLZZc．${ }^{-}$ | ¢0－G¢TLZZ¢ ${ }^{-}$ |  |  |
| 0L－马6999\％L0 $\%$ |  |  | 8L－G98才ILSE9 |  |  | HGON－STN |  |
| 70－马0000920 ${ }^{\text {\％}}$ | 70－H00009LI＇も | 70－乌00028L0 ${ }^{-}$ | L0－G0006978＊ | L0－H000000才＇ |  | SZY－GAVCN |  |
| ［L－马̧ZもG680．6 |  |  | LI－H0LEち969＊9 |  | \＆0－G78LLZ7c．${ }^{-}$ | SZ4－ST－V＇SN |  |
| 70＋出0000L0＊ | ［0＋鸟0098G9 9 | \＆L－＇H006070 9 | 00＋年000000＊0 | 00＋号000000＊0 | 00＋号000000＊0 | НФ－¢ONYV－LHOG |  |
| 80＋出988LLİL |  |  | 70＋芷886989．7 |  |  | V V－ONVS $^{\text {a }}$ |  |
| 60＋年0088t8 $8^{\circ}$ | 60＋出00LS68．［ | ［0＋走00296 ${ }^{\circ} \mathrm{E}$ | ［I＋鸟00［ $287^{\circ} \mathrm{Z}$ |  | CL－＇H002968＇Z | OSdTDº |  |
|  | $8\left[+\right.$ 鸟0币9867 ${ }^{\circ}$ | ［L＋年007898．6 |  | てI＋直007972．L | 60＋ $30898677^{\circ}$ | गGVə |  |
|  | 6I－G7960才C．${ }^{\text {L }}$ | ¢6－马96L02¢ ${ }^{\text {L }}$ | ¢6－马888L80＇L |  | 00＋岛000000＊0 | xeugd－T |  |
| L0－HLLSGtS ${ }^{\text {\％}}$ | L0＋马马SLI978．8 | ［0＋马7007¢ ${ }^{\circ} \mathrm{¢}$ | 00＋年000000＊0 | 00＋${ }^{\text {－}} 0000000^{\circ}$ | 00＋${ }^{\text {（2000000000 }}$ |  | $0{ }^{5}$ |
| 10＋马67L\＆7T「万 | ［0＋鸟08L096．${ }^{\text {I }}$ |  |  | L0－＇g99929才才 | $00+$ 年00000000 | HGONVS |  |
|  | 07－乌787Zしだも | 97－＇马887909 ${ }^{\text {T }}$ | 97－马8068E\＆＇¢ | 97－＇马9［SEEE＇L | 00＋ |  |  |
| 26－9987ILも9＊6 |  | 00＋舄0000000＊0 | 00＋鸟0000000＊0 |  | 00＋慁0000000．0 | HGON－STN |  |
|  |  | 20＋直000608L ${ }^{\circ}$ |  | 0工＋G000cccit | 00＋直0000000＊0 | SzC－HCVfN |  |
|  | L7－岛gctu909．9 | 00＋年0000000＊0 | 00＋马过000000＊0 | 00＋马30000000＊0 | 00＋直0000000＊0 | SZY－ST－VGL |  |
| －P7S | บеәЈ | 7səg | ＇P7S | 廿еәJ | 7Səg | ＇8． IV | แәโqoıd |
|  | T0\＆ |  |  | （10I |  |  |  |


Table D．15：Function values obtained by MEA－LS－R2S，MJADE－R2S，MLS－MODE，DEbavDBmax ，SAMODE，DE－DBmax，
Table D.16: Function values obtained by MEA-LS-R2S, MJADE-R2S, MLS-MODE, DEbavDBmax, SAMODE, DE-DBmax, SAMO-DE, eABC, Co-CLPSO, SAMO-GA, $\epsilon$ DEg, and ECHT-ARMOR-DE for CEC2010 for c13-c15

|  |  | 10 D |  |  |  |  |  |  | 30 D |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| problem | Alg. | Best | Mean | Std. | Best | Mean | Std. |  |  |  |  |  |  |
|  | MEA-LS-R2S | $-6.8429365 \mathrm{E}+01$ | $-6.8429118 \mathrm{E}+01$ | $5.0963112 \mathrm{E}-04$ | $-6.2363464 \mathrm{E}+01$ | $-6.0130423 \mathrm{E}+01$ | $1.2087678 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | MJADE-R2S | $-6.8429000 \mathrm{E}+01$ | $-6.8315000 \mathrm{E}+01$ | $5.7018000 \mathrm{E}-01$ | $-6.8429000 \mathrm{E}+01$ | $-6.5867000 \mathrm{E}+01$ | $1.6725000 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | MLS-MODE | $-6.8429363 \mathrm{E}+01$ | $-6.8416666 \mathrm{E}+01$ | $8.3825697 \mathrm{E}-03$ | $-6.1630347 \mathrm{E}+01$ | $-5.8816532 \mathrm{E}+01$ | $1.4972294 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | DEbavDBmax | $-6.842937 \mathrm{E}+01$ | $-6.750889 \mathrm{E}+01$ | $1.414780 \mathrm{E}+00$ | $-6.583213 \mathrm{E}+01$ | $-6.018059 \mathrm{E}+01$ | $5.066890 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | SAMODE | $-6.842937 \mathrm{E}+01$ | $-6.842937 \mathrm{E}+01$ | $1.542877 \mathrm{E}-07$ | $-6.842940 \mathrm{E}+01$ | $-6.819178 \mathrm{E}+01$ | $3.891641 \mathrm{E}-01$ |  |  |  |  |  |  |
| c 13 | $\epsilon$ DEag | $-6.842937 \mathrm{E}+01$ | $-6.842936 \mathrm{E}+01$ | $1.025960 \mathrm{E}-06$ | $-6.642473 \mathrm{E}+01$ | $-6.535310 \mathrm{E}+01$ | $5.733005 \mathrm{E}-01$ |  |  |  |  |  |  |
|  | DE-DBmax | $-6.842937 \mathrm{E}+01$ | $-6.755373 \mathrm{E}+01$ | $1.275098 \mathrm{E}+00$ | $-6.575545 \mathrm{E}+01$ | $-6.002365 \mathrm{E}+01$ | $5.274321 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | eABC | $-6.842890 \mathrm{E}+01$ | $-6.568060 \mathrm{E}+01$ | $2.502700 \mathrm{E}+00$ | $-6.756870 \mathrm{E}+01$ | $-6.485590 \mathrm{E}+01$ | $1.382130 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | Co-CLPSO | $-6.842936 \mathrm{E}+01$ | $-6.397445 \mathrm{E}+01$ | $2.134080 \mathrm{E}+00$ | $-6.275200 \mathrm{E}+01$ | $-6.077400 \mathrm{E}+01$ | $1.117600 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | SAMO-GA | $-6.842803 \mathrm{E}+01$ | $-6.837658 \mathrm{E}+01$ | $1.558530 \mathrm{E}-01$ | $-6.637738 \mathrm{E}+01$ | $-6.309871 \mathrm{E}+01$ | $1.286011 \mathrm{E}+00$ |  |  |  |  |  |  |
|  | ECHT-ARMOR-DE | $-6.842900 \mathrm{E}+01$ | $-6.716900 \mathrm{E}+01$ | $2.100000 \mathrm{E}+00$ | $-6.741600 \mathrm{E}+01$ | $-6.464600 \mathrm{E}+01$ | $1.970000 \mathrm{E}+00$ |  |  |  |  |  |  | $\begin{array}{cc}3.0652610 \mathrm{E}-27 & 1.0423172 \mathrm{E}-26 \\ 9.8075000 \mathrm{E}+05 & 3.4831000 \mathrm{E}+06\end{array}$ $3.0384713 \mathrm{E}-27 \quad 7.2647679 \mathrm{E}-27$ $1.010587 \mathrm{E}-25 \quad 8.052860 \mathrm{E}-26$ $1.196910 \mathrm{E}-08-2.569420 \mathrm{E}-08$




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 $4.6049062 \mathrm{E}-27$
$5.7336000 \mathrm{E}+13$
 $2.968697 \mathrm{E}-22$ $4.510670 \mathrm{E}+00$
 6.666822E-20




| 00＋H000000＊ 0 | 00＋${ }^{\text {H00000000 }}$ | 00＋H000000 0 | 00＋H000000 0 | 00＋ $70000000^{\circ}$ | 00＋H000000 0 | HG－צONYV－LHOE |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| I0＋GE02IS $0^{\circ} \mathrm{I}$ | 00＋G872989 2 | L0－H067818 \％ |  | 70－G960¢c0 ${ }^{\text {－}}$ | LI－H000698．t | Vサ－ONVS |  |
|  | L0＋H002L80＇I | て0－H002700．9 | L0－H006996．6 | 10－g00z6L\＆\％ | L\％－4007082： | OSdTD－o， |  |
| 70＋H0¢ $¢ 88 \mathrm{c}^{-8}$ | 70＋H098E¢6 7 | L0－H098096． | 70＋H0920LLE | Z0＋G0¢ $202 \pm$ ¢ | ع0－H027860 \％ | ग¢və |  |
| ォ0－H2LZ0¢\％6 | モ0－®゙て0106 \％ | LI－H992IE9－ | もて－gzLItst 6 | モて－GLZ8L9\％ | 96－9689078：8 | xセugの－эФ |  |
| 70＋HEGL799 | L0＋\＃69cts ${ }^{\text {c }}$ |  |  | 61－Gc9L829\％6 | 07－G0tticis |  | $85^{2}$ |
| もL－H00G8LC． 9 | モL－G01ヵ882．も |  | ¢t－H0才¢078．8 | モI－G0682L9 ${ }^{\text {I }}$ | ¢t－H0t998\％\％ | gaonvs |  |
| 00＋GL98998． |  | $8 \mathrm{I}-\mathrm{HL} 60080$－ | も\％－489998E： | モて－g8LもG88＇8 | 9\％－98\％96\％z＇t |  |  |
| モ0－G9c976LI＇I | 90－HE0616768 |  | L\＆－gcese9ti＇t | IE－Gt¢L0LIZ＇\＆ | 00＋ 0 0000000 0 | gaon－stiv |  |
| 80＋H000gcslit | 80＋ 0000 ctex て | 00＋ 000000000 | 80＋ $00008887^{\prime}$ I | 70＋ $7000 \mathrm{G} 767^{\circ} \mathrm{C}$ | 00＋ 0 0000000 0 | szy－gavin |  |
| 80－H60z68¢才 8 |  | L\＆－gctoett6\％ | 28－g0ct60f8 I | 8¢－马69Lzett＂ 8 | 00＋H0000000－0 | Szy－ST－vain |  |
| L0－G0000L¢ ¢ | 10－G009¢¢0＇も | 9T－H00ヶ998． | ¢¢－－H00000I＇$¢$ | ¢¢－G008269\％ | 00＋H000000 0 | Hब－yONYV－LHOE |  |
| 70－H0079L9 ${ }^{\text {I }}$ | \％0－g009¢ぇE I | $00+$ H000000 0 | 70－H6z0tEE＇ | 70－g00202\％${ }^{\text {I }}$ | 00＋H00000000 | Vn－ONVS |  |
|  | 00＋ H006I68．$^{\text {I }}$ | L0－H00L8L9 ${ }^{\text {I }}$ | L0－H00ヶ889．t | 10－100986 ${ }^{\text {c \％}}$ | LI－H00L299 2 | OSdTD－o， |  |
| L0＋H0gctec i | L0＋H002089\％ | 00＋H07g L9\％¢ | 00＋H098te8．9 | 00＋G0067ヶで¢ | 70－H0988E¢ z | गяv |  |
| LI－HLZG689 ${ }^{\text {I }}$ | 2T－G650678．9 | 0\％－3291もLİ | ¢0－H8899¢İt | co－b9tctat I | $88^{-9990860 \%}$ | xruga－gの |  |
| 00＋HL69986 ${ }^{\text {\％}}$ | 00＋马287978． 9 | L0－H6TL99「\％ | L0－H26ILE6 ${ }^{\text {I }}$ | 10－GL9c6\％z＇I | LI－H08t89才 ${ }^{\text {L }}$ |  | $\angle 15$ |
| 0I－G0gtcet | 0I－G0¢97\％0 ${ }^{\text {I }}$ | $00+$ H000000 0 | 8\％－9L66LIz＇8 |  |  | GGONVS |  |
| てL－H0モ6188．9 | てL－Gz¢6IL8 | 81－H87\％T90＇L | 85－H96L620 ${ }^{\text {I }}$ | 65－G9ちも¢¢0 2 |  |  |  |
| \＆L－HzL986てL＇ | モL－H9も¢Gt6e $\%$ | 7\％－G09c09ces | ¢6－g96пL091＇t |  | L6－gezr9tce | HGON－STN |  |
| 10－G0002IS6 \％ | 10－G000¢ち¢¢ $冖$ | 00＋ $70000000{ }^{\circ}$ | L0－G000768L＇¢ | L0－马0008099． | $00+$ H0000000 0 | Szq－gavin |  |
| LI－HLIEzLL6\％ | LI－H967687¢． | ¢\％－H0¢9L069：¢ | \＆\＆－gIt0e\％7T＇\＆ | \＆\＆－gs99ticte | 00＋ 0 0000000 0 | Szy－ST－van |  |
| 00＋H000000＊0 | 00＋H00000000 | $00+$ H000000 0 | 20－H000000 ${ }^{\circ}$ | 70－G008L78．${ }^{\text {\％}}$ | 00＋H000000 0 | HG－yONYV－LHDE |  |
| ¢0－G000788：9 | ¢0－G0002\＆L ¢ | 00＋马00000000 | ¢0－H000088＇t | ¢0－G00t¢07． | 00＋马000000 0 | Vn－ONVS |  |
| 91－H00zz29＇も | 91－ษ00¢0才で¢ | 00＋ $7000000^{\circ} 0$ | 70－H009tE8＇L | ¢0－G00L986 ¢ | 00＋ $0^{0} 0000000$ | OSdTD－o， |  |
| L0－g088699\％ | 10－g0zz20\％ 8 |  | 20－H068901．6 |  | 00＋H000000＊0 | गgvə |  |
| 00＋H00000000 | 00＋H00000000 | 00＋马00000000 | L0－G98LIOE¢ | L0－G008zEE I | 00＋H000000 0 | xpugの－ษФ |  |
| 07－GL6z790 ${ }^{\text {I }}$ |  | $00+$ 可000000 0 | 20－G6LT0TL． | L0－®tcoz02 ¢ | $00+$ H000000 0 |  | $9{ }^{5}$ |
| 80－H006LL9 ${ }^{\text {L }}$ | 80－g00209Tt | 00＋ 000000000 |  | ¢0－g009697． 9 | 00＋H000000 0 | gaonvs |  |
| 00＋G000000\％ 0 | 00＋H00000000 | 00＋马00000000 | 00＋马00000000 | 00＋G000000＊0 | 00＋ 700000000 |  |  |
| $00+$ H0000000 0 | 00＋ $00000000{ }^{\circ}$ | 00＋马0000000 0 | 00＋ 000000000 | 00＋ $70000000^{\circ}$ | 00＋ 0 0000000 0 | faon－stu |  |
| 00＋ $00000000{ }^{\circ}$ | 00＋ $00000000{ }^{\circ}$ | 00＋ $00000000{ }^{\circ}$ | 00＋ $70000000{ }^{\circ}$ | 00＋马000000000 |  | Szy－gatin |  |
| 00＋ $00000000 \cdot 0$ | 00＋ $70000000{ }^{\circ}$ | 00＋ H0000000 $^{\circ}$ | 00＋ 000000000 | $00+$ H00000000 | 00＋H0000000＊ | SzY－ST－vain |  |
| －P7S | чеәЈ | $7^{\text {sag }}$ | －P7S | чеәЈ | $7^{\text {sag }}$ | ${ }^{\text {¢ }}$ IV | шәq¢．ıd |
|  | ¢0¢ |  |  | đ0I |  |  |  |

Table D.18: Function values obtained by MEA-LS-R2S, MJADE-R2S, MLS-MODE, ADE , EPSDE, SAMODE, DE-Acr, CDELS, CDASA and ISAMODE-CMA for CEC2011 for r01-r04

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r01 | MEA-LS-R2S | $1.5444180 \mathrm{E}+04$ | $1.5444180 \mathrm{E}+04$ | $5.9094187 \mathrm{E}-06$ |
|  | MJADE-R2S | $1.5444180 \mathrm{E}+04$ | $1.5444180 \mathrm{E}+04$ | $1.0855000 \mathrm{E}-06$ |
|  | MLS-MODE | $1.5444180 \mathrm{E}+04$ | $1.5444180 \mathrm{E}+04$ | 6.1846980E-07 |
|  | ADE | $1.5445380 \mathrm{E}+04$ | $1.5482070 \mathrm{E}+04$ | $3.0473660 \mathrm{E}+01$ |
|  | EPSDE | $1.5400000 \mathrm{E}+04$ | $1.5500000 \mathrm{E}+04$ | $1.5500000 \mathrm{E}+01$ |
|  | SAMODE | $1.5444190 \mathrm{E}+04$ | $1.5444230 \mathrm{E}+04$ | $3.7333110 \mathrm{E}-02$ |
|  | DE-Acr | $1.5445000 \mathrm{E}+04$ | $1.5446000 \mathrm{E}+04$ | $8.4385000 \mathrm{E}-01$ |
|  | CDELS | $1.5446550 \mathrm{E}+04$ | $1.5446999 \mathrm{E}+04$ | $1.5449634 \mathrm{E}+04$ |
|  | CDASA | $1.5461000 \mathrm{E}+04$ | $1.5511000 \mathrm{E}+04$ | $4.2337000 \mathrm{E}+01$ |
|  | ISAMODE-CMA | $1.5444190 \mathrm{E}+04$ | $1.5444190 \mathrm{E}+04$ | $1.1438000 \mathrm{E}-05$ |
| r02 | MEA-LS-R2S | $1.8022057 \mathrm{E}+04$ | $1.8099598 \mathrm{E}+04$ | $4.1904473 \mathrm{E}+01$ |
|  | MJADE-R2S | $1.8028000 \mathrm{E}+04$ | $1.8120000 \mathrm{E}+04$ | $5.0666000 \mathrm{E}+01$ |
|  | MLS-MODE | $1.8050910 \mathrm{E}+04$ | $1.8104920 \mathrm{E}+04$ | $3.7112340 \mathrm{E}+01$ |
|  | ADE | $1.8224720 \mathrm{E}+04$ | $1.8550260 \mathrm{E}+04$ | $1.4151470 \mathrm{E}+02$ |
|  | EPSDE | $1.8100000 \mathrm{E}+04$ | $1.8100000 \mathrm{E}+04$ | $4.3900000 \mathrm{E}+01$ |
|  | SAMODE | $1.8046840 \mathrm{E}+04$ | $1.8185590 \mathrm{E}+04$ | $1.0714080 \mathrm{E}+02$ |
|  | DE-Acr | $1.8028000 \mathrm{E}+04$ | $1.8096000 \mathrm{E}+04$ | $3.9913000 \mathrm{E}+01$ |
|  | CDELS | $1.9007720 \mathrm{E}+04$ | $1.9120010 \mathrm{E}+04$ | $1.9185830 \mathrm{E}+04$ |
|  | CDASA | $1.8942000 \mathrm{E}+04$ | $1.9323000 \mathrm{E}+04$ | $2.1267000 \mathrm{E}+02$ |
|  | ISAMODE-CMA | $1.8026760 \mathrm{E}+04$ | $1.8104590 \mathrm{E}+04$ | $3.7545240 \mathrm{E}+01$ |
| r03 | MEA-LS-R2S | $3.2692510 \mathrm{E}+04$ | $3.2692963 \mathrm{E}+04$ | $2.5587740 \mathrm{E}-01$ |
|  | MJADE-R2S | $3.2692000 \mathrm{E}+04$ | $3.2694000 \mathrm{E}+04$ | $9.5705000 \mathrm{E}+00$ |
|  | MLS-MODE | $3.2797750 \mathrm{E}+04$ | $3.2890930 \mathrm{E}+04$ | $4.7772960 \mathrm{E}+01$ |
|  | ADE | $3.2744200 \mathrm{E}+04$ | $3.2859400 \mathrm{E}+04$ | $6.8413650 \mathrm{E}+01$ |
|  | EPSDE | $3.2600000 \mathrm{E}+04$ | $3.2700000 \mathrm{E}+04$ | $3.5900000 \mathrm{E}+01$ |
|  | SAMODE | $3.2721950 \mathrm{E}+04$ | $3.2737580 \mathrm{E}+04$ | $7.7779080 \mathrm{E}+00$ |
|  | DE-Acr | $3.2730000 \mathrm{E}+04$ | $3.2790000 \mathrm{E}+04$ | $3.0447000 \mathrm{E}+01$ |
|  | CDELS | $3.2928030 \mathrm{E}+04$ | $3.2958290 \mathrm{E}+04$ | $3.3031150 \mathrm{E}+04$ |
|  | CDASA | $3.2966000 \mathrm{E}+04$ | $3.3181000 \mathrm{E}+04$ | $1.0457000 \mathrm{E}+02$ |
|  | ISAMODE-CMA | $3.2694660 \mathrm{E}+04$ | $3.2699270 \mathrm{E}+04$ | $9.4083270 \mathrm{E}+00$ |
| r04 | MEA-LS-R2S | $1.2174208 \mathrm{E}+05$ | $1.2228089 \mathrm{E}+05$ | $3.2780024 \mathrm{E}+02$ |
|  | MJADE-R2S | $1.2145000 \mathrm{E}+05$ | $1.2157000 \mathrm{E}+05$ | $8.5076000 \mathrm{E}+01$ |
|  | MLS-MODE | $1.2281680 \mathrm{E}+05$ | $1.2448750 \mathrm{E}+05$ | $7.2852280 \mathrm{E}+02$ |
|  | ADE | $1.2406900 \mathrm{E}+05$ | $1.2553230 \mathrm{E}+05$ | $8.3625570 \mathrm{E}+02$ |
|  | EPSDE | $1.2800000 \mathrm{E}+05$ | $1.3100000 \mathrm{E}+05$ | $2.4700000 \mathrm{E}+03$ |
|  | SAMODE | $1.2278753 \mathrm{E}+05$ | $1.2409967 \mathrm{E}+05$ | $8.0725815 \mathrm{E}+02$ |
|  | DE-Acr | $1.2313000 \mathrm{E}+05$ | $1.2389000 \mathrm{E}+05$ | $4.5430000 \mathrm{E}+02$ |
|  | CDELS | $1.3590694 \mathrm{E}+05$ | $1.3771068 \mathrm{E}+05$ | $1.4118462 \mathrm{E}+05$ |
|  | CDASA | $1.3242000 \mathrm{E}+05$ | $1.4666000 \mathrm{E}+05$ | $6.3435000 \mathrm{E}+03$ |
|  | ISAMODE-CMA | $1.2161578 \mathrm{E}+05$ | $1.2222620 \mathrm{E}+05$ | $3.2839232 \mathrm{E}+02$ |

Table D.19: Function values obtained by MEA-LS-R2S, MJADE-R2S, MLS-MODE, ADE , EPSDE, SAMODE, DE-Acr, CDELS, CDASA and ISAMODE-CMA for CEC2011 for $\mathrm{r} 05-\mathrm{r} 08$

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r05 | MEA-LS-R2S | $1.6816543 \mathrm{E}+06$ | $1.6884982 \mathrm{E}+06$ | $4.5464334 \mathrm{E}+03$ |
|  | MJADE-R2S | $1.6649000 \mathrm{E}+06$ | $1.6685000 \mathrm{E}+06$ | $3.4583000 \mathrm{E}+03$ |
|  | MLS-MODE | $1.6769140 \mathrm{E}+06$ | $1.7812770 \mathrm{E}+06$ | $4.9848520 \mathrm{E}+04$ |
|  | ADE | $1.8906710 \mathrm{E}+06$ | $1.9250980 \mathrm{E}+06$ | $2.3429040 \mathrm{E}+04$ |
|  | EPSDE | $1.9100000 \mathrm{E}+06$ | $1.9200000 \mathrm{E}+06$ | $1.1800000 \mathrm{E}+04$ |
|  | SAMODE | $1.8891308 \mathrm{E}+06$ | $1.9876716 \mathrm{E}+06$ | $1.2556507 \mathrm{E}+05$ |
|  | DE-Acr | $1.7124000 \mathrm{E}+06$ | $1.8386000 \mathrm{E}+06$ | $4.5074000 \mathrm{E}+04$ |
|  | CDELS | $1.9209047 \mathrm{E}+06$ | $1.9464404 \mathrm{E}+06$ | $1.9573575 \mathrm{E}+06$ |
|  | CDASA | $1.8828000 \mathrm{E}+06$ | $2.0375000 \mathrm{E}+06$ | $2.4110000 \mathrm{E}+05$ |
|  | ISAMODE-CMA | $1.6932933 \mathrm{E}+06$ | $1.7047279 \mathrm{E}+06$ | $7.3628216 \mathrm{E}+03$ |
| r06 | MEA-LS-R2S | $4.2463168 \mathrm{E}+04$ | $4.3584413 \mathrm{E}+04$ | $6.4356329 \mathrm{E}+02$ |
|  | MJADE-R2S | $4.5730000 \mathrm{E}+04$ | $4.6586000 \mathrm{E}+04$ | $5.5149000 \mathrm{E}+02$ |
|  | MLS-MODE | $4.8705940 \mathrm{E}+04$ | $5.0643040 \mathrm{E}+04$ | $1.2705080 \mathrm{E}+03$ |
|  | ADE | $5.0170600 \mathrm{E}+04$ | $5.4181520 \mathrm{E}+04$ | $4.8669640 \mathrm{E}+03$ |
|  | EPSDE | $5.1100000 \mathrm{E}+04$ | $5.2200000 \mathrm{E}+04$ | $7.2400000 \mathrm{E}+02$ |
|  | SAMODE | $5.0981400 \mathrm{E}+04$ | $5.3278380 \mathrm{E}+04$ | $2.0317090 \mathrm{E}+03$ |
|  | DE-Acr | $4.4847000 \mathrm{E}+04$ | $4.6321000 \mathrm{E}+04$ | $1.3962000 \mathrm{E}+03$ |
|  | CDELS | $6.8146400 \mathrm{E}+04$ | $7.3806300 \mathrm{E}+04$ | $8.0638850 \mathrm{E}+04$ |
|  | CDASA | $5.1210000 \mathrm{E}+04$ | $5.2017000 \mathrm{E}+04$ | $3.9028000 \mathrm{E}+02$ |
|  | ISAMODE-CMA | $4.7110730 \mathrm{E}+04$ | $4.8765770 \mathrm{E}+04$ | $7.8542710 \mathrm{E}+02$ |
| r07 | MEA-LS-R2S | $1.0709458 \mathrm{E}+06$ | $1.0741581 \mathrm{E}+06$ | $1.9933780 \mathrm{E}+03$ |
|  | MJADE-R2S | $9.2271000 \mathrm{E}+05$ | $9.4068000 \mathrm{E}+05$ | $8.0356000 \mathrm{E}+03$ |
|  | MLS-MODE | $1.0544620 \mathrm{E}+06$ | $1.0684960 \mathrm{E}+06$ | $4.9241360 \mathrm{E}+03$ |
|  | ADE | $1.0785260 \mathrm{E}+06$ | $1.0866840 \mathrm{E}+06$ | $4.4556550 \mathrm{E}+03$ |
|  | EPSDE | $1.0600000 \mathrm{E}+06$ | $1.0700000 \mathrm{E}+06$ | $2.1300000 \mathrm{E}+03$ |
|  | SAMODE | $1.0675010 \mathrm{E}+06$ | $1.0707990 \mathrm{E}+06$ | $1.2727460 \mathrm{E}+03$ |
|  | DE-Acr | $1.0354000 \mathrm{E}+06$ | $1.0490000 \mathrm{E}+06$ | $2.9044000 \mathrm{E}+05$ |
|  | CDELS | $2.4228390 \mathrm{E}+06$ | $2.4461757 \mathrm{E}+06$ | $2.5662654 \mathrm{E}+06$ |
|  | CDASA | $1.2683000 \mathrm{E}+06$ | $1.2717000 \mathrm{E}+06$ | $1.8724000 \mathrm{E}+03$ |
|  | ISAMODE-CMA | $1.0597810 \mathrm{E}+06$ | $1.0698800 \mathrm{E}+06$ | $8.7739890 \mathrm{E}+03$ |
| r08 | MEA-LS-R2S | $9.1582841 \mathrm{E}+05$ | $9.1639120 \mathrm{E}+05$ | $3.7769095 \mathrm{E}+02$ |
|  | MJADE-R2S | $9.1692000 \mathrm{E}+05$ | $9.1733000 \mathrm{E}+05$ | $3.8198000 \mathrm{E}+02$ |
|  | MLS-MODE | $9.1578410 \mathrm{E}+05$ | $9.1618010 \mathrm{E}+05$ | $2.6227390 \mathrm{E}+02$ |
|  | ADE | $9.2482150 \mathrm{E}+05$ | $9.3060260 \mathrm{E}+05$ | $3.5027700 \mathrm{E}+03$ |
|  | EPSDE | $9.3900000 \mathrm{E}+05$ | $9.4300000 \mathrm{E}+05$ | $2.6300000 \mathrm{E}+03$ |
|  | SAMODE | $9.2435370 \mathrm{E}+05$ | $9.2580000 \mathrm{E}+05$ | $6.7159130 \mathrm{E}+02$ |
|  | DE-Acr | $9.2280000 \mathrm{E}+05$ | $9.2393000 \mathrm{E}+05$ | $7.4822000 \mathrm{E}+02$ |
|  | CDELS | $9.8301754 \mathrm{E}+05$ | $1.0188345 \mathrm{E}+06$ | $1.2755968 \mathrm{E}+06$ |
|  | CDASA | $9.4142000 \mathrm{E}+05$ | $9.4569000 \mathrm{E}+05$ | $3.6946000 \mathrm{E}+03$ |
|  | ISAMODE-CMA | $9.2665670 \mathrm{E}+05$ | $9.2820880 \mathrm{E}+05$ | $7.3186610 \mathrm{E}+02$ |

Table D.20: Function values obtained by MEA-LS-R2S, MJADE-R2S, MLS-MODE, ADE , EPSDE, SAMODE, DE-Acr, CDELS, CDASA and ISAMODE-CMA for CEC2011 for r09-r10

| problem | Alg. | Best | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: |
| r09 | MEA-LS-R2S | $9.1665633 \mathrm{E}+05$ | $9.1804031 \mathrm{E}+05$ | $8.2400159 \mathrm{E}+02$ |
|  | MJADE-R2S | $9.1749000 \mathrm{E}+05$ | $9.1837000 \mathrm{E}+05$ | $5.2993000 \mathrm{E}+02$ |
|  | MLS-MODE | $9.1970990 \mathrm{E}+05$ | $9.2427600 \mathrm{E}+05$ | $1.6122740 \mathrm{E}+03$ |
|  | ADE | $9.2832270 \mathrm{E}+05$ | $9.9296430 \mathrm{E}+05$ | $1.9642450 \mathrm{E}+05$ |
|  | EPSDE | $9.4000000 \mathrm{E}+05$ | $9.9000000 \mathrm{E}+05$ | $4.1400000 \mathrm{E}+04$ |
|  | SAMODE | $9.2432330 \mathrm{E}+05$ | $9.2602220 \mathrm{E}+05$ | $7.2979820 \mathrm{E}+02$ |
|  | DE-Acr | $9.2717000 \mathrm{E}+05$ | $9.3001000 \mathrm{E}+05$ | $1.6287000 \mathrm{E}+03$ |
|  | CDELS | $1.4593034 \mathrm{E}+06$ | $1.5374957 \mathrm{E}+06$ | $1.8722742 \mathrm{E}+06$ |
|  | CDASA | $1.1044000 \mathrm{E}+06$ | $1.4012000 \mathrm{E}+06$ | $1.7944000 \mathrm{E}+05$ |
|  | ISAMODE-CMA | $9.2867730 \mathrm{E}+05$ | $9.3071350 \mathrm{E}+05$ | $1.3829670 \mathrm{E}+03$ |
| r10 | MEA-LS-R2S | $9.2611291 \mathrm{E}+05$ | $9.2748192 \mathrm{E}+05$ | $7.4658811 \mathrm{E}+02$ |
|  | MJADE-R2S | $9.2737000 \mathrm{E}+05$ | $9.2926000 \mathrm{E}+05$ | $9.6017000 \mathrm{E}+02$ |
|  | MLS-MODE | $9.2689750 \mathrm{E}+05$ | $9.3485490 \mathrm{E}+05$ | $4.4514900 \mathrm{E}+03$ |
|  | ADE | $9.2714540 \mathrm{E}+05$ | $9.3052880 \mathrm{E}+05$ | $3.0638130 \mathrm{E}+03$ |
|  | EPSDE | $9.3900000 \mathrm{E}+05$ | $9.4300000 \mathrm{E}+05$ | $2.6300000 \mathrm{E}+03$ |
|  | SAMODE | $9.2437627 \mathrm{E}+05$ | $9.2584595 \mathrm{E}+05$ | $7.6154770 \mathrm{E}+02$ |
|  | DE-Acr | $9.2303000 \mathrm{E}+05$ | $9.2382000 \mathrm{E}+05$ | $5.1463000 \mathrm{E}+02$ |
|  | CDELS | $1.0026198 \mathrm{E}+06$ | $1.0295312 \mathrm{E}+06$ | $1.2755968 \mathrm{E}+06$ |
|  | CDASA | $9.3967000 \mathrm{E}+05$ | $9.4887000 \mathrm{E}+05$ | $1.8056000 \mathrm{E}+04$ |
|  | ISAMODE-CMA | $9.2614541 \mathrm{E}+05$ | $9.2795464 \mathrm{E}+05$ | $9.1952510 \mathrm{E}+02$ |

## Appendix E

# Two-phase Differential Evolution Framework for Solving Optimization Problems 

Karam M. Sallam, Saber M. Elsayed, Ruhul A. Sarker and Daryl L. Essam<br>School of Engineering and Information Technology<br>University of New South Wales at Canberra<br>Australia<br>Emails: karam.sallam@student.adfa.edu.au;\{s.elsayed, r.sarker, d.essam\}@adfa.edu.au


#### Abstract

Over the last two decades, different differential evolution (DE) variants have been successfully used to solve different optimization problems. However, no single DE algorithm has consistently been the best for solving a wide range of them. In the literature, this drawback has been tackled by using multiple DE operators in a single framework. However, utilizing a problem's landscape in the design of an efficient selection mechanism to emphasize the best-performing DE variant has not yet been thoroughly explored. Motivated by this fact, in this paper, a new two-phase (exploration and exploitation) multioperator DE algorithm is proposed. It starts with the exploration phase, dynamically placing emphasis on the best-performing DE based on two landscape indicators and its performance history, and then repeats this process during the exploitation phase. To judge the performance of this algorithm, a variety of real-world optimization problems taken from different disciplines are solved. According to the results obtained, this algorithm shows superior performance to those of state-of-the-art algorithms.


Index Terms-differential evolution, multi-operator, landscape indicators, real-world problems

## I. Introduction

Many real-world problems in different fields, such as operations research, biology, data mining and engineering design, can be formulated as optimization problems with one or more objective functions subject to some constraints.

Due to the importance of solving these problems, researchers and practitioners have proposed exact methods. However, as they usually encounter many challenges, such as (1) requiring specific mathematical properties, such as convexity, continuity and differentiability, to be used; and/or (2) maybe needing the problem to be simplified by making various assumptions for the convenience of mathematical modeling [1], their use in the majority of real-world cases is unverified. For these reasons, many evolutionary algorithms (EAs) have been proposed and implemented in order to tackle real-world optimization problems. However, although they do not require specific mathematical properties to be satisfied, are flexible to dynamic changes, can handle evaluating each solution in parallel, have the capability for self-organization and are more broadly applicable in practice, there is no guarantee that they can reach an optimal solution and the quality of their solutions depends on their parameter settings. Indeed, selecting an appropriate algorithm for solving an optimization problem is not an easy task.

The family of EAs contains various algorithms, such as DE [2], genetic algorithms (GAs) [3] and evolution strategy (ES) [4], with the major difference among them the ways in which they produce new solutions. Of EAs, DE has gained popularity for solving continuous optimization problems [5][6]. However, there is no guarantee that a DE algorithm, which performs well for one or a certain class of problems will work well for another or a range of problems. One reason for this is the variability of the underlying mathematical properties of optimization problems.

To overcome this limitation, multi-methods and/or multioperator algorithms, in which more than one algorithm and/or search operator are used in a single framework with a mechanism for emphasizing the best-performing one during the search process [7], [8], have been developed. In the literature, there are different categories of these methods, such as ensemble-based [9][10], hyper-heuristics [11], mutlimethods [12][13], multi-operators [7] and heterogeneous [14] approaches. They all consist of a pool of different algorithms and/or operators, and use a selection mechanism to emphasize the best-performing algorithm and/or operator during the search process based on different criteria, such as a reenforcement learning mechanism [15][16], improvement in the solution quality and/or constraint violations and/or feasibility rate [8], and convergence differences and progress ratios [17].
However, determining a way of combining these operators and/or methods is still challenging. Also, utilizing a problem's landscape to design an efficient selection mechanism has not been comprehensively explored. Although it has been noted that the pool of operators is always fixed during the evolutionary process, this may lead to consuming too much computational effort because of poorly performing DE operators. Therefore, in this paper, we investigate using landscape metrics to obtain information about the characteristics of problems, such as modality, separability, etc., and place emphasis on better-performing DE operators, and changing the pool of DE operators based on the optimization phase.

Consequently, a novel two-phase multi-operator DE with a landscape selection mechanism, referred to as TP-MODE, is proposed in this paper. In TP-MODE the whole evolutionary process is divided into two phases based on the number
of fitness evaluations. In the first, a group of DE mutation strategies which have the capability to maintain diversity are chosen to generate trial vectors and, in the latter, other DE mutation strategies characterized by their ability to converge fast are chosen to produce offspring. Simultaneously, a landscape metric is used to place more emphasis on the best-performing operator in each phase. TP-MODE is tested on 22 benchmark test functions taken from the IEEE CEC2011 competition for solving real-world applications [18]. The experimental results imply that the performance of TPMODE is better than those of four other state-of-the-art DE variants.

The rest of this paper is organized as follows: in Section II, a review of DE algorithms and operators, and some landscape measures is presented. Section III describes the proposed framework; the simulation results for the benchmark problems and values of the parameters are provided in Section IV; and finally, Section V discusses the conclusions drawn from this study and possible future research directions.

## II. DE AND THE RELATED WORK

In this section, a literature review of DE and the concept of landscape analysis are discussed.

## A. DE algorithm

Generally speaking, DE algorithm has shown good performance for solving optimization problems. It has three main operations (mutation, crossover, and selection) to evolve a population of individuals during the search process. DE starts with a uniform random population, such that

$$
\begin{equation*}
\vec{X}_{i, G}=x_{i, G}^{\min }+\left(x_{i, G}^{\max }-x_{i, G}^{\min }\right) \times \operatorname{rand}(1, D) \tag{1}
\end{equation*}
$$

where $i \in N P, j=1,2, \ldots, D, N P$ is the number of individuals, $D$ the dimension of the problem and rand a random real number uniformly generated between 0 and 1 , and $G$ the generation number.

1) mutation: Before the mutation operator is applied, every vector $\vec{X}_{i, G}$ in the population is considered a parent vector (target vector), and corresponding to each parent vector, a mutant vector $\vec{V}_{i, G}=\left(v_{i, G}^{1}, v_{i, G}^{2}, \ldots, v_{i, G}^{D}\right)$ is produced by the weighted difference between two random vectors to a third vector (the base vector) from the current population ( D is the number of decision variables), such that

$$
\begin{equation*}
\vec{V}_{i, G}=\vec{X}_{r_{1}^{i}, G}+F \times\left(\vec{X}_{r_{2}^{i}, G}-\vec{X}_{r_{3}^{i}, G}\right) \tag{2}
\end{equation*}
$$

where $r_{1}^{i} \neq r_{2}^{i} \neq r_{3}^{i}$ are random integer numbers selected from the range $[1, N P]$, which are all different from the index $i$, the scaling factor $F$ is the control parameter for scaling the difference vectors and $G$ the generation number.
2) crossover: Following the mutation operation, a trial vector $\vec{U}_{i, G}=\left\{u_{i, G}^{1}, u_{i, G}^{2}, \ldots, u_{i, G}^{D}\right\}$ is produced by
crossing a parent vector and its corresponding trial vecto, such that

$$
u_{i, G}^{j}=\left\{\begin{array}{cc}
v_{i, G}^{j} & \text { if }(\operatorname{rand}(0,1) \leq C R) \text { or }\left(j=j_{\text {rand }}\right)  \tag{3}\\
x_{i, G}^{j} & \text { otherwise }
\end{array}\right.
$$

where $\operatorname{rand}(0,1)$ a random real number uniformly generated between 0 and $1, C R$ the crossover control parameter and $j_{\text {rand }} \in[1,2, \ldots, D]$ a randomly chosen index which ensures that the trail vector, $\vec{U}_{i, G}$ obtains at least one element from the mutant vector, $\vec{V}_{i, G}$.
3) selection: To decide whether parent $\vec{X}_{i, G}$ or child $\vec{U}_{i, G}$ vectors survive to the next generation a selection operation is employed. This operation is performed using

$$
\vec{X}_{i, G+1}=\left\{\begin{array}{cc}
\vec{U}_{i, G} & \text { if } f\left(\vec{U}_{i, G}\right) \leq f\left(\vec{X}_{i, G}\right)  \tag{4}\\
\vec{X}_{i, G} & \text { otherwise }
\end{array}\right.
$$

where $f\left(\vec{U}_{i, G}\right)$ and $f\left(\vec{X}_{i, G}\right)$ are the objective functions of the child and parent, respectively. Similar to other EAs algorithms, DE repeats the aforementioned steps, generation after generation, to evolve its population of solutions until some specific termination condition is met.

## B. Improved DE Algorithms

In this section, commonly used improved variants of DE are discussed.

As mentioned earlier, in DE the quality of the obtained solutions depends on its parameter (population size $N P$, crossover rate $C R$, and scaling factor $F$ ) settings. Thus, in the literature there are some different adaptation schemes that have been proposed, and we will review some of them in this section.

A fuzzy adaptive DE algorithm (FADE), in which fuzzy logic controllers were used to adapt the parameters $F$ and $C R$, was proposed by Liu and Lampinen [19]. An adaptive DE algorithm (ADE) was proposed by Zaharie and Daniela [20], in which $F$ and $C R$ were adapted with regard to population diversity. A self-adaptive (jDE) strategy to adapt the $F$ and $C R$ values of the DE algorithm, was proposed by Breast et al. [21]. In jDE , both $F$ and $C R$ are also encoded into the individuals and their values survive to the next generation with a particular probability, $\tau_{1}$ and $\tau_{2}$, and otherwise, $F$ and $C R$ values are randomly re-initialized to new values within the given range for the next generation [22]. An adaptive DE algorithm with an optional external memory (JADE) was proposed by Zhang et al. [23], in which the control parameters $C R$ and $F$ of each individual were automatically updated according to previously successful experiences. Also, it implements a "DE/current-to$p$ best" mutation strategy, with an external archive, which some of the good solutions are stored on it to avoid premature convergence and also diversify the population. Tanabe and Fukunaga [24] introduced success-history based parameter adaptation for differential evolution (SHADE), which is an improved version of JADE, uses a history based parameter
adaptation method. The L-SHADE [25] algorithm is a SHADE algorithm that uses linear population size reduction (LPSR) to dynamically re-size the population during a run. LPSR reduces the population linearly as the number of fitness evaluations increases. L-SHADE showed good performance, in comparison with other algorithm over a set of unconstrained optimization problems. A new Sinusoidal DE (SinDE), in which new sinusoidal formulas was used to automatically adjust the values of $F$ and $C R$, was proposed by Draa et al. [26]. It was claimed by the author that, SinDE especially gives good results for multi-modal and composition functions. To dynamically select the a best compromise of parameters (i.e. $F, C R$ and $N P$ ) for solving a specific problem in each run, Sarker et al. [27] designed a new mechanism to do it. The experimental results demonstrated its superior performance over the state-of-the-art DE variants.

To follow our discussion about DE algorithms and as mentioned earlier that no single DE algorithm was able to solve all kind of optimization problems, a considerable number of DE algorithms, which uses more than one mutation strategy or incorporated with other algorithms, have been proposed to solve this drawback and here we will review some of them.

Sallam et. al [5] proposed a neuro-dynamic differential evolution algorithm for solving CEC2015 single objective optimization problems. An adaptive mechanism was proposed for the appropriate use of L-SHADE and neuro-dynamic during the search process. A self-adaptive $\mathrm{DE}(\mathrm{SaDE})$ was proposed by Qin et al. [28] for solving unconstrained real-parameter optimization. In SaDE , both the trial vector generation strategy and its associated control parameter values, were gradually self-adapted by learning from their previous search experience. A composite DE (CoDE) was proposed by Wang et al. [29] for solving optimization problems. It uses three mutation strategies randomly with three fixed control parameter settings for generating a new trial vector at each generation. To generate a new solution, three vectors were generated, then the best one among them was selected to enter the next generation. From the experimental results, it was concluded that CoDE is a promising optimization algorithm for solving optimization problems. A self adaptive multi-operator differential evolution (SAMO-DE), for solving constrained optimization problems, was proposed by Elsayed et al. [8]. In SAMO-DE, each operator had its own sub-population which was evolved by a different DE operator. Based on an improvement measure in which the solution quality, constraint violation and feasibility ratio were used to calculate the success of each operator, the number of individuals in each sub-population was adaptively updated and more emphasis was given to the operator with the highest success. The results showed that SAMO-DE performed better than other-state-of-the-art algorithms. Using a mix of four different DE mutation strategies, two crossover operators and two constraint handling techniques for constrained optimization problems was proposed by Elsayed et al. [30]. The experimental results show that the proposed algorithm is better than other state-of-the-art algorithms. Mallipeddi et al. [9] designed the ensemble differential evolution algorithms
(EPSDE). In these algorithms, a pool of distinct DE mutation strategies, crossover strategies and a pool of associated values for the control parameters not only coexist throughout the evolutionary process, but also compete with each other to produce offspring. All of the above mentioned methods did not incorporate any landscape information in the selection phase. For more inforatiomation regarding DE algorithms, readers are refered to [31] [32].

In the recent past, researchers and practitioners have used fitness landscape to determine and select an appropriate algorithm or operator for solving optimization problems. In [33], the authors suggested using a cost sensitive learning model to select the best algorithm amongst a set of four algorithms. The four algorithms were selected manually from the algorithms solving Black-Box Optimization Benchmarking (BBOB) in 2009 and 2010 [34][35]. The functions in $10 D$ were characterized using 19 measurements extracted by the exploratory landscape analysis (ELA) technique. In their work, low-level features [36] were obtained by systematic sampling of the functions on the search space. Then separability, modality, and global structures of the optimization problem were measured as the first step to characterize the landscape (this step was done offline). Next, a machine learning model was constructed to select the best algorithm from the portfolio. Based on two different cross validation schemes, the model was validated. However, the results may not be general for a knowledge base with problems of different dimensionality such as $2 D$, $3 D, 5 D$, and $20 D$. Also, because the low level features were extracted in a different step, the authors did not add the computational cost for calculating the features to the function evaluations. Further, as the selection of the four algorithms was done manually, this weakened its validation on unobserved problems. In [37], decision trees were employed to predict the failure of seven different particle swarm optimization algorithms (PSO), by using a number of fitness landscape metrics. In [38], an adaptive operator selection mechanism, based on a set of four fitness landscape analysis techniques, was used to train an online regression learning model (dynamic weighted majority), which was used to predict the weight of each operator in each generation. Their proposed mechanism was used to determine the most suitable crossover operator, among four crossover operators, to solve a set of Capacitated Arc Routing Problem (CARP) instances. The authors used instantaneous reward, in which the reward was considered as the value computed at the last evaluation. In comparison with some of the-state-of-the-art algorithms, the algorithm did not show significant benefit.

## III. Two-Phase multi-operator DE

In this section, the two-phase multi-operator DE with a landscape selection mechanism is presented.

## A. TP-MODE

In designing the proposed algorithm, two considerations taken into account are that, (1) as no single mutation strategy might be able to solve all kinds of problems, it is beneficial
to use a multi-operator [8], [13], and (2) the new algorithm should exhibit an exploration capability in the early phase of the evolution and fast convergence in a later one.

The framework of TP-MODE is presented in Algorithm 1.
Generally speaking, the entire evolutionary process is divided into two phases, exploration and exploitation. In the first, TP-MODE focuses on improving its exploration by using two DE mutation strategies which maintain diversity and, in the second, two other DE strategies which can converge quickly are used. Initially, $N P$ individuals are randomly generated by equation 15. Subsequently, based on the type of phase, two mutation strategies, in which each operator is randomly assigned the same number of individuals ( $n_{o p}, \forall o p=\{1,2\}$ ), are implemented. Then, a new solution is generated using its assigned DE variant and evaluated according to the fitness function value. If it is better than its parent, it survives to the next generation; otherwise its parent is retained for the next generation. At the same time, two landscape metrics (the information landscape negative searchability metric/ searchability indicator (SI), fitness distance correlation (FDC)) and one performance measure (success rate (SR)) are calculated for each operator, with the overall normalized measure computed from these values using equation (13) based on which, $n_{o p}, \forall o p=\{1,2\}$ is updated. As this process may abandon certain operators which could be useful in later stages of the evolutionary process, we set a minimum number of individuals for each operator. The above process is repeated until the maximum number of fitness function evaluations ( $M A X_{F E S}$ ) is reached. In this paper, the algorithm switches from the first to second phase based on a predefined number of FEs ( $\frac{M A X_{F E S}}{3}$ ).

In the following subsections, TP-MODE's components are discussed in more detail.

1) Two-phase mutation strategies:: As, in the first phase, the main objective is to maintain exploration capability of TP-MODE to avoid premature convergence, $\mathrm{DE} / \mathrm{rand} / 1 / \mathrm{bin}$ is chosen to be placed in its pool while the second variant is $\mathrm{DE} / \phi$ best $/ 1$, where $\phi$ is set to $[1,0.6 * N P]$, as described in [39].

On the other hand as, in the second phase, the aim is to speed up convergence; information from the best solution is of great interest. Therefore, DE/current-to- $\phi$ best/1/bin/with archive and $\mathrm{DE} / \phi$ best $/ 1$ are used, with $\phi$ is equal to 0.1 for both operators.
2) Selection mechanism: As previously mentioned, in each phase, two operators are used, with TP-MODE placing emphasis on the best-performing one based on three indicators: (1) the SR; (2) SI; and (3) FDC.

- SR

The SR of each operator $\left(S R_{o p}\right)$ is defined as the number of successful offspring generated by a search operator (op), divided by the number of individuals assigned to $o p$ as :
$S R_{o p}=\frac{\text { Number of successful offsprings }}{n_{o p}}, \forall o p=\{1,2\}$
Then, the normalized value for the $S R$ is calculated using:

$$
\begin{equation*}
N M_{S R_{o p}}=\frac{\overline{S R}_{o p}}{\sum_{O P=1}^{m} \overline{S R}_{o p}} \tag{6}
\end{equation*}
$$

where the $\overline{S R}_{o p}$ is the mean value of the SR of operator $o p$.

- SI

The searchability of the algorithm, which is the capability of its search operator to move to a region of the search space with a better fitness value, is measured by computing an information landscape metric based on the difference between the information landscape vector of the problem to be solved and a reference landscape vector. The reference landscape is the landscape of a function that can be easily optimized by any optimization algorithm in any dimension [40] and the reference function $f_{\text {ref }}(\vec{x})$ is determined using:

$$
\begin{equation*}
f_{r e f}(\vec{x})=\sum_{j=1}^{D}\left(x_{j}-x_{j}^{*}\right)^{2} \tag{7}
\end{equation*}
$$

where $\vec{x}_{i}^{*}$ is the best individual in the sample.
An information matrix for a minimization problem $M=$ [ $a_{i, j}$ ] is constructed using:

$$
a_{i, j}= \begin{cases}1 & \text { if } f\left(x_{i}\right)<f\left(x_{j}\right)  \tag{8}\\ 0.5 & \text { if } f\left(x_{i}\right)=f\left(x_{j}\right) \\ 0 & \text { otherwise }\end{cases}
$$

Not all the entries in the information landscape are required to define it [40] [41]. There are duplicates in the entries due to symmetry (the lower triangle should be omitted), the entries on the diagonal are always 0.5 (and should be omitted), and the row and column of the optimum solution should also be omitted. Therefore, the information matrix can be reduced to a vector $L S=$ $\left(l s 1, l s_{2}, \ldots, l s_{|L S|}\right)$, where the number of elements in LS is: $|L S|=\frac{(N P-1) \times(N P-2)}{2}$.
After constructing the landscape vector of the problem to be optimized $\left(L S_{f}\right)$ and the vector landscape of the reference function ( $L S_{\text {ref }}$ ), the SI is computed as:

$$
\begin{equation*}
L D_{o p}=\frac{1}{\left|L S_{f}\right|} \times \sum_{i=1}^{\left|L S_{f}\right|}\left|l s_{1 i}-l s_{2 i}\right| \tag{9}
\end{equation*}
$$

When $L D$ is close to 0 , the problem is considered easy and difficult when $L D$ is close to 1 .
The normalized value for the $L D$ is then calculated as:

$$
\begin{equation*}
N M_{L D_{o p}}=\frac{\left(1-M_{L D_{O P}}\right)}{\sum_{O P=1}^{m}\left(1-M_{L D_{O P}}\right)} \tag{10}
\end{equation*}
$$

where $M_{L D}$ is the mean value of information landscape.

- FDC

The FDC, which was proposed by Jones and Forrest [42] and measures the correlation between the objective value and distance to the nearest optimum in the search domain is another method to determine a problem's difficulty [43].
Given a set of solutions $X=\left\{\vec{x}_{1}, \vec{x}_{2}, \ldots, \vec{x}_{N P}\right\}$ and their objective function values $F=\left\{f_{1}, f_{2}, \ldots, f_{N P}\right\}$, the FDC value is computed by:

$$
\begin{equation*}
F D C_{o p}=\frac{\sum_{i=1}^{N P}\left(f_{i}-\bar{f}\right)_{o p} \times\left(d_{i}-\bar{d}\right)_{o p}}{n \times\left(\sigma_{f} \times \sigma_{d}\right)_{o p}} \tag{11}
\end{equation*}
$$

where $d_{i}$ is the distance between the $i^{\text {th }}$ individual and the best solution in the population, $\bar{f}, \bar{d}, \sigma_{f}$, and $\sigma_{d}$ are the mean and standard deviations of fitness function and distance, respectively.
For a minimization problem, a value of $F D C_{o p}$ closes to 1 means that the problem is relatively easy, and one near 0 that it is difficult.
The normalized FDC $\left(N M_{F D C}\right)$ is calculated using equation by:

$$
\begin{equation*}
N M_{F D C_{o p}}=\frac{\overline{F D C}_{o p}}{\sum_{O P=1}^{m} \overline{F D C}_{o p}} \tag{12}
\end{equation*}
$$

where the $\overline{F D C}_{o p}$ is the mean value of FDC of operator $o p$.
Subsequently, the overall normalized value for each operator is computed using:

$$
\begin{equation*}
O N M_{o p, G}=\frac{N M_{S R_{o p}}+N M_{L D_{o p}}+N M_{F D C_{o p}}}{\sum_{o p=1}^{m}\left(N M_{S R_{o p}}+N M_{L D_{o p}}+N M_{F D C_{o p}}\right)}, \tag{13}
\end{equation*}
$$

After determining the overall normalized value for each operator, the number of individuals for each operator in each generation, is calculated by:

$$
\begin{equation*}
n_{o p, G}=M S S+\frac{O N M_{o p, G}}{\sum_{o p=1}^{m} O N M_{o p, G}} \times(N P-M S S \times m) \tag{14}
\end{equation*}
$$

where $n_{o p, G}$ is the number of individuals operator op will evolve at generation $G, M S S$ is the minimum number of individuals for operator op at generation $G$.
3) Population Initialization and Updating Method: In the initialization phase, the Latin Hypercube Design, which is a type of stratified sampling, is used to generate the initial population because of its capability to generate a sample of points thatmore efficiently covers the whole search region .

The initialization is performed using:

$$
\begin{gather*}
x_{i, j}=x_{i}^{\min }+\left(x_{i}^{\max }-x_{i}^{\min }\right) \times \operatorname{lhd}(1, N P)  \tag{15}\\
i \in N P \text { and } j=1,2, \ldots, D
\end{gather*}
$$

where $l h d$ is a function that generates random numbers using the Latin Hypercube Design.

Moreover, a linear population size reduction schema is used to adaptively re-size the $N P$ during the evolutionary process [25], as follows:

$$
\begin{equation*}
N P_{t+1}=\operatorname{round}\left[\left(\frac{N P^{\min }-N P^{i n i t}}{M A X_{F E S}}\right) \times F E S+N P^{i n i t}\right] \tag{16}
\end{equation*}
$$

where $N P^{\min }$ is the smallest number of individuals that the proposed algorithm can use. $F E S$ is the current number of fitness evaluations, $M A X_{F E S}$ is the maximum number of fitness evaluations.
4) Managing $F$ and $C R$ : As it is a fact that the performance of the DE algorithm is affected by the values of the control parameters ( $F$ and $C R$ ) in each phase [44] [45], we use a different adaptation mechanism for their values. In the first, the mechanism proposed by Elsayed et al. [46] is adopted as it has shown its capability to maintain diversity.

Initially, for each individual in the population, two sets of control parameters, $F \in N(0.5,15)$ and $C R \in(0.5,0.15)$, are generated using a Gaussian distribution with mean and standard deviation values of 0.5 and 0.15 , respectively. Then, as in [7], to generate new offspring, $F$ and $C R$ are calculated, respectively,:

$$
\begin{align*}
& F=F_{r 1}+N(0,0.5) \times\left(F_{r 2}-F_{r 3}\right)+N(0,0.5) \\
& \left(F_{r 4}-F_{r 5}\right)+N(0,0.5) \times\left(F_{r 6}-F_{r 7}\right) \tag{17}
\end{align*}
$$

$$
\begin{align*}
C R= & C R_{r 1}+N(0,0.5) \times\left(C R_{r 2}-C R_{r 3}\right)+N(0,0.5) \\
& \left(C R_{r 4}-C R_{r 5}\right)+N(0,0.5) \times\left(C R_{r 6}-C R_{r 7}\right) \tag{18}
\end{align*}
$$

where $r_{1}^{i} \neq r_{2}^{i} \neq r_{3}^{i} \neq r_{4}^{i} \neq r_{5}^{i} \neq r_{6}^{i} \neq r_{7}^{i}$ are random integer numbers selected from the range $[1, N P]$.
If the value of $F$ is less than 0.1 or larger than 1 , it is truncated to 0.1 and 1 , respectively, while if the value of $C R$ is less than 0.01 or larger than 1 , it is truncated to 0.01 and 1 , respectively.
In the second phase, inspired by [47], a scaling factor pool (i.e., $F_{\text {pool }}=[0.6,0.8,1.0]$ ) and a crossover control parameter pool (i.e., $C R_{\text {pool }}=[0.1,0.2,1.0]$ ) are established in DE. Then, at each generation, $F$ and $C R$ are randomly chosen from $F_{p o o l}$ and $C R_{\text {pool }}$, respectively.

## IV. Experimental results

In this section, the performances of the proposed algorithm for solving a benchmark test set of 22 problems taken from the CEC2011 competition considering real-world applications is discussed [18]. The proposed algorithm was run following the guidelines of the competition that required 25 independent runs for each test problem with up to $F E S_{M A X}=150,000$ fitness evaluations. It was coded using Matlab R2014a and run on a PC with a 3.4 GHz Core I7, 16 GB RAM, and windows 7.

```
Algorithm 1 Proposed framework
    Generate an initial population \((X)\) of size \(N P\) using Latin
    Hypercube Design; \(F E S \leftarrow 0\);
    Evaluae \(X\);
    \(F E S \leftarrow F E S+N P ;\)
    \(n_{o p_{1}}=n_{o p_{2}}=\frac{N P}{2}\);
    while \(F E S \leq M A X_{F E S}\) do
        if \(F E S \leq\) limit then
            \{Phase1\}
            Set operators \(o p_{1}=D E / \phi\) best \(/ 1 ; \quad o p_{2}=\)
            DE/rand/2;
            Calculate \(F\) and \(C R\) using equations (17), and (18);
        else
            \{Phase2\}
            Set operators \(o p_{1}=D E /\) current - to -
            \(\phi b e s t / 1 /\) Archive \(; o_{2}=D E / \phi b e s t / 1\);
            Calculate control parameters \(F\) and \(C R\) as in the last
            paragraph of Sec III-A4 ;
        end if
        Evolve individuals using its assigned operators op;
        Compute \(N M_{S R_{o p}}, N M_{L D_{o p}}\), and \(N M_{F D C_{o p}}\) using
        equations (6), (10), and (11);
        Update \(n_{o p_{1}}\) and \(n_{o p_{2}}\) using equation (14);
        \(F E S \leftarrow F E S+N P ;\)
        if \(F E S==\) limit then
            \(n_{o p_{1}}=n_{o p_{2}}=\frac{N P}{2}\);
        end if
        Update the \(N P\) using equation (16);
    end while
```


## A. Algorithm Parameters and Operators

The default values of $N P^{i n i t}$ of 200 and $N P^{m i n}$ of 10 were set based on our empirical analysis, with $\varphi$ set at a value of 0.6 for $\mathrm{DE} / \varphi$ best/ 1 to maintain diversity, and 0.1 for the other two variants, to speed up the convergence rate. For DE/current-to- $\phi$ best/1/bin/with archive the archive rate $(A)$ was set at a value of 1.4 , limit the maximum limit for running phase 1 , after which phase two started, and set at a value of $\frac{F E S_{M A X}}{3}$ was set based on our empirical analysis and this parameter was fixed for all problems.

## B. Detailed Results of proposed algorithm

The detailed results (best, worst, median, average, and standard deviation (Std.)) are shown in Table I. The performance of TP-MODE was compared with those of three algorithms, GA-MPC [48] (the winner of the CEC2011 competition), SAMO-DE [7], an ensemble DE algorithm (EPSDE) [9], that uses different strategies, and SHADE [24] . All Algorithms used the same stopping criteria; i.e., 150, 000 fitness function evaluations.

Table II presents the best, mean and standard deviation values of these algorithms. Based on the best fitness values obtained, TP-MODE was better than GA-MPC, SAMO-DE and EPSDE for 7, 12 and 14 problems, respectively, and the same for 9,7 and 3 , respectively, while it was inferior for 6,3
and 5, respectively. Regarding the average fitness values, TPMODE was superior to GA-MPC, SAMO-DE and EPSDE for 10,15 and 15 problems, respectively, obtained the same mean results for only 4,3 and 2 , respectively, and was inferior for 8, 4 and 5, respectively.

As it is also possible to study the statistical difference between any two algorithms using a non-parametric test, the Wilcoxon Signed Rank Test [49] was performed, with the results regarding the best and average fitness values presented in Table III. As a null hypothesis, it was assumed that there was no significant difference between the best and/or mean values of two samples while an/the alternative hypothesis was that there was a significant difference at a $10 \%$ significance level. Based on the test results, we assigned one of three signs (,+- , and $\approx$ ) for the comparison of any two algorithms (shown in the last column), where the " + " sign means the first algorithm was significantly better than the second, the "-" sign means that the first algorithm was significantly worse, and the " $\approx$ " sign means that there was no significant difference between thim. It is clear that, from Table III that TP-MODE was superior to GA-MPC, SAMO-DE, EPSDE, and SHADE in terms of the average results and very competitive with them regarding the best.

Finally, the Friedman Test was conducted to rank all algorithms, with the results shown in Table IV in which it is clear that TP-MODE was superior to the other three algorithms regarding both the best and average fitness results, followed by GA-MPC, SHADE, EPSDE and SAMODE, respectively.

## V. Conclusion and future work

In this study, a new multi-operator DE algorithm for solving real-world application problems was proposed. It focused on diversity without losing convergence through dividing the whole search process into two phases, with two DE mutation operators used in each phase to achieve the aim of the corresponding phase. Furthermore, a new measure based on the quality of solutions and characteristics of the landscape was used to emphasize the best-performing operator in each phase. The performance of the proposed algorithm was tested on 22 real-world application problems taken from the CEC2011 competition, with the results demonstrating its superiority over three other state-of-the-art algorithms.

Possible extensions of this work include obtaining a dynamic balance between convergence and diversity, and analyzing each component in the algorithm's design. Also, using more than one EA may be of great interest.

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Table I
The function values obtained by TP-MODE over 25 RUns and 150000 Fitness function evaluations

| Problems | Best | Worst | Median | Mean | Std. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| P01 | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| P02 | $-2.842253 \mathrm{E}+01$ | $-2.163764 \mathrm{E}+01$ | $-2.589359 \mathrm{E}+01$ | $-2.573171 \mathrm{E}+01$ | $1.594532 \mathrm{E}+00$ |
| P03 | $1.151489 \mathrm{E}-05$ | $1.151489 \mathrm{E}-05$ | $1.151489 \mathrm{E}-05$ | $1.151489 \mathrm{E}-05$ | $0.000000 \mathrm{E}+00$ |
| P04 | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ |
| P05.1 | $-3.684537 \mathrm{E}+01$ | $-3.163659 \mathrm{E}+01$ | $-3.479658 \mathrm{E}+01$ | $-3.465468 \mathrm{E}+01$ | $1.119970 \mathrm{E}+00$ |
| P05.2 | $-2.916612 \mathrm{E}+01$ | $-2.300456 \mathrm{E}+01$ | $-2.916612 \mathrm{E}+01$ | $-2.822079 \mathrm{E}+01$ | $1.385154 \mathrm{E}+00$ |
| P06 | $5.000000 \mathrm{E}-01$ | $1.096765 \mathrm{E}+00$ | $7.510147 \mathrm{E}-01$ | $7.603013 \mathrm{E}-01$ | $1.655763 \mathrm{E}-01$ |
| P07 | $2.200000 \mathrm{E}+02$ | $2.200000 \mathrm{E}+02$ | $2.200000 \mathrm{E}+02$ | $2.200000 \mathrm{E}+02$ | $0.000000 \mathrm{E}+00$ |
| P08 | $1.628873 \mathrm{E}+03$ | $3.059153 \mathrm{E}+03$ | $2.442968 \mathrm{E}+03$ | $2.453615 \mathrm{E}+03$ | $3.755708 \mathrm{E}+02$ |
| P09 | $-2.184235 \mathrm{E}+01$ | $-2.164293 \mathrm{E}+01$ | $-2.164414 \mathrm{E}+01$ | $-2.165958 \mathrm{E}+01$ | $5.411104 \mathrm{E}-02$ |
| P10.1 | $5.116130 \mathrm{E}+04$ | $5.247562 \mathrm{E}+04$ | $5.175826 \mathrm{E}+04$ | $5.180184 \mathrm{E}+04$ | $3.431911 \mathrm{E}+02$ |
| P10.2 | $1.068335 \mathrm{E}+06$ | $1.076211 \mathrm{E}+06$ | $1.072737 \mathrm{E}+06$ | $1.072583 \mathrm{E}+06$ | $1.572728 \mathrm{E}+03$ |
| P11.1 | $1.544419 \mathrm{E}+04$ | $1.544419 \mathrm{E}+04$ | $1.544419 \mathrm{E}+04$ | $1.544419 \mathrm{E}+04$ | $1.897504 \mathrm{E}-05$ |
| P11.2 | $1.812350 \mathrm{E}+04$ | $1.867086 \mathrm{E}+04$ | $1.833903 \mathrm{E}+04$ | $1.835748 \mathrm{E}+04$ | $1.507295 \mathrm{E}+02$ |
| P11.3 | $3.271559 \mathrm{E}+04$ | $3.278829 \mathrm{E}+04$ | $3.276597 \mathrm{E}+04$ | $3.276269 \mathrm{E}+04$ | $1.931411 \mathrm{E}+01$ |
| P11.4 | $1.259621 \mathrm{E}+05$ | $1.295006 \mathrm{E}+05$ | $1.279397 \mathrm{E}+05$ | $1.278757 \mathrm{E}+05$ | $1.111803 \mathrm{E}+03$ |
| P11.5 | $1.881031 \mathrm{E}+06$ | $1.941075 \mathrm{E}+06$ | $1.913161 \mathrm{E}+06$ | $1.913606 \mathrm{E}+06$ | $1.427120 \mathrm{E}+04$ |
| P12.1 | $9.362562 \mathrm{E}+05$ | $9.420340 \mathrm{E}+05$ | $9.392626 \mathrm{E}+05$ | $9.392934 \mathrm{E}+05$ | $1.544130 \mathrm{E}+03$ |
| P12.2 | $9.400879 \mathrm{E}+05$ | $1.068943 \mathrm{E}+06$ | $9.697023 \mathrm{E}+05$ | $9.788815 \mathrm{E}+05$ | $3.926205 \mathrm{E}+04$ |
| P12.3 | $9.362562 \mathrm{E}+05$ | $9.420340 \mathrm{E}+05$ | $9.392626 \mathrm{E}+05$ | $9.392934 \mathrm{E}+05$ | $1.544130 \mathrm{E}+03$ |
| P13 | $9.875190 \mathrm{E}+00$ | $1.797719 \mathrm{E}+01$ | $1.409832 \mathrm{E}+01$ | $1.412068 \mathrm{E}+01$ | $1.616015 \mathrm{E}+00$ |
| P14 | $8.593443 \mathrm{E}+00$ | $1.877439 \mathrm{E}+01$ | $9.827477 \mathrm{E}+00$ | $1.147226 \mathrm{E}+01$ | $3.270544 \mathrm{E}+00$ |

Table II
The function values achived by TP-MODE, GA-MPC, SAMO-DE and EPSDE over 25 Runs and 150000 FES

|  | TP-MODE |  |  | GA-MPC |  |  | SAMO-DE |  |  | EPSDE |  |  | SHADE |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Problems | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. | Best | Mean | Std. |
| P01 | $0.00000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $1.21203 \mathrm{E}+00$ | $3.37622 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $1.78000 \mathrm{E}+00$ | $4.18000 \mathrm{E}+00$ | $2.73700 \mathrm{E}-02$ | $7.59030 \mathrm{E}-01$ | $2.29845 \mathrm{E}+00$ |
| P02 | $-2.84225 \mathrm{E}+01$ | -2.573171E+01 | $1.59453 \mathrm{E}+00$ | $-2.84225 \mathrm{E}+01$ | -2.77007E+01 | $4.67305 \mathrm{E}-01$ | $-2.84225 \mathrm{E}+01$ | -2.70698E+01 | $6.62481 \mathrm{E}-01$ | -2.14000E+01 | $-1.83000 \mathrm{E}+01$ | $1.65000 \mathrm{E}+00$ | $-2.44943 \mathrm{E}+01$ | -2.30316E+01 | $7.46050 \mathrm{E}-01$ |
| P03 | $1.15149 \mathrm{E}-05$ | $1.151489 \mathrm{E}-05$ | $0.00000 \mathrm{E}+00$ | $1.15149 \mathrm{E}-05$ | $1.15149 \mathrm{E}-05$ | $0.00000 \mathrm{E}+00$ | $1.15149 \mathrm{E}-05$ | $1.15149 \mathrm{E}-05$ | $0.00000 \mathrm{E}+00$ | 1.15149E-05 | $1.15149 \mathrm{E}-05$ | $1.52000 \mathrm{E}-19$ | $1.15000 \mathrm{E}-05$ | 1.15000E-05 | $5.19000 \mathrm{E}-21$ |
| P04 | $0.00000 \mathrm{E}+00$ | $0.000000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $1.37708 \mathrm{E}+01$ | $1.38154 \mathrm{E}+01$ | $1.54600 \mathrm{E}-01$ | $1.37708 \mathrm{E}+01$ | $1.39407 \mathrm{E}+01$ | $2.50222 \mathrm{E}-01$ | $1.38000 \mathrm{E}+01$ | $1.67000 \mathrm{E}+01$ | $3.26000 E+00$ | $0.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ | $0.00000 \mathrm{E}+00$ |
| P05.1 | $-3.68454 \mathrm{E}+01$ | -3.465468E+01 | $1.11997 \mathrm{E}+00$ | $-3.68454 \mathrm{E}+01$ | $-3.50388 \mathrm{E}+01$ | $8.32925 \mathrm{E}-01$ | -3.68439E+01 | -3.35947E+01 | $1.57514 \mathrm{E}+00$ | $-3.20000 \mathrm{E}+01$ | $-2.90000 \mathrm{E}+01$ | $1.84000 \mathrm{E}+00$ | -3.66566E+01 | $-3.60052 \mathrm{E}+01$ | $6.38070 \mathrm{E}-01$ |
| P05.2 | $-2.91661 \mathrm{E}+01$ | $-2.822079 \mathrm{E}+01$ | $1.38515 \mathrm{E}+00$ | $-2.91661 \mathrm{E}+01$ | -2.74881E+01 | $1.78214 \mathrm{E}+00$ | -2.91661E+01 | -2.76347E+01 | $1.92353 \mathrm{E}+00$ | $-1.99000 \mathrm{E}+01$ | $-1.70000 \mathrm{E}+01$ | $2.68000 \mathrm{E}+00$ | -2.91420E+01 | $-2.90486 \mathrm{E}+01$ | $1.23890 \mathrm{E}-01$ |
| P06 | $5.00000 \mathrm{E}-01$ | $7.603013 \mathrm{E}-01$ | $1.65576 \mathrm{E}-01$ | $5.00000 \mathrm{E}-01$ | $7.48409 \mathrm{E}-01$ | $1.24914 \mathrm{E}-01$ | $5.00000 \mathrm{E}-01$ | $8.16624 \mathrm{E}-01$ | $1.19367 \mathrm{E}-01$ | $1.28000 \mathrm{E}+00$ | $1.42000 \mathrm{E}+00$ | $7.38000 \mathrm{E}-02$ | $9.06410 \mathrm{E}-01$ | $1.12130 \mathrm{E}+00$ | $8.34400 \mathrm{E}-02$ |
| P07 | $2.20000 \mathrm{E}+02$ | $2.200000 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $2.20000 \mathrm{E}+02$ | $2.20000 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $2.20000 \mathrm{E}+02$ | $2.20000 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $2.20000 \mathrm{E}+02$ | $2.20000 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ | $2.20000 \mathrm{E}+02$ | $2.20000 \mathrm{E}+02$ | $0.00000 \mathrm{E}+00$ |
| P08 | $1.62887 \mathrm{E}+03$ | $2.453615 \mathrm{E}+03$ | $3.75571 \mathrm{E}+02$ | $4.66763 \mathrm{E}+02$ | $1.22059 \mathrm{E}+03$ | $3.61119 \mathrm{E}+02$ | $9.44119 \mathrm{E}+02$ | $2.26440 \mathrm{E}+03$ | 8.54213E+02 | $7.84500 \mathrm{E}+02$ | $2.52900 \mathrm{E}+03$ | $1.32800 \mathrm{E}+03$ | $1.14114 \mathrm{E}+03$ | $2.22875 \mathrm{E}+03$ | $7.14195 \mathrm{E}+02$ |
| P09 | $-2.18424 \mathrm{E}+01$ | $-2.165958 \mathrm{E}+01$ | $5.41110 \mathrm{E}-02$ | $-2.18425 \mathrm{E}+01$ | $-2.17022 \mathrm{E}+01$ | $1.16347 \mathrm{E}-01$ | $-2.18217 \mathrm{E}+01$ | $-2.16589 \mathrm{E}+01$ | $1.12958 \mathrm{E}-01$ | $-2.18000 \mathrm{E}+01$ | $-1.56000 \mathrm{E}+01$ | $3.79000 \mathrm{E}+00$ | $-2.18425 \mathrm{E}+01$ | $-2.16289 \mathrm{E}+01$ | $1.40740 \mathrm{E}-01$ |
| P10.1 | $5.11613 \mathrm{E}+04$ | $5.180184 \mathrm{E}+04$ | $3.43191 \mathrm{E}+02$ | $5.09251 \mathrm{E}+04$ | $5.20546 \mathrm{E}+04$ | $4.49912 \mathrm{E}+02$ | $5.12682 \mathrm{E}+04$ | $5.23475 \mathrm{E}+04$ | $5.78021 \mathrm{E}+02$ | $5.11000 \mathrm{E}+04$ | $5.22000 \mathrm{E}+04$ | $7.24000 \mathrm{E}+02$ | $5.15596 \mathrm{E}+04$ | $5.32252 \mathrm{E}+04$ | $3.80380 \mathrm{E}+03$ |
| P10.2 | $1.06834 \mathrm{E}+06$ | $1.072583 \mathrm{E}+06$ | $1.57273 \mathrm{E}+03$ | $1.06955 \mathrm{E}+06$ | $1.07338 \mathrm{E}+06$ | $1.61759 \mathrm{E}+03$ | $1.07021 \mathrm{E}+06$ | $1.07313 \mathrm{E}+06$ | $1.70325 \mathrm{E}+03$ | $1.06000 \mathrm{E}+06$ | $1.07000 \mathrm{E}+06$ | $2.13000 \mathrm{E}+03$ | $1.07000 \mathrm{E}+06$ | $1.10000 \mathrm{E}+06$ | $5.34206 \mathrm{E}+04$ |
| P11.1 | $1.54442 \mathrm{E}+04$ | $1.544419 \mathrm{E}+04$ | $1.89750 \mathrm{E}-05$ | $1.54442 \mathrm{E}+04$ | $1.54442 \mathrm{E}+04$ | 1.75112E-07 | $1.54442 \mathrm{E}+04$ | $1.54442 \mathrm{E}+04$ | $7.24128 \mathrm{E}-04$ | $1.54000 \mathrm{E}+04$ | $1.55000 \mathrm{E}+04$ | $1.55000 \mathrm{E}+01$ | $1.54442 \mathrm{E}+04$ | $1.54442 \mathrm{E}+04$ | $5.57000 \mathrm{E}-12$ |
| P11.2 | $1.81235 \mathrm{E}+04$ | $1.835748 \mathrm{E}+04$ | $1.50730 \mathrm{E}+02$ | $1.81006 \mathrm{E}+04$ | $1.82610 \mathrm{E}+04$ | $6.98163 \mathrm{E}+01$ | $1.82843 \mathrm{E}+04$ | $1.85249 \mathrm{E}+04$ | $1.34481 \mathrm{E}+02$ | $1.81000 \mathrm{E}+04$ | $1.81000 \mathrm{E}+04$ | $4.39000 \mathrm{E}+01$ | $1.80286 \mathrm{E}+04$ | $1.81307 \mathrm{E}+04$ | $5.17471 \mathrm{E}+01$ |
| Pl1.3 | $3.27156 \mathrm{E}+04$ | $3.276269 \mathrm{E}+04$ | $1.93141 \mathrm{E}+01$ | $3.27238 \mathrm{E}+04$ | $3.27698 \mathrm{E}+04$ | $2.68249 \mathrm{E}+01$ | $3.27840 \mathrm{E}+04$ | $3.28462 \mathrm{E}+04$ | $3.45006 \mathrm{E}+01$ | $3.26000 \mathrm{E}+04$ | $3.27000 \mathrm{E}+04$ | $3.59000 \mathrm{E}+01$ | $3.27429 \mathrm{E}+04$ | $3.27600 \mathrm{E}+04$ | $2.80246 \mathrm{E}+01$ |
| P11.4 | $1.25962 \mathrm{E}+05$ | $1.278757 \mathrm{E}+05$ | $1.11180 \mathrm{E}+03$ | $1.29213 \mathrm{E}+05$ | $1.33230 \mathrm{E}+05$ | $1.87880 \mathrm{E}+03$ | $1.30037 \mathrm{E}+05$ | $1.32707 \mathrm{E}+05$ | $1.14873 \mathrm{E}+03$ | $1.28000 \mathrm{E}+05$ | $1.31000 \mathrm{E}+05$ | $2.47000 \mathrm{E}+03$ | $1.26951 \mathrm{E}+05$ | $1.29231 \mathrm{E}+05$ | $1.58563 \mathrm{E}+03$ |
| P11.5 | $1.88103 \mathrm{E}+06$ | $1.913606 \mathrm{E}+06$ | $1.42712 \mathrm{E}+04$ | $1.92026 \mathrm{E}+06$ | $1.95332 \mathrm{E}+06$ | $1.40836 \mathrm{E}+04$ | $1.91925 \mathrm{E}+06$ | $1.97709 \mathrm{E}+06$ | $3.53818 \mathrm{E}+04$ | $1.91000 \mathrm{E}+06$ | $1.92000 \mathrm{E}+06$ | $1.18000 \mathrm{E}+04$ | $1.88000 \mathrm{E}+08$ | $1.91000 \mathrm{E}+06$ | $1.40754 \mathrm{E}+04$ |
| P12.1 | $9.36256 \mathrm{E}+05$ | $9.392934 \mathrm{E}+05$ | $1.54413 \mathrm{E}+03$ | $9.49500 \mathrm{E}+05$ | $9.71289 \mathrm{E}+05$ | $1.03874 \mathrm{E}+04$ | $9.43215 \mathrm{E}+05$ | $9.48921 \mathrm{E}+05$ | $3.91430 \mathrm{E}+03$ | $9.39000 \mathrm{E}+05$ | $9.43000 \mathrm{E}+05$ | $2.63000 E+03$ | $9.37267 \mathrm{E}+05$ | $9.40475 \mathrm{E}+05$ | $2.16143 \mathrm{E}+03$ |
| P12.2 | $9.40088 \mathrm{E}+05$ | $9.788815 \mathrm{E}+05$ | $3.92621 \mathrm{E}+04$ | $9.72102 \mathrm{E}+05$ | $1.05630 \mathrm{E}+06$ | $5.70416 \mathrm{E}+04$ | $1.00815 \mathrm{E}+06$ | $1.20594 \mathrm{E}+06$ | 9.95328E+04 | $9.40000 \mathrm{E}+05$ | $9.90000 \mathrm{E}+05$ | $4.14000 \mathrm{E}+04$ | $9.39771 \mathrm{E}+05$ | $9.52462 \mathrm{E}+05$ | $1.21308 \mathrm{E}+04$ |
| P12.3 | $9.36256 \mathrm{E}+05$ | $9.392934 \mathrm{E}+05$ | $1.54413 \mathrm{E}+03$ | $9.46598 \mathrm{E}+05$ | $9.75109 \mathrm{E}+05$ | $1.18489 \mathrm{E}+04$ | $9.47654 \mathrm{E}+05$ | $9.58792 \mathrm{E}+05$ | 5.99265E+03 | $9.39000 \mathrm{E}+05$ | $9.43000 \mathrm{E}+05$ | $2.63000 E+03$ | $9.34264 \mathrm{E}+05$ | $9.40667 \mathrm{E}+05$ | $2.99161 \mathrm{E}+03$ |
| P13 | $9.87519 \mathrm{E}+00$ | $1.412068 \mathrm{E}+01$ | $1.61602 \mathrm{E}+00$ | $7.09556 \mathrm{E}+00$ | $1.28182 \mathrm{E}+01$ | $3.24134 \mathrm{E}+00$ | $6.94322 \mathrm{E}+00$ | $1.10675 \mathrm{E}+01$ | $2.65228 \mathrm{E}+00$ | $1.66000 \mathrm{E}+01$ | $1.88000 \mathrm{E}+01$ | $1.67000 \mathrm{E}+00$ | $1.41104 \mathrm{E}+01$ | $1.75903 \mathrm{E}+01$ | $1.42842 \mathrm{E}+00$ |
| P14 | $8.59344 \mathrm{E}+00$ | $1.147226 \mathrm{E}+01$ | $3.27054 \mathrm{E}+00$ | $8.39869 \mathrm{E}+00$ | $9.35934 \mathrm{E}+00$ | $9.45433 \mathrm{E}-01$ | $8.61063 \mathrm{E}+00$ | $1.09952 \mathrm{E}+01$ | $2.38898 \mathrm{E}+00$ | $8.78000 \mathrm{E}+00$ | $1.39000 \mathrm{E}+01$ | $4.08000 \mathrm{E}+00$ | $1.31146 \mathrm{E}+01$ | $1.99439 \mathrm{E}+01$ | $2.87591 \mathrm{E}+00$ |

Table III
Comparison summary between TP-MODE And other STATE-OF-THE-ART ALGORITHMS

| Criteria | Algorithms | better | equal | worse | Dec. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Best | TP-MODE vs. GA-MPC | 8 | 8 | 6 | $\approx$ |
|  | TP-MODE vs. SAMO-DE | 13 | 7 | 2 | + |
|  | TP-MODE vs. EPSDE | 12 | 3 | 7 | $\approx$ |
|  | SHADE | 11 | 8 | 3 | $\approx$ |
|  | TP-MODE vs. GA-MPC | 10 | 4 | 8 | + |
|  | TP-MODE vs. SAMO-DE | 15 | 3 | 4 | + |
|  | TP-MODE vs. EPSDE | 17 | 2 | 3 | + |
|  | SHADE | 11 | 6 | 5 | $\approx$ |

Table IV
FRIEDMAN's TEST RESULTS

|  | Best results | Mean results | Overall mean rank | Order |
| :---: | :---: | :---: | :---: | :---: |
| Algorithm | rank | rank |  |  |
| TP-MODE | $\mathbf{2 . 4 3}$ | $\mathbf{2 . 3 2}$ | 2.79 | 2 |
| GA-MPC | 2.73 | 2.84 | 3.50 | 5 |
| SAMO-DE | 3.50 | 3.50 | 3.44 | 4 |
| EPSDE | 3.18 | 3.70 | 2.90 | 3 |
| SHADE | 3.16 | 2.64 |  |  |

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